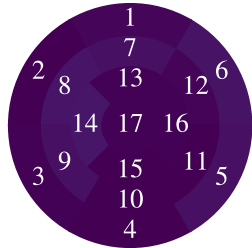
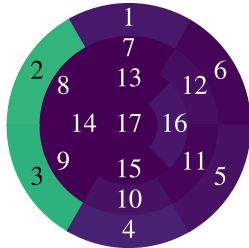
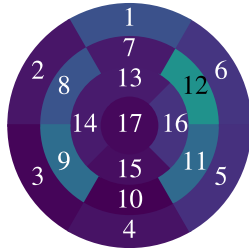
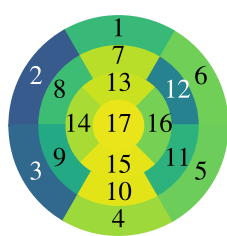


$y_d$  $z_d$  $\alpha$  $R_L$  $\mathcal{S}$ 

1.0

0.8

0.5

0.2

0.0