

Requesting an Alarm Signal SIGALRM using alarm() System Call

System Call : unsigned int alarm(unsigned int count)

- alarm() instructs the kernel to send the SIGALRM signal to the calling process after counting seconds.
 - If an alarm had already been scheduled, that alarm is overwritten.
 - If count is 0, any pending alarm requests are cancelled.
- The default handler for this signal **displays the message “Alarm clock”** and terminates the process.
- alarm() returns the number of seconds that remain until the alarm signal is sent

System Call alarm() example

- Set Alarm for 3 second with default action handler which will display a default message “**Alarm clock**” and exit the program [alarm_test.c](#)

1_alarm_test.c (~/Desktop/IPC-Signals-Lab) - gedit

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1_alarm_test.c x

```
1 #include <stdio.h>
2 #include <unistd.h>
3
4 int main(void)
5 {
6     alarm(3);
7     printf("Looping forever\n");
8     while(1);
9     printf("This point is never reached\n");
10 }
```

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jayprakash@jayprakash-System-AsusPG500: ~/Desktop/IPC-Signals-Lab

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ gcc 1
1_alarm_test.c 1_alarm_test.c~ 1.png
```

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ gcc 1_alarm_te
st.c -o 1_alarm_test.out
```

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ ./1_alarm_test
.out
```

Looping forever

Alarm clock

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$
```

1_alarm_test.c (~/Desktop/IPC-Signals-Lab) - gedit

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1_alarm_test.c x

```
1 #include <stdio.h>
2 #include <unistd.h>
3
4 int main(void)
5 {
6     alarm(3);
7     printf("Looping forever\n");
8     //while(1);
9     printf("This point is never reached\n");
10 }
```

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jayprakash@jayprakash-System-AsusPG500: ~/Desktop/IPC-Signals-Lab

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ gcc 1_alarm_test.c -o 1_alarm_test.out
```

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ ./1_alarm_test.out
```

```
Looping forever
```

```
This point is never reached
```

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$
```

Handling Signals (Overriding Default Action)

System Call: `void(*signal(int sigCode, void (*func)(int))) (int)`

- `signal()` allows a process to specify the action that it will take when a particular signal is received.
 - `sigCode` specifies the signal number (as per the table shown in earlier slides) that is to be reprogrammed
 - `func` may be one of several values:
 - `SIG_IGN`, which indicates that the specified signal should be ignored and discarded
 - `SIG_DFL`, which indicates that the kernel's default handler should be used.
 - an address of a user-defined function, which indicates that the function should be executed when the specified signal arrives.

Handling Signals

- The valid signal numbers are stored in `/usr/include/signal.h` or `/usr/include/bits/signum.h`
 - The signals `SIGKILL` and `SIGSTP` may not be reprogrammed.
- `signal()` returns the previous func value associated with sigCode if successful; otherwise, it returns a value of -1
- `signal()` system call can be used to override the default action
- A child process inherits the signal settings from its parent during a `fork()`

System Call pause()

System Call: `int pause(void)`

- `pause()` suspends the calling process and returns when a calling process receives a signal.
- It is most often used to wait efficiently for a signal.
- `pause()` doesn't return anything useful.

Catch SIGALRM of alarm() system call using signal() system call

- Write your own handler to handle alarm signal SIGALRM
- Override default action using signal() system call
- [alarm_override.c](#)

2_alarm_override.c (~/Desktop/IPC-Signals-Lab) - gedit

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2_alarm_override.c x

```
1 #include <stdio.h>
2 #include <signal.h>
3 #include <unistd.h>
4
5 int alarmFlag = 0;      /* Global alarm flag */
6 void alarmHandler();    /* Forward declaration of alarm handler */
7
8 int main(void)
9 {
10     signal( SIGALRM, alarmHandler );      /* Install signal handler */
11     alarm(3);                             /* Schedule an alarm signal in three seconds */
12     printf("Looping \n");
13     while( !alarmFlag )      /* Loop until flag set */
14     {
15         pause();             /* Wait for a signal */
16     }
17     printf("Loop ends due to alarm signal \n");
18 }
19
20 void alarmHandler()
21 {
22     printf("An alarm clock signal was received \n");
23     alarmFlag=1;
24 }
```

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```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ gcc 2_alarm_ov
erride.c -o 2_alarm_override.out
```

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ ./2_alarm_over
ride.out
```

```
Looping
```

```
An alarm clock signal was received
```

```
Loop ends due to alarm signal
```

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$
```

