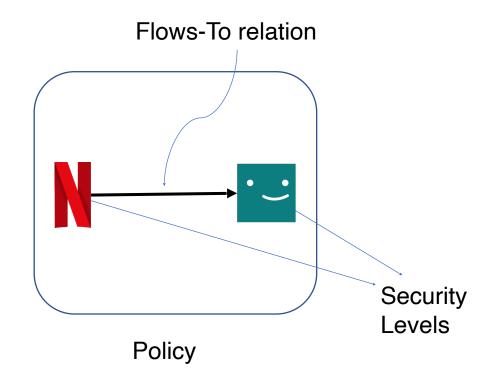
Design, implementation, and mechanisation of dynamic policies

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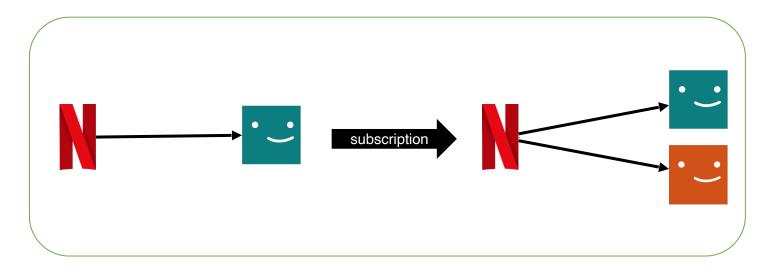
Information flow control

Secure exchange of information in a system



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Secure exchange of information in a system



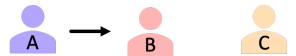
Dynamic Policy

Permitted flows can change during computation

Problem

It is unclear how to interpret dynamic policies

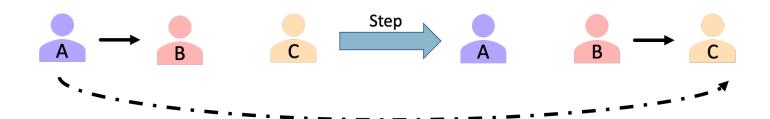
Example of Dynamic Policy



Example of Dynamic Policy



Is this safe?



Information is shared from A to C via B through time

It depends!



```
Allowed ✓

-- A = Input

-- B = Sanitizer

-- C = DB

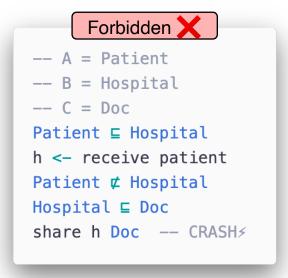
Input ⊑ Sanitizer

s <- sanitize input

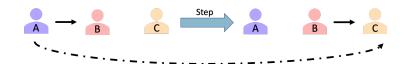
Input ⊄ Sanitizer

Sanitizer ⊑ DB

store s
```



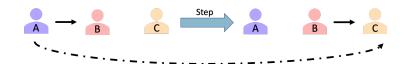
It depends!



```
-- A = Input
-- B = Sanitizer
-- C = DB
Input ⊑ Sanitizer
s <- sanitize input
Input ⊄ Sanitizer
Sanitizer ⊑ DB
store s
```

We want to **allow** the exchange

It depends!



```
Forbidden ★

-- A = Patient

-- B = Hospital

-- C = Doc

Patient ⊑ Hospital

h <- receive patient

Patient ⊄ Hospital

Hospital ⊑ Doc

share h Doc -- CRASH≶
```

We want to **forbid** the exchange

By knowing the value of h, DOC learns the patient's information

Safety of IF depends on the security policy.

There exist various interpretations of dynamic policies (a.k.a. facets): We just saw that one

- Time-transitive: moves information from A to C via B
- Termination insensitive: leak information via divergence
- Replaying: release of information is permanent
- Whitelisting: allowed by some other part of the policy

Design of Systems with Dynamic Policies

- Security condition: predicate that gives semantics to the policy to express the intended interpretation
- 2 Enforcement mechanism: a monadic library that enforces the security condition
- Proof mechanisation: that we can only build programs that satisfy the security condition

Security Condition

Can we securely execute a program e with an original state Σ ?

$$\begin{array}{c} \langle \Sigma \mid e \rangle \Downarrow t \cdot \alpha \\ \text{is an execution trace, i.e., there exists a sequence} \\ \langle \Sigma \mid e \rangle \rightarrow \langle \Sigma_1 \mid e_1 \rangle \rightarrow \ldots \rightarrow \langle \Sigma_n \mid e_n \rangle \end{array}$$

To define the security condition for an attacker A, we use

Erasure $\varepsilon_A(\cdot)$ to encode observability and

Exclusion knowledge $ek_A(\cdot)$ to encode what is observed by an attacker.

