Time-dependent variational principles: application for quantum dynamics

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How do we calculate quantum dynamics?

Time-dependent Shrödinger equation:

$$i\hbar\frac{\partial\Phi}{\partial t} = \hat{H}\Phi$$

Let's solve it formally:

$$\Phi(t) = \Phi(0) \exp\left(-\frac{i}{\hbar}\hat{H}t\right) \Rightarrow \frac{\partial}{\partial t}\langle\Phi(t)|\Phi(t)\rangle = 0$$

We can use evolution operator to calculate dynamics of wave function — **Split operator technique**.

Pros

• accurate (Δt^3)

Cons
• slow

Is there any other way to estimate accurate quantum dynamics?

Time-dependent variational principleS(!)

Time-dependent variational principle (TDVP):

$$\delta S = \delta \left(\int_0^t L(\Phi, \Phi^*) \, d\tilde{t} \right) = 0, \ L(\Phi, \Phi^*) = \frac{\left\langle \Phi \left| \hat{H} - i\hbar \frac{\partial}{\partial t} \right| \Phi \right\rangle}{\left\langle \Phi \middle| \Phi \right\rangle}$$

McLachlan's variational principle:

$$\delta\left(\frac{\left\langle\Phi\left|\hat{H}-i\hbar\frac{\partial}{\partial t}\right|\Phi\right\rangle}{\left\langle\Phi|\Phi\right\rangle}\right)=0$$

Dirac-Frenkel variational principle:

$$\left\langle \delta \Phi \left| \hat{H} - i\hbar \frac{\partial}{\partial t} \right| \Phi \right\rangle = 0$$

Wave function ansatz

Basis $\{\phi_k(\lambda_1,\ldots,\lambda_M)\}_{k=1}^N$:

$$\begin{split} |\Psi\rangle &= \sum_{i=1}^{N} C_{k} \phi_{k} \\ |\delta\Psi\rangle &= \sum_{i=1}^{N} \left(\delta C_{k} \phi_{k} + C_{k} \sum_{l=1}^{M} \frac{\partial \phi_{k}}{\partial \lambda_{k l}} \delta \lambda_{k l} \right) \\ \delta C_{m}^{*} \sum_{k=1}^{N} \left\langle \phi_{m} \left| \hat{H} - i\hbar \frac{\partial}{\partial t} \right| C_{k} \phi_{k} \right\rangle &= 0 \\ \delta \lambda_{m j} \sum_{l=1}^{N} C_{m}^{*} \left\langle \frac{\partial \phi_{m}}{\partial \lambda_{m j}} \left| \hat{H} - i\hbar \frac{\partial}{\partial t} \right| C_{k} \phi_{k} \right\rangle &= 0 \end{split}$$

Equation of motions

$$\dot{ec{C}} = -rac{i}{\hbar} \mathbb{S}^{-1} \left(\mathbb{H} - i\hbar au
ight) \vec{C}$$
 — vector of coeficients $\dot{\Lambda} = -rac{i}{\hbar} \mathbb{X}^{-1} \mathbb{Y}$ — matrix of parameters

$$\mathbb{S}_{mk} = \langle \phi_m | \phi_k \rangle, \ \mathbb{H}_{mk} = \left\langle \phi_m \left| \hat{H} \right| \phi_k \right\rangle, \ \boldsymbol{\tau}_{mk} = \sum_{l=1}^{M} \left\langle \phi_m \left| \frac{\partial \phi_k}{\partial \lambda_{kl}} \right\rangle \dot{\lambda}_{kl} \right\rangle$$

$$\mathbb{Y}_{m}^{j} = \sum_{k=1}^{N} \rho_{mk} \left(\mathbb{H}_{mk}^{(j0)} - (\mathbb{S}^{(j0)} \mathbb{S}^{-1} \mathbb{H})_{mk} \right), \ \mathbb{X}_{mk}^{jl} = \rho_{mk} \left(\mathbb{S}_{mk}^{(jl)} - (\mathbb{S}^{(j0)} \mathbb{S}^{-1} \mathbb{S}^{(0l)})_{mk} \right)$$

$$\rho_{mk} = C_m^* C_k, \ \mathbb{H}_{mk}^{(j0)} = \left\langle \frac{\partial \phi_m}{\partial \lambda_{mj}} \left| \hat{H} \right| \phi_k \right\rangle$$

$$\mathbb{S}_{mk}^{(j0)} = \left\langle \frac{\partial \phi_m}{\partial \lambda_{mj}} \middle| \phi_k \right\rangle, \ \mathbb{S}_{mk}^{(0l)} = \left\langle \phi_m \middle| \frac{\partial \phi_k}{\partial \lambda_{kl}} \right\rangle, \ \mathbb{S}_{mk}^{(jl)} = \left\langle \frac{\partial \phi_m}{\partial \lambda_{mj}} \middle| \frac{\partial \phi_k}{\partial \lambda_{kl}} \right\rangle$$

Basis set

Frozen width gaussian wave packets:

$$|g_{k}\rangle = \exp\left(\frac{1}{\hbar} \sum_{\alpha} \left[-\frac{1}{2} \omega r_{\alpha}^{2} + \xi_{k\alpha} r_{\alpha} + \eta_{k\alpha} \right] \right)$$

$$\begin{cases} \xi_{k\alpha} = \omega q_{k\alpha} + i p_{k\alpha} \\ \eta_{k\alpha} = \frac{1}{4} \left(\ln \left[\frac{\omega}{\pi} \right] - 2\omega q_{k\alpha}^{2} \right) - i q_{k\alpha} p_{k\alpha} \end{cases}$$

$$|g_{k}\rangle = \left(\frac{\omega}{\pi}\right)^{\alpha/4} \exp\left(\frac{1}{\hbar} \sum_{\alpha} \left[-\frac{1}{2} \omega (r_{\alpha} - q_{k\alpha})^{2} + i \frac{p_{k\alpha}}{m_{k}} (r_{\alpha} - q_{k\alpha}) \right] \right)$$

$$\frac{\langle g_{k} | r_{\alpha} | g_{k} \rangle}{\langle g_{k} | g_{k} \rangle} = q_{k\alpha}, \quad \frac{\langle g_{k} | - i \hbar \frac{\partial}{\partial r_{\alpha}} | g_{k} \rangle}{\langle g_{k} | g_{k} \rangle} = p_{k\alpha}$$