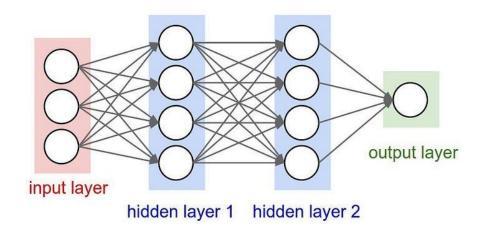
Deep Learning

CS473/CS573: Computer Vision

The goal of deep learning is to obtain a function that answers a specific question.

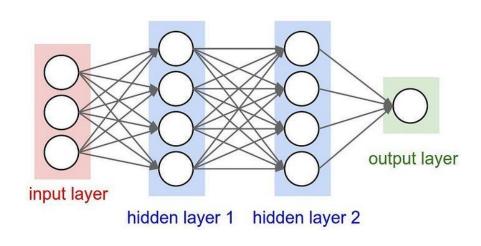
The goal of deep learning is to obtain a function that answers a specific question.



Deep

Function is multi-layered

The goal of deep learning is to obtain a function that answers a specific question.



dog



cat



elephant

Deep

Function is multi-layered

Learning

Function is estimated from data

How do machines learn?

How do machines learn?

Feature Extraction followed by Feature Reasoning

How do machines learn?

Feature Extraction followed by Feature Reasoning

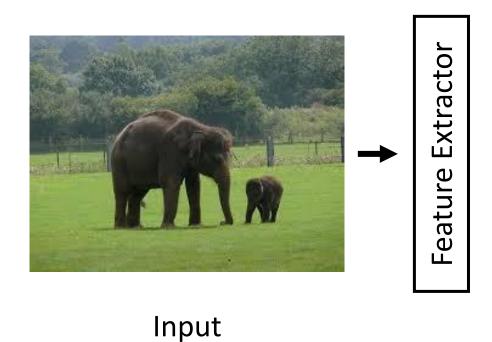
Example: Let's answer a specific question:

How do machines learn?

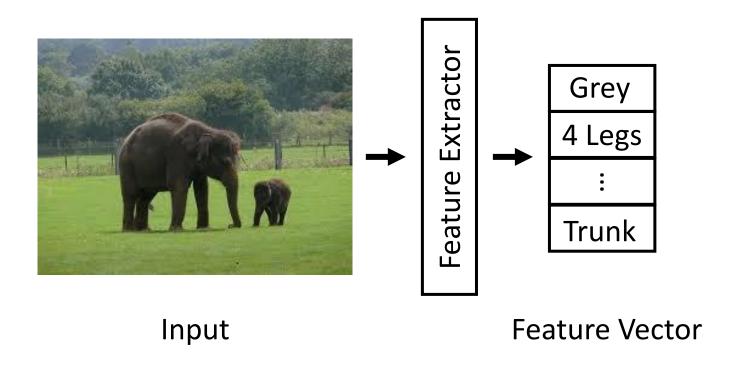


Input

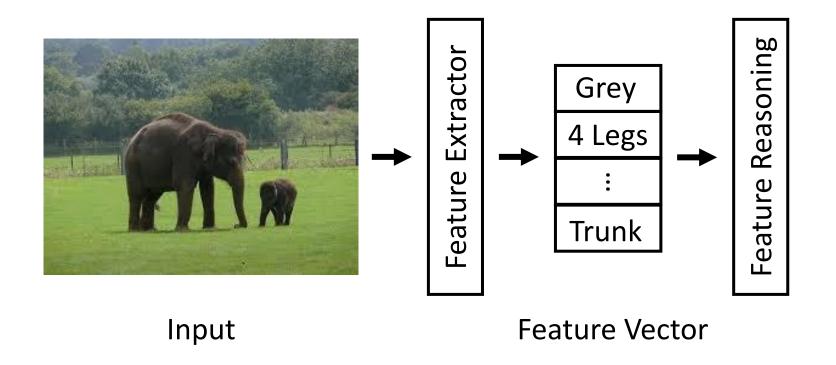
How do machines learn?



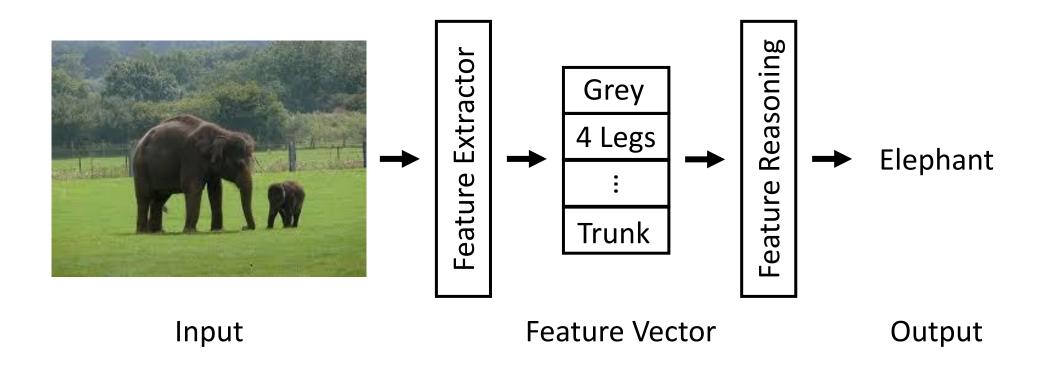
How do machines learn?

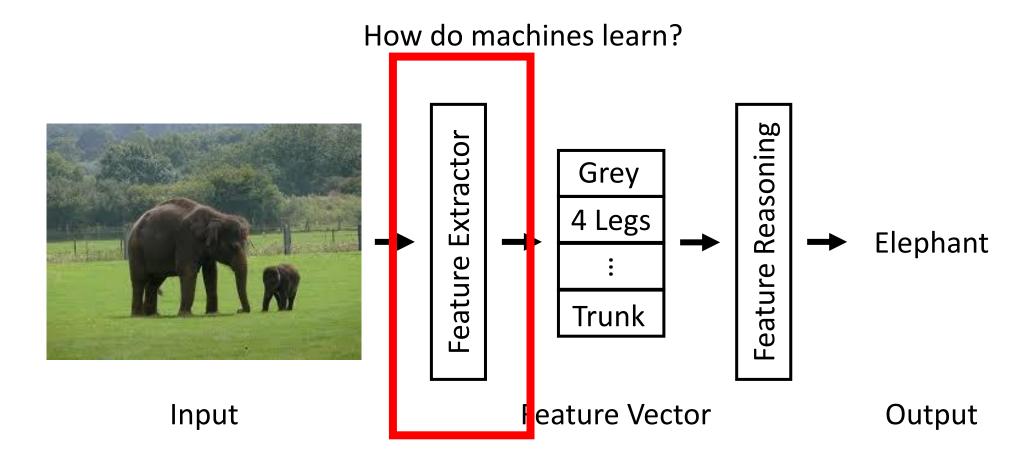


How do machines learn?



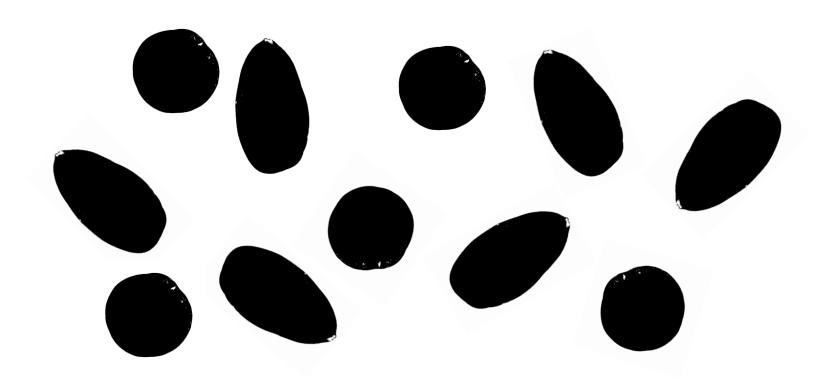
How do machines learn?





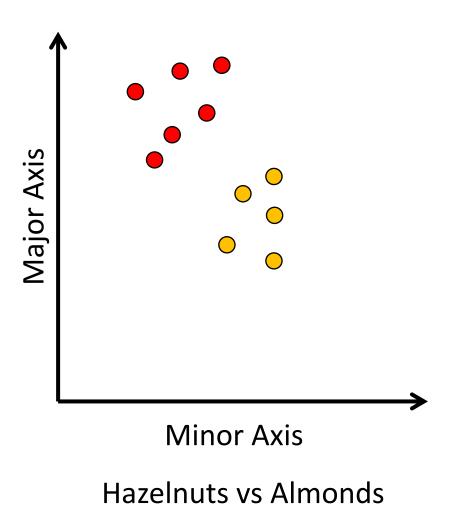


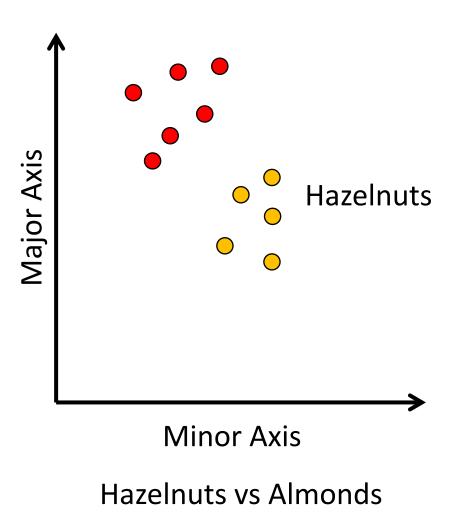


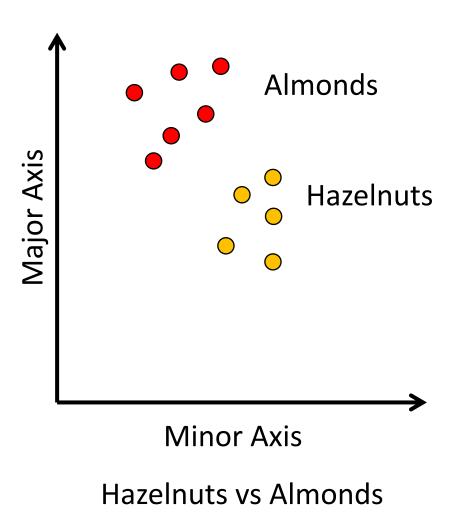


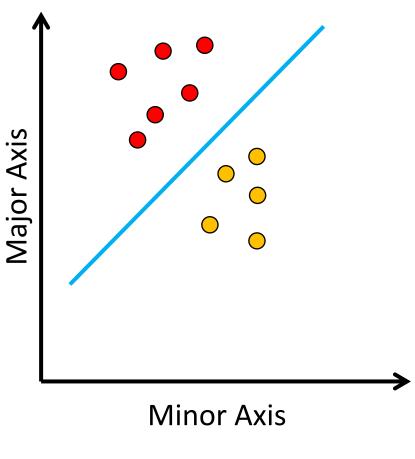




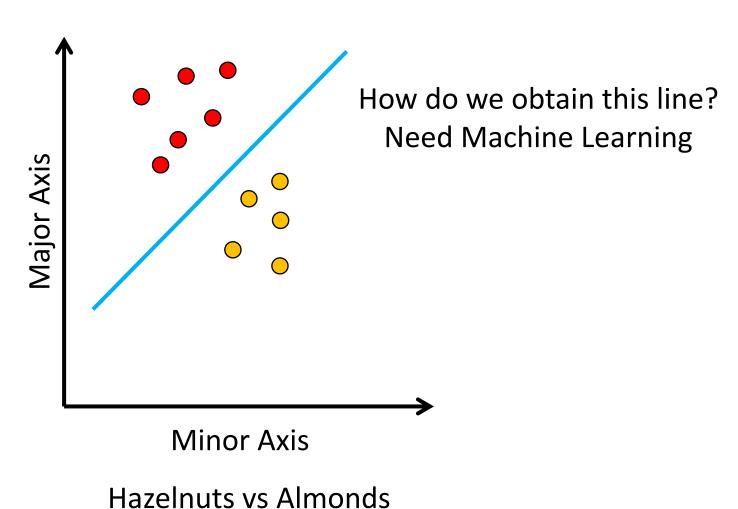


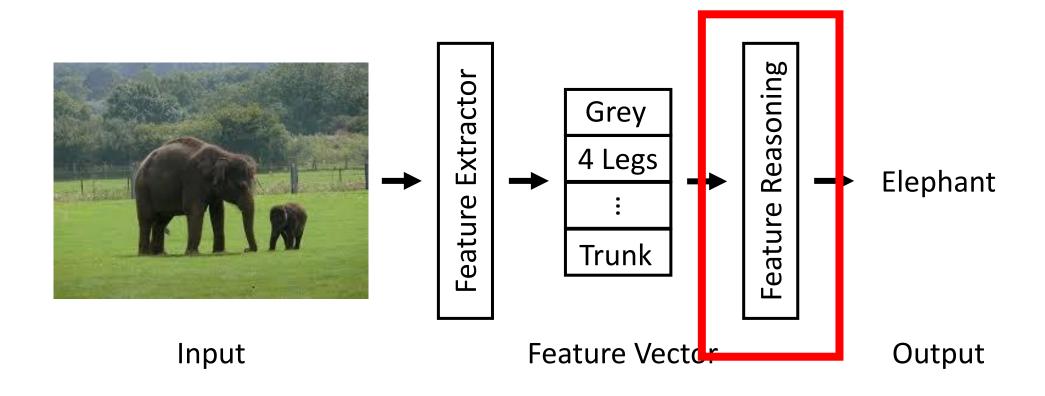




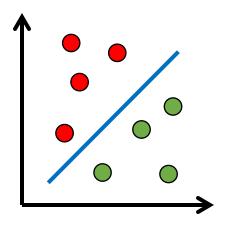


Hazelnuts vs Almonds



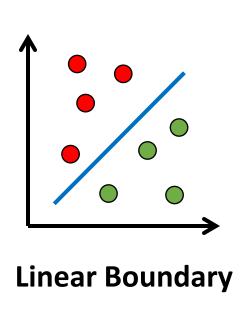


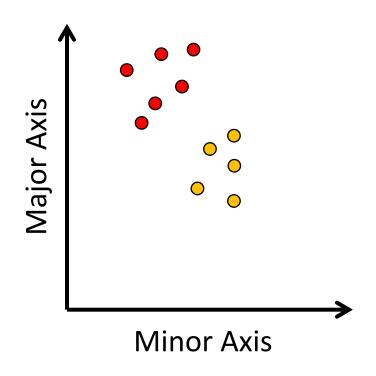
Decision Boundary for Binary Classification



