## HIGHER ORDER MDS CODES

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ABSTRACT. We study the combinatorics of the Wasserstein-1 metric for various distances.

## 1. Introduction

The probability simplex

$$\Delta_{n-1} := \left\{ (p_1, \dots, p_n) \mid \sum_{i=1}^n p_i = 1 \text{ and } p_i \ge 0 \ \forall \ i = 1, \dots, n \right\}$$

consists of probability distributions of a discrete random variable with a state space of size n. We take this state space to be  $[n] := \{1, \ldots, n\}$ . A statistical model  $\mathcal{M}$  is a subset of  $\Delta_{n-1}$  which represents distributions to which a hypothesized unknown distribution  $\boldsymbol{\nu}$  belongs. Typically, after collecting data  $\boldsymbol{u} = (u_1, \cdots, u_n)$  where  $u_i$  is the number of times outcome i is observed, one forms the empirical distribution  $\bar{\boldsymbol{\mu}} = \frac{1}{N}\boldsymbol{u}$  where  $N = \sum_{i=1}^{n}u_i$  is the sample size. Note that  $\bar{\boldsymbol{\mu}} \in \Delta_{n-1}$ . To estimate the unknown distribution  $\boldsymbol{\nu}$ , a standard approach is to locate  $\boldsymbol{\nu} \in \mathcal{M}$ , that is a "closest" point to  $\bar{\boldsymbol{\mu}}$ . For instance,  $\boldsymbol{\nu}$  can be taken to be the maximum likelihood estimator [Sul18, Chapter 7] of  $\bar{\boldsymbol{\mu}}$ . In this case,  $\boldsymbol{\nu}$  is the point on  $\mathcal{M}$  that minimizes the Kullback-Leibler divergence from  $\bar{\boldsymbol{\mu}}$  to  $\mathcal{M}$ . However, Kullback-Leibler divergence is not a metric, and the maximum likelihood estimator does not minimize a true distance function from  $\bar{\boldsymbol{\mu}}$  to  $\mathcal{M}$ .

For the above density estimation problem, one can use a distance minimization approach if the state space [n] is also a metric space. A metric on [n] is a collection of nonnegative real numbers  $d_{ij}$  for  $i, j \in [n]$  such that  $d_{ii} = 0$  for all  $i \in [n]$ ,  $d_{ij} = d_{ji}$ , and the triangle inequality  $d_{ik} \leq d_{ij} + d_{jk}$  holds for all  $i, j, k \in [n]$ . Sometimes, the metric on [n] is written as an  $n \times n$  nonnegative symmetric matrix  $d = (d_{ij})_{i,j \in [n]}$ . Common examples include the discrete metric (all  $d_{ij} = 1$ ), the  $L_1$  metric  $(d_{ij} = |i - j|)$ , the  $L_0$  metric, and the Hamming distance metric.

For two probability distributions  $\boldsymbol{\mu}$  and  $\boldsymbol{\nu}$  in  $\Delta_{n-1}$ , the optimal value  $W_d(\boldsymbol{\mu}, \boldsymbol{\nu})$  of the following linear program is the Wasserstein distance between  $\boldsymbol{\mu}$  and  $\boldsymbol{\nu}$  based on the metric  $(d_{ij})$ :

(1) maximize 
$$\sum_{i=1}^{n} (\mu_i - \nu_i) x_i$$
 subject to  $|x_i - x_j| \le d_{ij}$  for all  $1 \le i < j \le n$ .

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This means we can define  $W_d(\boldsymbol{\mu}, \boldsymbol{\nu})$  for any pair of vectors  $\boldsymbol{\mu}, \boldsymbol{\nu}$  satisfying  $\mathbf{1}^\top \boldsymbol{\mu} = \mathbf{1}^\top \boldsymbol{\nu}$ . One should note that the constraint set of the variable  $\boldsymbol{x}$  in problem 1 is unbounded and that if  $\boldsymbol{\alpha} \in H_{n-1} := \{ \boldsymbol{x} \in \mathbb{R}^n \mid \mathbf{1}^\top \boldsymbol{x} = 0 \}$  and  $\boldsymbol{\lambda} \in \mathbb{R}$  then  $\boldsymbol{\alpha}^\top (\boldsymbol{x} + \lambda \mathbf{1}) = \boldsymbol{\alpha}^\top \boldsymbol{x}$ . So we can equivalently formulate it as

$$W_d(\boldsymbol{\mu}, \boldsymbol{\nu}) = \max \left\{ (\boldsymbol{\mu} - \boldsymbol{\nu})^\top \boldsymbol{x} \mid \boldsymbol{x} \in H_{n-1}, |x_i - x_j| \le d_{ij} \ \forall \ i, j \right\}$$

which has a bounded constraint set. The constraint set of this linear program is called the Lipshitz polytope

$$P_d = \{ \boldsymbol{x} \in H_{n-1} \mid |x_i - x_j| \le d_{ij} \ \forall \ 1 \le i < j \le n \}.$$