Protecting Critical Code from Ctrl-C attack

- Overriding may be used to protect critical pieces of code against Control-C attacks and other such signals.
- it can be restored after the critical code has executed.
- Here's the source code of a program that protects itself against SIGINT signals [ctrl c override.c](#)

3_ctrl_c_override.c (~/Desktop/IPC-Signals-Lab) - gedit

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3_ctrl_c_override.c x

```
1 #include <stdio.h>
2 #include <signal.h>
3 #include <unistd.h>
4 int main(void)
5 {
6     //void (*oldHandler) () /* To hold old handler value */
7     printf("I can be Control-C ed\n");
8     sleep(3);
9     void (*oldHandler)()= signal(SIGINT, SIG_IGN); /* Ignore Control-C */
10    printf("I am protected from Control-C now\n");
11    sleep(3);
12    signal(SIGINT, oldHandler); /* Restore old handler */
13    printf("I can be Control-C ed again\n");
14    sleep(3);
15    printf("Bye! \n");
16 }
```

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jayprakash@jayprakash-System-AsusPG500: ~/Desktop/IPC-Signals-Lab

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ gcc 3_ctrl_c_override.c -o 3_ctrl_c_override.out
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ ./3_ctrl_c_override.out
I can be Control-C ed
^C
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$
```


3_ctrl_c_override.c (~/Desktop/IPC-Signals-Lab) - gedit

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3_ctrl_c_override.c x

```
1 #include <stdio.h>
2 #include <signal.h>
3 #include <unistd.h>
4 int main(void)
5 {
6     //void (*oldHandler) () /* To hold old handler value */
7     printf("I can be Control-C ed\n");
8     sleep(3);
9     void (*oldHandler)()= signal(SIGINT, SIG_IGN); /* Ignore Control-C */
10    printf("I am protected from Control-C now\n");
11    sleep(3);
12    signal(SIGINT, oldHandler); /* Restore old handler */
13    printf("\nI can be Control-C ed again\n");
14    sleep(3);
15    printf("Bye! \n");
16 }
```

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jayprakash@jayprakash-System-AsusPG500: ~/Desktop/IPC-Signals-Lab

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ gcc 3_ctrl_c_override.c -o 3_ctrl_c_override.out
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ ./3_ctrl_c_override.out
I can be Control-C ed
I am protected from Control-C now
^C
I can be Control-C ed again
^C
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$
```

3_ctrl_c_override.c (~/Desktop/IPC-Signals-Lab) - gedit

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3_ctrl_c_override.c x

```
1 #include <stdio.h>
2 #include <signal.h>
3 #include <unistd.h>
4 int main(void)
5 {
6     //void (*oldHandler) () /* To hold old handler value */
7     printf("I can be Control-C ed\n");
8     sleep(3);
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10    printf("I am protected from Control-C now\n");
11    sleep(3);
12    signal(SIGINT, oldHandler); /* Restore old handler */
13    printf("\nI can be Control-C ed again\n");
14    sleep(3);
15    printf("Bye! \n");
16 }
```

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jayprakash@jayprakash-System-AsusPG500: ~/Desktop/IPC-Signals-Lab

```
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ gcc 3_ctrl_c_override.c -o 3_ctrl_c_override.out
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$ ./3_ctrl_c_override.out
I can be Control-C ed
I am protected from Control-C now

I can be Control-C ed again
Bye!
jayprakash@jayprakash-System-AsusPG500:~/Desktop/IPC-Signals-Lab$
```

Process Groups and Control Terminals

- When you're in a shell and you execute a program that creates several children, a single Control-C from the keyboard will normally terminate the program and its children and then return you to the shell.
- In order to support this kind of behavior, UNIX introduced a few new concepts.
 - In addition to having a unique process ID number, every process is also a member of a process group.
 - Several processes can be members of the same process group.
 - When a process forks, the child inherits its process group from its parent.
 - A process may change its process group to a new value by using `setpgid()`
 - When a process execs, its process group remains the same.

Process Groups and Control Terminals

- Every process can have an associated control terminal, which is typically the terminal where the process was started.
 - When a process forks, the child inherits its control terminal from its parent.
 - When a process execs, its control terminal stays the same.
- Every terminal can be associated with a single control process.
 - When a metacharacter such as a Control-C is detected, the terminal sends the appropriate signal to all of the processes in the process group of its control process.
- If a process attempts to read from its control terminal and is not a member of the same process group as the terminal's control process,
 - the process is sent a SIGTTIN signal, which normally suspends the process.