Linear Boundary

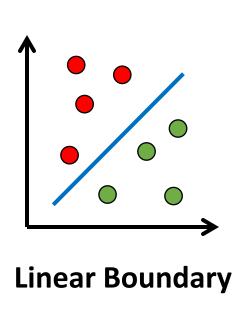
Decision Boundary for Binary Classification



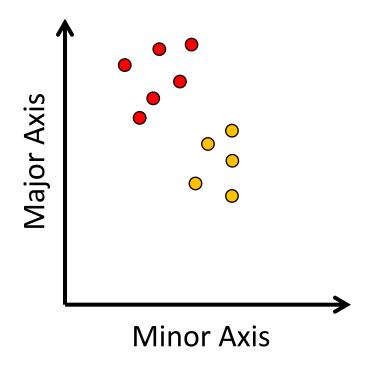


Hazelnuts vs Almonds

Decision Boundary for Binary Classification

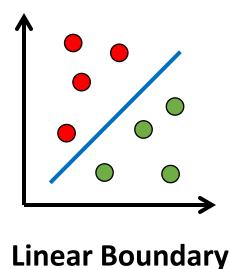


Linear Support Vector Machine

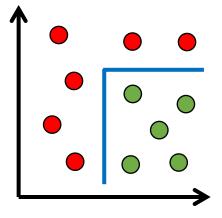


Hazelnuts vs Almonds

Decision Boundary for Binary Classification



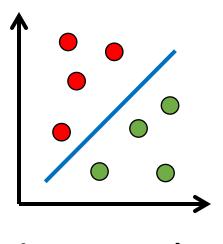
Linear Support Vector Machine



Axis Aligned Non-Linear Boundary

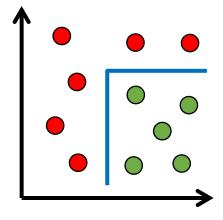
Decision Tree

Decision Boundary for Binary Classification



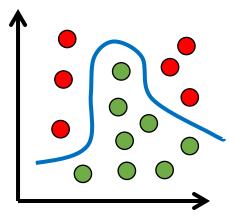
Linear Boundary

Linear Support Vector Machine



Axis Aligned Non-Linear Boundary

Decision Tree



Complex Non-Linear Boundary

Neural Network

Classical Machine Learning	Deep Learning
Interpretability and explainability is a priority.	Very high accuracy is a priority.
Smaller amounts of relatively simple data.	Large amounts of precisely labeled data.
Straightforward feature engineering.	Complex feature engineering.

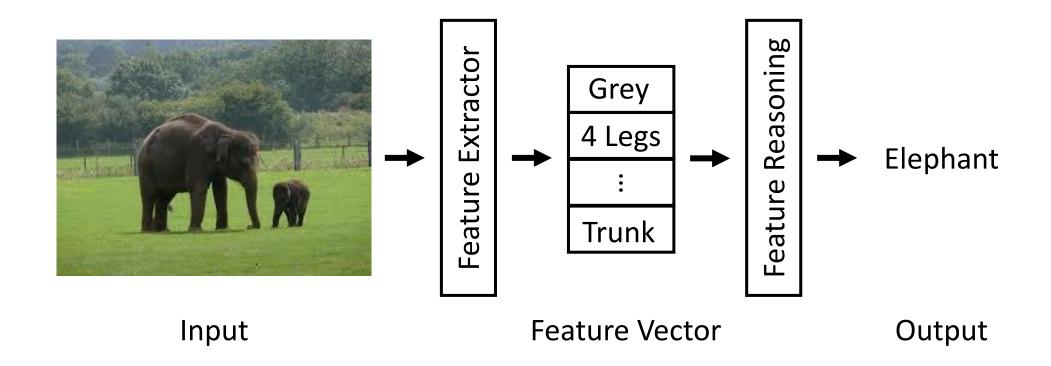
https://blog.dataiku.com/when-and-when-not-to-use-deep-learning

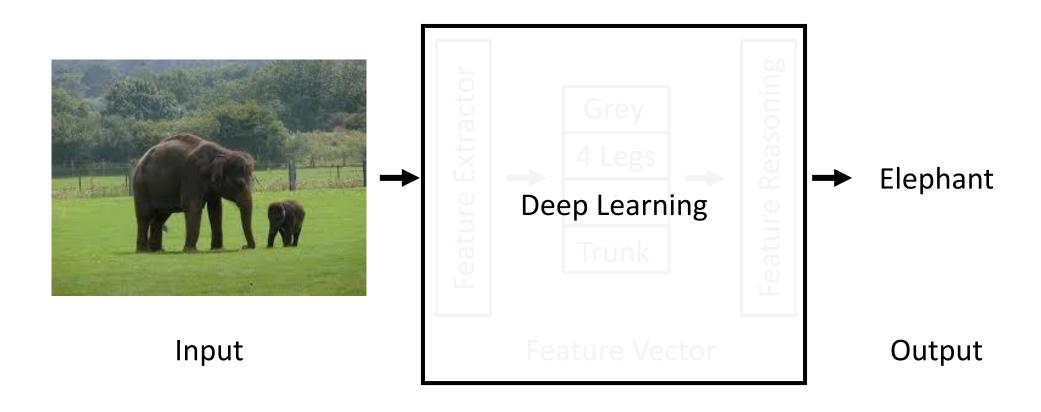
Classical Machine Learning

Deep Learning

K-Means Clustering
Linear Regression
Decision Trees
Random Forest

Fully Connected Network
Convolutional Neural Network





Deep Learning for Computer Vision

What specific questions can we answer?

Circa 1966: Marvin Minsky at MIT gives Gerald Jay Sussman, an undergraduate student, a summer project to link a computer to a camera and get the computer to "describe what it saw".

Deep Learning for Computer Vision

What specific questions can we answer?

Circa 1966: Marvin Minsky at MIT gives Gerald Jay Sussman, an undergraduate student, a summer project to link a computer to a camera and get the computer to "describe what it saw".



How would you describe this image?

What specific questions can we answer?

Circa 1966: Marvin Minsky at MIT gives Gerald Jay Sussman, an undergraduate student, a summer project to link a computer to a camera and get the computer to "describe what it saw".



How would you describe this image?

First: What does "describe this" even mean?

Deep Learning Tasks

Binary Classification (binary label):
 "Is there an elephant in this image?"



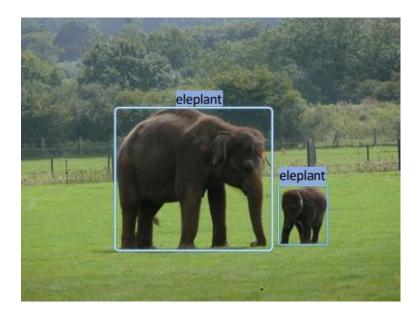
- Binary Classification (binary label):
 "Is there an elephant in this image?"
- Classification (integer label):
 "What animal is in this image?"
 An Elephant



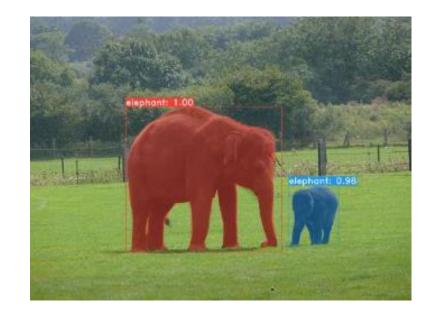
- Binary Classification (binary label):
 "Is there an elephant in this image?"
- Classification (integer label):
 "What animal is in this image?"
- Regression (real number):
 "How old is the elephant in this image?"



- Binary Classification (binary label):
 "Is there an elephant in this image?"
- Classification (integer label):
 "What animal is in this image?"
- Regression (real number):
 "How old is the elephant in this image?"
- Detection (bounding box):"Where is the elephant in this image?"



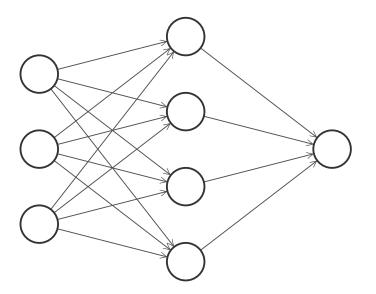
- Binary Classification (binary label):
 "Is there an elephant in this image?"
- Classification (integer label):
 "What animal is in this image?"
- Regression (real number):
 "How old is the elephant in this image?"
- Detection (bounding box):"Where is the elephant in this image?"
- Segmentation (pixel mask):
 "Which pixels in this image are elephant?"



We know what specific questions we can ask.

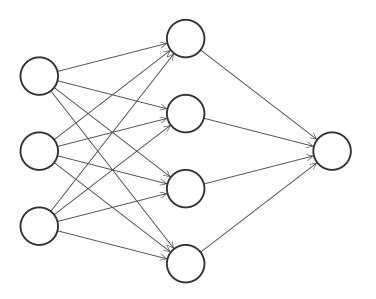
But how do we get a computer to answer them?

Fully Connected Network (FCN)



Idea: learn a bunch of functions that make incrementally more complex decisions.

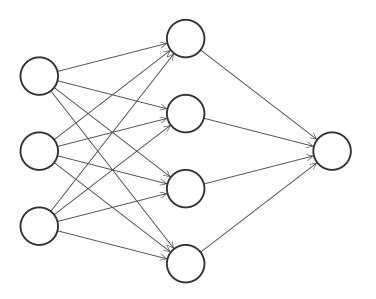
Fully Connected Network (FCN)



input layer

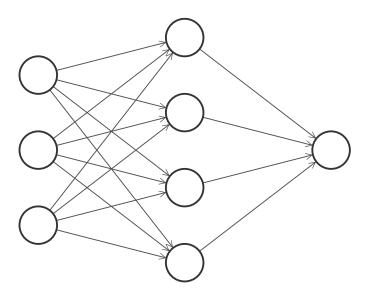
input your data here

Fully Connected Network (FCN)



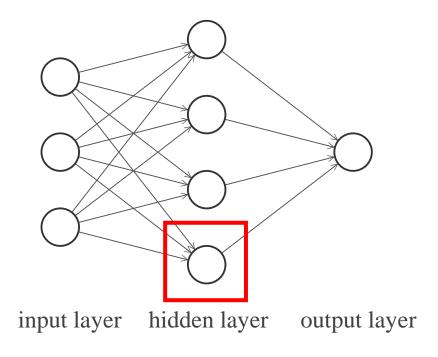
input layer hidden layer
extract some features and
do some reasoning

Fully Connected Network (FCN)

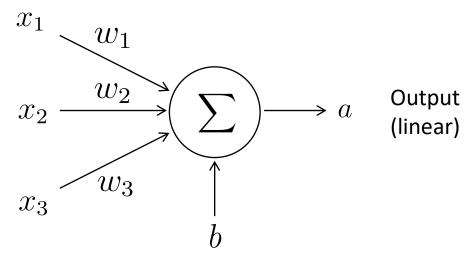


input layer hidden layer output layer make a decision

Fully Connected Network (FCN)

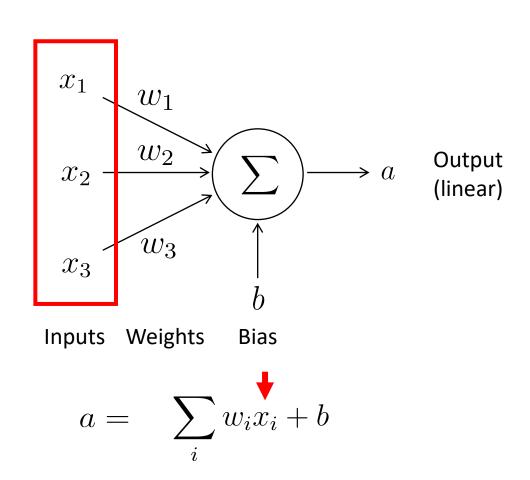


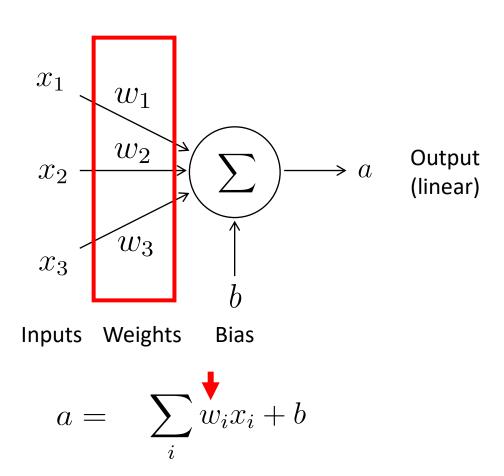
Building Blocks: Perceptron

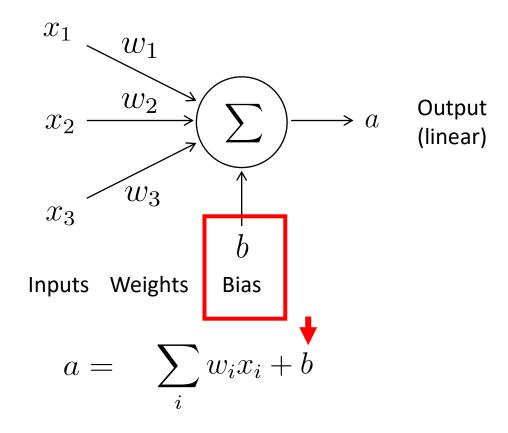


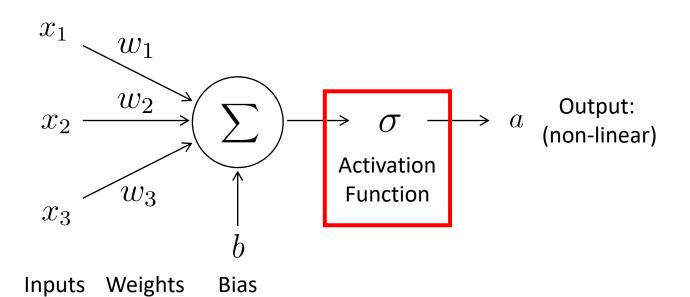
Inputs Weights Bias

$$a = \sum_{i} w_i x_i + b$$



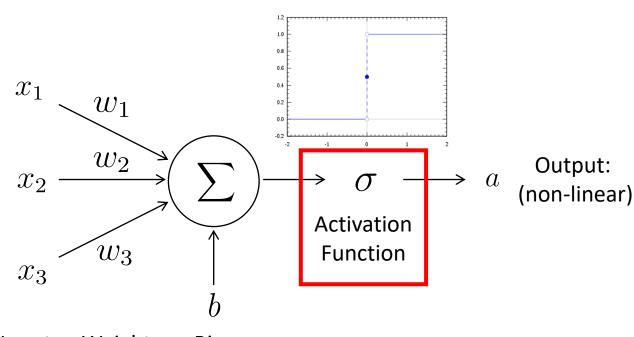






$$a = \sigma(\sum_{i} w_i x_i + b)$$

Building Blocks: Perceptron

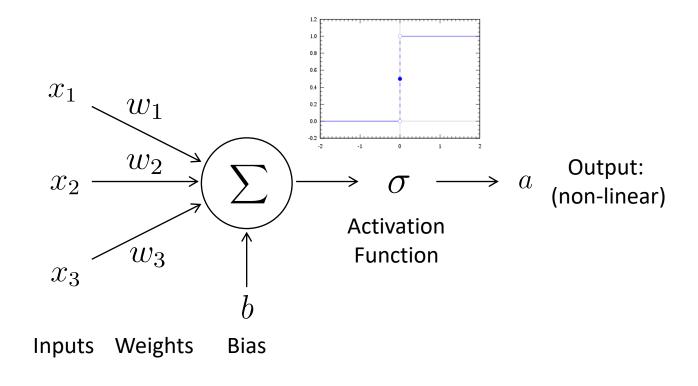


Inputs Weights Bias

$$a = \sigma(\sum_{i} w_{i} x_{i} + b)$$

Building Blocks: Perceptron

Neurons (or Nodes) are based on biological neurons that "fire" if the linear output is high. The "firing" is modeled by the activation function.

