

# Niladri Das

---

POSITION	A Ph.D. candidate in Aerospace Engineering at Texas A&M University. Graduating in <b>August 1, 2020</b> <sup>1</sup>		
CONTACT	Intelligent Systems Research Laboratory, Dept. of Aerospace Engineering, Texas A&M, 575 Ross St, College Station, TX 77843	E-Mail : <a href="mailto:niladriDas@tamu.edu">NiladriDas@tamu.edu</a> Ph. No. : +1 979-985-7527 GitHub : <a href="https://github.com/NiladriDas">github.com/NiladriDas</a> Homepage : <a href="http://www.NiladriDas.com">www.NiladriDas.com</a>	
RESEARCH TOPICS	<ul style="list-style-type: none"><li>• <b>Non-Linear estimation</b></li><li>• <b>Situational awareness</b></li><li>• <b>Optimal sensing and data sharing</b></li><li>• <b>Non-linear control, robotics, and machine learning</b></li></ul>		
EDUCATION	Doctor of Philosophy in <b>Aerospace Engineering</b> Texas A&M University, USA <b>Dissertation:</b> Optimal Sensing for Estimation of Nonlinear Dynamical Systems.	Adviser: <a href="#">Dr. R. Bhattacharya</a> 2015 - 2020 GPA: 3.826/4	
	Master of Technology in <b>Electrical Engineering</b> Indian Institute of Technology Kanpur, India <b>Dissertation:</b> Learning to Grasp & Programming by Demonstration Using a 7-DOF <a href="#">Barrett WAM</a> .	Adviser: <a href="#">Dr. L. Behera</a> 2012 - 2014 GPA : 7.91/10	
	Bachelor of Engineering in <b>Electrical Engineering</b> Jadavpur University, Kolkata, India <b>Project:</b> Image Processing Based Object Detection.	Adviser: Dr. A. Chatterjee 2008 - 2012 GPA : 7.84/10	
RESEARCH EXPERIENCES	<b>Graduate Research Assistantship during PhD</b> Dept. of Aerospace Engineering, Texas A&M. <ul style="list-style-type: none"><li>• Worked on an <a href="#">AFRL</a> project project, <i>Adaptive Markov Inference Game Optimization for Rapid Discovery of Evasive Satellite Behaviors</i>, in collaboration with Intelligent Fusion Technology, Inc (2018-Present)</li><li>• Worked on an AFOSR project, <i>Cloud Computing Based Robust Space Situational Awareness</i>, in collaboration with Dept. of Statistics, TAMU (2015-2018)<ul style="list-style-type: none"><li>– Developed Optimal Transport filter based framework for SSA.</li><li>– Developed Orbit Propagator.</li></ul></li></ul>	Adviser: Dr. R. Bhattacharya Sep 2015-Present	
	<b>Project Associate</b> Dept. of Electrical Engineering, IIT Kanpur <ul style="list-style-type: none"><li>• Developed Gaussian Mixture based model to compensate the unknown non-linearities of 7 degree of freedom <a href="#">Barrett WAM</a>.</li><li>• Collaborated in implementing a inverse kinematic model and higher order Sliding Mode Control for 7 degree of freedom Barrett WAM. <a href="#">[C++ codes]</a><a href="#">[video]</a></li></ul>	PI: Dr. L. Behera Aug 2014 - Jun 2015	

---

<sup>1</sup>Last edited: February 28, 2020

- Developed dynamical system based trajectory learning for Barrett WAM.
- Served as a Thesis mentor for a master's student.
- Taught ROS to two Master's student.

#### Graduate Research during M.Tech

Dept. of Electrical Engineering, IIT Kanpur

Adviser: Dr. L. Behera

July 2013-July 2014

- Developed Inverse Kinematic model for Barrett WAM.
- Implemented Kinect based Object segmentation for grasping using **Deep Learning**.
- Developed a hand-eye autonomous calibration technique for Barrett WAM.
- Implemented Symbolic Encoding based skill learning on Barrett WAM.[\[video1\]](#)[\[video2\]](#)
- Mentored two Under-Graduate interns.

#### PUBLICATIONS *Journals*

1. *Optimal Precision for Multi-Rate Sensor Fusion with Bounded Errors in a Kalman Filtering Framework* [preparing, 2020]
2. *Privacy-Utility Aware Kalman Filtering for LTI Systems* [preparing, 2020]
3. *Privacy and Utility Aware Data Sharing for Space Situational Awareness from Ensemble and Unscented Kalman Filtering Perspective*  
**IEEE Transactions on Aerospace and Electronic Systems** [Submitted, 2019][\[arXiv\]](#)
4. *Optimal Transport Based Tracking of Space Objects in Cylindrical Manifolds.*  
**Journal of Astronautical Sciences** (Springer) [accepted, 2019][\[preprint\]](#)
5. *Optimal Transport based Tracking of Space Objects using Range Data from a Single Ranging Station.*  
**Journal of Guidance, Control, and Dynamics** [accepted, 2019][\[preprint\]](#)

#### *Conferences*

1. *Privacy and Utility in Multi-object Tracking using Kalman Filter*  
**International Conference on Information Fusion 2020** [abstract submitted]
2. *Eigen Value Analysis in Lower Bounding Uncertainty of Kalman Filter Estimates*  
**IFAC World Congress 2020** [accepted]
3. *Optimal Transport Based Filtering with Nonlinear State Equality Constraints*  
**IFAC World Congress 2020** [accepted]
4. *Optimal Sensing Precision in Ensemble and Unscented Kalman Filtering*  
**IFAC World Congress 2020** [accepted]
5. *Combining Visible and Infrared Spectrum Imagery using Machine Learning for Small Unmanned Aerial System Detection*  
**SPIE Automatic Target Recognition 2020** [Accepted]
6. *Sparse Sensing Architecture For Kalman Filtering With Guaranteed Error Bound.*  
**IAA Conference on Space Situational Awareness 2017** .
7. *Control of a 4 DoF Barrett WAM Robot - Modeling, Control Synthesis and Experimental Validation.*  
**IEEE First International Conference on Control, Measurement and Instrumentation 2016**

