

CM 1606 Computational Mathematics

Tensors

Week 09 | Ganesha Thondilege

Learning Outcomes

- Covers LO1 for Module
- On completion of this lecture, students are expected to be able to:
 - Recall direction cosines of vectors
 - Identify tensors
 - Identify the way that high dimensional input data can specify using tensors
 - Discuss applications in Machine learning

CONTENT

- Introduction
- What is a tensor
- Rank of a tensor
- Transformation rules
- Coordinate transformation
- Summation convention

Introduction

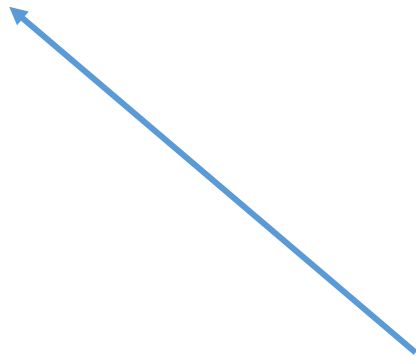
Temperature – Colombo city

303 K

- Single component to specify the temperature
- Scalar
- Component – Zero basis vectors

Displacement from Homagama to 30th floor of the WTC west tower
32km

B : WTC west tower 30th floor



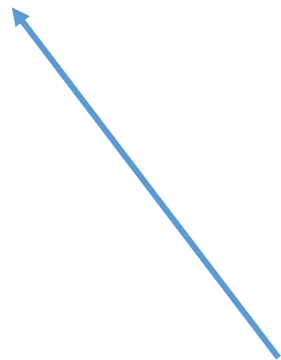
A : Homagama

Displacement $\vec{AB} = 32\text{km}$

Direction : From A to $B = \vec{AB}$

- Displacement from Homagama to 30th floor of the WTC west tower
- 32km

B : WTC west tower 30th floor



A : Homagama

Displacement $\vec{AB} = 32\text{km}$