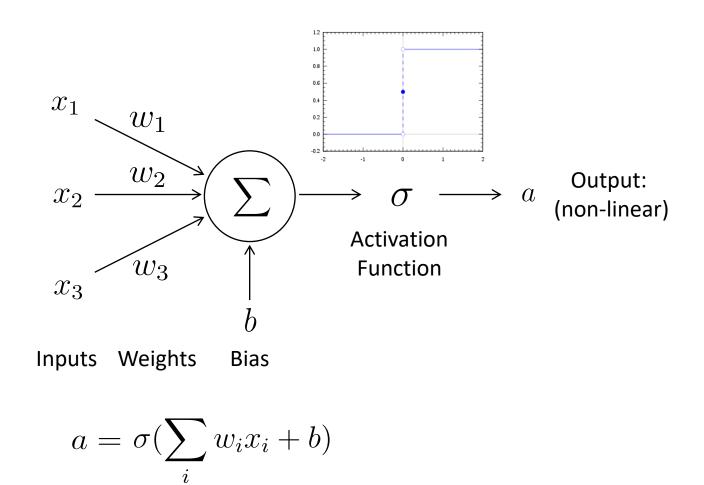


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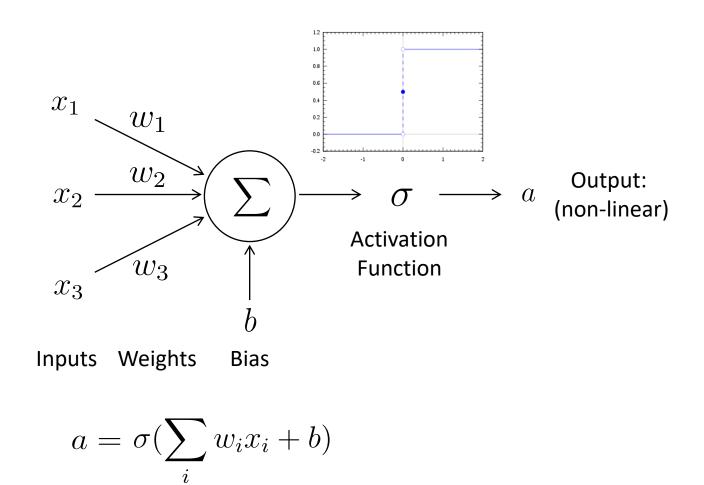
Neurons correspond to feature descriptors that "fire" when the "see" their corresponding feature.



Building Blocks: Perceptron

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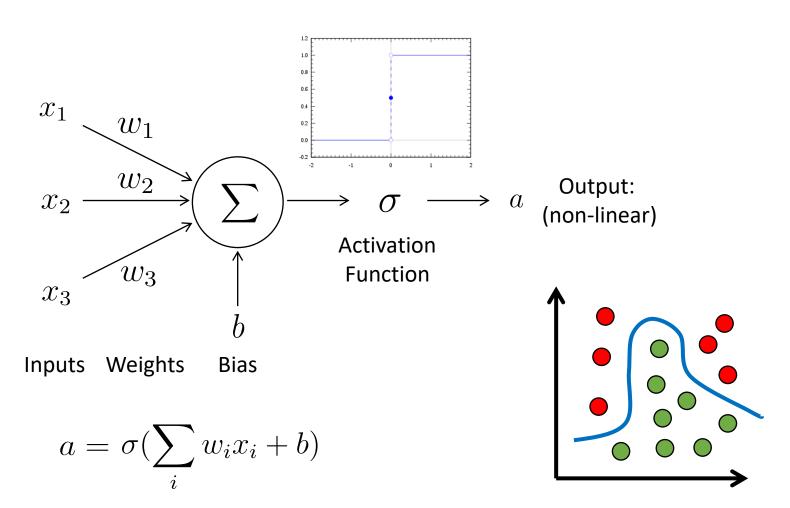
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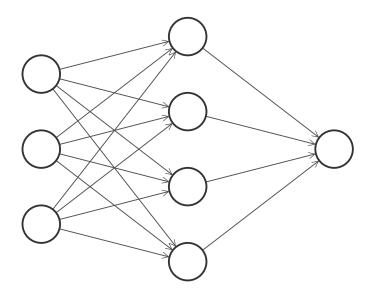
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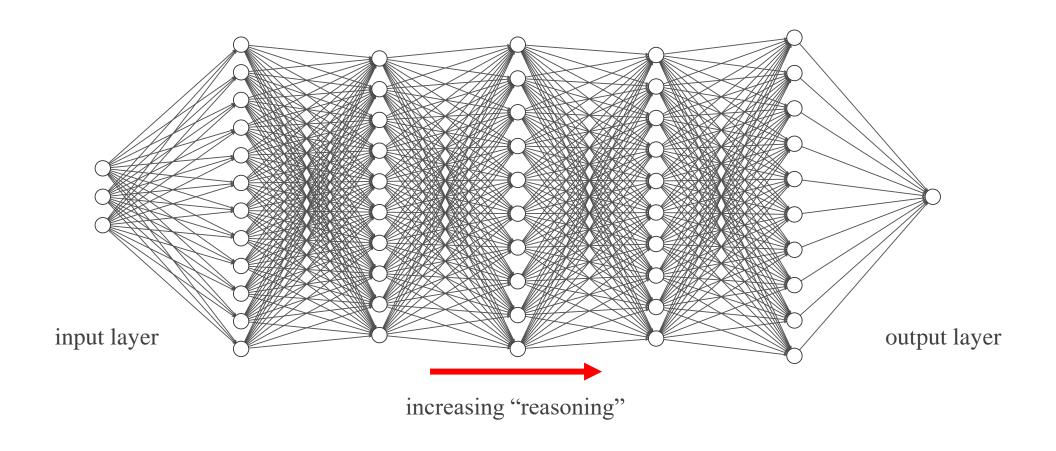


String many functions together to answer "reason" about the input

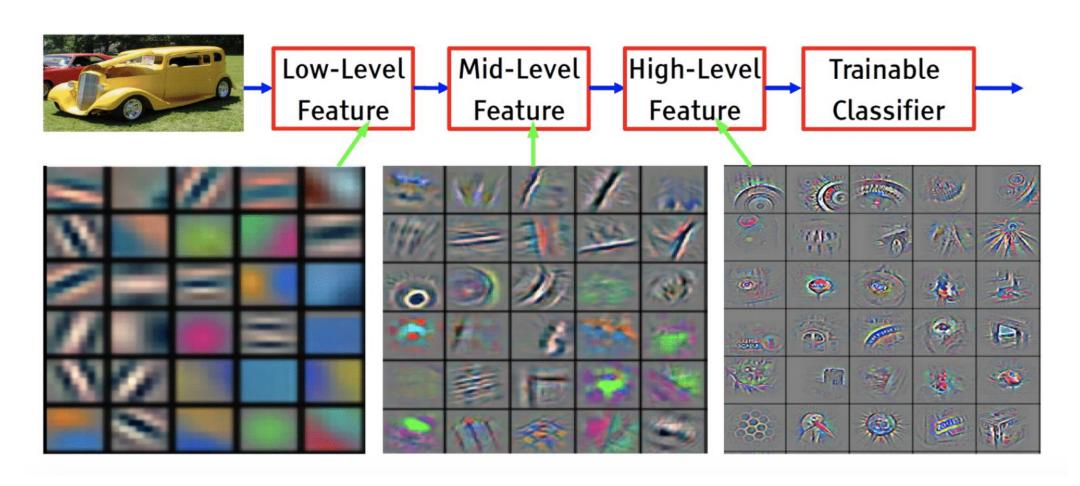


input layer hidden layer output layer

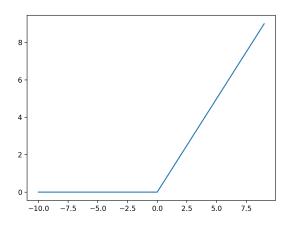
String many functions together to answer "reason" about the input

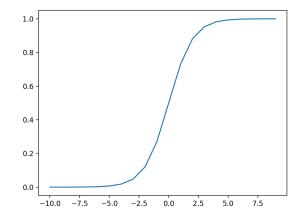


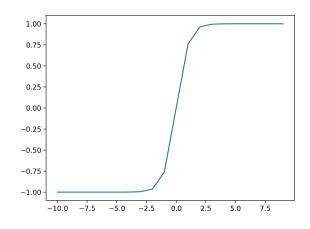
String many functions together to answer "reason" about the input



Building Blocks: Activation Functions







Rectified Linear Unit (ReLU)

Good general purpose fn, overcomes vanishing gradient issues

Sigmoid

Used for RNNs and binary classification output

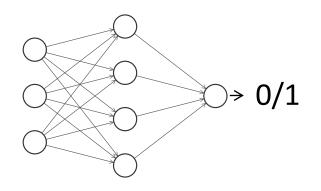
Hyperbolic Tangent

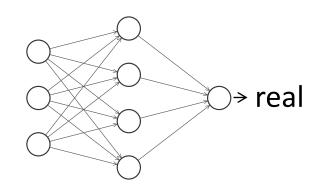
Used for RNNs

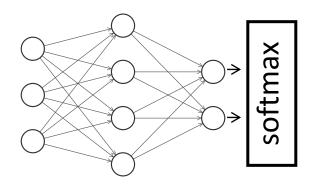
https://towardsdatascience.com/how-to-choose-the-right-activation-function-for-neural-networks-3941ff0e6f9c https://machinelearningmastery.com/choose-an-activation-function-for-deep-learning/

Building Blocks: Output Layer

$$\sigma(z_i) = rac{e^{z_i}}{\sum_{j=1}^K e^{z_j}}$$
 softmax







Binary Classification

Single Node Sigmoid activation

Regression

Single Node Linear activation

Classification

Multiple Nodes
ReLU activation with Softmax

Building Blocks: Network Size

How many nodes/layers should I use?

"Width and depth are both important and should be carefully tuned... depth may determine the abstraction level but the width may influence the loss of information in the forwarding pass."

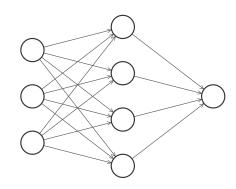
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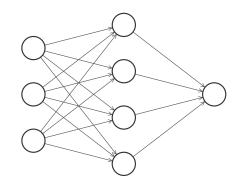
At a minimum you should have more nodes than the dimensionality of your input.

How do we input images to a Neural Network?



Can't use a FCN

How do we input images to a Neural Network?



