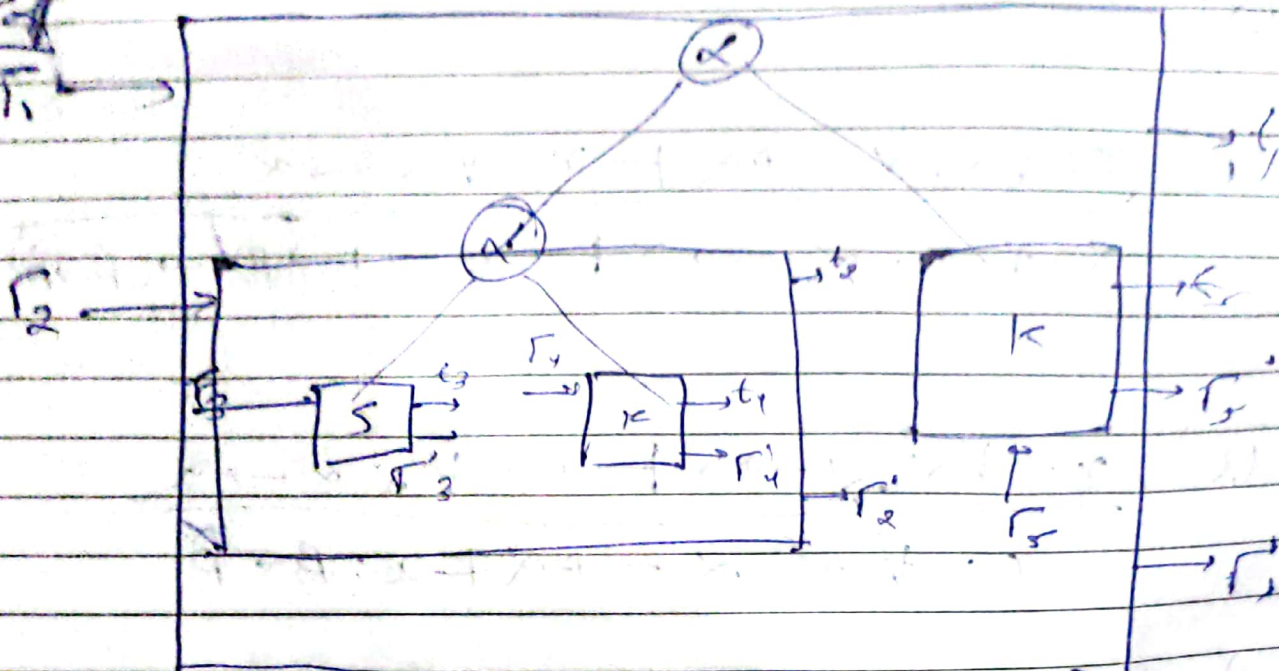


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Sol



Given let

$$K = \lambda x y \rightarrow x$$

in SKK

$$S :: \forall \alpha \beta \gamma. (\alpha \rightarrow \beta \rightarrow \gamma) \rightarrow (\alpha \rightarrow \beta) \rightarrow \alpha \rightarrow \gamma$$

- type of K (observe box of K).

$$\Gamma_2 = \Gamma_1 \cup (x :: \alpha)$$

$$\Gamma_4 = \Gamma_1 \cup (x :: \alpha) \cup (y :: \beta)$$

$$K = \lambda \Gamma \rightarrow (\beta \rightarrow \alpha)$$

$$K \Rightarrow \forall \alpha \beta. \alpha \rightarrow (\beta \rightarrow \alpha)$$

- Now if observing the box of S & also type of S is given, we get

$$\vdash \Gamma_1 = \alpha / S :: \forall \alpha \beta \gamma. (\alpha \rightarrow \beta \rightarrow \gamma) \rightarrow (\alpha \rightarrow \beta) \rightarrow \alpha \rightarrow \gamma$$

$$K :: \forall \alpha \beta. \alpha \rightarrow (\beta \rightarrow \alpha)$$

- ~~$\Gamma_1 \neq \Gamma_2$~~ $\Gamma_1 = \Gamma_2$ & $\Gamma_3 = \Gamma_2$ [same environment]

So $\Gamma_1 = \Gamma_2 = \Gamma_3 = \Gamma_3'$ as $t_3 = (\alpha \rightarrow \beta \rightarrow \alpha) \rightarrow \alpha \rightarrow \alpha$

- $\Gamma_4 = \theta_3 \Gamma_3 = \Gamma_3$ [$\Gamma_3 = \Gamma_3' \Rightarrow \theta_3 = \text{Id}$]

- $\Gamma_4 = \Gamma_3$ (observing box for K), $t_4 = \alpha \rightarrow (\beta \rightarrow \alpha)$

- $\Gamma_4' = \theta_4 \Gamma_4 = \Gamma_4$ [$\theta_4 = \text{Id}$]

- $\theta_3 = \text{Id} = \theta_4$, $\theta_2 = \text{Id}$, $\Gamma_2' = \theta_2 \Gamma_2$

