

Clustering Methods

- Clustering is the process of grouping the data into classes or clusters, so that objects within a cluster have high similarity in comparison to one another but are very dissimilar to objects in other clusters.
- Some major clustering approaches are:
 - Partitioning Methods
 - Hierarchical Methods
 - Density based methods

Requirements and Challenges

- Scalability
 - Clustering all the data instead of only on samples
- Ability to deal with different types of attributes
 - Numerical, binary, categorical, ordinal, and mixture of these
- Constraint-based clustering
 - User may give inputs on constraints
 - Use domain knowledge to determine input parameters
- Interpretability and usability
- Others
 - Discovery of clusters with arbitrary shape
 - Ability to deal with noisy data
 - Incremental clustering and insensitivity to input order
 - High dimensionality

Partitioning Methods

- This method generally results in a set of *k* clusters. Each cluster maybe represented by a centroid or a cluster representative
- A partitioning method creates an initial partitioning, given k, the number of partitions to construct. It uses an iterative relocation technique that attempts to improve partitioning by moving objects from one group to another
- Partitioning methods can be used for high dimensional data.
 However, one disadvantage is that a user needs to initialize the number of clusters.

K-Means Clustering Algorithm

Algorithm: *K-Means*

Input: k, D

k, is the number of clusters, D a data set containing n objects.

Output: A set of *k* clusters

Method:

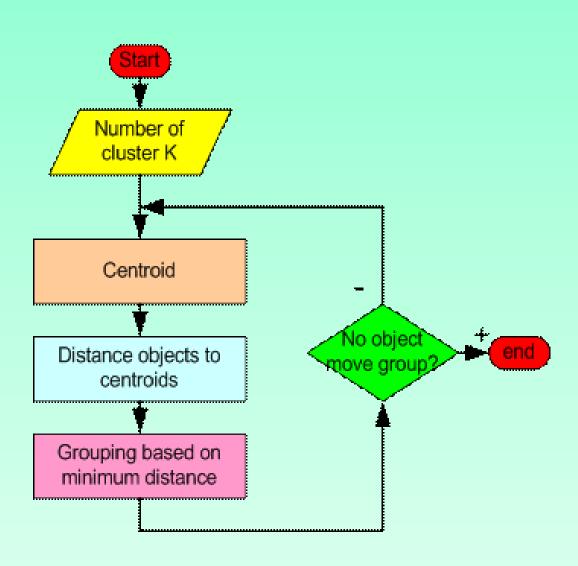
1: arbitrarily choose k objects from D as the initial cluster centers;

2: repeat

3: (re)assign each object to the cluster to which the object is the most similar based on the mean value of the objects in the cluster;

4: update the cluster means, i.e. calculate the mean value of the objects for each cluster;

5: **until** no change;



Example 1: K-Means Clustering

Use k-Means and Euclidean Distance to cluster the following 8 samples into 3 clusters: A1=(2,10), A2=(2,5), A3=(8,4), A4=(5,8), A5=(7,5), A6=(6,4), A7=(1,2), A8=(4,9)

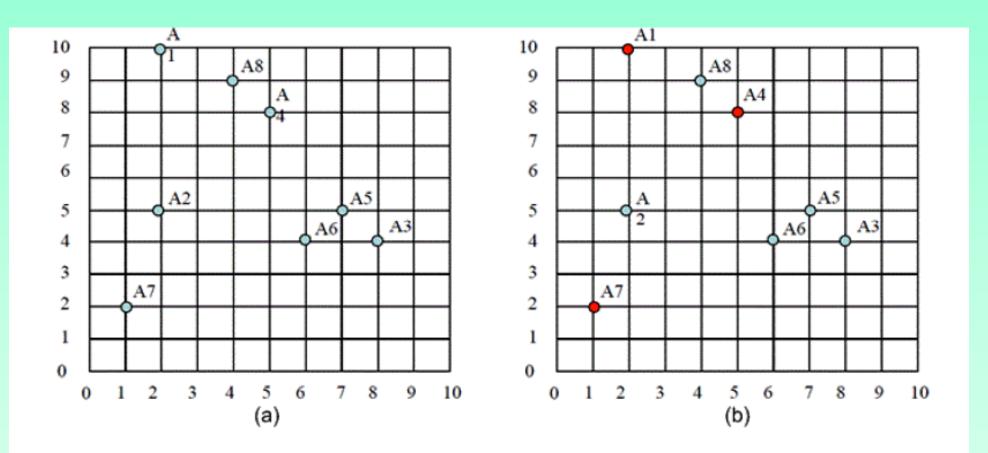


Figure 1: (a) 8 samples (b) 3 clusters (seed1, seed2 and seed3) in red

At the beginning, we initial the centre of the 3 clusters (seed1, seed2 and seed3) to A1, A4 and A7 (Figure 1 (b)).