Erasure

- Removes any non observable information
- Maps expressions to equivalence classes that cannot be distinguished by an attacker

```
-- A = Patient
-- B = Hospital
-- C = Doc
Patient ⊑ Hospital
h <- receive patient
Patient ⊄ Hospital
Hospital ⊑ Doc
share h Doc -- CRASH≶
```

Erasure

- Removes any non observable information
- Maps expressions to equivalence classes that cannot be distinguished by an attacker



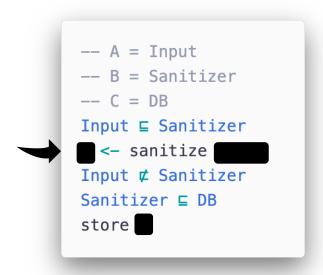
```
-- A = Patient
-- B = Hospital
-- C = Doc
Patient ⊑ Hospital
-- receive
Patient ⊄ Hospital
Hospital ⊑ Doc
share □ Doc -- CRASH۶
```

Attacker's Knowledge

Exclusion Knowledge set

 All expressions that can be excluded since they can't produce the same observations

```
-- A = Patient
-- B = Hospital
-- C = Doc
Patient ⊑ Hospital
-- receive
Patient ⊄ Hospital
Hospital ⊑ Doc
share □ Doc -- CRASH۶
```



$$ek_{DB} = \emptyset$$

```
-- A = Input
-- B = Sanitizer
-- C = DB
Input ⊑ Sanitizer
s <- sanitize input
Input ⊄ Sanitizer
Sanitizer ⊑ DB
store s
```

$$ek_{DB} = \{v \mid s \neq \text{sanitize } v\}$$

Exclusion Knowledge

The exclusion knowledge of an attacker A i.e., the set of initial inputs that could not have lead to A's observations.

$$ek_A(o) = \{e' \mid \neg \exists t'. \langle \Sigma \mid e' \rangle \Downarrow t' \text{ and } \varepsilon_A(t') = o\}$$

Why exclusion?

Because it is better to convey what information **cannot** be leaked

Exclusion Knowledge

The exclusion knowledge of an attacker A i.e., the set of initial inputs that could not have lead to A's observations.

$$ek_A(o) = \{e' \mid \neg \exists t'. \langle \Sigma \mid e' \rangle \Downarrow t' \text{ and } \varepsilon_A(t') = o\}$$

The exclusion progress knowledge of an attacker A also requires that the final state is observable

$$ek_A^+(o) = \{e' \mid \neg \exists t', \alpha'. \langle \Sigma \mid e' \rangle \Downarrow t' \cdot \alpha' \text{ and } \varepsilon_A(t') = o \land obs_A(\alpha')\}$$

Security Condition

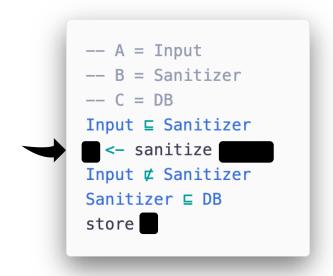
What the attacker A can exclude up to the latest observation

What the attacker is allowed to learn with the latest observation according to the policy

$$oxed{ek_A(arepsilon_A(t\cdot lpha))}ackslash ek_A^+(arepsilon_A(t))\subseteq oxed{\mathcal{B}_A(t,lpha)}$$

What the attacker A can exclude knowing that the next step is observable

where $\langle \Sigma \mid e \rangle \Downarrow t \cdot \alpha$ is an execution trace, i.e., there exists a sequence $\langle \Sigma \mid e \rangle \rightarrow \langle \Sigma_1 \mid e_1 \rangle \rightarrow \ldots \rightarrow \langle \Sigma_n \mid e_n \rangle$



$$ek_{DB} \backslash ek_{DB}^+ = \emptyset$$

$$B_{DB} = \emptyset$$

```
-- A = Input
-- B = Sanitizer
-- C = DB
Input ⊑ Sanitizer
s <- sanitize input
Input ⊄ Sanitizer
Sanitizer ⊑ DB
store s
```

