# **Laboratory Report Cover Sheet**

SRM Institute of Science and Technology
College of Engineering and Technology
Department of Electronics and Communication Engineering

### 21ECE201J-Python and Scientific Python Lab

Fourth Semester, 2024-25 (even semester)

## Mini Project report

On

## Flight Path Estimation

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Mark Split up		
Novelty of the project (5)		
Understanding (5)		
Execution &Demonstration (15)		
Report preparation (15)		
Total (40)		

Date :

Staff Name :

Signature :

#### FLIGHT PATH ESTIMATION

#### Introduction:

The Flight Path Estimation and Visualization Tool is a Python-based application designed to calculate and display potential flight routes between airports. It offers functionalities to fetch airport coordinates via an external API, calculate the great-circle distance, estimate basic flight metrics like time and fuel consumption, and visualize the path on an interactive map. The system requires user input for origin and destination airport IATA codes and a specific aircraft type to perform estimations based on simplified performance data. Users interact with the system through a console-based interface for input and receive feedback, including calculated metrics and a generated map file. Additionally, the project utilizes data visualization tools (Folium library) to provide a clear graphical representation of the flight path and key airport information. This project demonstrates the integration of fundamental programming concepts such as API interaction, geographical calculations, data handling using dictionaries, user input processing, and map-based data representation using Python libraries like requests, geopy, and folium. It serves as a practical model for applications involving geospatial data processing and visualization.

#### Software used:

- Python 3.x
- requests library (for API calls)
- geopy library (for distance calculation)
- folium library (for map generation)
- webbrowser library (to open the map)
- json library (for handling API errors)
- Aviationstack API (external data source)
- Jupyter Notebook

### Theory/Explanation:

The Flight Path Estimation and Visualization Tool is a Python application that simulates basic flight planning calculations and visualization. It operates by taking user inputs for origin airport, destination airport (using 3-letter IATA codes), and an aircraft type. Key data points like airport coordinates (latitude, longitude) are fetched dynamically using the requests library to call the Aviationstack API. This external API provides access to real-world airport data.

The core calculation involves determining the shortest path between the two airport coordinates on the Earth's surface using the great\_circle function from the geopy.distance module. This provides the distance in kilometers. Based on this distance and pre-defined, simplified performance characteristics (average cruise speed and fuel burn rate in kg/hour) stored in a Python dictionary (AIRCRAFT\_PERFORMANCE) for the selected aircraft type, the script estimates the flight duration (Time = Distance / Speed) and total fuel consumption (Fuel = Time \* Fuel Burn Rate).

User interaction occurs via the console for inputting the IATA codes and aircraft type. The script provides textual feedback on the console, displaying the fetched airport names, the calculated distance, and the estimated time and fuel.

A key output is an interactive HTML map generated using the folium library. This map visually plots the origin and destination airports as markers. Clicking these markers reveals pop-ups containing airport details and, for the destination, the estimated flight metrics. A line representing the great-circle path connects the two airports. The webbrowser library is used to automatically open this generated HTML file for immediate viewing.

