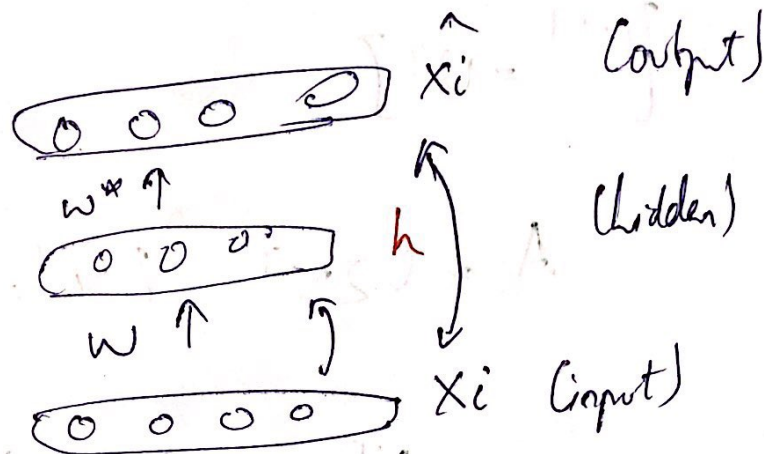


# Lecture 9

7.1

## Introduction to Autoencoders



Special type of feed forward ~~net~~ neural network

Encodes its input  $x_i$  into a hidden representation  $h$

Encoder function

$$h = g(Wx_i + b)$$

$$x_i \in \mathbb{R}^n \quad h \in \mathbb{R}^d$$

$$W \in \mathbb{R}^{d \times n}$$

$$b \in \mathbb{R}^{d \times n}$$

$$\hat{x}_i = f(W^*h + c) \quad \begin{matrix} W^* \in \mathbb{R}^{n \times d} \\ x_i \in \mathbb{R}^n \end{matrix}$$

Decoder, decodes the input again from the hidden representation

The model is trained to minimize a certain loss function which will ensure that  $\hat{x}_i$  is close to  $x_i$ .

if  $\dim(h) < \dim(x_i)$

~~Not~~ Under Complete Autoencoder.

if we are able to reconstruct  $x_i^n$  perfectly from  $h$ , then  $h$  is a loss-free encoding of  $x_i$ . It captures all the ~~important~~ important characteristics of  $x_i$ .

Analogy with PCA.

$\dim(h) \geq \dim(x_i)$

Over complete Autoencoder.

Identity encoding is useless.

- 
- Choice of  $f(x_i)$  &  $g(x_i)$
  - Choice of loss function

If it's binary → for decoder is logistic function

if  $\phi$  is real number,  
the function will be linear  
 $g$  is typically chosen as sigmoid.

### Loss function

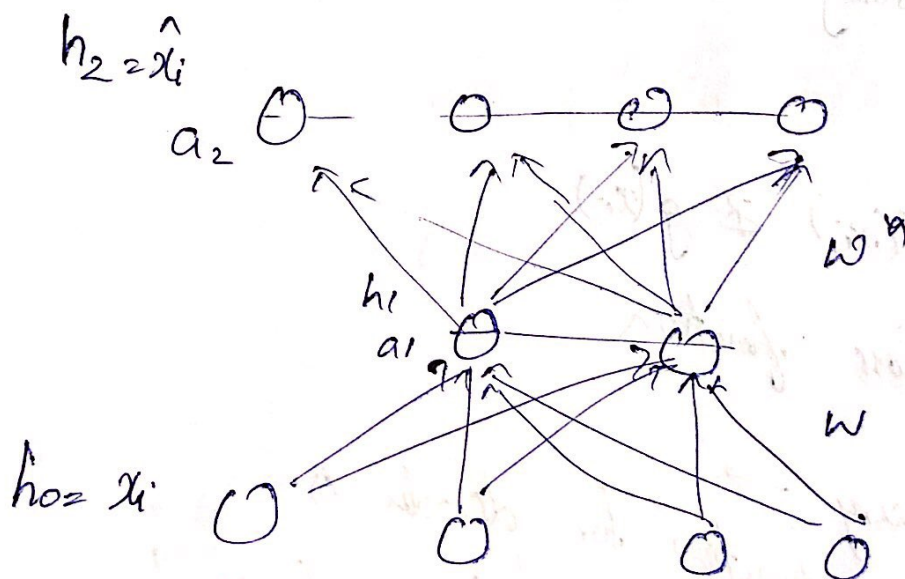
$\phi$  are real-valued.