Concluding from above line $\Gamma_2' = \Gamma_2$
 $t_2 = (\alpha \rightarrow \beta) \rightarrow \alpha \rightarrow \alpha$

~~We have calculated Γ_1 in stating
 $\theta_1 = \theta_1 \cdot \theta_2$, $t_1 = \alpha \rightarrow \alpha$~~

- Same environment follows for $\Gamma_5 \neq \Gamma_2$ ($\Gamma_5' = \Gamma_2$)
 $\Gamma_5 = \theta_2 \Gamma_2 = \Gamma_2$

By box of K - we have

$$t_5 = \alpha \rightarrow (\beta \rightarrow \alpha)$$

$$\Gamma_5' = \Gamma_5 \Rightarrow (\theta_5 = \text{Id})$$

- We have calculated Γ_1 .

$$\theta_1 = \theta_1 \cdot \theta_2, \quad t_1 \rightarrow \alpha \rightarrow \alpha$$

Concluding $\theta_2 = \theta_3 = \theta_4 = \theta_5 = \text{Id}$

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Q-3

$$(i) \frac{x: \forall \alpha. \alpha \rightarrow \alpha \vdash x: \forall \alpha \rightarrow \alpha}{x: \forall \alpha. \alpha \rightarrow \alpha \vdash x: (\beta \rightarrow \beta) \rightarrow (\beta \rightarrow \beta)}$$

$$(ii) \frac{x: \forall \alpha. \alpha \rightarrow \alpha \vdash x: \forall \alpha \alpha \rightarrow \alpha}{x: \forall \alpha. \alpha \rightarrow \alpha \vdash x: \beta \rightarrow \beta}$$

Apply P-APP on both (i) & (ii)

$$(iii) \frac{x: \forall \alpha. \alpha \rightarrow \alpha \vdash x: (\beta \rightarrow \beta) \rightarrow (\beta \rightarrow \beta) \quad x: \forall \alpha. \alpha \rightarrow \alpha \vdash x: \beta \rightarrow \beta}{x: \forall \alpha. \alpha \rightarrow \alpha \vdash x x: \beta \rightarrow \beta}$$

• P-ABS on (iii)

$$\frac{x: \forall \alpha. \alpha \rightarrow \alpha \vdash x x: \beta \rightarrow \beta}{x: \forall \alpha. \alpha \rightarrow \alpha \vdash \lambda x. x x: (\forall \alpha. \alpha \rightarrow \alpha) \rightarrow (\beta \rightarrow \beta)}$$

$$\vdash \lambda x. x x: \forall \beta. (\forall \alpha. \alpha \rightarrow \alpha) \rightarrow (\beta \rightarrow \beta)$$

$$\Rightarrow \forall \beta. (\forall \alpha. \alpha \rightarrow \alpha) \rightarrow (\beta \rightarrow \beta)$$

which proves $\boxed{M: \sigma}$

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Q-4

(a) $\therefore \alpha$ is not a unifier

$$\alpha C_1 = p(a, f(g(b)), b)$$

$$\alpha C_2 = p(a, f(f(v)), b)$$

ii) Outer functions of C_1 & C_2 are different, so MGU can't exist, thus α is also not MGU.

(b) α is unifier as well as MGU

$$\alpha = \{x := g(g(v)), y := h(a, z), w := x\}$$

$$w_1 = \{ \langle g(x, h(a, z), f(x)), \langle g(g(g(v))), y, f(w) \rangle \}$$

$$w_2 = \{ \langle g(x, h(a, z), f(x)), \langle g(g(g(v))), y, f(w) \rangle \}$$

$$w_3 = \{ \langle g(\langle x, g(g(v)) \rangle, \langle h(a, z), y \rangle, f(\langle x, w \rangle) \}$$

$$\text{MGU} = \{x := g(g(v)), y := h(a, z), w := x\}$$

$$(c) \alpha_C = \sigma(g(g(v)), h(a, z), f(g(g(v))))$$

$$\alpha_C = \sigma(g(g(v)), h(a, z), f(g(g(v))))$$

α is a unifier & MGU.

MGU is same as we defined in part (b)

because on substituting α we get same

(d) α is a unifier but not MGU

$$WS = \sigma(\sigma(x, (f(x), g(y)), \sigma(z, g(v))))$$

$$WS = \sigma(\sigma(\sigma(f(x), z), \sigma(g(y), g(v))))$$

$$WS = \sigma(\sigma(\sigma(f(x), z), g(\sigma(y, v))))$$

$$MGU = \sigma(z := f(x), y := v)$$

$$\sigma = \sigma(x := a, z := f(a), y := v)$$

$$z := f(a) \neq f(v)$$

Not MGU but unifier.

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Q2

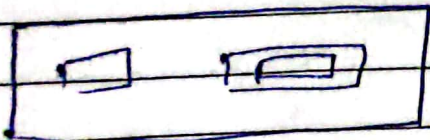
concat $[] = []$

Concat $(x:xs) = x ++ \text{Concat } xs$

Initial environment

$(++) :: \text{List } a \rightarrow \text{List } a \rightarrow \text{List } a$

Top-level: r, \emptyset, t



1x