Can't use a FCN

Let's input a 128x128 image



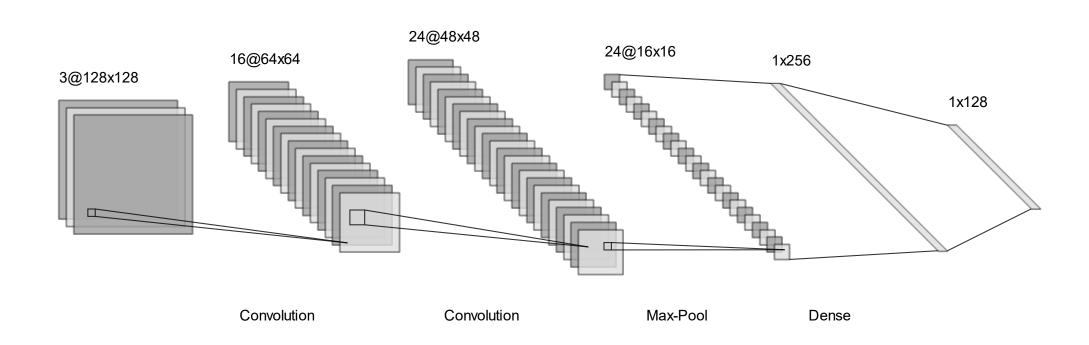
Need 16,384 input nodes

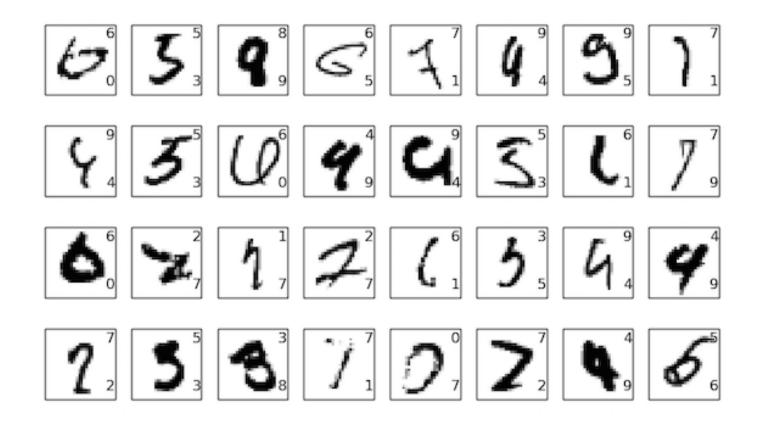
Assume 3 layers with 16,384 nodes each

(16,384x2x16,384)x3 + 2x16,384 = 1.6 billion

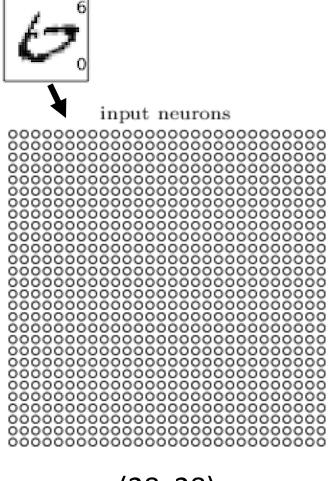
This is not trainable in a reasonable amount of time

Does not model inherent structure of images





MNIST as an example (28x28px) images



(28x28) Input Values

input neurons

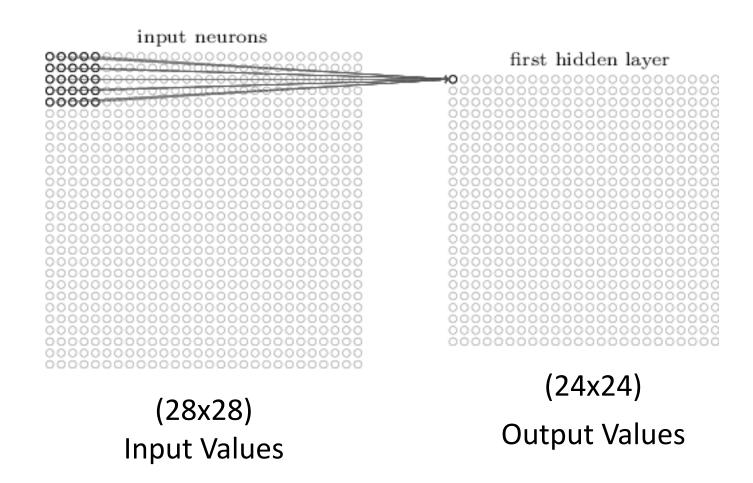
hidden neuron ⇒∞ (5x5)

00000

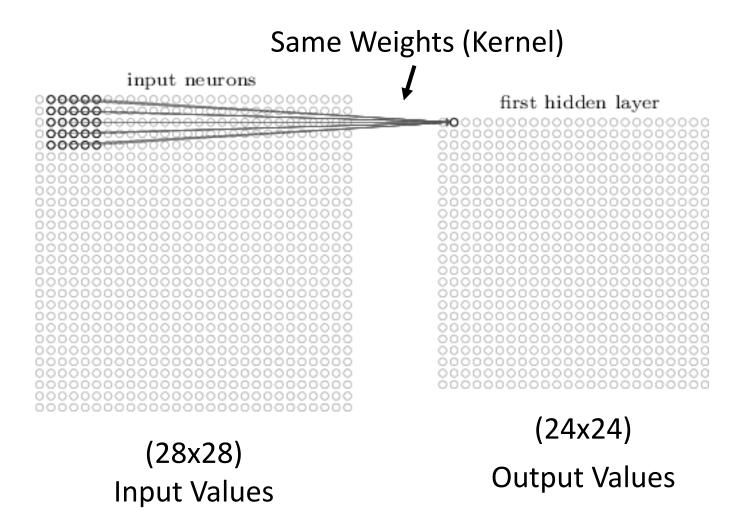
 have each hidden neuron process a small window of the input, called the "receptive field".

Grid of weights we multiply by the input to get a single output value

(28x28) Input Values

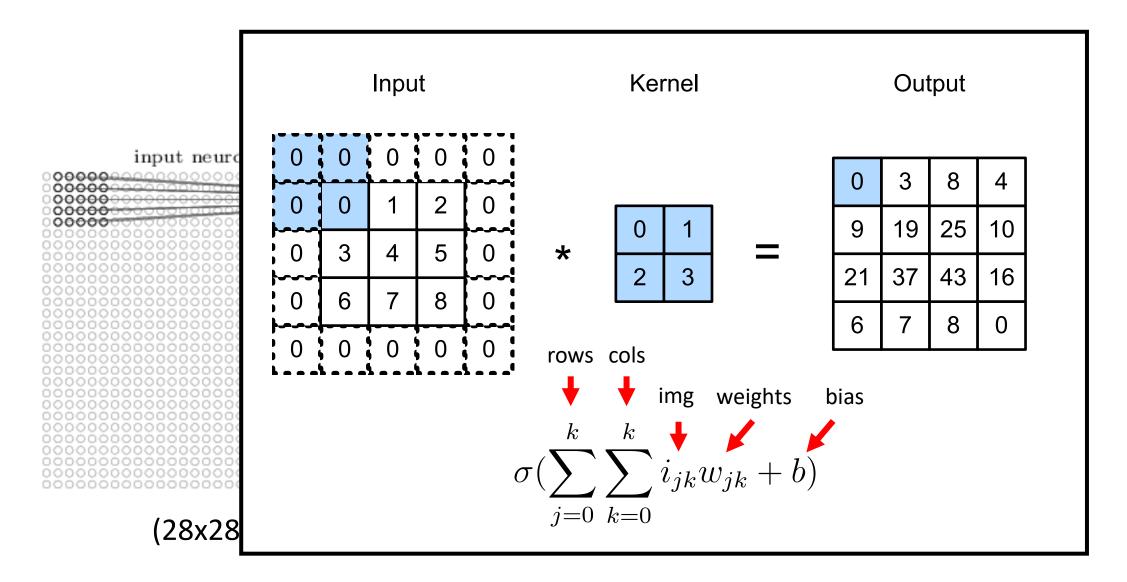


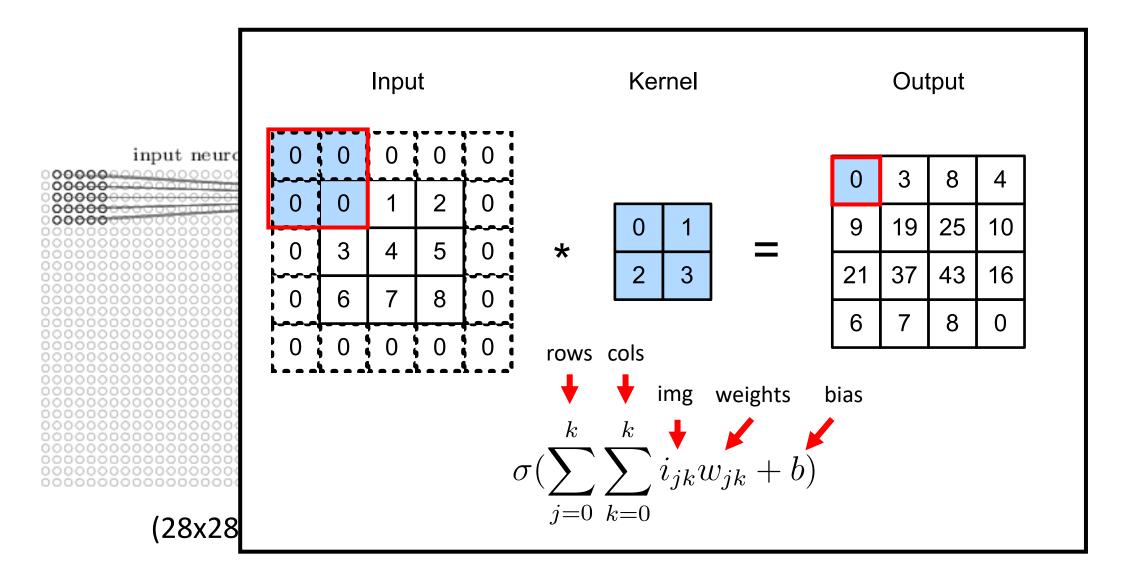
- have each hidden neuron process a small window of the input, called the "receptive field".
- 2. Slide the receptive field across the image.

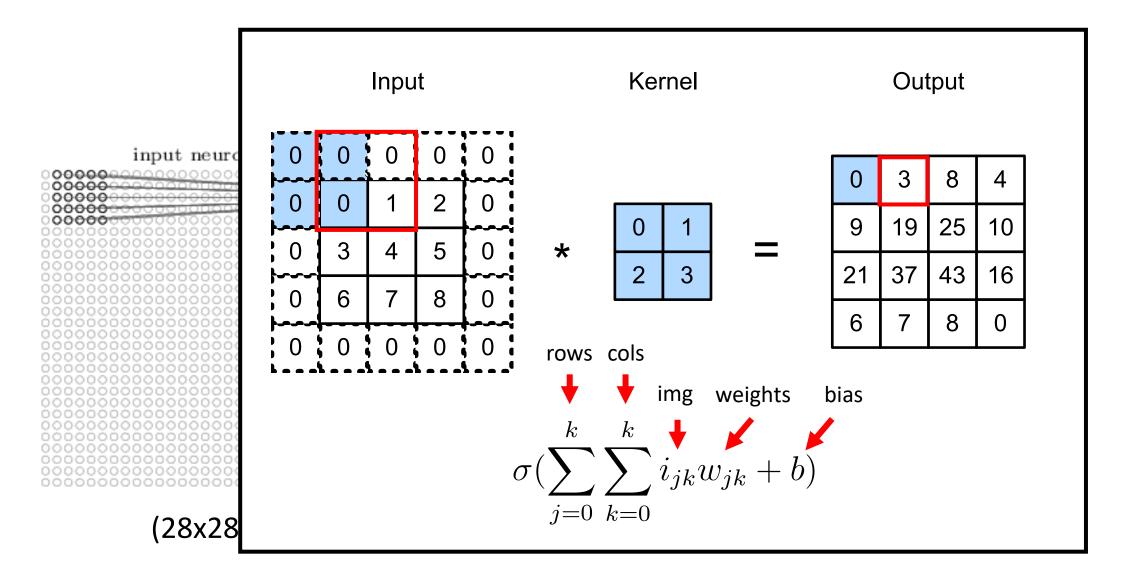


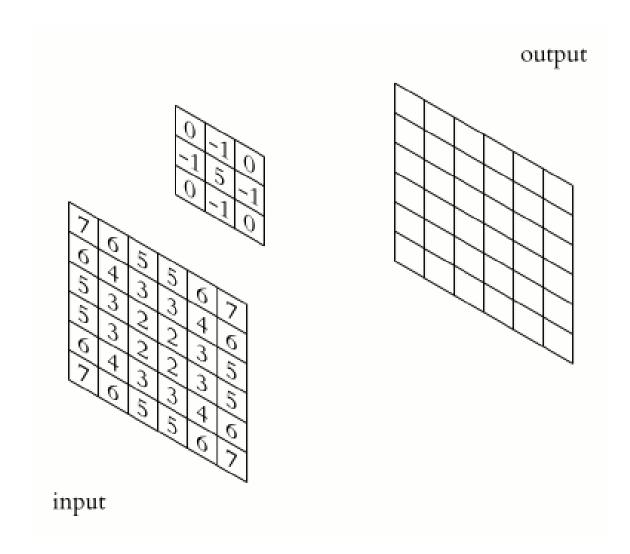
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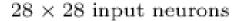
Kernel (or Filter): the weights applied inside the receptive field to obtain the next layer output.



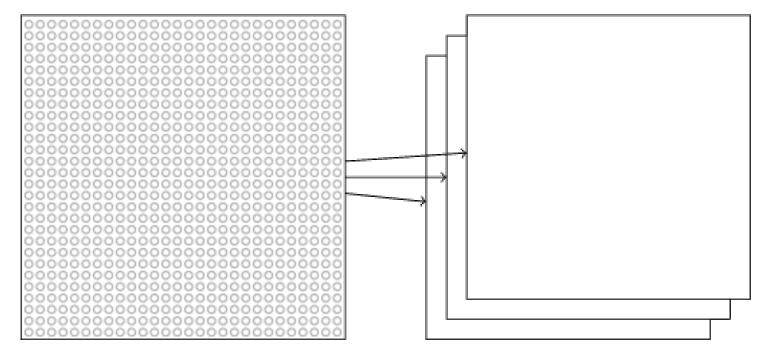




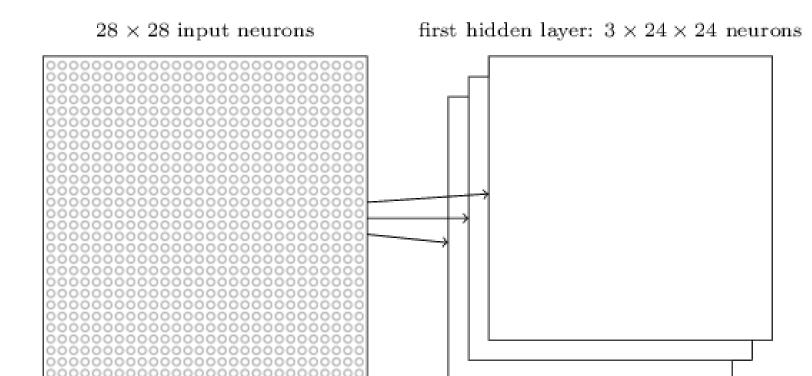


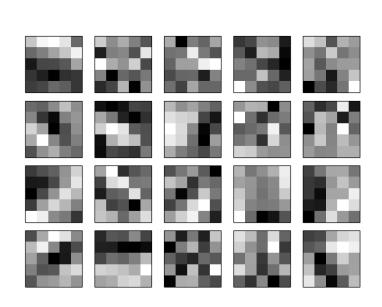


first hidden layer: $3 \times 24 \times 24$ neurons



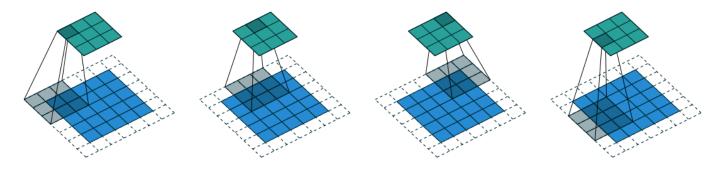
Applying 3 filters





Some Learned Filters

Applying 3 filters



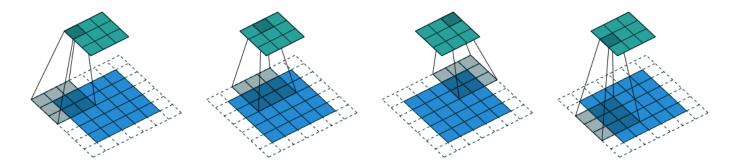
Stride: 2, Padding: 1, no Dilation

Stride: Apply the kernel using a step size.