This system demonstrates practical Python application development involving API integration, geospatial calculations, data manipulation, user interaction, and visualization, providing a foundation for more complex geospatial analysis tools. It highlights how different libraries can be combined to create a functional application, while acknowledging the simplifications made in the flight model (e.g., ignoring wind, climb/descent phases, actual air routes).

```
Programme:
import requests
import folium
from geopy.distance import great circle
import json # Used for pretty printing API errors if needed
import webbrowser
# --- Configuration ---
AVIATIONSTACK API KEY = '33ecd3b0dbedda04539b663e40ed1fba' # Replace with
your key
AVIATIONSTACK BASE URL = 'http://api.aviationstack.com/v1/'
# Simplified Aircraft Performance Data
# Speeds are approximate cruise speeds in km/h
# Fuel burn is approximate average cruise burn in kg/hour
AIRCRAFT PERFORMANCE = {
  'A320': {'cruise speed kmh': 830, 'fuel burn kgh': 2500},
  'B737': {'cruise speed kmh': 830, 'fuel burn kgh': 2750},
  # Add more aircraft types as needed
```

```
}
# --- Functions ---
def get airport coords(api key, iata code):
  """Fetches airport coordinates from aviationstack API."""
  params = {
     'access key': api key,
     'iata code': iata code
  }
  try:
     response = requests.get(f"{AVIATIONSTACK BASE URL}airports", params=params)
     response.raise for status() # Raise an exception for bad status codes (4xx or 5xx)
     data = response.json()
     # Check if 'data' key exists and is a non-empty list
     if data.get('data') and isinstance(data['data'], list) and len(data['data']) > 0:
       # * FIXED: Access the first dictionary inside the list *
       airport_info = data['data'][0]
       # Now extract details from the airport info dictionary
       lat = airport info.get('latitude')
       lon = airport info.get('longitude')
       name = airport info.get('airport name', 'N/A')
       city = airport info.get('city', airport info.get('city iata code', 'N/A'))
       country = airport info.get('country name', 'N/A')
       if lat is not None and lon is not None:
                 print(f"Successfully retrieved coordinates for {iata code}: {name}, {city},
{country}")
          return float(lat), float(lon), name
```

```
else:
         print(f"Error: Latitude or Longitude missing for {iata code} in API response.")
         print("Airport Info Received:", json.dumps(airport_info, indent=2))
         return None, None, None
    else:
              print(f"Error: No data found or unexpected format for airport IATA code:
{iata code}")
       print("API Response:", json.dumps(data, indent=2)) # Print response for debugging
       return None, None, None
  except requests.exceptions.RequestException as e:
    print(f"Error fetching data for {iata code} from aviationstack: {e}")
    try:
       error details = response.json()
       print("API Error Details:", json.dumps(error_details, indent=2))
    except Exception:
       pass
    return None, None, None
  except json.JSONDecodeError:
    print(f"Error: Could not decode JSON response from aviationstack for {iata code}.")
    print("Raw Response Text:", response.text)
    return None, None, None
  except IndexError:
    print(f"Error: API returned an empty list for {iata code}.")
    print("API Response:", json.dumps(data, indent=2))
    return None, None, None
def calculate great circle distance(coord1, coord2):
  """Calculates Great Circle distance between two coordinates."""
  if coord1 and coord2:
    # Ensure coordinates are tuples of floats
```

```
coord1 float = (float(coord1[0]), float(coord1[1]))
    coord2 float = (float(coord2[0]), float(coord2[1]))
    distance = great circle(coord1 float, coord2 float).km
    return distance
  return 0
def estimate flight metrics(distance km, cruise speed kmh, fuel burn kgh):
  """Estimates flight time and fuel burn."""
  if cruise speed kmh <= 0:
    print("Error: Cruise speed must be positive.")
    return 0, 0
  if distance km \le 0:
     print("Warning: Distance is zero or negative.")
     return 0, 0
  estimated time hr = distance km / cruise speed kmh
  estimated fuel kg = estimated time hr * fuel burn kgh
  return estimated time hr, estimated fuel kg
def create flight map(origin coord, dest coord, origin iata, dest iata,
             origin name, dest name, distance km, time hr, fuel kg):
  """Creates and saves a Folium map with the flight path."""
  if not origin coord or not dest coord:
    print("Error: Cannot create map without valid coordinates.")
    return
  # Ensure coordinates are tuples of floats for Folium
  origin coord float = (float(origin coord[0]), float(origin coord[1]))
  dest coord float = (float(dest coord[0]), float(dest coord[1]))
  # Create map centered roughly between origin and destination
```

