



Koneru Lakshmaiah Education Foundation

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Department of Computer Science and Engineering
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DESIGN AND ANALYSIS ALGORITHMS
(23CS2205R)

ALM - CASE STUDY

**Case Study on Bellman-Ford Algorithm for
Shortest Path in Weighted Graphs**

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Bellman-Ford Algorithm

The Bellman-Ford algorithm is used to compute the shortest paths from a single source to all other vertices in a weighted graph, and it is capable of handling graphs with negative-weight edges. Given a weighted graph $G=(V,E)$ with V vertices and E edges, the goal is to find the shortest path from a source vertex to all other vertices. The algorithm also detects negative-weight cycles in the graph.

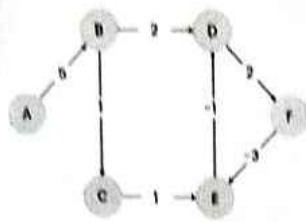
Application/Example:

To provide a practical case study for the Bellman-Ford algorithm, consider its application in a public transportation network. This network is represented as a weighted graph where vertices symbolize bus stops and the edges denote routes between these stops with weights as travel times. Some routes may have negative weights due to subsidies or special discounts during off-peak hours. The objective is to determine the shortest travel time from a central bus station to all other stations.

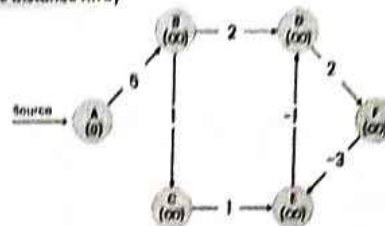
In this scenario, the Bellman-Ford algorithm is critical for two reasons. Firstly, it provides the shortest travel times even in the presence of negative weights, unlike other shortest path algorithms such as Dijkstra's, which only work with non-negative weights. Secondly, the algorithm's ability to detect negative-weight cycles is invaluable because such cycles could represent a scheduling or routing anomaly in the transportation system, like a route that continually decreases total travel time, indicating a potential flaw in route planning.

By applying the Bellman-Ford algorithm to the transportation network, transit planners can optimize travel schedules, ensure fair and efficient route management, and detect and rectify any discrepancies in the routing system that could lead to impractical or inefficient travel times. This application showcases the algorithm's practical utility in managing complex systems with varied route conditions.

ALGORITHM / PSEUDO CODE



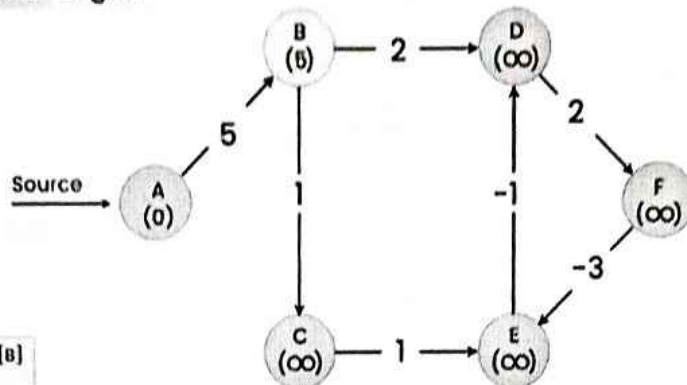
Initialize The Distance Array



Distance Array
Dist[]

| A | B | C | D | E | F |
|---|---|---|---|---|---|
| 0 | ∞ | ∞ | ∞ | ∞ | ∞ |

1st Relaxation Of Edges



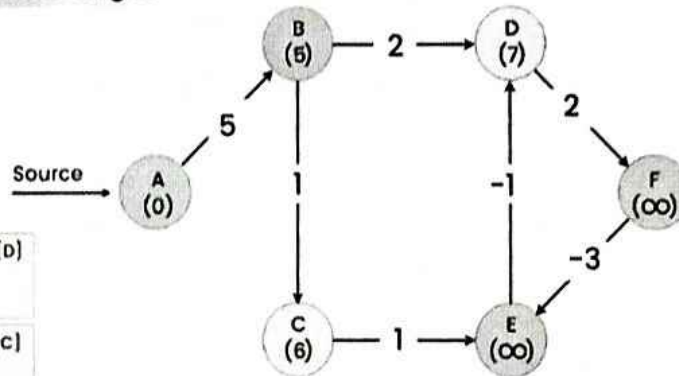
Dist[A] + 5 < Dist[B]
0 + 5 < (∞)
Dist[B] = 5