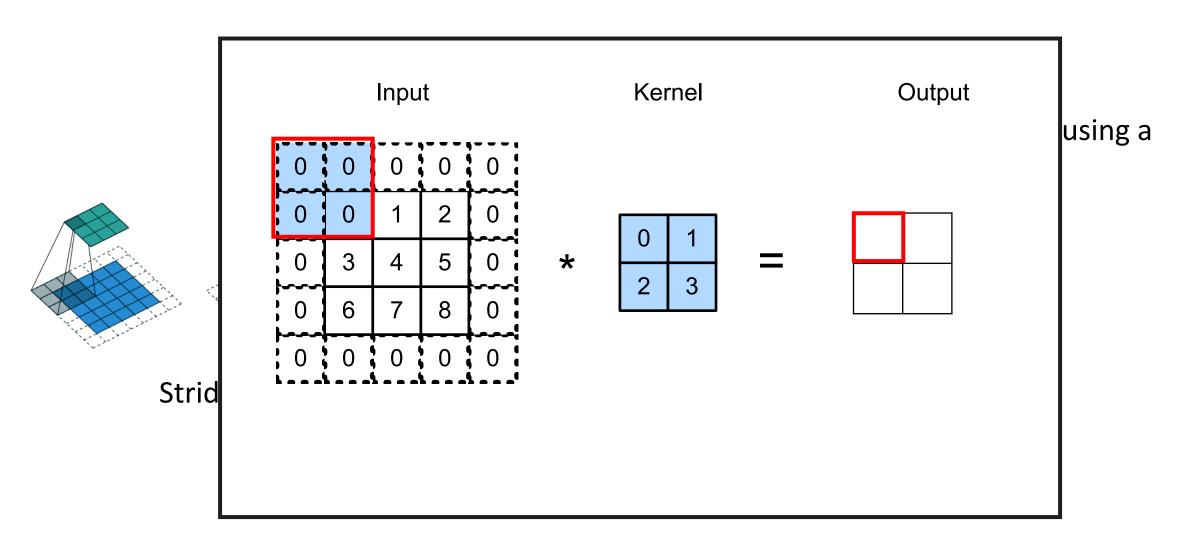
Padding: Surround the input with a pad value to prevent shrinking of the input.

Dilation: Dilate the kernel to artificially increase the receptive field.

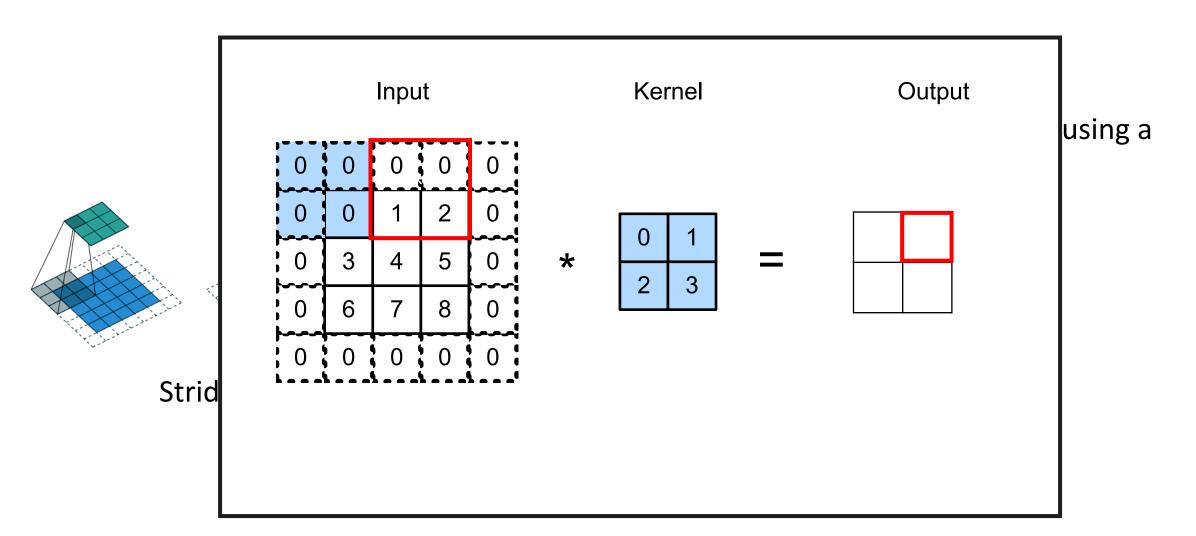
Stride: Apply the kernel using a step size.



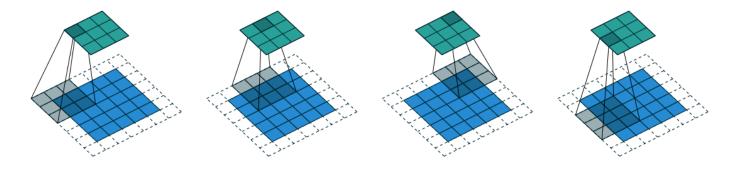
Stride: 2, Padding: 1, no Dilation



https://arxiv.org/pdf/1603.07285.pdf



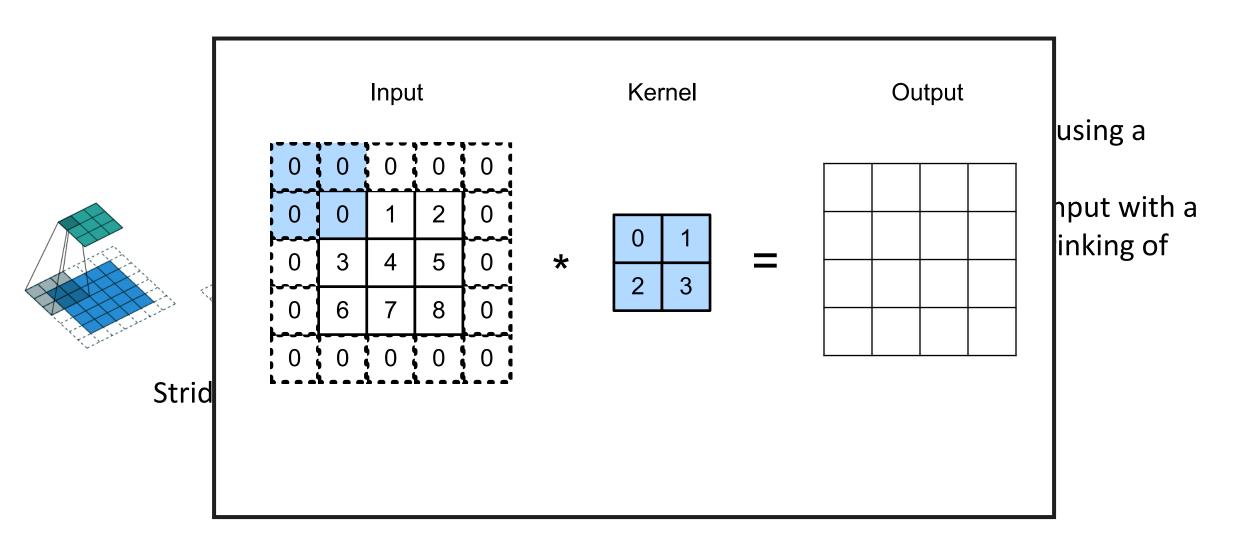
https://arxiv.org/pdf/1603.07285.pdf

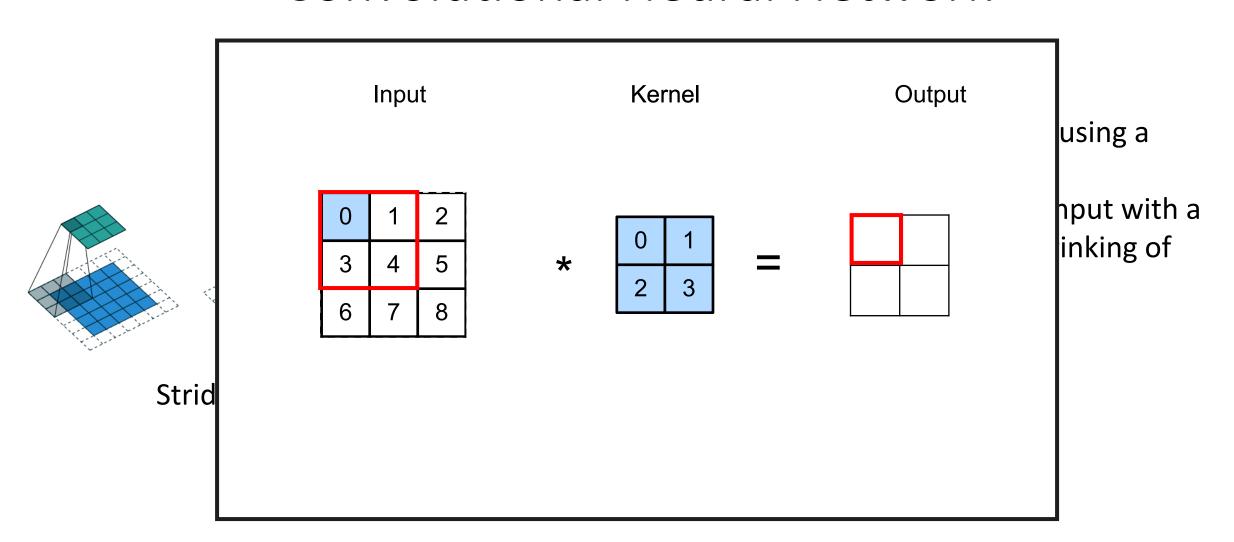


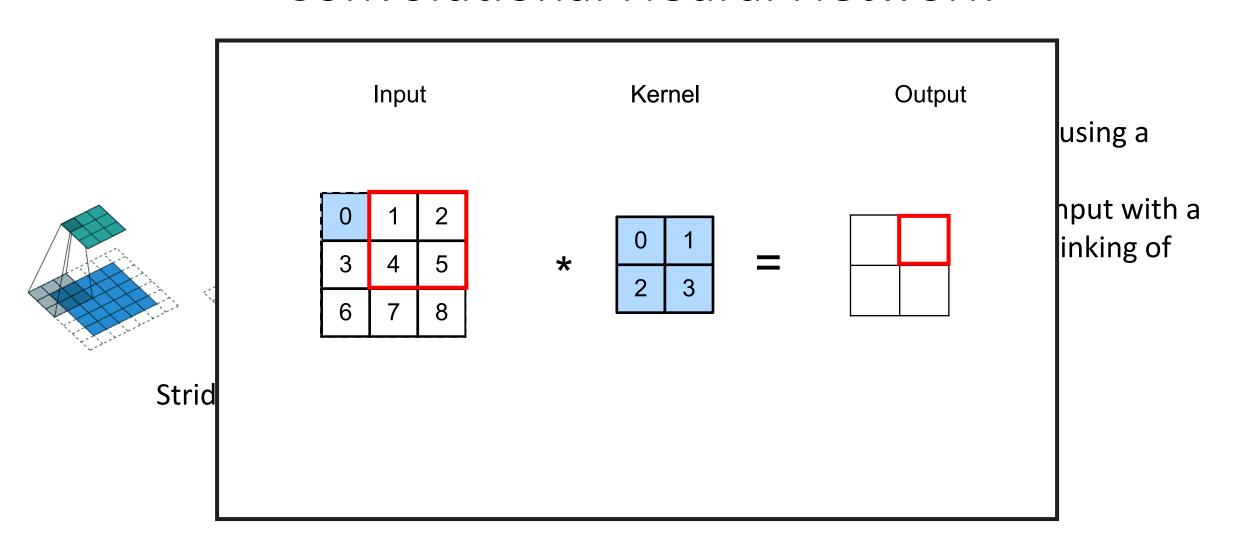
Stride: Apply the kernel using a step size.

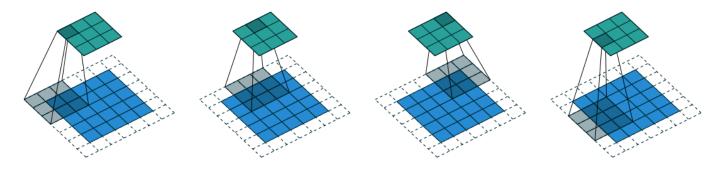
Padding: Surround the input with a pad value to prevent shrinking of the input.