Direction : From A to B = \vec{AB}

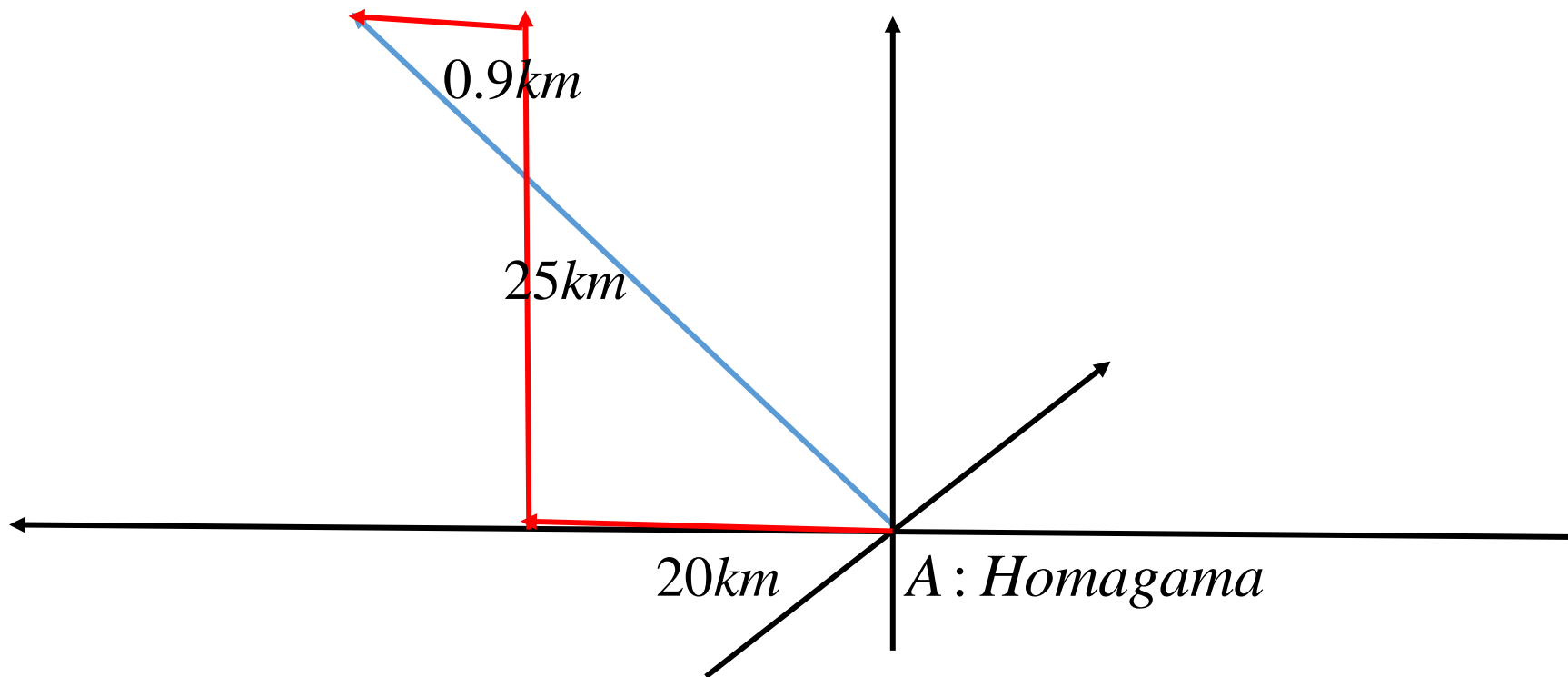
20km – To west

25km – To North

0.9km – up

- Displacement using basis vectors

B : WTC west tower 30th floor

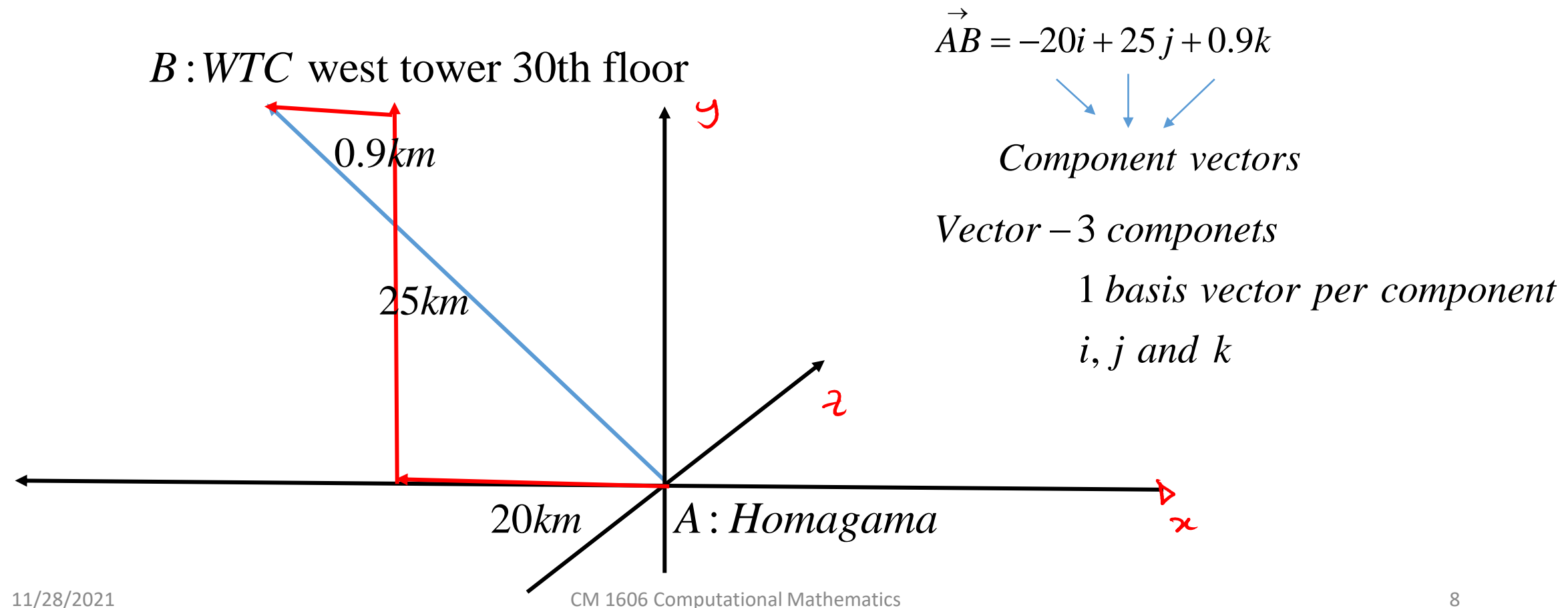


$$\vec{AB} = -20i + 25j + 0.9k$$



Component vectors

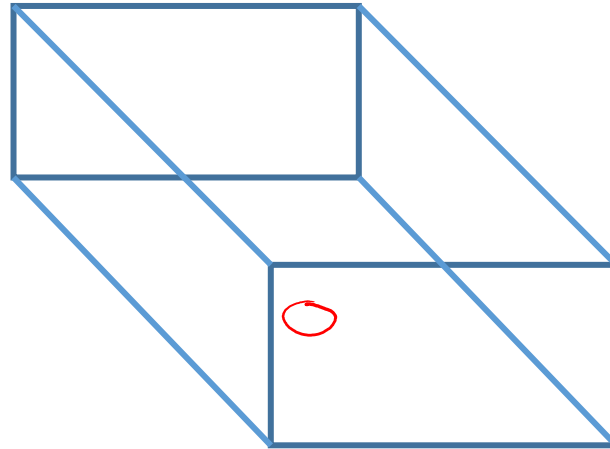
- Displacement using basis vectors



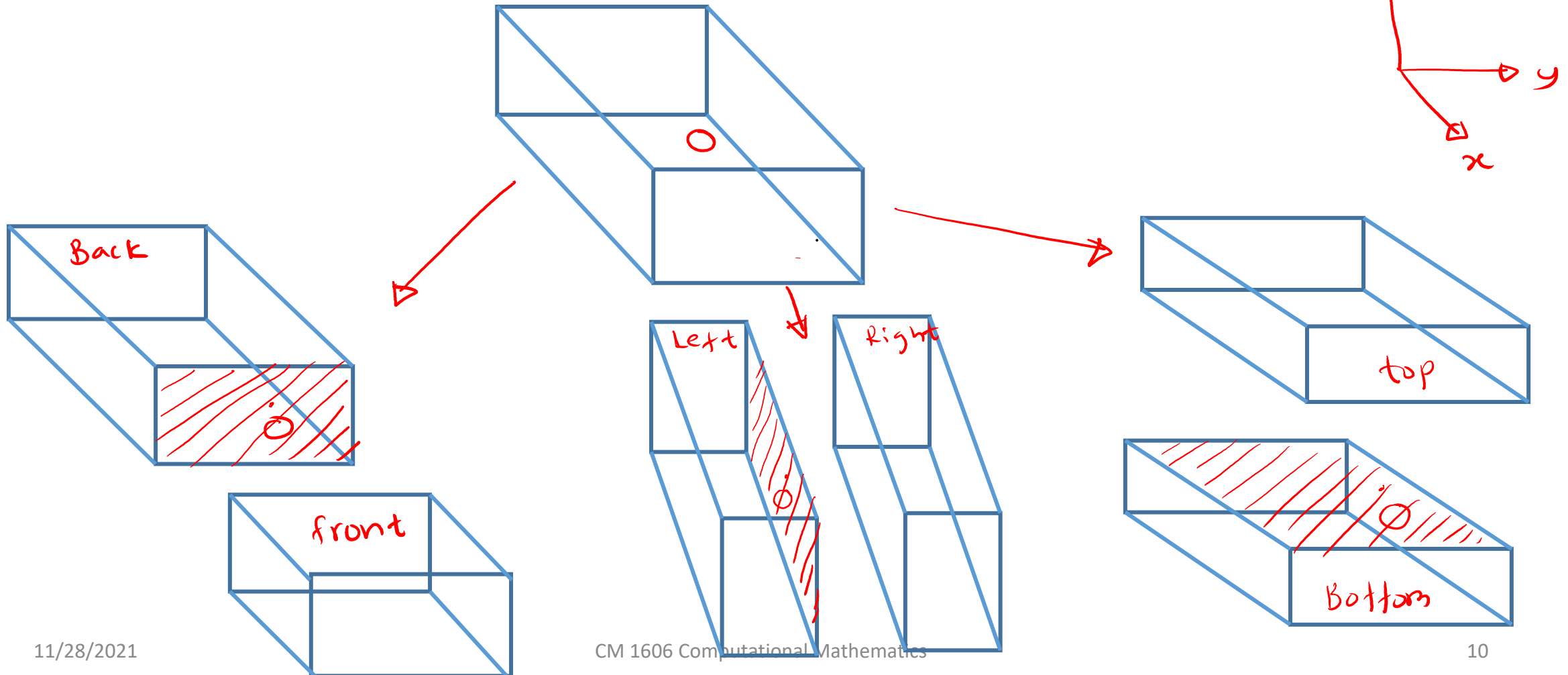
Introduction ctd.

- Consider a rectangular steel beam and the point O inside the beam
- How we can specify all the stresses act on the point O