Distance Array

| A | B | C | D | E | F |
|---|---|---|---|---|---|
| 0 | ∞ | ∞ | ∞ | ∞ | ∞ |

| A | B | C | D | E | F |
|---|---|---|---|---|---|
| 0 | 5 | ∞ | ∞ | ∞ | ∞ |

2nd Relaxation Of Edges



Dist[B] + 2 < Dist[D]
5 + 2 < (∞)
Dist[D] = 7

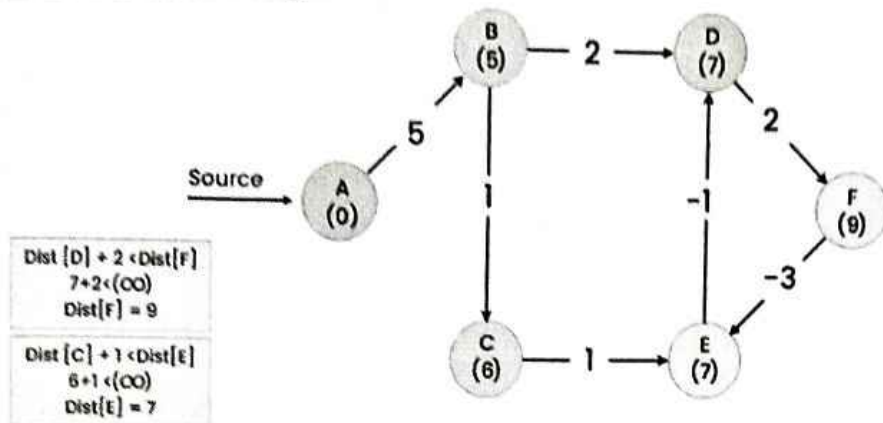
Dist[B] + 1 < Dist[C]
5 + 1 < (∞)
Dist[C] = 6

Distance Array

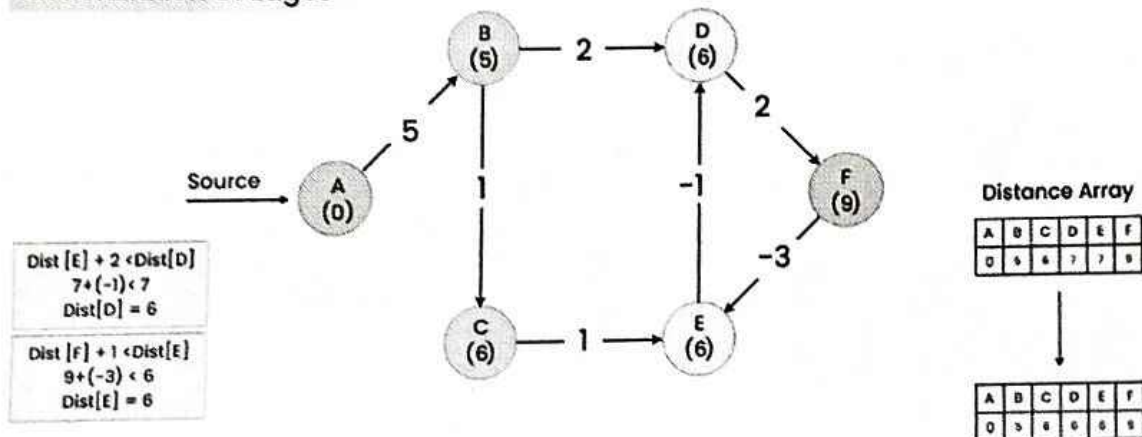
| A | B | C | D | E | F |
|---|---|---|---|---|---|
| 0 | 5 | ∞ | ∞ | ∞ | ∞ |