A1: • d(A1, seed1)=0 as A1 is seed1 (smallest) • d(A1, seed2)=√13 • d(A1, seed3)=√65 → A1 ε cluster1	A2: • d(A2, seed1)= √25 • d(A2, seed2)= √18 • d(A2, seed3)= √10 (smallest) → A2 ε cluster3
A3: • d(A3, seed1)= √36 • d(A3, seed2)= √25 (smallest) • d(A3, seed3)= √53 → A3 ∈ cluster2	 A4: d(A4, seed1)= √13 d(A4, seed2)= 0 as A4 is seed2 (smallest) d(A4, seed3)= √52 → A4 ε cluster2
A5: • d(A5, seed1)= $\sqrt{50}$ • d(A5, seed2)= $\sqrt{13}$ (smallest) • d(A5, seed3)= $\sqrt{45}$ → A5 ϵ cluster2	A6: • d(A6, seed1)= √52 • d(A6, seed2)= √17 (smallest) • d(A6, seed3)= √29 → A6 ε cluster2
A7: • d(A7, seed1)= √65 • d(A7, seed2)= √52 • d(A7, seed3)= 0 as A7 is seed3 (smallest) → A7 ∈ cluster2	A8: • d(A8, seed1)= √5 • d(A8, seed2)= √2 (smallest) • d(A8, seed3)= √58 → A8 ε cluster2

New cluster 1: {A1}, 2: {A3, A4, A5, A6, A8}, 3: {A2, A7}, see Figure 2 (a) Then, the centres of the new clusters (see Figure 2 (b)):

C1=(2,10), C2=(
$$\frac{8+5+7+6+4}{5}$$
, $\frac{4+8+5+4+9}{5}$)=(6,6), C3=($\frac{2+1}{2}$, $\frac{5+2}{2}$)=(1.5, 3.5)

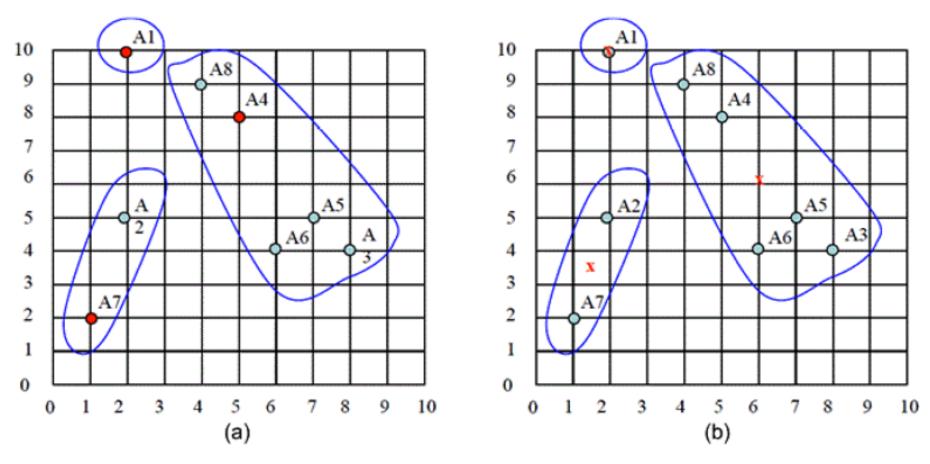


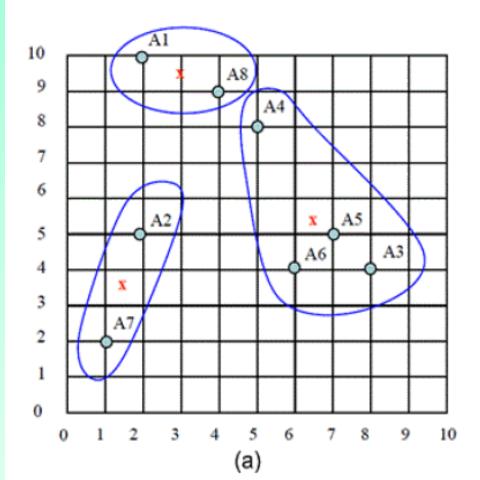
Figure 2: (a) before Epoch 1; (b) centroid has been changed after Epoch 1

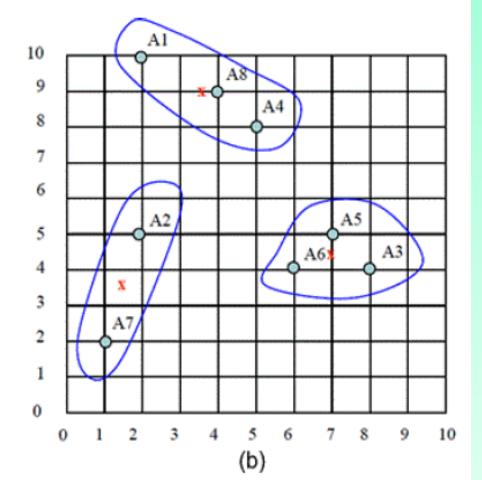
Epoch 2 (Omit), after the 2nd epoch the results would be:

1: {A1, A8}, 2: {A3, A4, A5, A6}, 3: {A2, A7} with centres C1= (3, 9.5), C2= (6.5, 5.25) and C3= (1.5, 3.5)

Epoch 3 (Omit), after the 3rd epoch the results would be:

1: {A1, A4, A8}, 2: {A3, A5, A6}, 3: {A2, A7} with centre C1= (3.66, 9), C2= (7, 4.33) and C3= (1.5, 3.5)





Strengths and weakness of K-Means Method

• Strength: Efficient: O(tkn), where n is # objects, k is # clusters, and t is # iterations. Normally, k, t << n.

Weakness

- Need to specify *k*, the *number* of clusters, in advance (there are ways to automatically determine the best k.
- Sensitive to noisy data and *outliers*
- Not suitable to discover clusters with non-convex shapes