

Niklas Lauffer

✉ nlauffer@berkeley.edu 🏠 niklaslauffer.github.io 🎓 niklaslauffer 📺 niklaslauffer

Education

University of California, Berkeley

2021 — May 2026 (expected)

PhD in Computer Science (Artificial Intelligence)

Advised by Stuart Russell and Sanjit Seshia – NSF Fellowship – CAIF Fellowship

University of Texas at Austin

2017 — 2021

BS in Computer Science Honors and Mathematics

Dean's Honored Graduate (awarded to the top 1% of graduates) – Turing Scholars honors – 3.96/4.0 GPA

Selected Publications

ICLR 2026	Imitation Learning for Multi-Turn LM Agents via On-policy Expert Corrections – In submission N. Lauffer, X. Deng, S. Kundurthy, B. Kenstler, J. Da
NeurIPS 2025	Robust and Diverse Multi-Agent Learning via Rational Policy Gradient N. Lauffer, A. Shah, M. Carroll, S. Seshia, S. Russell, M. Dennis
Arxiv 2025	Multi-Agent Risks from Advanced AI Hammond et al.
AAMAS 2025	Learning Task Decompositions for Multi-agent Teams A. Shah*, N. Lauffer*, T. Chen*, N. Pitta*, S. Seshia
NeurIPS 2024	Compositional Automata Embeddings for Goal-Conditioned Reinforcement Learning B. Yalcinkaya*, N. Lauffer*, M. Vazquez-Chanlatte, S. Seshia
arxiv 2024	Welfare Diplomacy: Benchmarking Language Model Cooperation G. Mukobi, H. Erlebach, N. Lauffer, L. Hammond, A. Chan, J. Clifton
NIPS GCRL 2023	Automata Conditioned Reinforcement Learning with Experience Replay – Spotlight N. Lauffer*, B. Yalcinkaya*, M. Vazquez-Chanlatte, S. Seshia
ICML 2023	Who Needs to Know? Minimal Knowledge for Optimal Coordination N. Lauffer, A. Shah, M. Carroll, M. Dennis, S. Russell
TAC 2023	No-regret Learning in Dynamic Stackelberg Games. N. Lauffer, M. Ghasemi, A. Hashemi, Y. Savas, and U. Topcu.
JAIR 2023	On Expected Value Strong Controllability. N. Lauffer, W. Lassiter, and J. Frank.
FMCAD 2022	Deterministic Finite Automata Decompositions from Examples and Demonstrations N. Lauffer, B. Yalcinkaya, M. Vazquez-Chanlatte, A. Shah, S. Seshia
Automatica 2021	Training Classifiers for Feedback Control with Safety in Mind. H. Poonawala, N. Lauffer, and U. Topcu
COCOA 2020	Reachability Games for Optimal Multi-Agent Scheduling of Tasks with Variable Durations D. Raju, N. Lauffer, U. Topcu.
ICAPS XAIP 2019	Human-Understandable Explanations of Infeasibility for Resource-Constrained Scheduling Problems N. Lauffer, and U. Topcu
CDC 2018	Expedited Learning in MDPs with Side Information M. Ornik, J. Fu, N. Lauffer, K. W. Perera, M. Alshiekh, M. Ono, and U. Topcu

Work Experience

Center for Human-Compatible AI, Learn & Verify | UC Berkeley

2021 — Present

PhD Candidate in Artificial Intelligence

My PhD is centered around AI safety, human-AI collaboration, multiagent reinforcement learning, and LLM agents.

- Developed a framework for generalizing adversarial learning algorithms to the cooperative and general-sum setting.
- Developed novel [pretraining method](#) for learning representations of multi-step-plans, frameworks for [evaluating LLM capabilities](#), a library for [decomposing formal specifications](#), more efficient LLM architectures in long-context settings, and wrote the “Coordination” section of the *Multi-Agent Risks from Advanced AI* report.
- Published eight first-author papers at top venues (NeurIPS, ICML, AAMAS, JAIR, FMCAD, TAC) with more co-authored.
- On the program committed for CHAI 2024 and CHAI 2025 which was attended by over 200 researchers. Led and organized all-hands meetings, discussions, and talks for CHAI from 2023-2025. This amounts to 140+ talks from external and internal researchers.

