9/11/17 Attribute (Dimensione) TTDT] -> projection of The line \vec{v} $\vec{v$ Rayleigh Bustient (y-Ely)]

eating action /N:

$$X \rightarrow \text{ random } \text{ variable}$$

$$L \Rightarrow \text{ parameters} \rightarrow 0$$

$$D \Rightarrow \text{ as seleromotor}$$

$$D \Rightarrow \text{ solentation} = ---$$

$$D \Rightarrow \text{ orientation} = ---$$

$$D \Rightarrow \text{ orie$$

estimation

set of parameters.

Variance =
$$E\left(\left[\hat{O} - E\left(\hat{O}\right)\right]^{\lambda}\right)$$

Unbiased estimator => bias =

$$\theta = E(\hat{\sigma})$$

$$((\theta | \pi))$$

((Ô(n) - meximum.

Log (((ô(n))) - log liklihood

$$\frac{d}{d\theta} = \frac{d(\hat{\theta} \mid n)}{d\theta}$$

$$= \frac{d\theta}{d\theta}$$

$$= \frac{d\theta}{d\theta}$$

$$=\frac{\lambda'(\hat{\sigma}|n)}{\lambda(\hat{\sigma}|n)}=\mathrm{I}(\hat{\sigma})$$

Fisher information.

Ver
$$(\hat{\theta})$$
 $(\hat{\theta})$ $(\hat{\theta})$

$$V_{\alpha\gamma}(\hat{\theta}) > \frac{E(\hat{\theta})}{N I(\hat{\theta})}$$

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