$$ek_{DB} \backslash ek_{DB}^{+} = \{ v \mid s \neq \text{sanitize } v \}$$

 $B_{DB} = \{ v \mid s \neq \text{sanitize } v \}$

```
-- A = Patient
-- B = Hospital
-- C = Doc
Patient ⊑ Hospital
h <- receive patient
Patient ⊄ Hospital
Hospital ⊑ Doc
share h Doc -- CRASH≶
```

$$ek_{Doc} \backslash ek_{Doc}^+ = \{ v \mid s \neq \text{receive } v \}$$

$$B_{Doc} = \emptyset$$

Design of Systems with Dynamic Policies

- 1) Security condition definition for each interpretation
- 2 Enforcement mechanism that satisfies the security condition
- Mechanization aiming for proof reuse

LIO: IFC in Haskell

```
class (Eq l) ⇒ Label l where

(\sqsubseteq) :: l → l → Bool -- Can flow to

(\sqcup) :: l → l -- Join

(\sqcap) :: l → l → l -- Meet ()
```

 $L \sqsubseteq L = True$ $L \sqsubseteq H = True$ $H \sqsubseteq L = False$ $H \sqsubseteq H = True$

Labels are lattices, e.g., (L | H) that are used to protect values

newtype Label $l \Rightarrow$ Labeled l = Lab l a

Lab H 42

LIO: IFC in Haskell

The labeled monad keeps track of the "current label"

```
newtype Label l \Rightarrow LIO l a = LIO (StateT l IO a)
```

$$\langle lc \mid e \rangle \rightarrow \langle lc \mid e \rangle$$

To create values labeled I, the current label should flow to the I

```
 \begin{array}{c} label :: Label \ l \Rightarrow l \rightarrow a \rightarrow LIO \ l \ (Labeled \ l \ a) \\ label \ l \ v = do \\ lc \leftarrow get \\ if \ lc \sqsubseteq l \ then \ return \ (Lab \ l \ v) \\ else \ throwError \end{array}
```

$$\langle L \mid label H 42 \rangle \longrightarrow \langle L \mid Lab H 42 \rangle$$

$$\langle H \mid label L 42 \rangle \longrightarrow \langle H \mid error \rangle$$

To unlabel it raises the current label

unlabel :: Label
$$l \Rightarrow$$
 Labeled $l \Rightarrow$ LIO $l \Rightarrow$ unlabel (Lab $l \Rightarrow$ v) = modify ($\sqcup l$) >> return v

$$\langle L \mid \text{unlabel (Lab H 42)} \rangle \longrightarrow \langle H \mid 42 \rangle$$

LIO: IFC in Haskell

LIO is very **simple**, has many extensions and applications, and comes **partially** verified in Coq.

But, does not support dynamic policies.

"Flexible Dynamic Information Flow Control in the presence of exceptions", by Stefan, Russo, Mitchell, and Mazieres. JFP'17

"Addressing covert termination and timing channels in concurrent information flow systems", by Stefan, Russo, Buiras, Levy, Mitchell, and Mazieres. ICFP'12. Most Influential Paper

SLIO: Stateful LIO for Dynamic Policies

The **state** now tracks the history of the flows-to relations

```
newtype SLIO l a = SLIO (StateT (l, [[(l,l)]]) IO a)
```

$$\langle lc, st \mid e \rangle \rightarrow \langle lc, st \mid e \rangle$$

Labelling now checks flows-to based on the state

```
\begin{aligned} \text{label} &:: l \to a \to \text{SLIO} \ l \ (\text{Labeled} \ l \ a) \\ \text{label} & \ l \ v = \text{do} \\ & \ (\text{lc,st}) \leftarrow \text{get} \\ & \ \text{if} \ lc \sqsubseteq_{\text{St}} l \ \text{then} \ \text{return} \ (\text{Lab} \ l \ v) \\ & \ & \ \text{else} \ \text{throwError} \end{aligned}
```

$$lc \sqsubseteq_{st} l = (lc,l) \in closure st$$

"Dynamic Enforcement of Dynamic Policies", by Buiras and van Delft. PLAS'15

SLIO: Stateful LIO for Dynamic Policies

SLIO was the first LIO extension that supports dynamic policies and comes with a paper and pencil security proof.

But, it only captures time-transitive flows.

