# nikhil\_supekar\_ns4486\_A1\_code

### February 18, 2020

```
[36]: # Import dependencies
     import random
     import numpy as np
     import torch
     import torch.nn as nn
     # You can find Alfredo's plotting code in plot_lib.py in this directory .
     # Download it along with this assignment and keep it in the same directory.
     from plot_lib import set_default, show_scatterplot, plot_bases
     from matplotlib.pyplot import plot, title, axis
     from time import perf_counter
[37]: # Set up your device
     cuda = torch.cuda.is_available()
     device = torch.device("cuda:0" if cuda else "cpu")
[38]: # Set up random seed to 1008. Do not change the random seed.
     # Yes, these are all necessary when you run experiments!
     def set random seed(seed):
         random.seed(seed)
         np.random.seed(seed)
         torch.manual_seed(seed)
     set_random_seed(1008)
     if cuda:
         torch.cuda.manual_seed(seed)
         torch.cuda.manual_seed_all(seed)
         torch.backends.cudnn.benchmark = False
         torch.backends.cudnn.deterministic = True
```

### 1 1. Full, slice, fill

Write a function warm\_up that returns the 2D tensor with integers below. **Do not use any loops**.

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```

Hint: Use torch.full, torch.fill\_, and the slicing operator.

```
[39]: def warm_up():
    x = torch.full((13, 13), 1)

    x[:, 1] = x[1, :] = 2
    x[:, 6] = x[6, :] = 2
    x[:, 11] = x[11, :] = 2

    x[3:5, 3:5] = x[3:5, 8:10] = x[8:10, 3:5] = x[8:10, 8:10] = 3

    return x

# Uncomment line below once you implement this function.
print(warm_up())
```

## 2 2. To Loop or not to loop

The motivation for the following three sub-questions is to get you to think critically about how to write your deep learning code. These sorts of choices can make the difference between tractable

and intractable model training.

### 2.1 2.1. mul\_row\_loop

Write a function mul\_row\_loop, using python loops with simple indexing but no advanced indexing/slicing, that receives a 2D tensor as input and returns a tensor of same size that is - equal to the input on the first row - 2 times the input's second row on the second row - 3 times the input's third row on the third row - etc..

For instance:

```
>>> t = torch.full((4, 8), 2.0)
    >>> t
    tensor([[2., 2., 2., 2., 2., 2., 2., 2.],
    [2., 2., 2., 2., 2., 2., 2., 2.]
    [2., 2., 2., 2., 2., 2., 2., 2.]
    [2., 2., 2., 2., 2., 2., 2., 2.]
    >>> mul_row(t)
    tensor([[2., 2., 2., 2., 2., 2., 2., 2.],
    [4., 4., 4., 4., 4., 4., 4., 4., 4.]
    [6., 6., 6., 6., 6., 6., 6., 6.]
    [8., 8., 8., 8., 8., 8., 8., 8.]
[40]: def mul_row_loop(input_tensor):
         rows = input tensor.size()[0]
         cols = input_tensor.size()[1]
         output_tensor = torch.full((rows, cols), 1)
         for i in range(rows):
             for j in range(cols):
                 output_tensor[i, j] = input_tensor[i, j] * (i + 1)
         return output_tensor
```

### 3 2.2. mul\_row\_fast

Write a second version of the same function named mul\_row\_fast which uses tensor operations and no looping.

Hint: Use broadcasting and torch.arange, torch.view, and torch.mul.

```
[41]: def mul_row_fast(input_tensor):
    num_rows = input_tensor.size()[0]
    x = torch.arange(1, num_rows + 1).view(num_rows, 1)
    return input_tensor.mul(x)
```

#### 4 2.3. times

Write a function times which takes a 2D tensor as input and returns the run times of mul\_row\_loop and mul\_row\_fast on this tensor, respectively. Use time.perf\_counter.

Use torch. ones to create a 2D tensor of size (1000, 400) full of ones and run times on it (there should be more than two orders of magnitude difference).

```
[42]: from time import perf_counter
def times(input_tensor):
    t1 = perf_counter()
    mul_row_loop(input_tensor)
    t2 = perf_counter()
    mul_row_fast(input_tensor)
    t3 = perf_counter()

    return t2 - t1, t3 - t2

# Uncomment lines below once you implement this function.
input_tensor = torch.ones(1000, 400)
time_1, time_2 = times(input_tensor)
print('{}, {}'.format(time_1, time_2))
```

5.5979539290000275, 0.00035807199992632377

### 5 3. Non-linearities

In this section, we explore similar concepts to Lab 1 and get comfortable initializing modules like nn.Linear and using non-linearities in PyTorch.

#### 5.1 3.1. ReLU

ReLU (Rectified Linear Unit) is a non-linear activation fuction defined as:

```
y = \max(0, x)
```

Define a fully connected neural network linear\_fc\_relu which: - takes 2 dimensional data as input and passes it through linear modules (torch.nn.Linear) - has one hidden layer of dimension 5 - has output dimension of 2 - has ReLu as an activation function

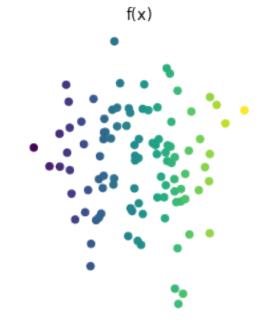
Create a tensor with input data *X* of size (100, 2) using torch.randn.

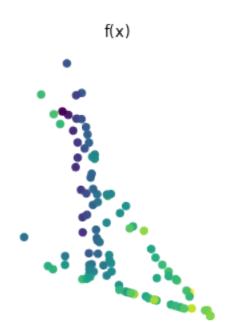
Following the example in https://github.com/Atcold/pytorch-Deep-Learning-Minicourse/blob/master/02-space\_stretching.ipynb, visualize the output of passing X through the neural network linear\_fc\_relu.

You can find Alfredo's plotting code in plot\_lib.py in this directory. Download it along with this assignment and keep it in the same directory.

```
nn.Linear(5, 2)
)
linear_fc_relu.to(device)

with torch.no_grad():
    Y = linear_fc_relu(X)
show_scatterplot(X, X[:, 0], title='f(x)')
show_scatterplot(Y, X[:, 0], title='f(x)')
```





### 5.2 3.2. Sigmoid

The sigmoid function is another popular choice for a non-linear activation function which maps its input to values in the interval (0,1). It is formally defined as:

$$\sigma(x) = \frac{1}{1 + exp[-x]}$$

Define a new neural network linear\_fc\_sigmoid which is the same architecture as in part 3.1. but with a sigmoid unit instead of ReLU.

Using the same X as in part 3.1, visualize the output of passing X through the neural network linear\_fc\_sigmoid.



