

Electronic Supplement to “ON THE ESTIMATION OF GROUND-MOTION DURATION MODELS WITH AN APPLICATION TO THE M9 SIMULATIONS”

This electronic supplement contains additional plots and information.

1 Graphical Posterior Predictive Checks

First, we show graphical posterior predictive checks, similar to Figure 8. Here, we compare the median, 5% and 95% fractile of simulated data sets with the corresponding values of the M9 simulations for data in distance of 25km.

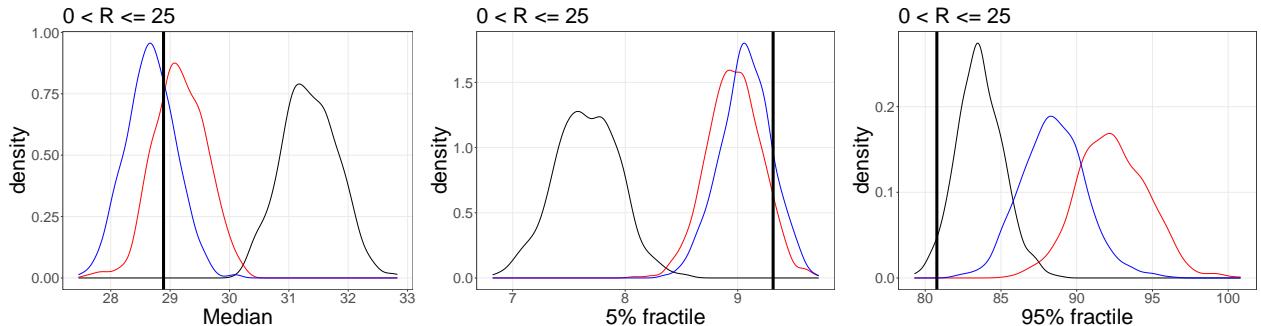


Figure S1: Posterior predictive checks for data in the range $0 < R \leq 25$ km. Shown are densities of the median and 5%/95% fractiles of 800 simulated data sets. The black vertical line displays the median or fractile of the M9 data.

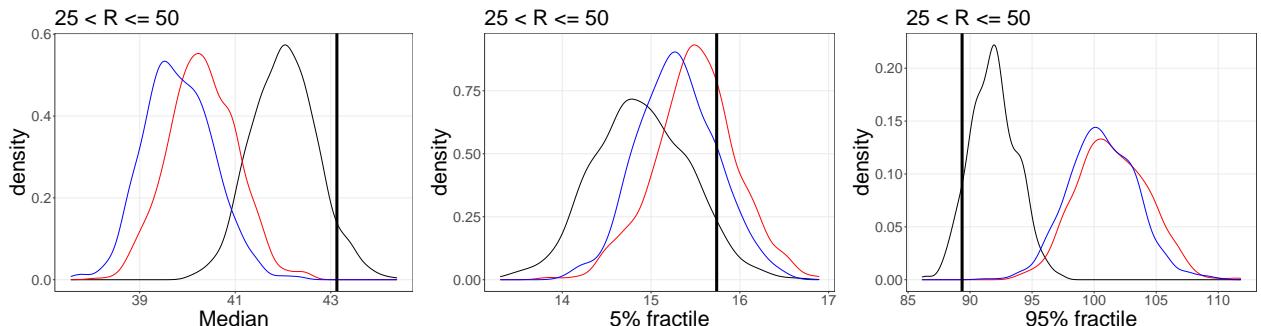


Figure S2: Posterior predictive checks for data in the range $25 < R \leq 50$ km. Shown are densities of the median and 5%/95% fractiles of 800 simulated data sets. The black vertical line displays the median or fractile of the M9 data.

