

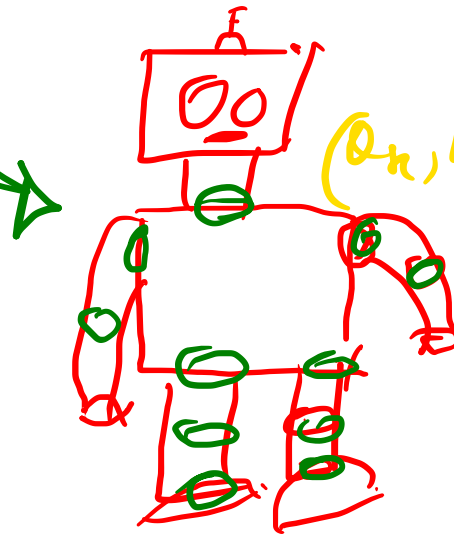
Coding	4 years	
Electronics		Company
Mathematics		looking coding, MBA
Computing		Skills =>
Communication		Math + Coding

AI/ML, Apps, Web . . .

Robotics

Coding in Python

Human Motion
 (x, y, z)



Simulator

$(\theta_x, \theta_y, \theta_z)$

18 joints is ok
Motor - Servo motor

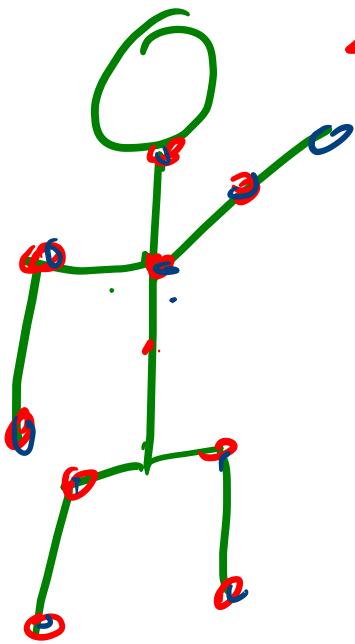
PoseNet \Rightarrow Neural Network

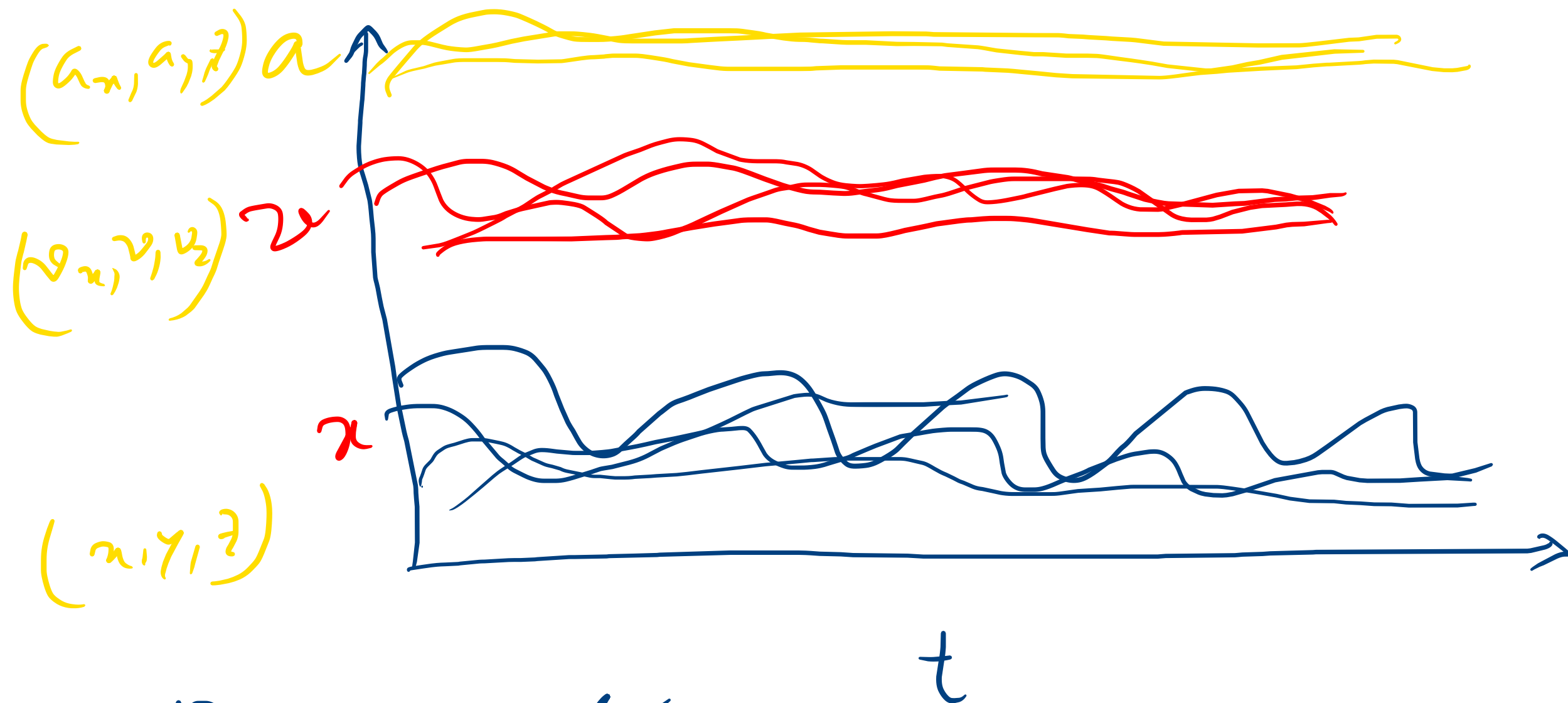
1. Vavare Koli \Rightarrow ML / AI \rightarrow Python Code

2. Rajesh + Indresh | Data Analysis
Data Visualization

Position, Velocity, Acceleration

PoseNet \Rightarrow



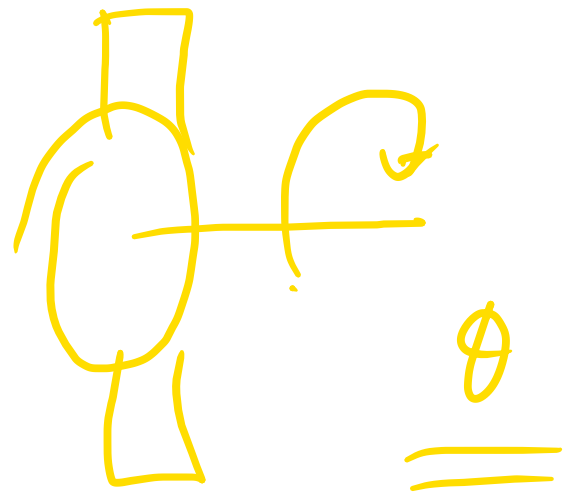


18 Servo-motor

Cartesian Co-ordinates (x, y, z) (v_x, v_y, v_z) a_x, a_y, a_z

Polar - Coordinates $(\theta_x, \theta_y, \theta_z)$, $(\alpha, \alpha, \alpha_2)$

$(\omega_x, \omega_y, \omega_z)$



18 servo

Robots

Humanoid, Industrial, Self-Driving-Car