8. *Learning Object Manipulation from Demonstration through Vision for the 7-DOF Barrett WAM.*  
**IEEE First International Conference on Control, Measurement and Instrumentation 2016**
9. *A probabilistic framework of learning movement primitives from unstructured demonstrations.*  
**IEEE 13th International Conference on Industrial Informatics 2015**
10. *Robot Learns from Human Teacher Through Modified Kinesthetic Teaching.*  
**International conference on Advances in Control and Optimization of Dynamic Systems 2014**

**TEACHING EXPERIENCES**      **Graduate Teaching Assistant at TAMU**      13 Jan - Present, 2020.  
Assisting [Prof. Kyle DeMars](#) for teaching *Advanced Control* textitfor Aerospace *Vehicles* to senior Aerospace undergrads.

**Graduate Teaching Fellow at TAMU**      26 Aug - 12 Dec, 2019.  
Taught *Advanced Control for Aerospace Vehicles* to senior Aerospace undergrads (72 students).  

- Linear Systems, PID control, Root Locus, Freq. Domain design
- Teaching Matlab to design linear controller

**Graduate Teaching Assistant at IIT Kanpur**      July 2012 - July 2014.

**TECHNICAL SKILLS**      *Programming Languages and Packages:* Matlab | Python| Julia | ROS | C++.

**CURRENT PROFESSIONAL AFFILIATIONS**

- American Institute of Aeronautics and Astronautics (Student Member)
- Institute of Electrical and Electronics Engineers (Student Member)
- Society for Industrial and Applied Mathematics (Student Member)
- American Astronautical Society (Student Member)

**PAST PROFESSIONAL AFFILIATIONS**

- Student Council **Member** of Aerospace Engineering Department at Texas A&M University. (Academic Year 2017)
- GPSC: Graduate and Professional Student Council **Delegate** of Aerospace Department. (Academic Year 2017)

**SERVICES**      *Journal Reviewer:* IEEE Systems Journal.  
*Conference Reviewer:* IFAC World Congress

**PROJECTS**

- National Science Foundation under Grant Award No. NSF 1762825 (2020) PI: Raktim Bhattacharya et.al.
- Graduate Teaching Fellowship for Fall 2019 from Department of Engineering at Texas A&M University.
- Adaptive Markov Inference Game Optimization (AMIGO) for Rapid Discovery of Evasive Satellite Behaviors (2018) PI: Raktim Bhattacharya, Intelligent Fusion Technology, Inc.

- Cloud Computing Based Robust Space Situational Awareness (2015-2018), PI: Raktim Bhattacharya, Co-PI: Bani Mallick, AFOSR

#### AWARDS

- Winner of A-Hack-of-the-Drones 28-30 Sep,2018.  
Member of the **A-Team** from Texas A&M that won the [A-Hack-of-the-Drones](#) competition (Sponsor: USArmy Futures Command and MD5) in Austin, Texas.
  - Developed vision based solution for C-SUAS.
  - Co-founded AIMS Technologies, LLC
- Awarded AERO Graduate Excellence Fellowship for Spring 2020.
- Awarded AERO Graduate Excellence Fellowship for Fall 2019.

#### HONORS

Student Council **Mentor** of Aerospace Engineering Department at Texas A&M University. (Academic Year 2018)

#### WORK

F1 Visa, Eligible to work in the US for 36 months with Optional Practical Training (OPT)

#### AUTHORIZATION

#### PRIMARY

#### REFeree

- Dr. Raktim Bhattacharya (Dissertation Advisor)  
Associate Professor, Departement of Aerospace Engineering  
Texas A&M University  
3141 TAMU  
College Station, TX 77843-3141  
Office: HRBB 727C  
Phone: +1 979.862.2914  
Email: raktim@tamu.edu
- Dr. Srinivas Rao Vadali (PhD Committee Member)  
Professor, Departement of Aerospace Engineering  
Texas A&M University  
3141 TAMU  
College Station, TX 77843-3141  
Office: HRBB 727B  
Phone: +1 979-845-3918  
Email: svadali@tamu.edu
- Dr. Suman Chakravorty (PhD Committee Member)  
Associate Professor, Departement of Aerospace Engineering  
Texas A&M University  
3141 TAMU  
College Station, TX 77843-3141  
Office: HRBB 741A  
Phone: +1 979-458-0064  
Email: schakrav@tamu.edu
- Dr. Laxmidhar Behera (Masters Advisor)  
Professor, Departement of Electrical Engineering  
Indian Institute of Technology Kanpur  
Phone: +91.0512.259.7198  
Email : lbehera@iitk.ac.in

- Dr. Amitava Chatterjee (Bachelors Advisor)  
Professor, Department of Electrical Engineering  
Jadavpur University  
Phone: +91 33 2414 6949 (O), +919433960972 (Mobile)  
Email: [achatterjee@ee.jdvu.ac.in](mailto:achatterjee@ee.jdvu.ac.in); [cha\\_ami@yahoo.co.in](mailto:cha_ami@yahoo.co.in)
- Dr. Swagata Munshi (Jadavpur University)  
Professor, Department of Electrical Engineering  
Jadavpur University, Kolkata, India  
Phone: +91 033 2414 6949 (O)  
Email: [smunshi@ee.jdvu.ac.in](mailto:smunshi@ee.jdvu.ac.in), [sugatamunshi@yahoo.com](mailto:sugatamunshi@yahoo.com)