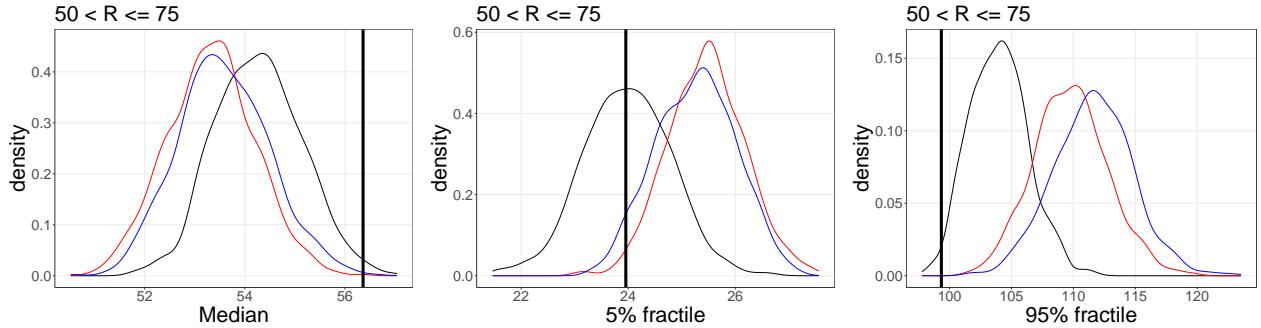


Figure S3: Posterior predictive checks for data in the range $50 < R \leq 75$ km. Shown are densities of the median and 5%/95% fractiles of 800 simulated data sets. The black vertical line displays the median or fractile of the M9 data.

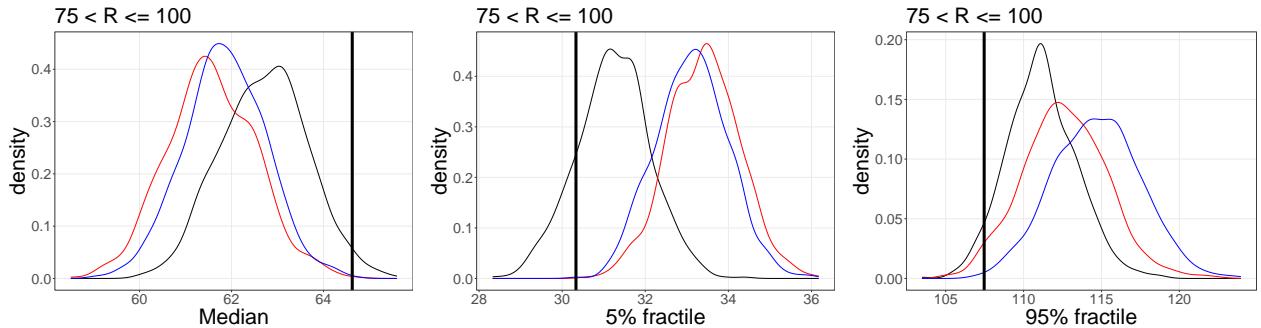


Figure S4: Posterior predictive checks for data in the range $75 < R \leq 100$ km. Shown are densities of the median and 5%/95% fractiles of 800 simulated data sets. The black vertical line displays the median or fractile of the M9 data.

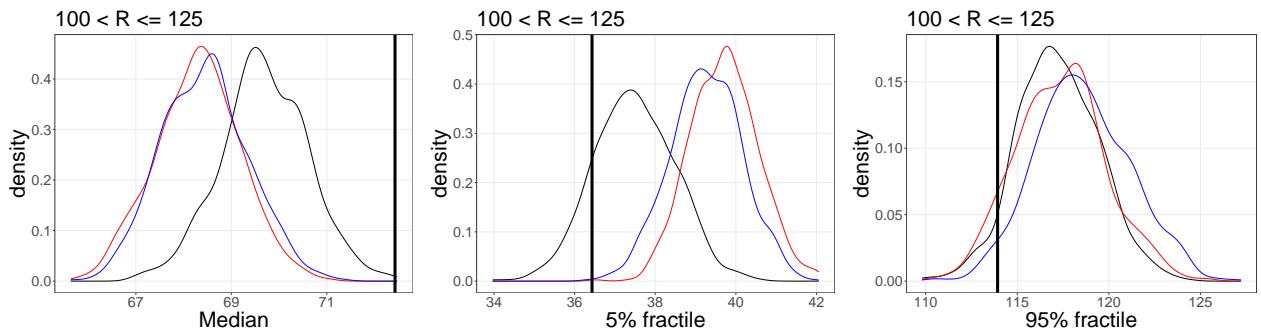


Figure S5: Posterior predictive checks for data in the range $100 < R \leq 125$ km. Shown are densities of the median and 5%/95% fractiles of 800 simulated data sets. The black vertical line displays the median or fractile of the M9 data.