DynLIO: Dynamic Policies

To capture various dynamic policies we "just" make the label guard parametric

```
label :: l \rightarrow a \rightarrow SLIO l (Labeled l a)
label l v = do
(lc,st) \leftarrow get
if lc \sqsubseteq_{st} l then return (Lab l v)

else throwError
```

```
class IFC l st where guard :: l \rightarrow st \rightarrow Bool
```

DynLIO: Dynamic Policies

To capture various dynamic policies we "just" make the label guard parametric

```
 \begin{array}{c} label :: IFC \ l \ st \Rightarrow l \rightarrow a \rightarrow DynLIO \ l \ st \ (Labeled \ l \ a) \\ label \ l \ v = do \\ st \leftarrow get \\ if \ guard \ l \ st \ then \ return \ (Lab \ l \ v) \\ else \ throwError \end{array}
```

```
class IFC l st where guard :: l \rightarrow st \rightarrow Bool
```

$$\langle i, st \mid e \rangle \rightarrow \langle st \mid e \rangle$$

"Just" because in reality IFC has more methods for other IFC functions, e.g., toLabeled

DynLIO: Dynamic Policies

class IFC l st where guard :: $l \rightarrow st \rightarrow Bool$

Time Transitive

```
instance IFC l _ where guard l (lc,st) = (lc, l) \in closure st
```

No Time Transitive

```
instance IFC l _ where guard l (lc,st) = (lc, l) \in latest st
```

Simple LIO

```
instance Label l \Rightarrow IFC l () where guard l lc = lc <math>\sqsubseteq l
```

DynLIO for Dynamic Policies

DynLIO provides a modular interface to encode **various** dynamic policies.

It is complicated to define a new instance (e.g., toLabeled definition is omitted and requires come complicated state) but easy to use.

We have use it to define instances for LIO, no time transitive, time transitive, and replaying.

We hope it can also be used for a modular proof.

Design of Systems with Dynamic Policies

- 1) Security condition definition for each interpretation
- 2 Enforcement mechanism that satisfies the security condition
- (3) Mechanization aiming for proof reuse

Mechanisation of IFC is difficult

LIO's partial mechanisation had an error (on the definition of erasure).

SLIO's paper and pencil proof had an error (on the definition of erasure).

There is no mechanised proof of dynamic policies.

Expressions are embedded as a data type

```
data Expr l
= ELabel (Expr l) (Expr l)
| ELab l | ERet (Expr l) ...
```

Evaluation is defined parametrised with the IFC methods

The security condition is encoded into a refinement type

$$ek_A(arepsilon_A(t\cdot lpha))ackslash ek_A^+(arepsilon_A(t))\subseteq \mathcal{B}_A(t,lpha)$$

```
 \begin{split} & security :: l:Label \rightarrow s\_0:State \\ & \rightarrow e\_1:Exprl \rightarrow e\_2:Exprl \\ \\ & \rightarrow t\_n:Tracelst \rightarrow s\_n:State \\ & \rightarrow e\_n:ObsEvalExprls\_0 e\_1 t\_n s\_n \rightarrow s:\{State \mid st s\_n = s \} \\ \\ & \rightarrow t\_m:Tracelst \rightarrow s\_m:State \\ & \rightarrow e\_m:ObsEvalExprls\_0 e\_2 t\_m s\_m \\ \\ & \rightarrow LowEquivTracel t\_n t\_m \\ & \rightarrow InputReleaselse_lse\_le\_2 \\ & \rightarrow SecurityBoundlst\_n t\_m \\ & \rightarrow LowEquivTracel(t\_n >> (Pg s\_n e\_n)) (t\_m >> (Pg s\_m e\_m)) \\ \end{aligned}
```

Goal: Define security

Currently:

security is almost defined for the time transitive instance
all the development (with comments) is 10K lines of code
security is property base tested
(to be presented at Lambda Days by Fernanda Andrade)
(we found errors in the definition of erasure)

Currently:

security is almost defined for the time transitive instance all the development (with comments) is 10K lines of code security is property base tested

Next:

Define security for more instances and hope to observe proof reuse Compose instances to define new dynamic policies

Design of Systems with Dynamic Policies

- Security condition: predicate that gives semantics to the policy to express the intended interpretation
- **Enforcement mechanism:** dynLIO, a monadic and parametric library that enforces the security condition
- Proof mechanisation: proof the dynLIO actually enforces the security condition under development, with aim of modularity

Thanks!