Scale AI | Reasoning and Agents Team**Summer 2025****Research Scientist Intern** in LLM Agents

Interned on the Reasoning and Agents team, researching how to improve LM agent training for long-horizon, multi-turn tasks.

- Developed a novel training scheme for multi-turn LM agents that combats the issue of covariate shift.
- Improved the state-of-the-art 7B LM agent performance on SWE-bench from 12% → 20% and 32B from 36% → 40%.
- A full conference paper is under review at ICLR.

Autonomous Systems Group | UT Austin**2017 — 2021****Student Researcher** in Autonomous Systems

Advised by Ufuk Topcu in the Institute for Computational Engineering and Science. As part of the Autonomous Systems Group, I developed formal and empirical approaches to decision making (MDPs, planning, RL) and control for autonomous systems.

- Published 5+ papers at top venues (CDC, ICAPS, COCOA, ACC, Automatica, Scientific Reports).
- Developed the first no-regret algorithm for learning in dynamic Stackelberg games resulting in a first-author publication at TAC.
- Built [quadcopter flight software](#) in C/C++, reinforcement learning [visualization tools](#) and a [neural controlled UAV](#) in Python.

NASA Ames Research Center**Research Intern** in Planning and Scheduling**Summer 2019 and 2020**

Interned at NASA Ames Research Center in the Automated Planning and Scheduling group under Dr. Jeremy Frank.

- Project resulted in a first-author journal publication at JAIR.
- Formulated the theory behind rescheduling policies for Expected Value Probabilistic Simple Temporal Networks (EvPSTNs).
- Implemented dynamic rescheduling simulations for EvPSTNs to evaluate the effectiveness of different rescheduling policies.

Academic Service

Organizer	CHAI Workshop 2024-2025, CHAI Internship 2023-2025, CHAI All-hands 2023-2025, PSBAI NSF Workshop 2022.
Reviewer	NeurIPS 2025, ICML 2025, RLC 2025, TAC 2024, ACC 2024, AAAI 2024, CAIF Grant Making 2024-2025
Advising	Darius Muglich, Rupali Bhati, Mariana Meireles, Sandy Tanwisuth, Martín Soto, Thomas Chen, Nikhil Pitta
Teaching	CS188: Artificial Intelligence (2022), CS370: Homotopy Type Theory (2020)

Honors

- 2024 • **Cooperative AI Foundation Fellowship:** Fellowship to support research in Cooperative AI
- 2023 • **NSF Graduate Research Fellowship:** Awarded to high-potential PhD students early in their career
- 2022 • **Hertz Fellowship Finalist:** One of 42 finalists selected from over 750 applicants
- 2021 • **University of Texas Dean's Honored Graduate** - highest honor awarded to 1% of graduating students
- 2021 • **Turing Scholars (Computer Science Honors)** - less than 7% of students are admitted
- 2021 • **Dean's Scholars (Math Honors)** - less than 1.5% of students are admitted
- 2021 • **Turing Scholars' Best Undergraduate Thesis Award Finalist**

Invited Talks

- Aug 2023 • **University of Maryland MARL Group:** Who Needs to Know? Minimal Knowledge for Optimal Coordination
- Aug 2023 • **Berkeley Multi-agent Learning Seminar:** Who Needs to Know? Minimal Knowledge for Optimal Coordination
- Aug 2023 • **MIT Algorithmic Alignment Group:** Who Needs to Know? Minimal Knowledge for Optimal Coordination
- Jul 2023 • **ICML 2023:** Who Needs to Know? Minimal Knowledge for Optimal Coordination
- Jun 2023 • **CHAI Workshop 2023:** Who Needs to Know? Minimal Knowledge for Optimal Coordination
- Dec 2022 • **Nissan Alliance Innovation Lab:** Learning DFA Decompositions from Examples and Demonstrations.
- Oct 2022 • **FMCAD 2022:** Learning DFA Decompositions from Examples and Demonstrations.

Technical Skills

Languages (Advanced)	Python, C, C++, Java, Bash, LaTeX
Languages (Basic)	MATLAB, R, Haskell, z/OS Assembly, HTML, CSS
Libraries (Python)	Jax, Pytorch, NumPy, SciPy, Scikit-Learn, Gym, Matplotlib, Seaborn, DGL, ROS, Gurobi, Z3
Foreign Languages	German (Fluent Reading, Fluent Speaking, Fluent Listening, Intermediate Writing)