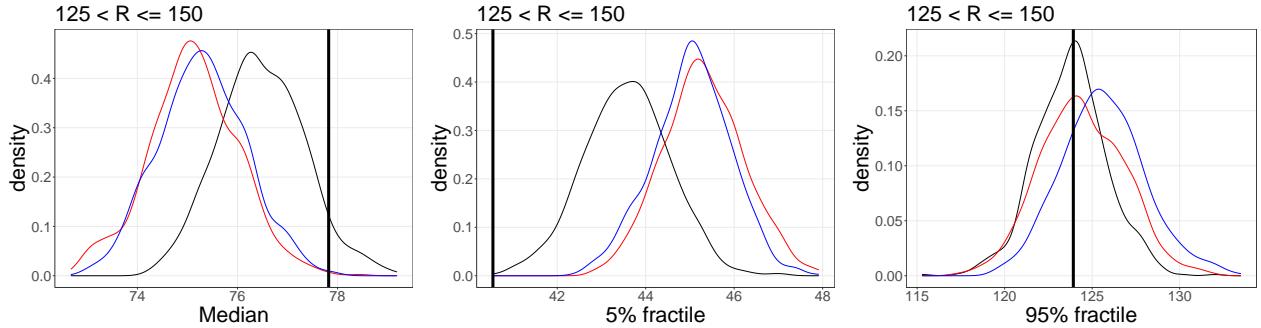


Figure S6: Posterior predictive checks for data in the range $125 < R \leq 150$ km. Shown are densities of the median and 5%/95% fractiles of 800 simulated data sets. The black vertical line displays the median or fractile of the M9 data.

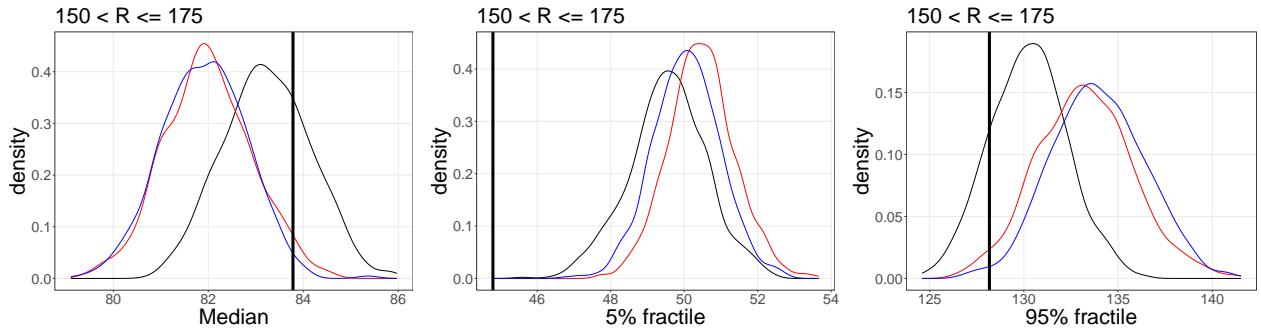


Figure S7: Posterior predictive checks for data in the range $150 < R \leq 175$ km. Shown are densities of the median and 5%/95% fractiles of 800 simulated data sets. The black vertical line displays the median or fractile of the M9 data.