Squared error loss

We can train the autoencoder just like a regular feedforward network.

$$\frac{\partial L(\theta)}{\partial W^x} \quad \& \quad \frac{\partial L(\theta)}{\partial W}$$

$$L(\theta) = (\hat{x}_i - x_i)^T (\hat{x}_i - x_i)$$





$$\frac{\partial \mathcal{L}(o)}{\partial w^x} = \frac{\partial \mathcal{L}(o)}{\partial h_2} \begin{bmatrix} \frac{\partial h_2}{\partial a_2} & \frac{\partial a_2}{\partial w^x} \end{bmatrix}$$

$$\frac{\partial \mathcal{L}(o)}{\partial w} = \frac{\partial \mathcal{L}(o)}{\partial h_2} \begin{bmatrix} \frac{\partial h_2}{\partial a_2} & \frac{\partial a_2}{\partial h_1} & \frac{\partial h_1}{\partial a_1} & \frac{\partial a_1}{\partial w} \end{bmatrix}$$

$$\frac{\partial \mathcal{L}(o)}{\partial h_2} = \frac{\partial \mathcal{L}(o)}{\partial \hat{x}_i}$$

$$= \nabla_{\hat{x}_i} \{ (\hat{x}_i - x_i)^T (\hat{x}_i - x_i) \}$$

$$= 2(\hat{x}_i - x_i)$$

Input - Binary  $\xrightarrow{\text{Logistic Sigmoid derodu}}$  output b/w 0 & 1

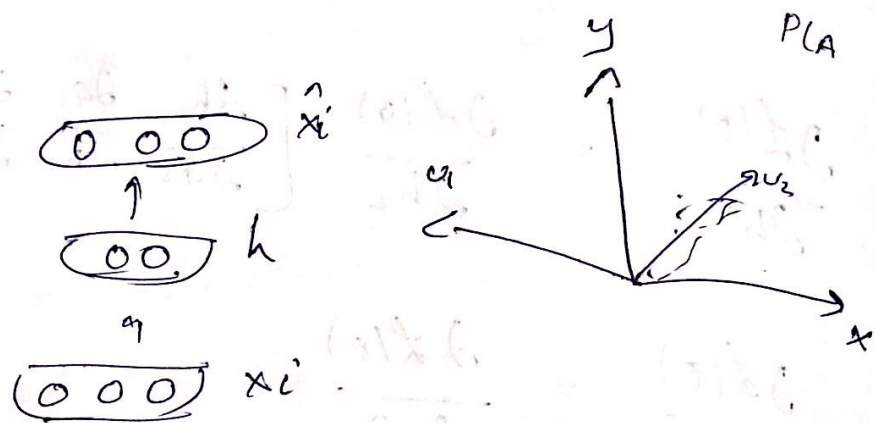
$$\min = \left\{ - \sum_{\substack{i=1 \\ p_0, p_1}}^n (x_{ij} \log \hat{x}_{ij} + (1-x_{ij}) \log (1-\hat{x}_{ij})) \right\}$$

$$p \in [0,1]$$

$$q \in [0.8, 0.2] \quad - \sum_{i=0}^1 p_i \log q_i$$

Cross Entropy Function  
for input is binary

## 7.2 Link b/w PCA & Auto Encoders



The encoder part of an autoencoder is equivalent to PCA if we

→ use a linear encoder

→ use a linear decoder

→ using squared error loss

→ normalize the inputs to

$$\hat{x}_{ij} = \frac{1}{\sqrt{m}} \left( x_{ij} - \frac{1}{m} \sum_{k=1}^m x_{kj} \right)$$

$$(X^T)X = \frac{1}{m} (X')^T X'$$

~~Optimal~~

Linear Decoder & <sup>Squared</sup> Error loss function  
 the optimal solution to the following  
 objective function

$$\frac{1}{m} \sum_{i=1}^m \sum_{j=1}^n (x_{ij} - \hat{x}_{ij})^2$$

when we use of a linear encoder

$$\min_W \sum_{i=1}^m \sum_{j=1}^n (x_{ij} - \hat{x}_{ij})^2$$

This is equivalent to

$$\min_{W \in \mathbb{R}^{n \times m}} (\|X - HW^T\|_F)^2$$

$$HW^* = U_{1 \leq k \leq r}$$

$H$  is actually a linear encoding & find  
 an expression for the encoder weights  $W$ .

$$H = U_{1 \leq k \leq r} \Sigma_{k,k} = (XX^T)^{-1} U_{1 \leq k \leq r} \Sigma_{k,k}$$

$$= XX^T$$



## 7.3 Regularization in Autoencoders

to generalization

~~training time~~

the

if less generalization (then overfitting)

Regularization is done to avoid overfitting

if the no. of parameters are high, it leads to overfitting

Case complete autoencoders a regularization is required as the number of parameters are very high. But there are situations where we need regularization for under complete auto encoders

