

## **BUILD PLAN**

1. Disassemble the DVD drives and take out the stepper motors
2. Wire the stepper motors
3. Mount the stepper motors perpendicular to each other
4. Create the z-axis and attach the servo motor
5. Connect the wires to the motor driver shield
6. Run the Arduino code
7. Run the processing code and upload a gcode file
8. Use Inkscape to create own gcode files