Process Groups and Control Terminals

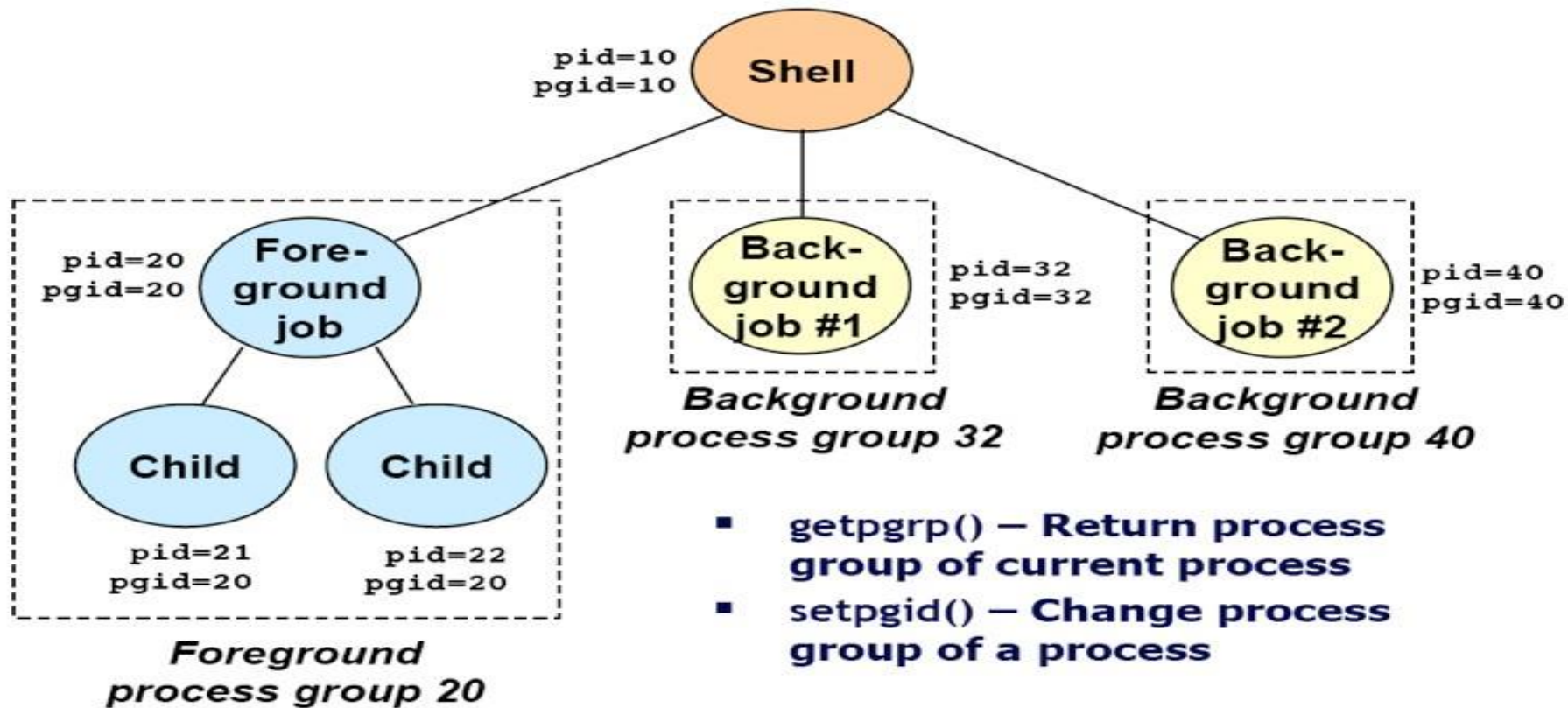
- When an interactive shell begins, it is the control process of a terminal and has that terminal as its control terminal.
- When a shell executes a foreground process:
 - the child shell places itself in a different process group before exec'ing the command and takes control of the terminal.
 - Any signals generated from the terminal thus go to the foreground command rather than to the original parent shell.
 - When the foreground command terminates, the original parent shell takes back control of the terminal.

Process Groups and Control Terminals

- When a shell executes a background process:
 - the child shell places itself in a different process group before executing, but does not take control of the terminal.
 - Any signals generated from the terminal continue to go to the shell.
 - If the background process tries to read from its control terminal, it is suspended by a SIGTTIN signal.

Process Groups and Control Terminals

- **Every process belongs to exactly one process group.**



- **getpgrp()** – Return process group of current process
- **setpgid()** – Change process group of a process