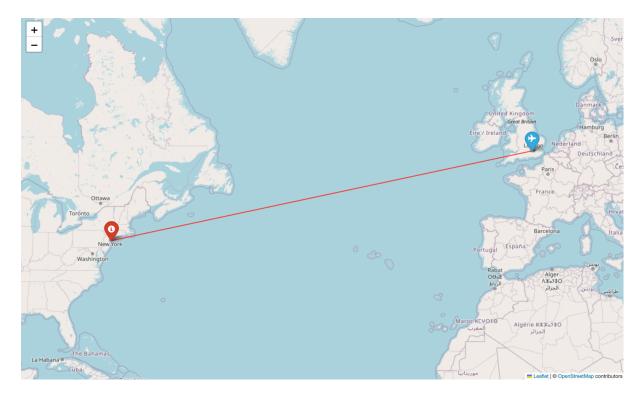
```
map center = [
  (origin coord float[0] + dest coord float[0]) / 2,
  (origin_coord_float[1] + dest_coord_float[1]) / 2
]
flight map = folium.Map(location=map center, zoom start=4)
# Add markers for origin and destination
tooltip origin = f"Origin: {origin iata} ({origin name})"
popup origin = f"""
<b>Origin: {origin iata}</b><br>
Name: {origin name} < br>
Coords: ({origin coord float[0]:.4f}, {origin coord float[1]:.4f})
folium.Marker(
  location=origin coord float,
  popup=popup origin,
  tooltip=tooltip origin,
  icon=folium.Icon(color='blue', icon='plane', prefix='fa')
).add to(flight map)
tooltip_dest = f"Destination: {dest iata} ({dest name})"
popup dest = f"""
<b>Destination: {dest iata}</b><br>
Name: {dest name} < br >
Coords: ({dest coord float[0]:.4f}, {dest coord float[1]:.4f}) <br/>br>
---<hr>
<b>Estimated Metrics:</b><br>
Distance: {distance km:,.2f} km<br/>br>
Time: {time hr:.2f} hours<br/>br>
Fuel: {fuel kg:,.2f} kg
,,,,,,
```

```
folium.Marker(
    location=dest coord float,
    popup=popup_dest,
    tooltip=tooltip_dest,
    icon=folium.Icon(color='red', icon='info-sign')
  ).add to(flight map)
  # Add PolyLine for the flight path
  points = [origin coord float, dest coord float]
  folium.PolyLine(
    locations=points,
    color='red',
    weight=2,
    opacity=0.8,
    tooltip=f"Great Circle Path: {distance km:,.2f} km"
  ).add to(flight map)
  # Save map to HTML file
  filename = f"flight_map_{origin_iata}to{dest_iata}.html"
  flight map.save(filename)
  print(f"\nMap saved as {filename}")
  webbrowser.open(filename)
if name == " main ":
  print("Flight Path Estimator")
  print("-" * 20)
  if AVIATIONSTACK API KEY == 'YOUR AVIATIONSTACK API KEY':
     print("\nError: Please replace 'YOUR AVIATIONSTACK API KEY' with your actual
key in the script.")
    exit()
```

```
origin iata = input("Enter Origin Airport IATA code (e.g., LHR): ").strip().upper()
  dest_iata = input("Enter Destination Airport IATA code (e.g., JFK): ").strip().upper()
                     aircraft type
                                              input(f"Enter
                                                                 Aircraft
                                                                              Type
                                                                                        (\{',
'.join(AIRCRAFT PERFORMANCE.keys())}): ").strip().upper()
  if aircraft type not in AIRCRAFT PERFORMANCE:
    print(f"\nError: Aircraft type '{aircraft type}' not found in performance data.")
    print(f"Available types: {', '.join(AIRCRAFT PERFORMANCE.keys())}")
    exit()
  print("\nFetching airport data...")
   origin lat, origin lon, origin name = get airport coords(AVIATIONSTACK API KEY,
origin iata)
      dest lat, dest lon, dest name = get airport coords(AVIATIONSTACK API KEY,
dest iata)
  if origin lat is None or dest lat is None:
    print("\nCould not retrieve coordinates for one or both airports. Exiting.")
    exit()
  origin coord = (origin lat, origin lon)
  dest_coord = (dest_lat, dest_lon)
  print("\nCalculating distance...")
  distance km = calculate great circle distance(origin coord, dest coord)
  if distance km > 0:
    print(f"Great Circle Distance: {distance km:,.2f} km")
  else:
    print("Could not calculate distance.")
    exit()
```

```
print("\nEstimating flight metrics...")
  perf = AIRCRAFT PERFORMANCE[aircraft type]
  est_time_hr, est_fuel_kg = estimate_flight_metrics(
     distance km,
     perf['cruise speed kmh'],
     perf['fuel burn kgh']
  )
  print(f"Aircraft Type: {aircraft type}")
  print(f" Estimated Cruise Speed: {perf['cruise speed kmh']} km/h")
  print(f" Estimated Fuel Burn: {perf['fuel burn kgh']} kg/hr")
  print(f"Estimated Flight Time: {est time hr:.2f} hours")
  print(f"Estimated Total Fuel Burn: {est fuel kg:,.2f} kg")
  print("\nGenerating map...")
  create flight map(origin coord, dest coord, origin iata, dest iata,
              origin name, dest name, distance km, est time hr, est fuel kg)
  print("\nProcess Complete.")
Result and Screenshots:
 Flight Path Estimator
 Enter Origin Airport IATA code (e.g., LHR): LHR
 Enter Destination Airport IATA code (e.g., JFK): JFK
 Enter Aircraft Type (A320, B737): A320
 Fetching airport data...
 Successfully retrieved coordinates for LHR: Heathrow, LON, United Kingdom
 Successfully retrieved coordinates for JFK: John F Kennedy International, NYC, United States
 Calculating distance...
 Great Circle Distance: 5,540.67 km
 Estimating flight metrics...
 Aircraft Type: A320
   Estimated Cruise Speed: 830 km/h
   Estimated Fuel Burn: 2500 kg/hr
 Estimated Flight Time: 6.68 hours
 Estimated Total Fuel Burn: 16,688.77 kg
 Generating map...
 Map saved as flight_map_LHRtoJFK.html
```

Process Complete.



#### Discussion of Results:

The Flight Path Estimation and Visualization Tool was successfully developed to take user inputs and fetch required airport data via the Aviationstack API. The system correctly calculates the great-circle distance using geopy and estimates flight time and fuel based on the selected aircraft's simplified performance data. Furthermore, using folium, a key visualization was created: an interactive HTML map showing the origin and destination airports as markers, connected by the calculated flight path. Popups on the markers provide relevant details, including the estimated metrics. The results from the console output and the interactive map provide clear feedback on the calculated distance and estimated flight parameters, making the system a useful tool for basic flight path visualization, suitable for extensions like adding more aircraft types or refining the flight model.

#### Conclusion:

The developed Flight Path Estimation and Visualization Tool effectively meets the core objective of calculating and displaying basic flight route information between two airports. The integration of external API calls, geographical calculations, and interactive map visualization enhances data interpretation by clearly showing the route and associated estimates. The system is designed with clear functions and user interaction via the console, providing a solid foundation for further enhancements such as incorporating wind data, using more complex flight phase models (climb, cruise, descent), or allowing data export.