

1)

$$G(s) = \frac{k e^{-sT}}{s^r}$$

$$G(j\omega) = k \frac{e^{-j\omega T}}{j\omega}$$

$$-TW - 90 = -110$$

$$\omega = \frac{90}{T} = \frac{\pi}{T}$$

$$|G(j\omega)| = \left| \frac{k}{\omega} \right| \rightarrow |G(j\frac{\pi}{T})| = \left| \frac{k}{\pi} \times T \right| = \frac{kT}{\pi}$$

$$G_m = 20 \log \frac{1}{|G(j\omega_P)|} = -20 \log \frac{kT}{\pi}$$

$$|G(j\omega)| = 1 = -dB \Rightarrow k = \omega$$

$$p_m = \angle G(j\omega) - 110$$

$$p_m = -kT + \frac{\pi}{T}$$

$$G_m > 0 \Rightarrow -20 \log \frac{kT}{\pi} > 0 \Rightarrow 0 < \frac{kT}{\pi} < 1 \Rightarrow 0 < k < \frac{\pi}{T}$$

$$p_m > 0 \Rightarrow -kT + \frac{\pi}{T} > 0 \Rightarrow k < \frac{\pi}{T}$$

2)

$$G(s) = \frac{k(s+r)}{s^2} \rightarrow \frac{k(j\omega+r)}{j^2\omega^2} = \frac{k(j\omega+r)}{-\omega^2}$$

$$|G(j\omega)| = \frac{k\sqrt{\omega^2 + r^2}}{\omega^2} \quad |G(j\omega)| = 1 \quad k\sqrt{\omega^2 + r^2} = \omega^2$$