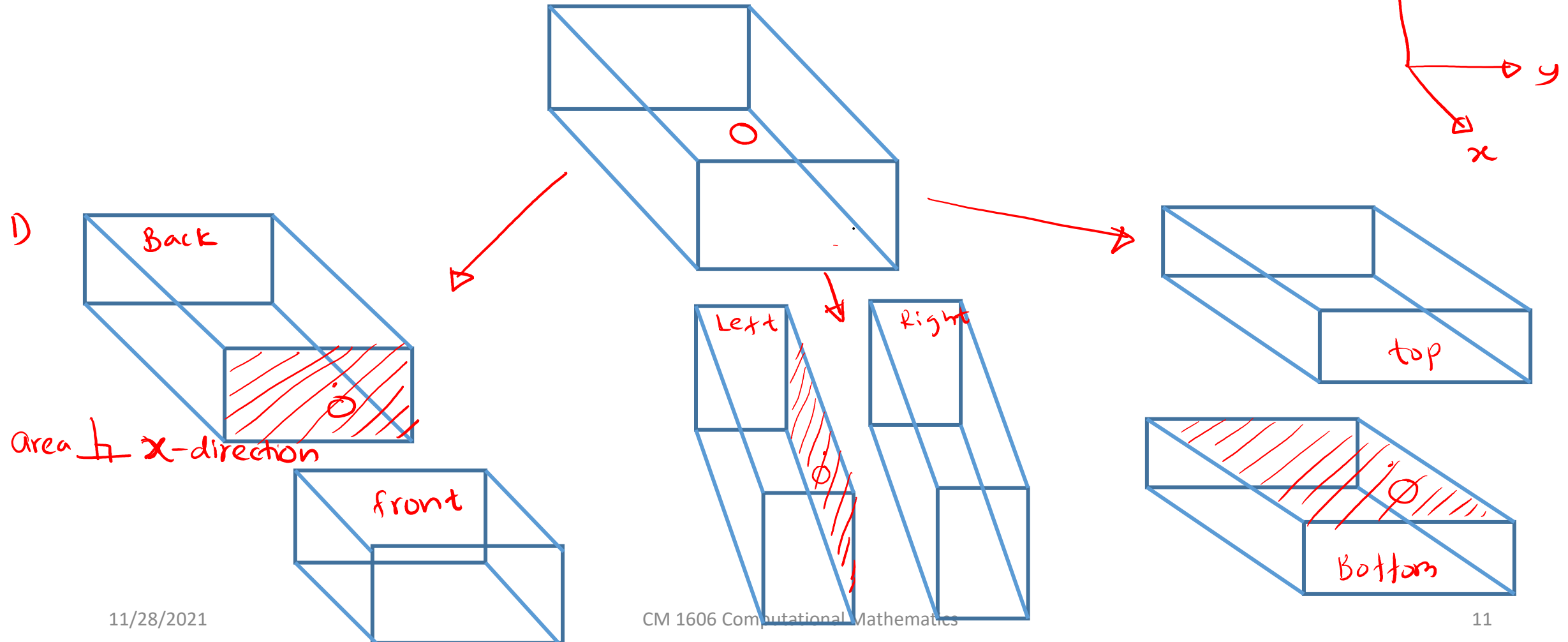
Stresses on O?



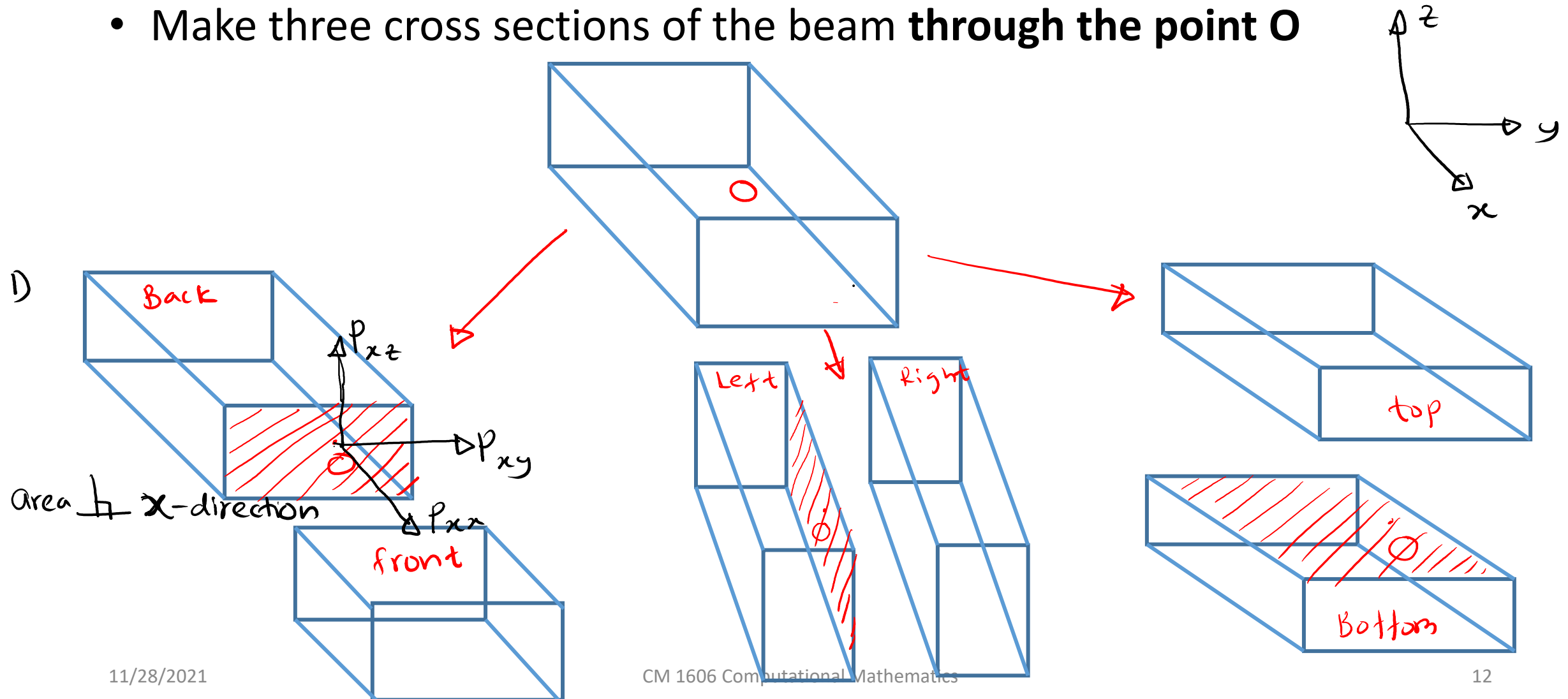
- Make three cross sections of the beam **through the point O**