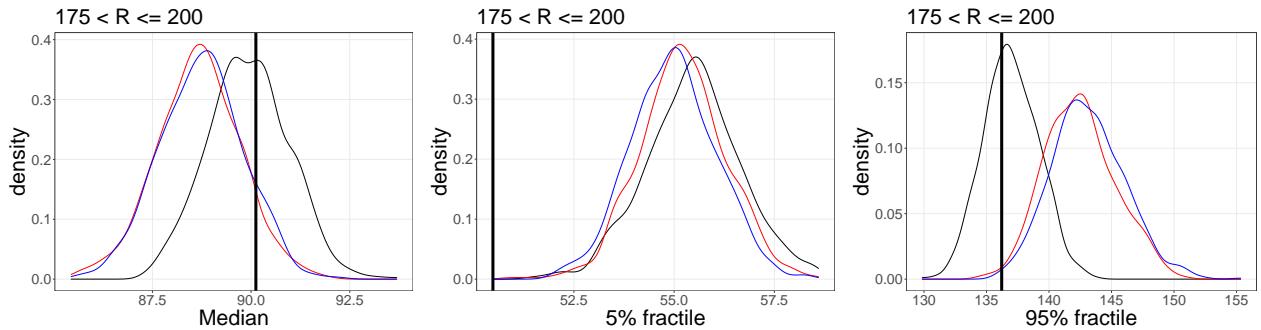


Figure S8: Posterior predictive checks for data in the range $175 < R \leq 200$ km. Shown are densities of the median and 5%/95% fractiles of 800 simulated data sets. The black vertical line displays the median or fractile of the M9 data.

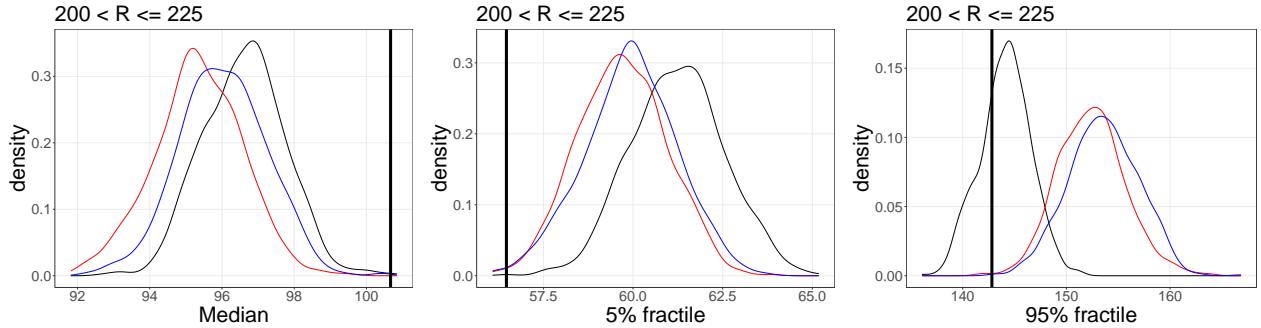


Figure S9: Posterior predictive checks for data in the range $200 < R \leq 225$ km. Shown are densities of the median and 5%/95% fractiles of 800 simulated data sets. The black vertical line displays the median or fractile of the M9 data.

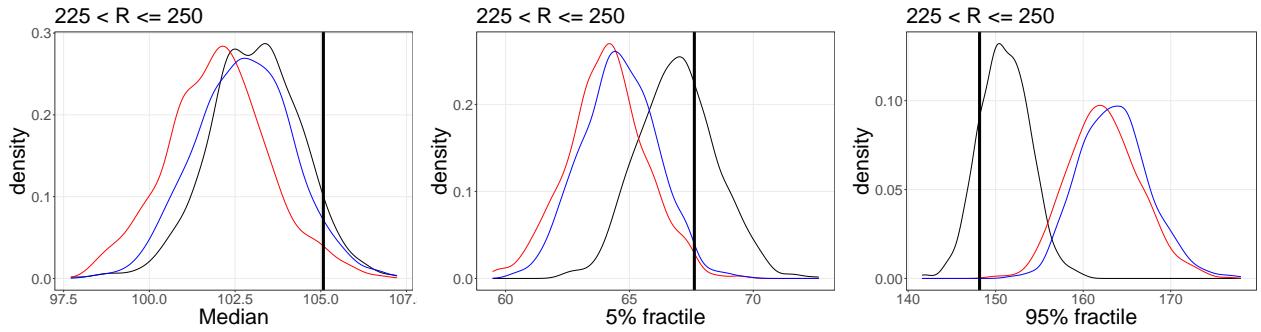


Figure S10: Posterior predictive checks for data in the range $225 < R \leq 250$ km. Shown are densities of the median and 5%/95% fractiles of 800 simulated data sets. The black vertical line displays the median or fractile of the M9 data.