Simplest solution add L2 regularization

$$\left[ \min_{\theta, w, w^*, b, c} \frac{1}{m} \sum_{i=1}^m \sum_{j=1}^n (\hat{x}_{ij} - x_{ij})^2 \right] + \lambda \|\theta\|^2$$

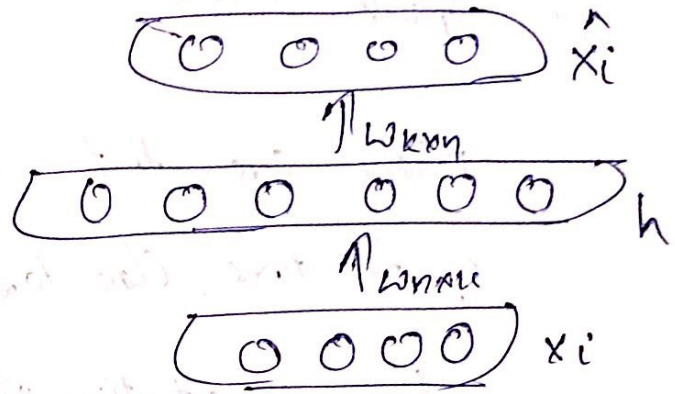
objective function  $J(\theta)$   $J_2(\theta)$

$$\theta = (w_1, w_2, \dots)$$

$$\frac{\partial J(\theta)}{\partial w_1}$$

adds the term  $\lambda w$  to the gradient  $J(\theta)$

$$W^* = W^T$$

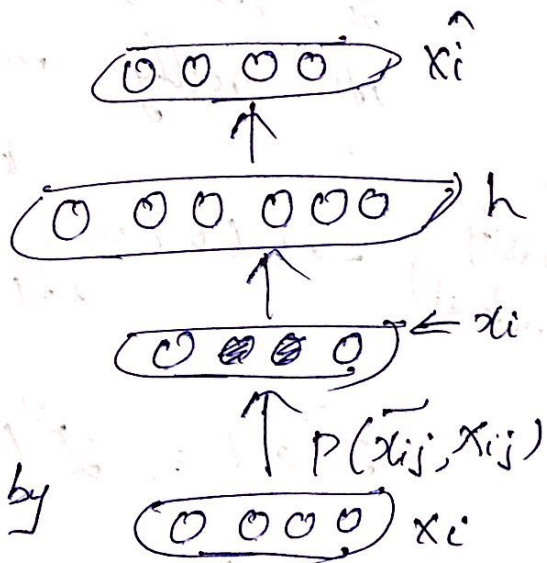


## 7.4 Denoising Autoencoders

A denoising encoder simply corrupts the input data using a probabilistic process ( $P(\tilde{x}_{ij} | x_{ij})$ ) before feeding it to the network

[ Robust to change at test times ]

No longer get away by memorising the data.



Or add Gaussian Noise  
 $\tilde{x}_{ij} = x_{ij} + \mathcal{N}(0, 1)$

Gaussian Noise is better than L2 regularisation



## 7.5 Sparse Encoder

Make sure that neuron is inactive most of the time close to zero

Average activation of neuron is close to zero.

Average value of activation of neuron  $\Rightarrow p_i^* = \frac{1}{m} \sum_{i=1}^m h(x_i) e_i$

This is kind of regularization,  
So it's like whenever it's active,  
it's really meaningful patterns.

(Sparsity constraint)  $\Omega(\theta) = \sum_{l=1}^k p \log \frac{p}{p_i^*} + (1-p) \log \frac{1-p}{1-p_i^*}$

$$L(\theta) = L'(\theta) + \Omega(\theta)$$

$$L(\theta) = \sum_{l=1}^k p \log \left( \frac{p}{p_i^*} \right) + (1-p) \log \left( \frac{1-p}{1-p_i^*} \right)$$

7.6

## Contractive Autoencoders

Some kind of regularization

$$\Omega(\theta) = \|\mathcal{J}_x(h)\|_F^2$$

(Jacobian)  $\mathbb{R}^n \rightarrow \mathbb{R}^k$

$$\|\mathcal{J}_x(h)\|_F^2 = \sum_{j=1}^n \sum_{k=1}^k \left( \frac{\partial h_k}{\partial x_j} \right)^2$$

Not very sensitive to variations.

## Regularization

Weight decay

$$\Omega(\theta) = \lambda \|\theta\|^2$$

Sparse

$$\Omega(\theta) = \sum_{k=1}^K p \log \frac{p}{p_k} + (1-p) \log \frac{1-p}{1-p_k}$$

Contractive

$$\Omega(\theta) = \sum_{j=1}^n \sum_{k=1}^k \left( \frac{\partial h_k}{\partial x_j} \right)^2$$