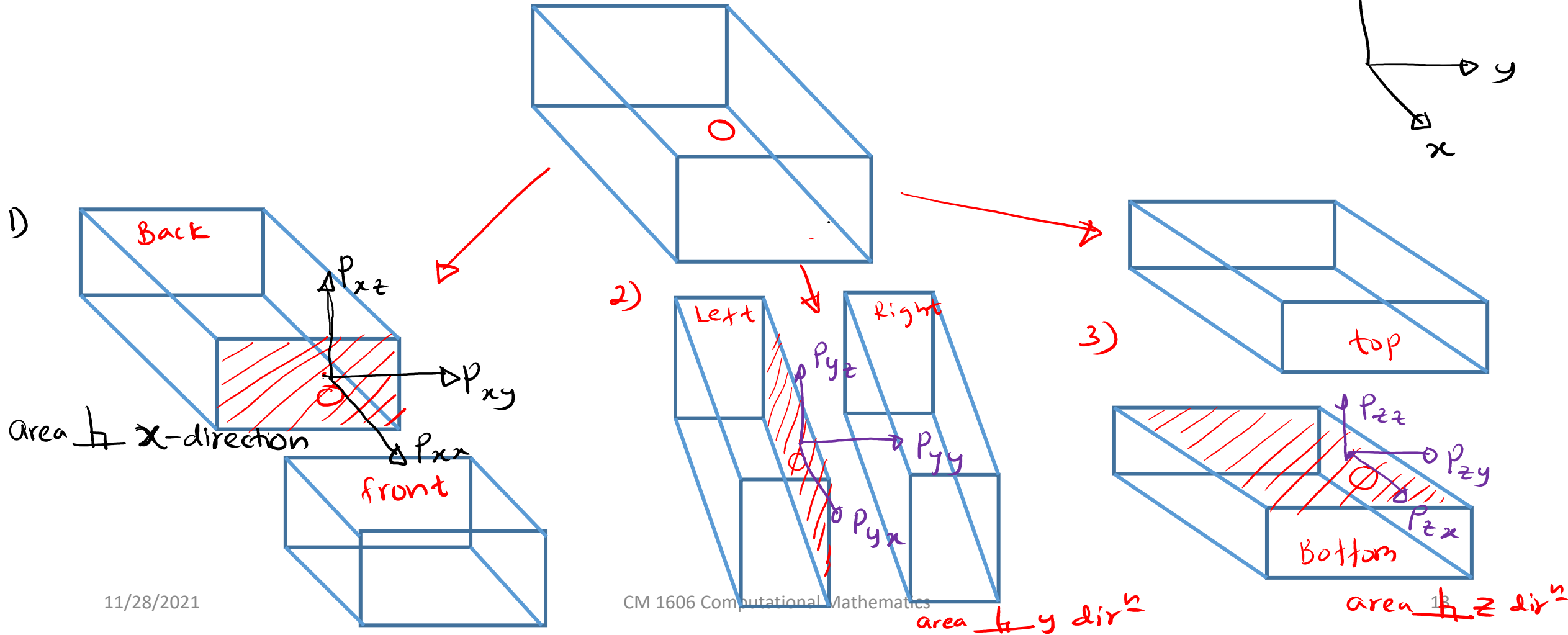
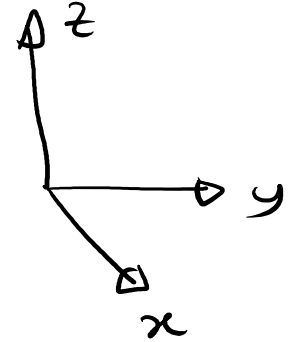
- Make three cross sections of the beam **through the point O**



- Make three cross sections of the beam **through the point O**



- Make three cross sections of the beam **through the point O**



- We can combine all these components in a 3*3 matrix as

$$P = \begin{pmatrix} P_{xx} & P_{xy} & P_{xz} \\ p_{yx} & P_{yy} & P_{yz} \\ P_{zx} & p_{zy} & P_{zz} \end{pmatrix}$$

Use this matrix P to specify all stresses acting on the point O

Tensors

- P has 9 components and 2 basis vectors per component
 - 2 basis vectors – 1 for the cross-sectional area
 - 1 for the direction of force
- This concept is known as Tensors

In an m dimensional space, a tensor of rank n is a mathematical object that has n indices, m^n components.