| A | B | C | D | E | F |
|---|---|---|---|---|---|
| 0 | 5 | 6 | 7 | ∞ | ∞ |

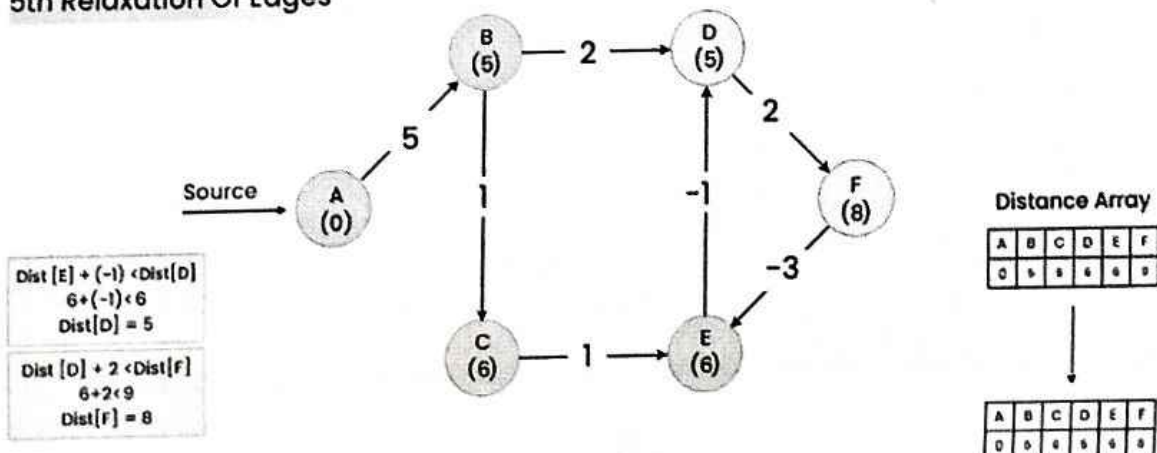
3rd Relaxation Of Edges



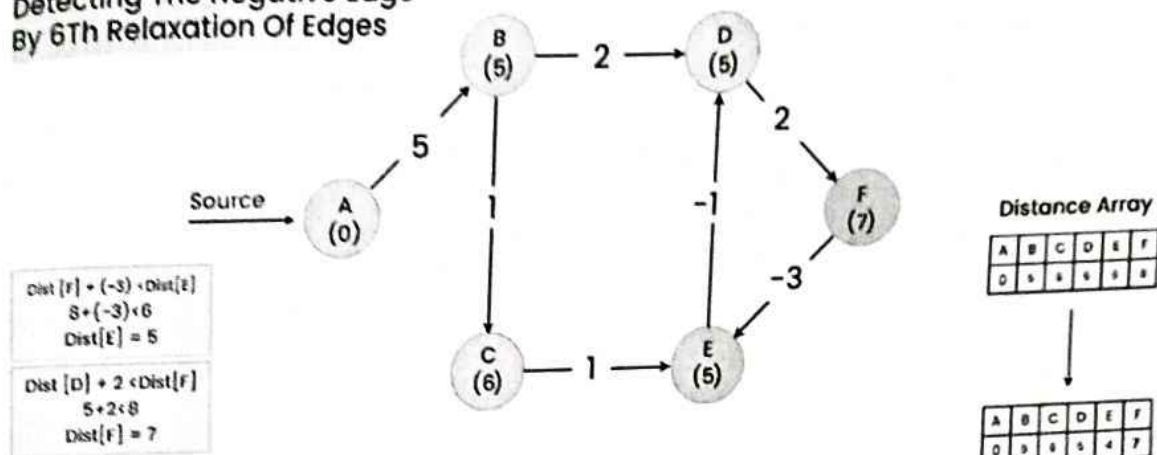
4th Relaxation Of Edges



5th Relaxation Of Edges



Detecting The Negative Edge By 6Th Relaxation Of Edges



Algorithm Bellman-Ford(Graph, source)

Input: Graph $G = (V, E)$ where V is the set of vertices and E is the set of edges, and
 Output: Shortest path from source to all vertices or detection of a negative-weight cycle

Step 1: Initialize distance to all vertices

```

for each vertex v in V
    if v is source
        distance[v] = 0
    else
        distance[v] = infinity
    
```

Step 2: Relax edges repeatedly

```

for i from 1 to |V|-1
    for each edge (u, v) in E
        if distance[u] + weight(u, v) < distance[v]
            distance[v] = distance[u] + weight(u, v)
    
```

Step 3: Check for negative-weight cycles

```

for each edge (u, v) in E
    if distance[u] + weight(u, v) < distance[v]
        report "Graph contains a negative-weight cycle"
    
```

Step 4: Return the distances

```

return distance
    
```

TIME COMPLEXITY

| Operation | Time Complexity |
|--------------------|-----------------|
| Initialization | $O(V)$ |
| Relaxation | $O(V * E)$ |
| Overall Complexity | $O(V * E)$ |

The time complexity of the Bellman-Ford algorithm is primarily determined by its two nested loops:

1. The outer loop runs $|V| - 1$ times, where $|V|$ is the number of vertices in the graph. This loop accounts for the fact that in the worst case, the shortest path through the graph could traverse up to $|V| - 1$ edges (the maximum number of edges in any simple path, preventing cycles).
2. The inner loop iterates over all edges, $|E|$, in the graph. For each iteration of the outer loop, every edge is examined to check if a shorter path can be established through that edge.

SPACE COMPLEXITY

| Space Complexity |
|------------------|
| $O(V)$ |
| $O(1)$ |
| $O(V)$ |

The space complexity of the Bellman-Ford algorithm is $O(V)$, where V is the number of vertices in the graph. This is because the algorithm primarily requires space to store the distance values for each vertex from the source vertex. Additional minimal space may be used for auxiliary data structures such as arrays or lists to manage the edges and vertices during the computation, but the primary storage requirement remains linear in terms of the number of vertices.