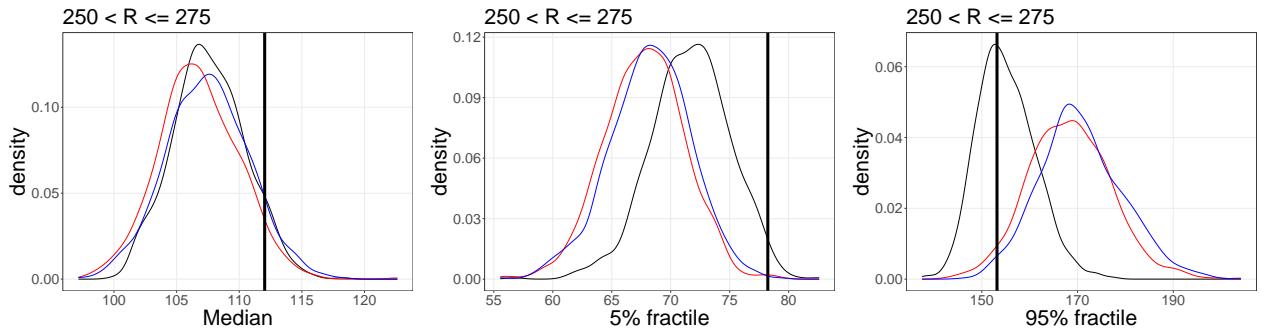


Figure S11: Posterior predictive checks for data in the range $250 < R \leq 275$ km. Shown are densities of the median and 5%/95% fractiles of 800 simulated data sets. The black vertical line displays the median or fractile of the M9 data.

2 Calculation of Leave-One Event-Out Log-Likelihood

In order to compare the models in terms of their log-likelihood values on test data (where the test data is all data from one event), the log-likelihood values need to be calculated. Since the event terms/source durations are unknown, this requires integration over the source duration uncertainty. The log-likelihood value for a single observation D_{obs} can be calculated as

$$\ln \mathcal{L} = \ln \int_0^\infty p(D_{obs}|D_S)p(D_S)dD_s \quad (1)$$

For the mixed model this can be calculated as

$$\ln \mathcal{L}(D_{Obs}) = p_{LN}(D_{obs}|\mu, \sigma_T) \quad (2)$$

where μ is the median prediction for the observation, and $\sigma_T^2 = \sigma_P^2 + \sigma_S^2$.

For the partially decoupled models, we use Monte Carlo Integration. We randomly sample a value of the source duration 1000 times, and calculate the likelihood of D_{obs} for each sample. We then average the likelihood values to get $\mathcal{L}(D_{Obs}) = \frac{\sum_{k=1}^{1000} \mathcal{L}_k(D_{Obs}|D_{S,k})}{1000}$, where $\mathcal{L}_k(D_{Obs}|D_{S,k})$ is the likelihood value for the k th sampled source duration $D_{S,k}$.

For the estimation, we run 3 chains with 300 warm-up and 200 sampling iterations, with the number of chains reduced compared to the paper for computational reasons. We calculate a likelihood value for each posterior sample, and average over samples to get a likelihood value for each observation (thus integrating over the source variability and the posterior uncertainty). We then calculate the sum of all log-likelihood values, which is reported in Table 1. The standard errors of the difference in log-likelihood values is calculated according to Equation (24) of [Vehtari et al. \(2017\)](#).

3 Epistemic Uncertainty

Figure S12 shows the epistemic uncertainty associated with the *mean* model predictions. For each of the posterior samples, we calculate a prediction for a given distance, which results in 800 model predictions. We then calculate mean, median, and 5%/95% fractiles of those 800 predictions and plot them against distance in Figure S12.