Stride: 2, Padding: 1, no Dilation







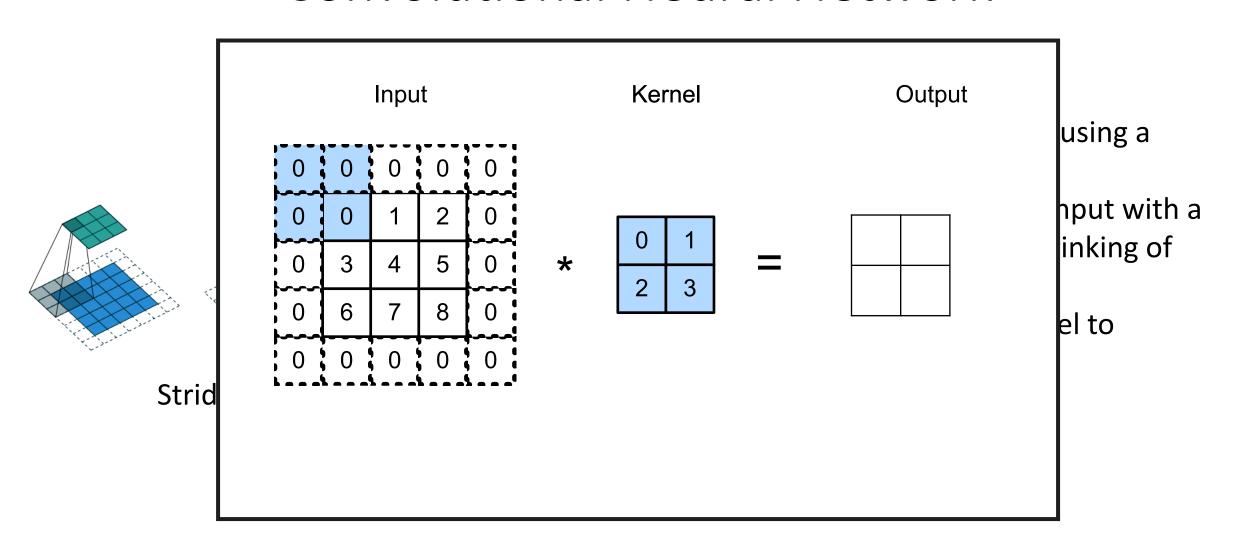


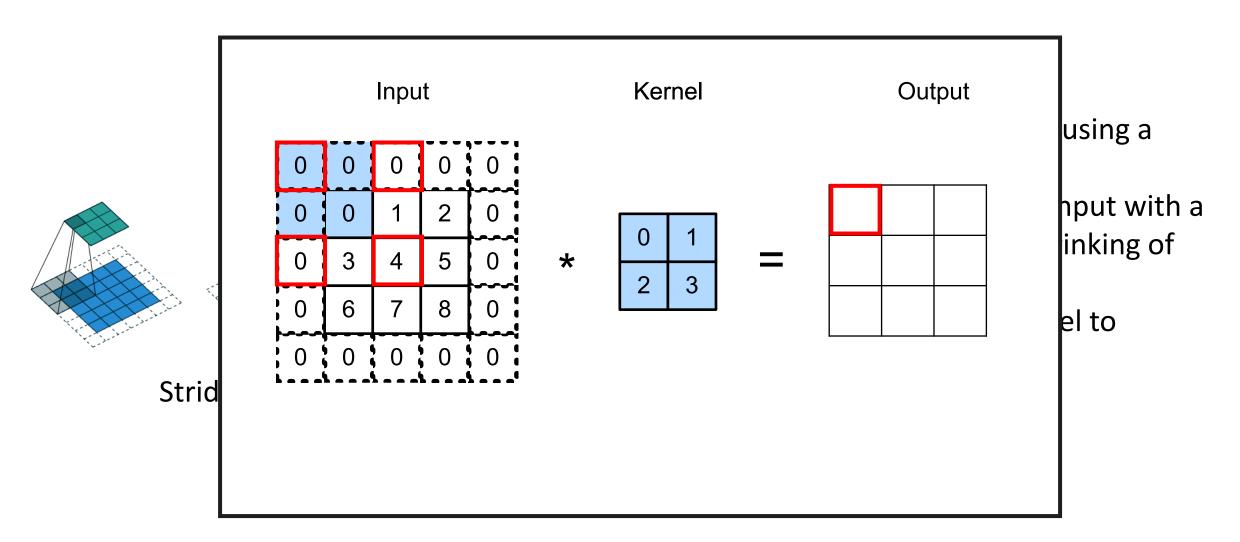
Stride: 2, Padding: 1, no Dilation

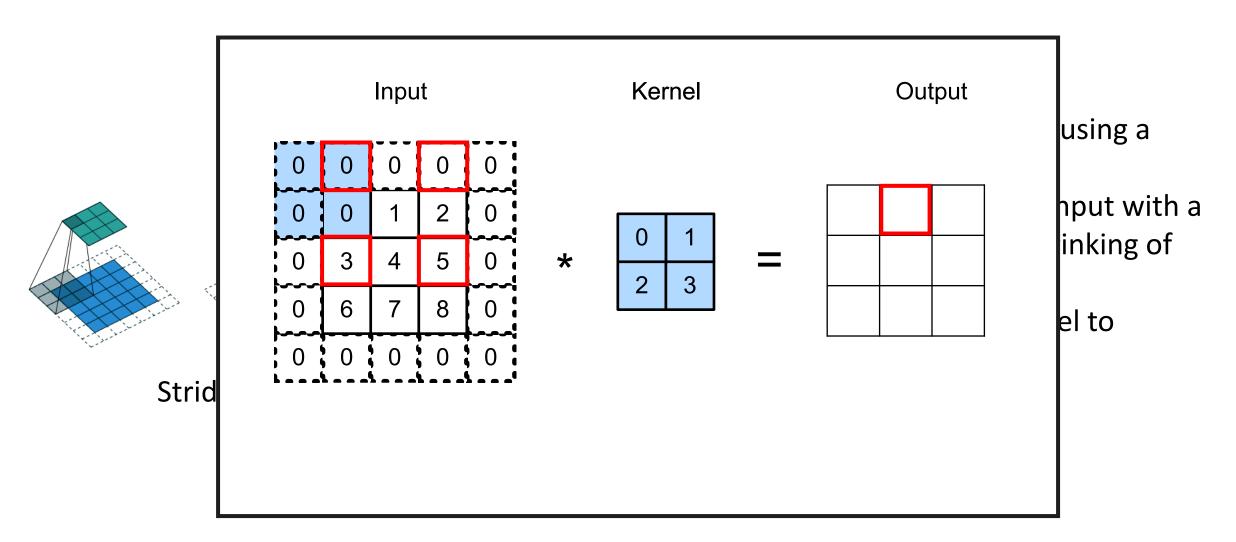
Stride: Apply the kernel using a step size.

Padding: Surround the input with a pad value to prevent shrinking of the input.

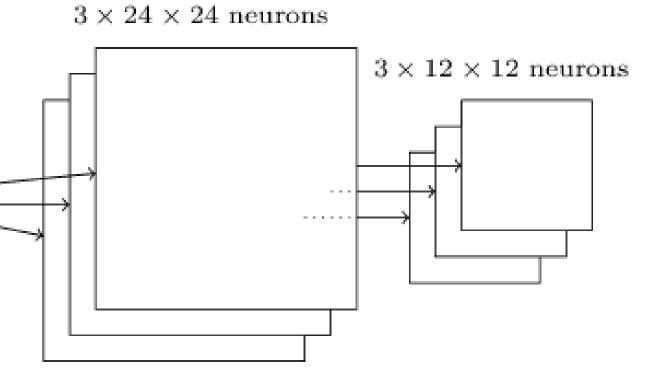
Dilation: Dilate the kernel to artificially increase the receptive field.







Pooling Operation

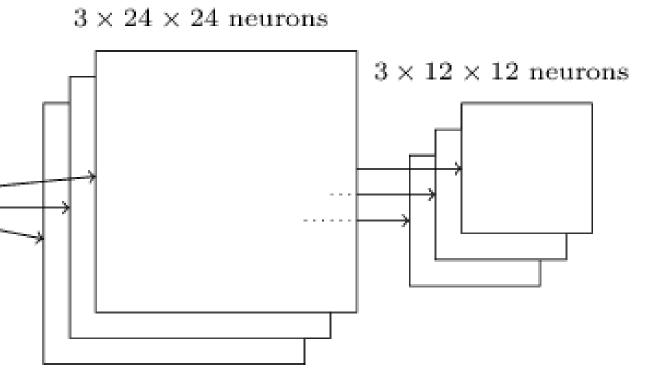


Applying 3 filters

Applying Max Pooling

Max Pooling: Select the most prominent feature in the receptive field.

Pooling Operation



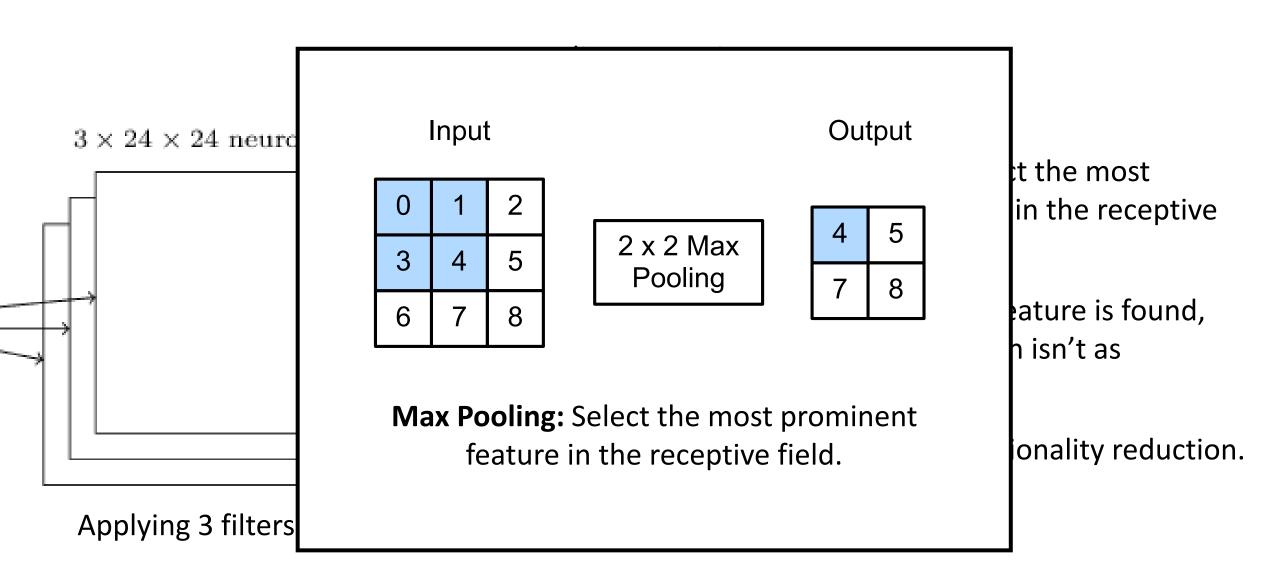
Applying 3 filters

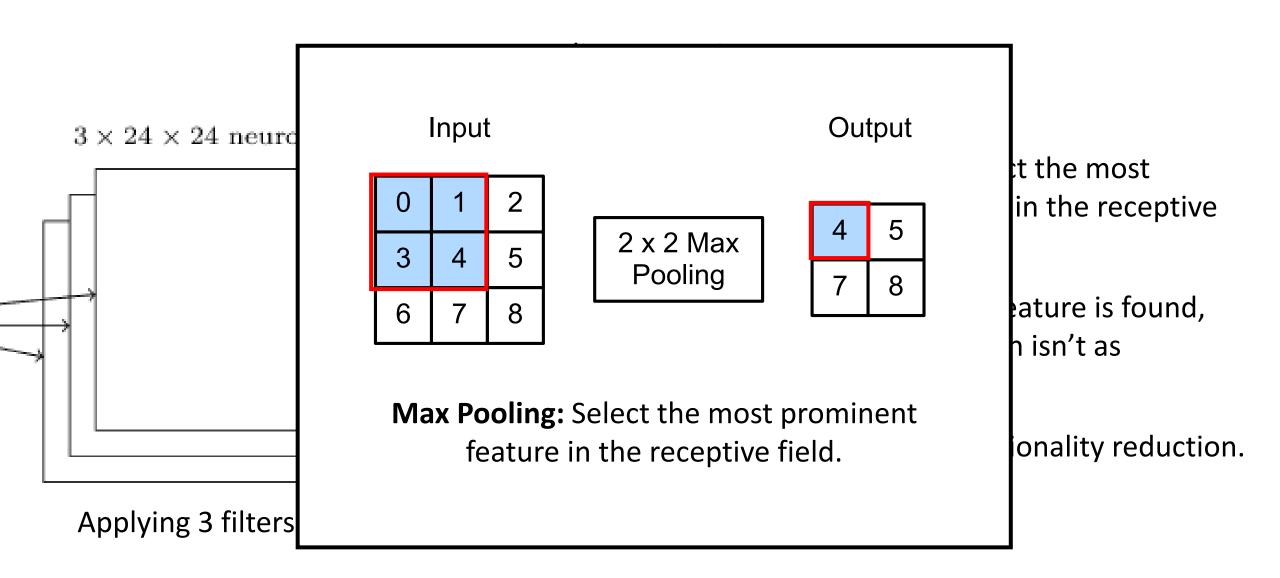
Applying Max Pooling

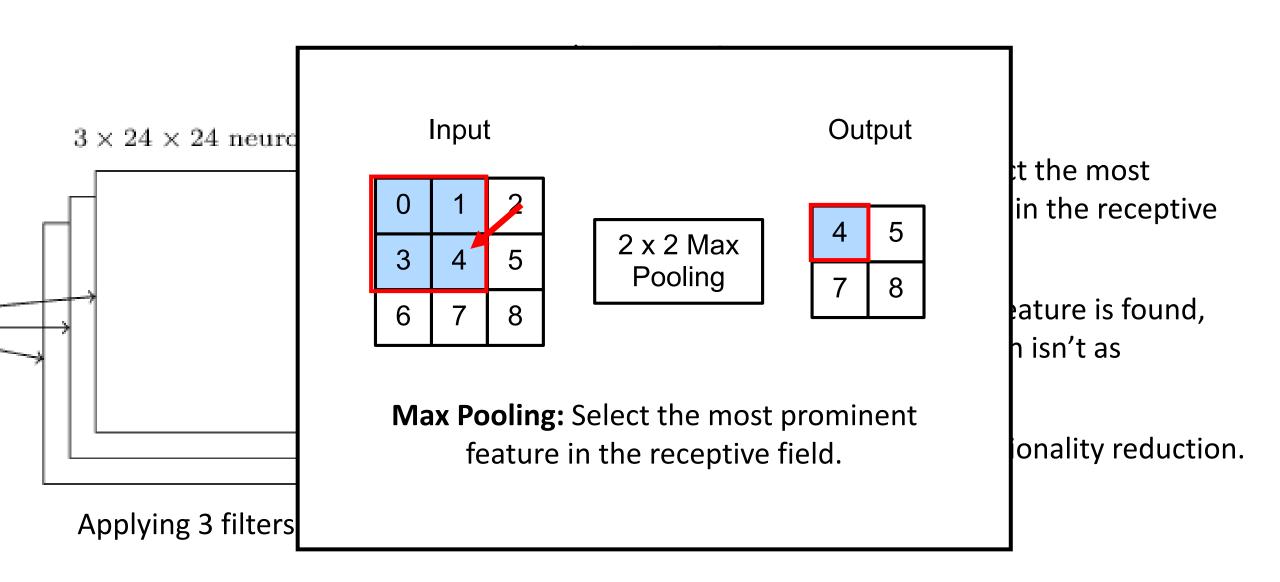
Max Pooling: Select the most prominent feature in the receptive field.