- obeys some transformation rules
- Generally, $m=3$

Rank of a Tensor

Number of basis vectors needed to fully specify a component of a tensor.

- Scalar

Component – Zero basis vectors – A tensor of rank zero

- *Vector – 3 componets*

1 basis vector per component

i, j and k

So, a vector is a tensor of rank 1

- P is a tensor of rank 2 – Stress tensor
- m dimensional space, rank n Tensor $\rightarrow m^n$ components

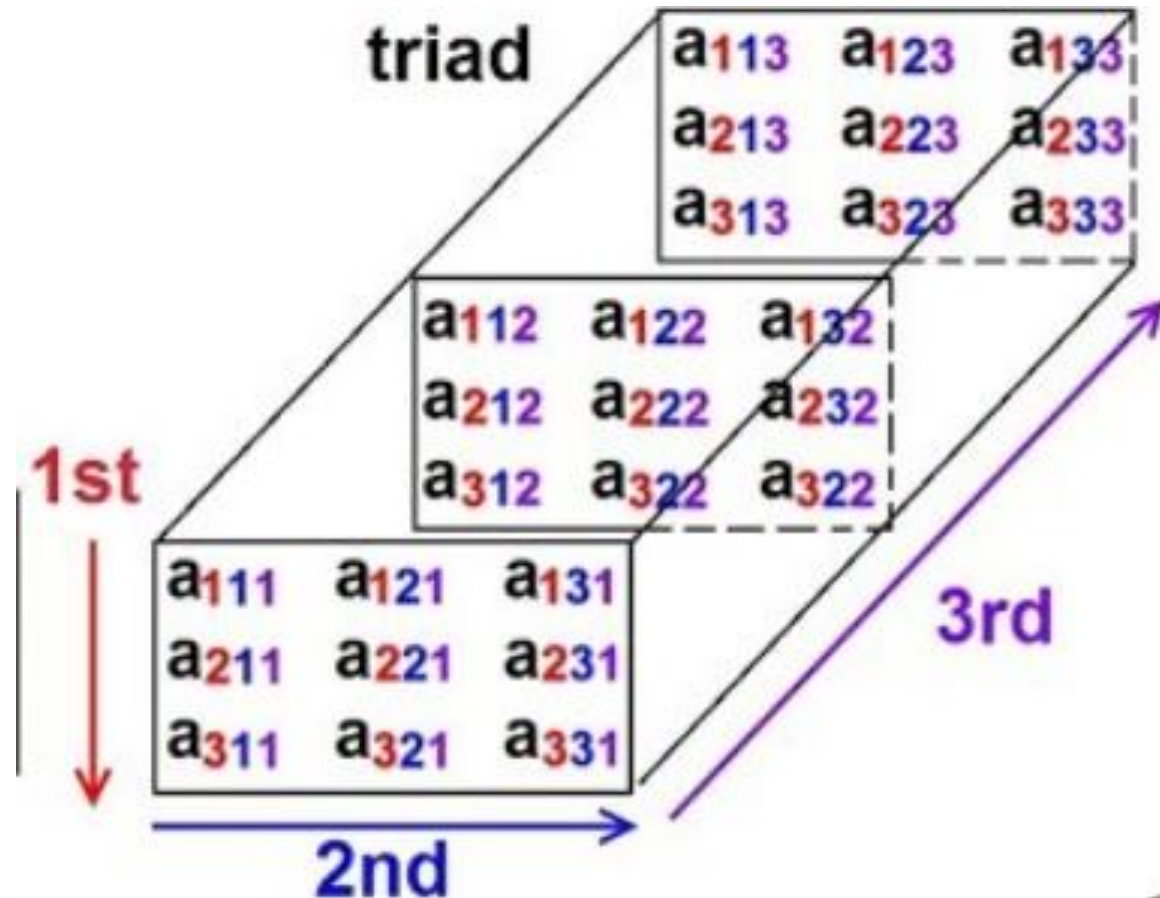
Scalar	Vector	Stress Tensor(P)
1 component	3 components	9 components
3^0	3^1	3^2
rank 0	rank 1	rank 2

Tensor of rank 3

- 27 components $\Rightarrow 3^3$ – rank 3 tensor
- How can we specify this 27 components?