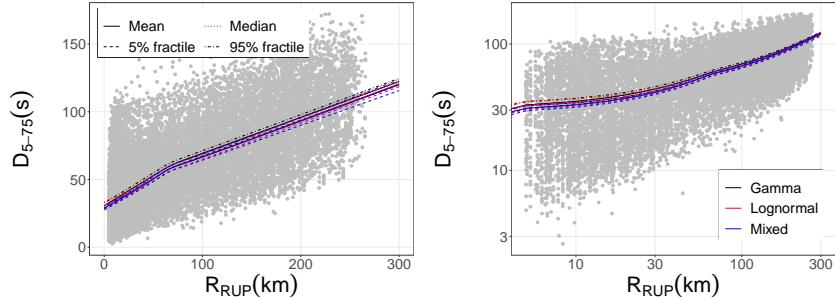


Figure S12: Epistemic uncertainty in mean model predictions based on posterior samples.

4 Residuals to NGA-Sub Data

This section shows residuals to the observed NGA-Sub data for the lognormal and mixed model, similar to Figure 9.

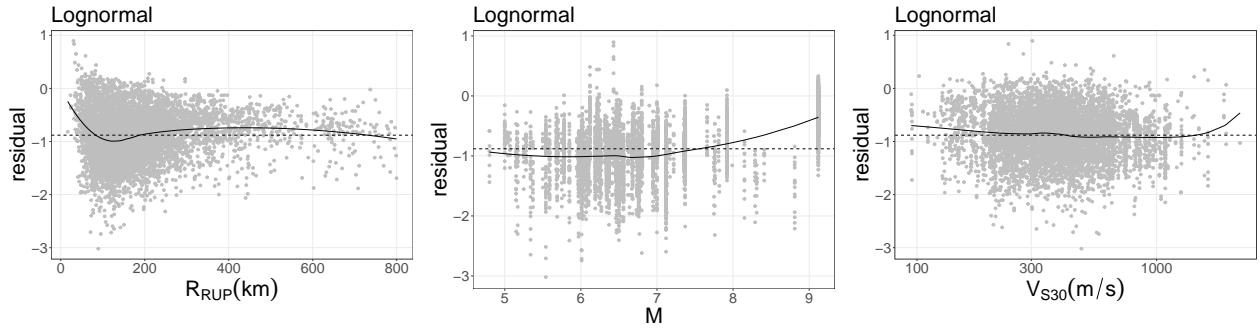


Figure S13: Residuals to Interface NGA-Sub data from KBCG with the lognormal model. The solid black lines show a loess fit to the residuals, the dashed black lines are the mean of the residuals.

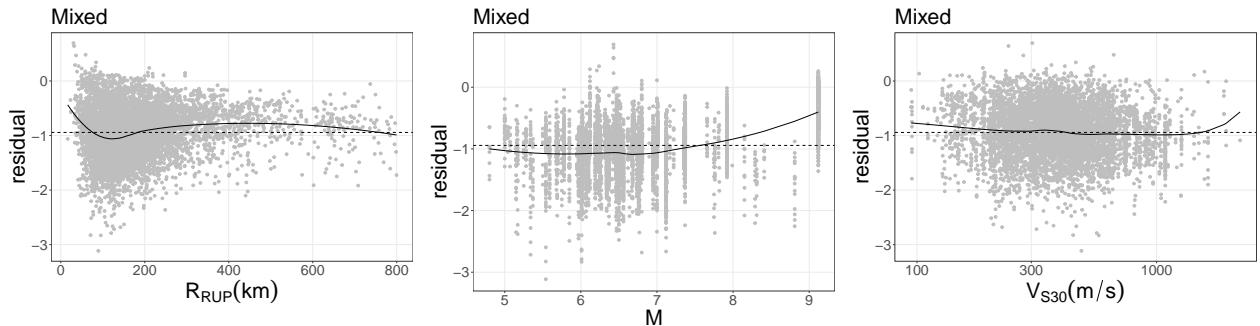


Figure S14: Residuals to Interface NGA-Sub data from KBCG with the mixed model. The solid black lines show a loess fit to the residuals, the dashed black lines are the mean of the residuals.

References

- Vehtari, A., A. Gelman, and J. Gabry (2017, sep). Practical Bayesian model evaluation using leave-one-out cross-validation and WAIC. *Statistics and Computing* 27(5), 1413–1432.