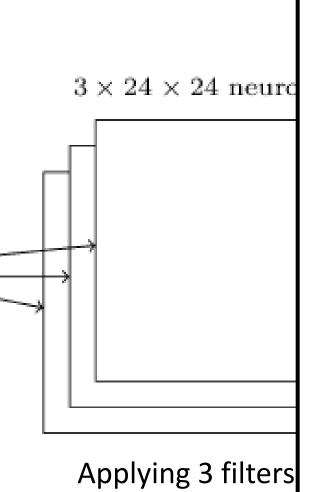
Intuition: Once a feature is found, the precise location isn't as important.

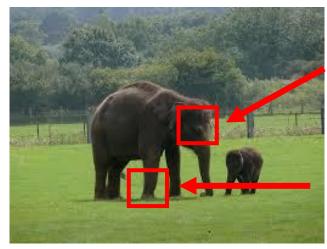
Helps with dimensionality reduction.











eye somewhere in here

leg somewhere in here

Max Pooling: Select the most prominent feature in the receptive field.

t the most in the receptive

ature is found, h isn't as

onality reduction.

Typically, we use a combination of layers for the task at hand.

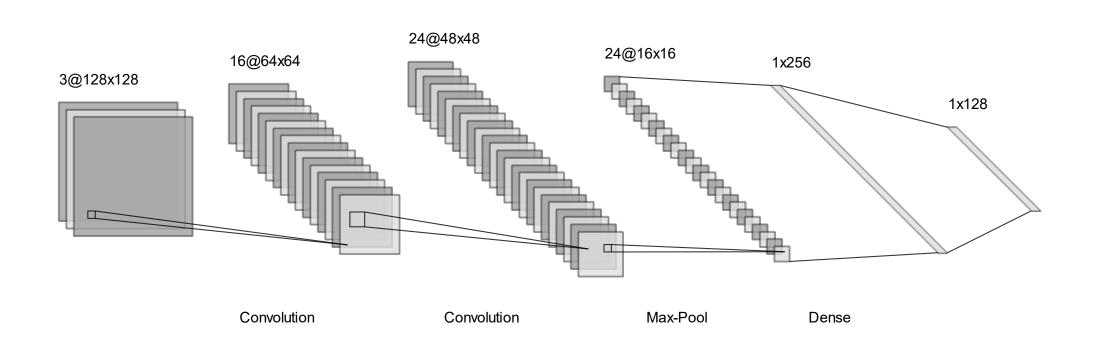


Image classification over 128 classes

Building Blocks: Normalization and Stability

Batch Normalization:

Tries to overcome "internal covariate shift."

Gradient updates assume the prior layer has a static distribution. Batch normalization normalizes the output of the prior layer so the distribution is standardized.

Dropout:

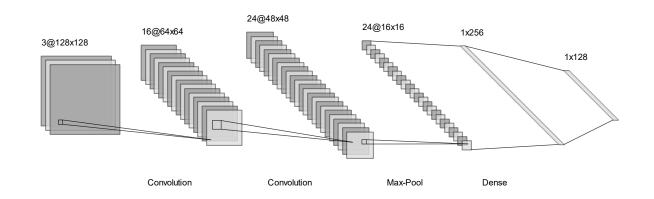
Tool to prevent overfitting.

Randomly removes nodes from a given layer, simulating training many architectures in parallel.

How do we get a network to learn?

How do we get a network to learn?

- 1. Estimate the error.
- Compute the change in weights most likely to reduce the error (gradient).
- 3. Update the weights according to the gradient.



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network input	0
ground truth label	\mathcal{I}
network	ر.

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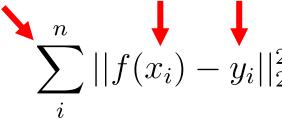
network input	x
ground truth label	y
network	f
network output	f(x)

How do we get a network to learn?

Gradient Descent.

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Sum over training data input label



L2 Loss Function

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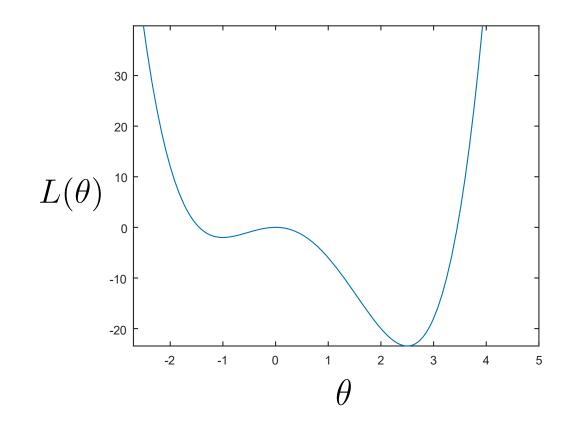
$$L(\theta) = \sum_{i=1}^{n} ||f_{\theta}(x_i) - y_i||_1$$

L2 Loss Function

Obtain θ that minimizes L

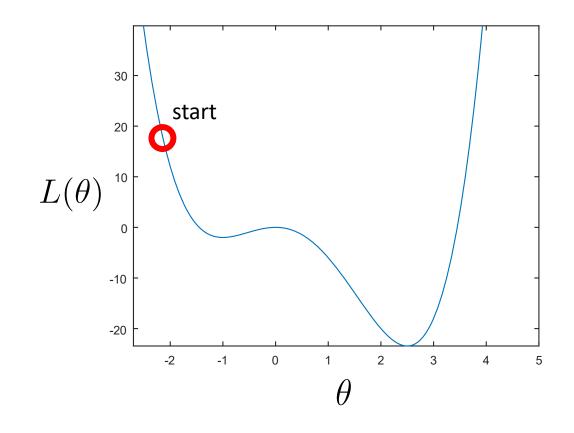
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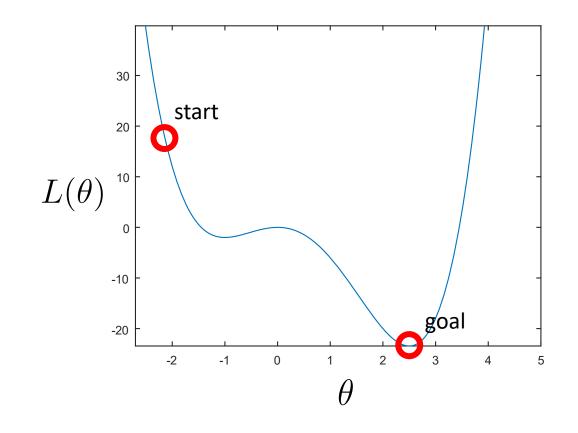
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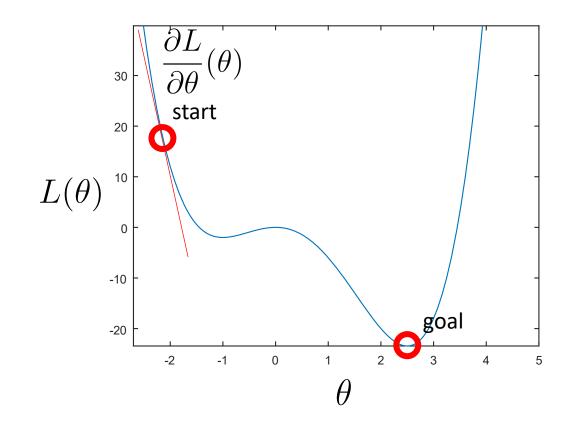
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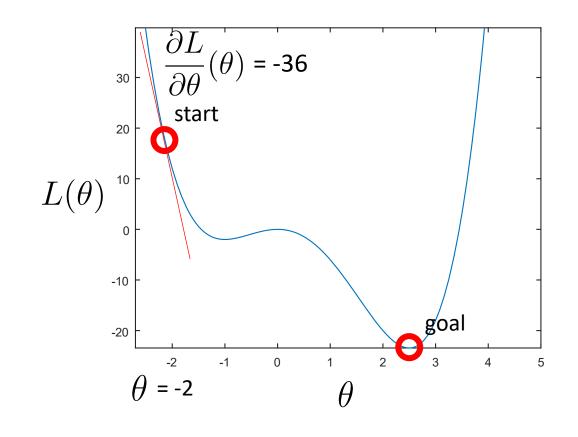
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How do we get a network to learn?

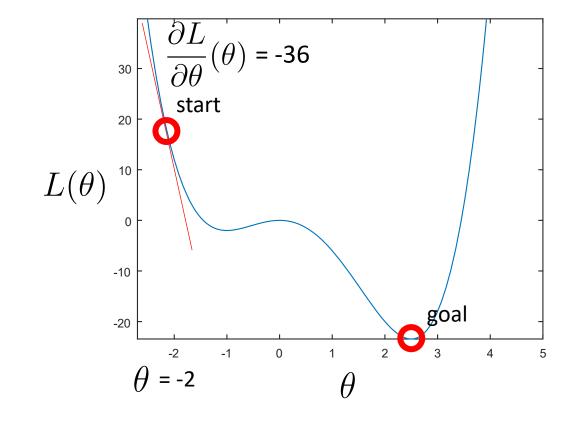
- 1. Estimate the error.
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How do we get a network to learn?

- 1. Estimate the error.
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- 3. Update the weights according to the gradient.

Learning Rate
$$\theta_{t+1} = \theta - \alpha \frac{\partial L}{\partial \theta}(\theta)$$
 Update Rule



How do we get a network to learn?

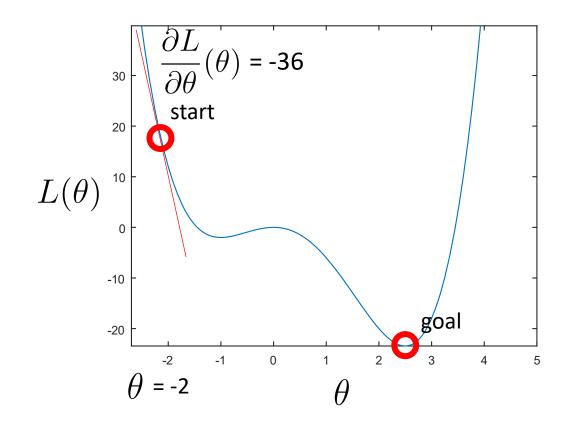
Gradient Descent.

- 1. Estimate the error.
- Compute the change in weights most likely to reduce the error (gradient).
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$$\theta_{t+1} = -2 - (0.01 * -36)$$

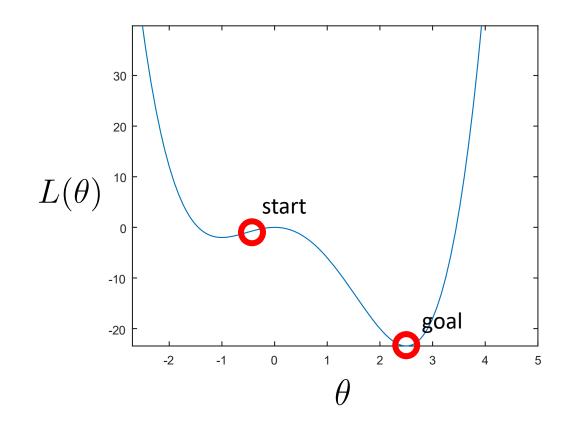
$$\theta_{t+1} = -1.64$$

Update Rule



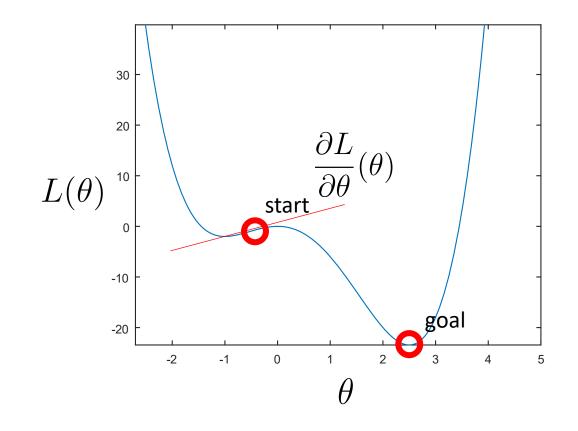
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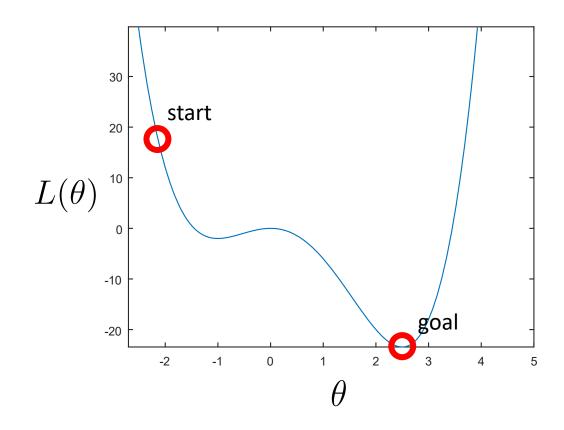
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How do we get a network to learn?

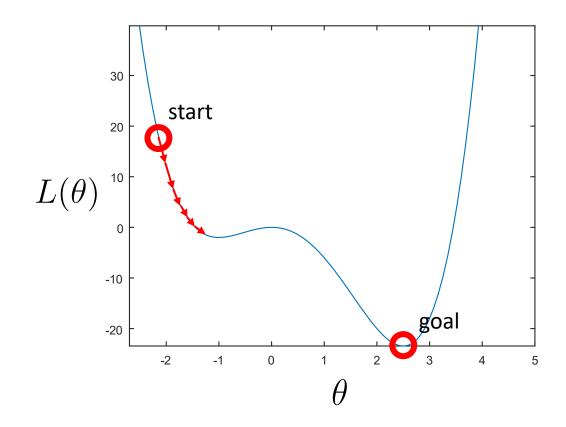
How do we choose Ir (alpha)?



Building Blocks: Optimizer

How do we choose Ir (alpha)?

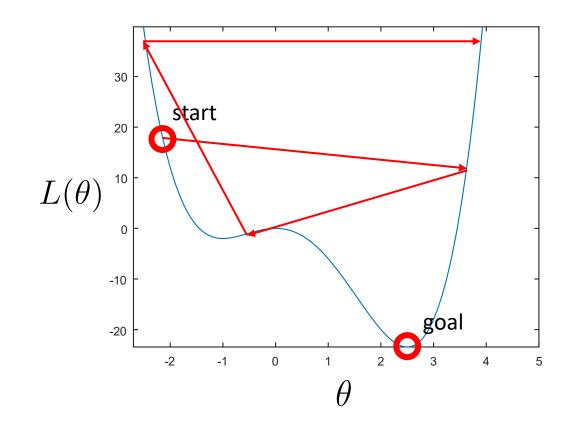
Small Ir will get caught in local minima.