Rank 3 tensor - Triad

- Any component a_{xyz}
- 3 pages

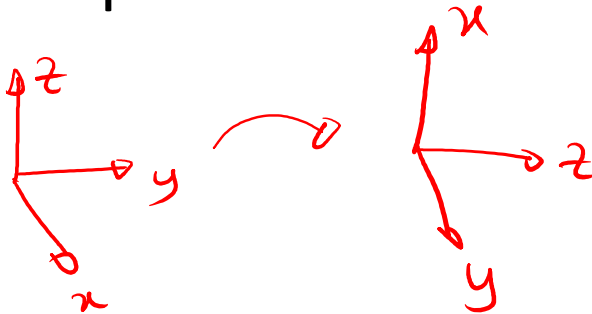


Transformation rules

- A tensor is an object that transforms like a tensor
- A tensor is an object that is invariant under a change of coordinate systems, with components that change according to a special set of mathematical formulae.

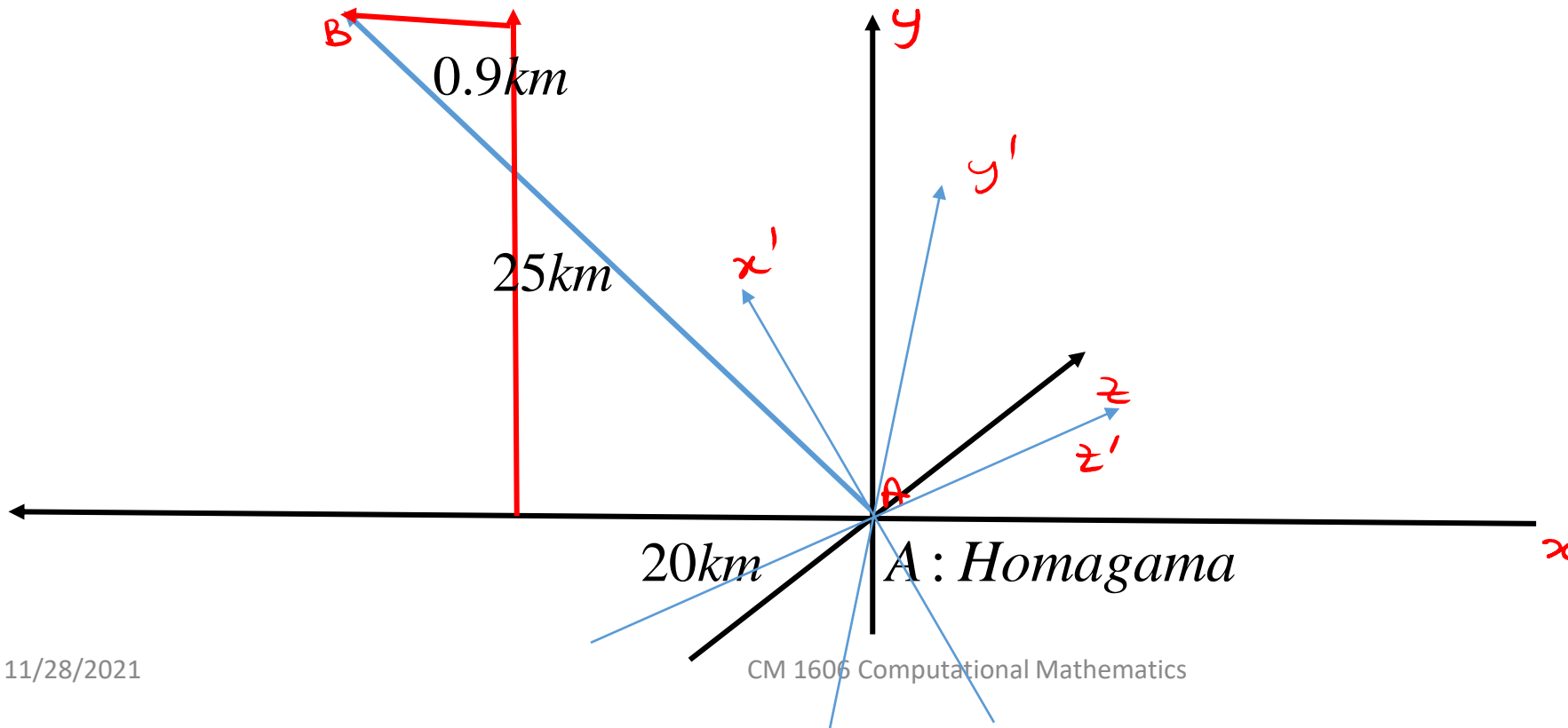
Rank zero tensor(scalar)

Temp=303K



Change of coordinate system does not change the temp.