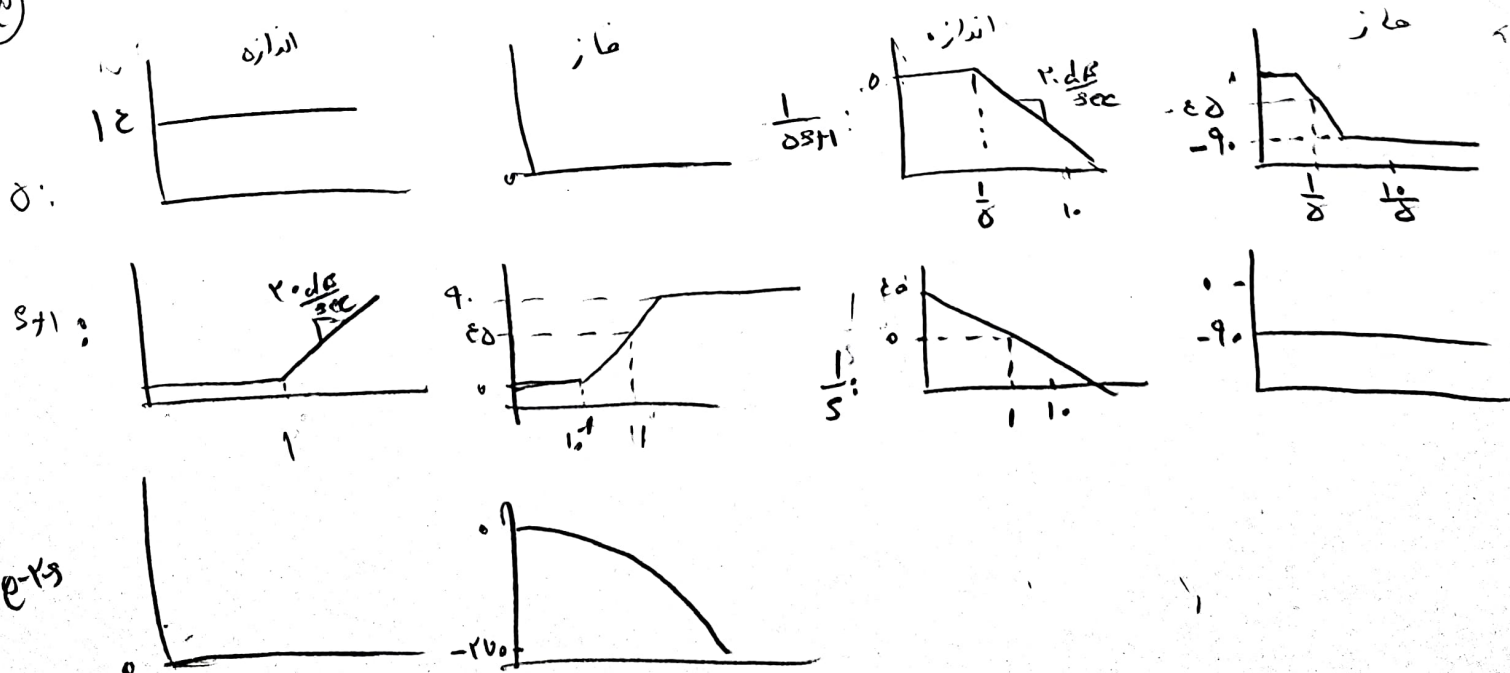
$$p_m = \angle G(j\omega_c) - 110$$

$$\tan^{-1}\left(\frac{\omega}{r}\right) - 0 - 110 = -\varepsilon \quad \tan^{-1}\left(\frac{\omega_c}{r}\right) = \varphi$$

$$k\sqrt{r^2} = \varepsilon \quad k = \sqrt{\varepsilon}$$

$$\omega_c = r$$

3)

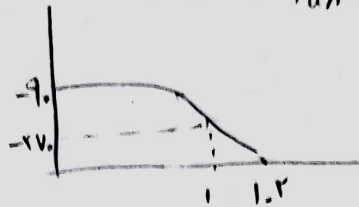
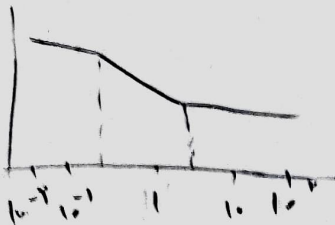


$$G = \frac{s}{s+1} \times e^{-\tau s} \times \frac{s+1}{s}$$

$$G(j\omega) = \frac{\omega(j\omega+1)e^{-\tau j\omega}}{j\omega(\omega j+1)}$$

$$\Delta G(j\omega) = \tan^{-1}(\omega) - \tau\omega - (\tan^{-1}(\omega) - \tau\omega) = -180^\circ$$

$$\omega \approx 0.1 \text{ rad/s}$$



$$|G(j\omega)| = \left| \frac{\omega(j\omega+1)e^{-\tau j\omega}}{j\omega(\omega j+1)} \right| = \frac{\omega \sqrt{1+\tau^2\omega^2}}{\omega \sqrt{1+\tau^2\omega^2}} \approx \omega \tau$$

$$G_m = -20 \log \omega \tau = -18 \text{ dB}$$

$$|G(j\omega)| = 1 \quad \frac{\omega \tau}{\omega \tau} = 1 \quad \omega \approx 1/\tau$$

$$P_m = \underbrace{\tan^{-1}(\omega) - \tan^{-1}(\omega\tau) - \tau\omega - 90^\circ - 180^\circ}_{\Delta G} \Rightarrow P_m = -180^\circ$$

$$P_m, G_m \Rightarrow \text{Bode plot}$$

②

$s = j\omega$

$$G(j\omega) = \frac{\epsilon a^2}{(j\omega + a)^2} = \frac{\epsilon a^2}{a^2 - \omega^2 + j2a\omega}$$

$$|G(j\omega)| = \frac{\epsilon a^2}{\sqrt{a^4 - 2a^2\omega^2 + \omega^4}} = \frac{\epsilon a^2}{\omega^2 + a^2}$$

$$\angle G(j\omega) = 0 - \tan^{-1}\left(\frac{\omega}{a}\right) - \tan^{-1}\left(\frac{\omega}{a}\right) = -180^\circ \quad \frac{\omega}{a} = \infty \Rightarrow G_m = -180^\circ$$

$$|G(j\omega)| = 1 \quad \epsilon a^2 = \omega^2 + a^2 \quad \omega = \sqrt{\epsilon} a \quad P_m = 0 - 2 \tan^{-1}\left(\frac{\omega}{a}\right) - 180^\circ = -180^\circ$$

$$\Rightarrow P_m = -180^\circ$$

← Bode plot

```
clc;
clear;
T = 2;
num = [5 5];
den = [5 1 0];
G = tf(num, den, 'InputDelay', T);
bode(G);
margin(G);
grid on;
```