Building Blocks: Optimizer

How do we choose Ir (alpha)?

- Small Ir will get caught in local minima.
- Large Ir will never converge.



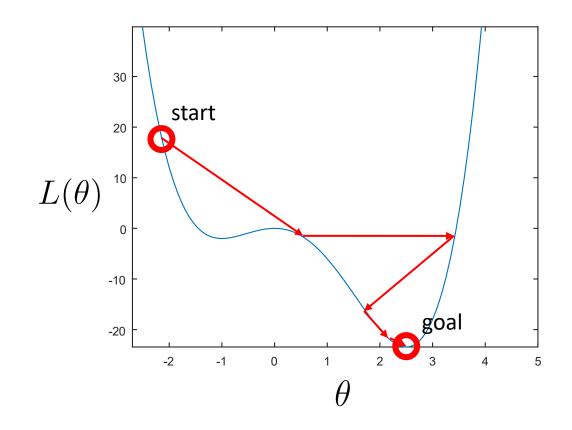
Building Blocks: Optimizer

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Adam Optimizer

- Separate Ir for each parameter.
- Update Ir based on momentum.
- Decay the Ir over time.



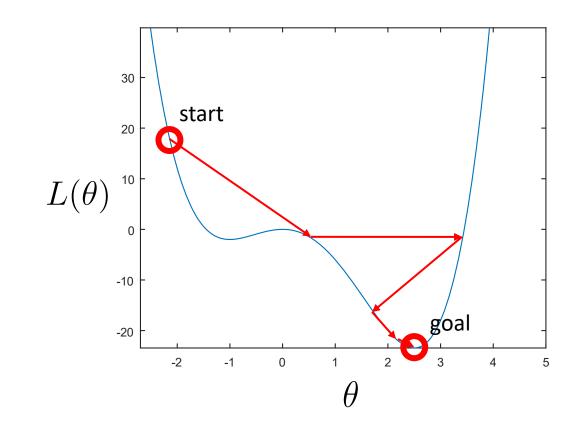
Building Blocks: Optimizer

How do we choose Ir (alpha)?

- Small Ir will get caught in local minima.
- Large Ir will never converge.

Adam Optimizer

- Separate Ir for each parameter.
- Update Ir based on momentum.
- Decay the Ir over time.
- Sensitive to Ir initialization.
- Can be used with an overall decay as an upper bound.



Building Blocks: batch size

Gradient Descent.

- 1. Estimate the error.
- Compute the change in weights most likely to reduce the error (gradient).
- 3. Update the weights according to the gradient.

How many samples should we see before we update the weights?

Building Blocks: batch size

Gradient Descent:

 Use all samples to compute the gradient and then update parameters.

Stochastic Gradient Descent:

 Use one sample to compute the gradient and then update parameters.

Minibatch Stochastic Gradient Descent:

• Use a subset of samples to compute the gradient and then update parameters.



14,197,122 samples in imagenet

Building Blocks: batch size

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 Use one sample to compute the gradient and then update parameters.

Minibatch Stochastic Gradient Descent:

 Use a subset of samples to compute the gradient and then update parameters.



14,197,122 samples in imagenet

Summary of Building Blocks

Fully Connected Layer: Every node is connected to every prior node.

Convolutional Layer: Apply a kernel to a sliding receptive field.

Max Pooling Layer: Select the largest value within the receptive field.

Batch Normalization Layer: Improves training stability.

Softmax Layer: Rescale outputs for classification so that the outputs sum to 1.

Dropout Layer: Randomly removes nodes from a given layer.

ReLU Activation: Go-to standard activation function.

TanH Activation: Good activation for RNNs.

Sigmoid Activation: Output for binary classification. Good activation for RNNs. **Linear Activation:** Output for regression.

Learning Rate: Size of gradient step.

Gradient Descent: Standard Ir updates.

Adam Optimizer: Adaptive Ir updates.

Batch Size: Number of samples to

estimate the gradient

"The literature on machine learning often reverses the meaning of 'validation' and 'test' sets. This is the most blatant example of the terminological confusion that pervades artificial intelligence research." -MLM

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Train Set:

A set of examples used for learning, that is to fit the parameters of the classifier.

Validation Set:

A set of examples used to tune the parameters of a classifier.

Test Set:

A set of examples used only to assess the performance of a fully-specified classifier.

"The literature on machine learning often reverses the meaning of 'validation' and 'test' sets. This is the most blatant example of the terminological confusion that pervades artificial intelligence research." -MLM

DO NOT MIX THESE

Train Set:

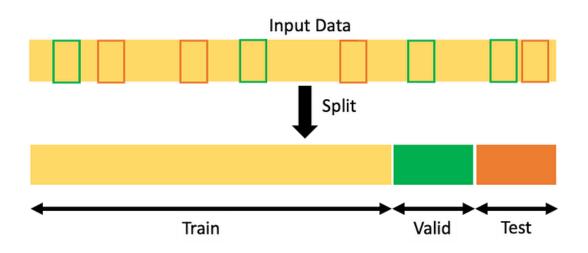
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Proper way to split your data.

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Diagnosing Neural Networks

Training Neural Networks is Hard:(

Incorrect Learning Rate:

Learning rate can have a strong impact on performance. Try adjusting the learning rate to aid convergence or adding a learning rate decay.

Forgot Data Normalization:

Networks typically perform better with normalized data.

Using large batch sizes:

Evidence suggests that overly large batch sizes inhibit learning.

Wrong Activation Function:

Some applications, e.g. Binary Classification, perform best with specific activation functions.

Network is too Deep:

Practically, deep networks are not always better. Start with a smaller network and grow it as needed.

https://arxiv.org/pdf/1206.5533.pdf

https://www.kaggle.com/general/196487

Diagnosing Neural Networks

Training Neural Networks is Hard:(

Incorrect Learning

Learning rate can performance. Try rate to aid converg learning rate deca Forgot Data Norm

Networks typically

normalized data.

Number One Cause of Network Failure:

Incorrect or improperly transformed input data.

Before training, be sure to inspect your input data, and visualize network inputs and outputs during training.

vith specific

e not always etwork and

Using large batch sizes:

Evidence suggests that overly large batch sizes inhibit learning.

https://arxiv.org/pdf/1206.5533.pdf

https://www.kaggle.com/general/196487

s://stats.stackexchange.com/questions/164876/what-is-the-trade-off-between-batch-size-and-number-of-iterations-to-train-a-neu

Tools

Operating Systems

Machine learning developers overwhelmingly use Linux.

The open source nature of Linux environments lends itself well to the complex installation and configuration processes required by many machine learning applications. Many machine learning algorithms are built on Linux already, fueling easy adoption.

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WSL (Windows Subsystem for Linux):

Lets developers run a GNU/Linux environment -- including most command-line tools, utilities, and applications -- directly on Windows

Development Environment

Environments (containerization)

Virtual environments allow multiple dependency configurations to be installed on a system at once.

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Why is this good?

- You can instruct people how to install your dependences.
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virtualenv:

Python package manager bundled with python. Sufficient for most projects.

anaconda:

System package manager with a gui. Useful for installing complex dependencies that extend beyond python.

docker:

Machine-level virtualization. Useful for installing and distributing projects with extremely complex dependencies.

virtualenv

- lambne@tarsserver2:~/dev/classes/cs473\$ python3 -m venv env
- lambne@tarsserver2:~/dev/classes/cs473\$ source env/bin/activate

virtualenv

```
lambne@tarsserver2:~/dev/classes/cs473$ python3 -m venv env
lambne@tarsserver2:~/dev/classes/cs473$ source env/bin/activate
(env) lambne@tarsserver2:~/dev/classes/cs473$ pip install pyjokes
Collecting pyjokes
    Downloading pyjokes-0.6.0-py2.py3-none-any.whl (26 kB)
Installing collected packages: pyjokes
Successfully installed pyjokes-0.6.0
(env) lambne@tarsserver2:~/dev/classes/cs473$ pyjoke
An SEO expert walks into a bar, bars, pub, public house, Irish pub, tavern, bartender, beer, liquor, wine, alcohol, spirits...
```

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(env) lambne@tarsserver2:~/dev/classes/cs473\$ deactivate

virtualenv

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(env) lambne@tarsserver2:~/dev/classes/cs473$ rm -rf env/
lambne@tarsserver2:~/dev/classes/cs473$
```

virtualenv

Every project should come with a requirements.txt file

```
requirements.txt ×
home > lambne > requirements.txt
      PyOpenGL==3.1.0
      pyparsing==3.0.9
 38 pyrender==0.1.45
 39 python-dateutil==2.8.2
 40 PyWavelets==1.3.0
 41 scikit-image==0.19.3
 42 scikit-learn==1.1.1
 43 scipv==1.8.1
 44 six==1.16.0
      threadpoolctl==3.1.0
 46 tifffile==2022.5.4
 47 torch==1.12.0
 48 tadm==4.64.0
     trimesh==3.12.8
     Twisted==22.4.0
 51 txaio==22.2.1
      typing extensions==4.3.0
 53 vedo==2022.2.3
 54 vtk==9.0.3
      wrapt==1.14.1
      wslink==1.6.6
      varl==1.7.2
```

virtualenv

Every project should come with a requirements.txt file

To create a requirements.txt file:

```
(env) lambne@tarsserver2:~/dev/classes/cs473$ pip list
 Package
               Version
              20.0.2
 pip
 pkg-resources 0.0.0
 pyjokes
               0.6.0
 setuptools
            44.0.0
               0.34.2
 wheel
(env) lambne@tarsserver2:~/dev/classes/cs473$ pip freeze > requirements.txt
(env) lambne@tarsserver2:~/dev/classes/cs473$ pip install -r requirements.txt
 Requirement already satisfied: pyjokes==0.6.0 in ./env/lib/python3.8/site-packages (from -r requirements.txt (line 1)) (0.6.0)
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(env) lambne@tarsserver2:~/dev/classes/cs473$
```

- 1) Data
- 2) Model
- 3) Training Loop

Using PyTorch

- 1) Data
- 2) Model
- 3) Training Loop

The dataset handles loading and transforming the input data.

Must implement the __len__ and __getitem__ methods.

Using PyTorch

```
from torch.utils.data import Dataset
import numpy as np
from PIL import Image
class CustomDataset(Dataset):
   def __init__(self, split, img_dir, transform=None, target_transform=None):
        self.split = split
        self.img_dir = img_dir
       self.data = []
       self.labels = []
        img dir = os.path.join(img dir, split)
        for f in os.listdir(img dir):
           img = Image.open(os.path.join(img_dir, f))
           label = f.split(".")[0]
           label = int(label)
           self.data.append(img)
           self.labels.append(label)
        print(f"Loaded {len(self.data)} images")
        self.transform = transform
        self.target transform = target transform
   def len (self):
        return len(self.labels)
   def __getitem__(self, idx):
        image = self.data[idx]
        label = self.labels[idx]
        if self.transform:
           image = self.transform(image)
       if self.target transform:
           label = self.target_transform(label)
        return image, label
```

- 1) Data
- 2) Model

Using PyTorch

3) Training Loop

Model defines the network you're going to use.

Must implement the forward method.

```
class Net(nn.Module):
   def __init__(self):
        super(Net, self). init ()
        self.conv1 = nn.Conv2d(1, 32, 3, 1)
        self.conv2 = nn.Conv2d(32, 64, 3, 1)
        self.fc1 = nn.Linear(9216, 10)
   def forward(self, x):
        x = self.conv1(x)
       x = F.relu(x)
       x = self.conv2(x)
        x = F.relu(x)
        x = F.max pool2d(x, 2)
        x = torch.flatten(x, 1)
        x = self.fc1(x)
        output = F.log softmax(x, dim=1)
        return output
```

- 1) Data
- 2) Model
- 3) Training Loop

Using PyTorch

The training loop does the following:

- Set model mode to train
- Iterate over the data and:
 - Reset the gradients
 - Pass the data through the network
 - Compute the loss
 - Perform backpropogation
 - Take a gradient step

```
def train(model, device, train_loader, optimizer):
    model.train()
    for batch_idx, (data, target) in enumerate(train_loader):
        data, target = data.to(device), target.to(device)
        optimizer.zero_grad()
        output = model(data)
        loss = F.nll_loss(output, target)
        loss.backward()
        optimizer.step()
```

Tools

VSCode:

Lightweight IDE replacement that is extremely popular for python programing with an extensive extensions library.

Screen:

Enables training "in the background".

Virtualenv:

Python environment containerization.

PyTorch:

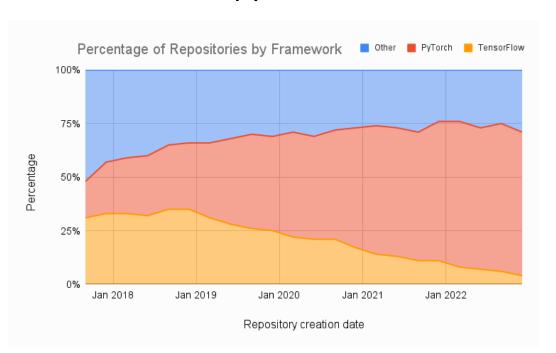
Machine learning framework based on the open-source torch library.

Remote Explorer (VSCode Extension):

Connect to remote servers through VSCode.

Pylance (VSCode Extension):

IntelliSense for python.



Resources

Machine learning mastery list of all tutorials:

https://machinelearningmastery.com/start-here/#statistical_methods

Stanford introduction to Deep Learning:

http://ufldl.stanford.edu/tutorial/

Neural Networks and Deep Learning:

http://neuralnetworksanddeeplearning.com/chap1.html

Deep Learning Specialization:

https://www.coursera.org/specializations/deep-learning

Convolutional Calculator:

https://madebyollin.github.io/convnet-calculator/

Figure Creation Resources

Neural Network Diagram Maker:

https://alexlenail.me/NN-SVG/index.html

Common Latex Formulas:

https://blmoistawinde.github.io/ml equations latex/#softmax

Latex Compiler:

https://latex.codecogs.com/eqneditor/editor.php