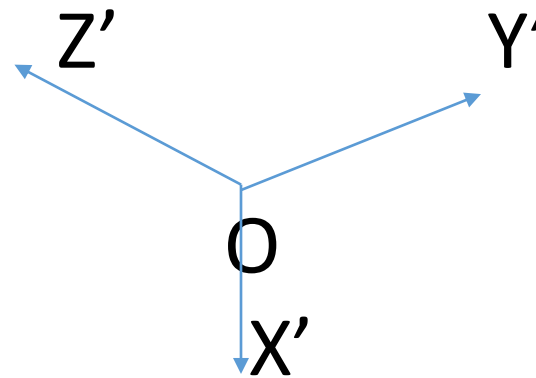
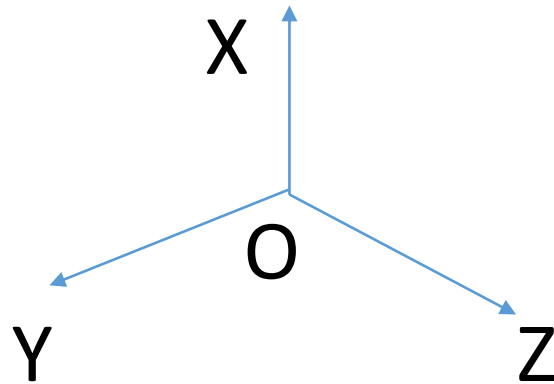
- Vector – Rank 1 tensor
- Displacement = $\overrightarrow{AB} = -20\mathbf{i} + 25\mathbf{j} + 0.9\mathbf{k}$
 B : WTC west tower 30th floor



-
- It change the way that we write the \overrightarrow{AB} using new basis vectors $i', j',$ and k'
 - Does it change the vector itself?
 No. vector still from A to B

Coordinate transformation

$$OXYZ \rightarrow OX'Y'Z'$$



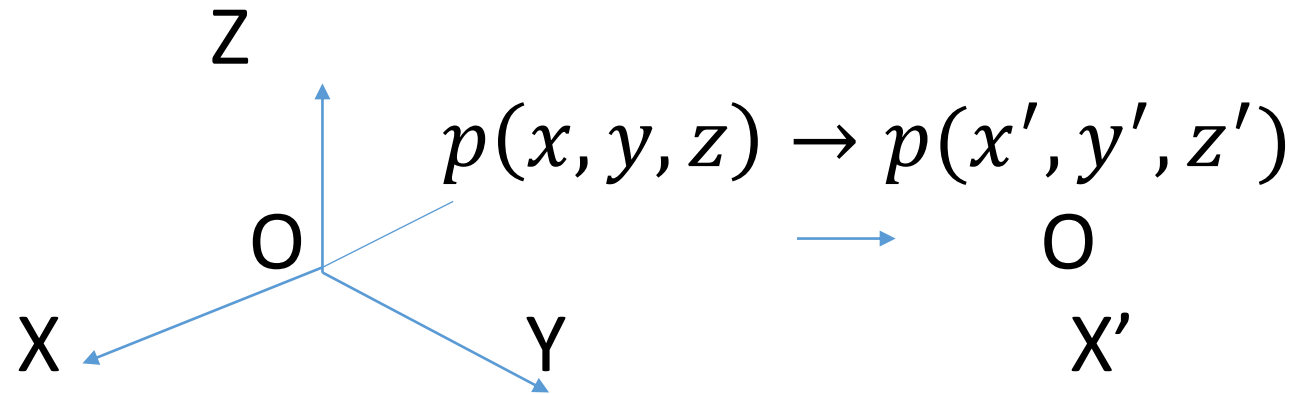
Direction cosines of Ox' , OY' & OZ' relative to $OXYZ$ are

$$OX' \rightarrow l_1, m_1, n_1$$

$$OY' \rightarrow l_2, m_2, n_2$$

$$OZ' \rightarrow l_3, m_3, n_3$$

Coordinate transformation



Then two equivalent systems of transformation equations

$$x' = l_1x + m_1y + n_1z$$

$$y' = l_2x + m_2y + n_2z$$

$$z' = l_3x + m_3y + n_3z$$

Coordinate transformation

$$x = l_1x' + m_1y' + n_1z'$$

$$y = l_2x' + m_2y' + n_2z'$$

$$z = l_3x' + m_3y' + n_3z'$$

This transformation can be written as

$$\begin{matrix} & \begin{matrix} x & y & z \end{matrix} \\ \begin{pmatrix} l_1 & m_1 & n_1 \\ l_2 & m_2 & n_2 \\ l_3 & m_3 & n_3 \end{pmatrix} \end{matrix}$$

Summation convention

The sum of

$a_1x_1 + a_2x_2 + a_3x_3 \dots \dots + a_nx_n$ can be written as

$$\sum_{i=1}^n a_i x_i$$

The compact notation for this is

$$a_i x^i \quad (\textit{Einstein Notation})$$

Example

Write $a_{rs}x^s = b_r(r, s = 1, 2, 3, \dots, n)$ in full.

Hint: Substitute values for r first and then substitute for s .

Example

- Write all the tensors in

$$T = a_{ij}x^i \text{ taking } n = 3$$

Tensor Addition

- Take the element wise addition of two tensors with same dimensions and results a new tensor with the same dimensions

Tensor subtraction

- Take the element wise subtraction of two tensors with same dimensions and results a new tensor with the same dimensions

Reference

- <https://www.youtube.com/watch?v=f5liqUk0ZTw>