The Wasserstein distance  $W_d(\boldsymbol{\mu}, \mathcal{M})$  from  $\boldsymbol{\mu} \in \Delta_{n-1}$  to a set  $\boldsymbol{\mathcal{M}}$  is the infimum of  $W_d(\boldsymbol{\mu}, \boldsymbol{\nu})$  as  $\boldsymbol{\nu}$  ranges over  $\boldsymbol{\mathcal{M}}$ :

(2) 
$$W_d(\boldsymbol{\mu}, \mathcal{M}) := \min_{\boldsymbol{\nu} \in \mathcal{M}} W_d(\boldsymbol{\mu}, \boldsymbol{\nu}).$$

This has been successfully used to construct a version of Generative Adversarial Networks [ACB17] where  $W_d(\cdot, \mathcal{M})$  is used as the loss function. However, for large n, computing  $W_d(\boldsymbol{\mu}, \mathcal{M})$  exactly is not feasible with the current state of knowledge. If we take  $\mathcal{M} = \{\boldsymbol{\nu}\}$  we recover the original Wasserstein distance  $W_d(\boldsymbol{\mu}, \boldsymbol{\nu}) = \min\{\lambda \geq 0 \mid \boldsymbol{\nu} \in \boldsymbol{\mu} + \lambda B\}$ .

In this paper our starting point is [ÇJM+20; ÇJM+21] to study the combinatorics of the Wasserstein unit ball. Such combinatorics is governs the combinatorial complexity (contrast against algebraic complexity) of problem 2. We first recall this approach.

The Wasserstein distance  $W_d$  induced by the finite metric d on [n] defines a norm on  $H_{n-1}$  namely

$$\|\boldsymbol{\alpha}\|_d = \|\boldsymbol{\alpha}\|_d^W = \max\left\{\boldsymbol{\alpha}^\top \boldsymbol{\mu} \mid \boldsymbol{x} \in H_{n-1}, |x_i - x_j| \le d_{ij} \ \forall \ 1 \le i < j \le n\right\}.$$

The unit ball of this norm is the polytope

(3) 
$$B_d = \operatorname{conv} \left\{ \frac{1}{d_{ij}} (\boldsymbol{e}_i - \boldsymbol{e}_j) : 1 \le i < j \le n \right\},$$

where B lies in the hyperplane  $H_{n-1}$  and is the dual of the Lipshitz polytope  $P_d$ . It is well known that the k dimensional facets of  $P_d$  are in on-to-one correspondence with the k codimensional facets of  $B_d$ . In other words, the number of k dimensional facets of  $P_d$  is equal to the number of n-2-k dimensional facets of  $B_d$ .

## 2. Vertices of $B_d$ with d induced by a graph

Consider the discrete metric d on [n]. Formally this is given by  $d_{ij} = 1 \,\forall i \neq j$ . [CM14;  $\Color CJM+21$ ] prove that the number of k dimensional facets of  $B_d$  is  $\binom{n}{k+2}(2^{k+2}-2)$ . In particular, the number of vertices (k=0) is n(n-1). This is the maximum number of possible vertices a Wasserstein ball can have, for any metric d, by the description in Equation (3). Here is an alternate way to think about the metric d. Consider the complete graph  $K_n$  on n vertices, labelled with [n], so every vertex is connected to every other vertex

by an edge. Then  $d_{ij} = 1$  is the length of the shortest path to reach j from i on this graph. This graph has precisely  $\binom{n}{2}$  edges. Soon it will turn out that the number of vertices of  $B_d$  being double the number of edges is not a coincidence. Further, based on this example, we propose the following definition.

**Definition 2.1** (Wasserstein metric based on a graph). Let G = ([n], E, w) be a connected weighted undirected graph without self loops that has vertices [n], edges E and non-negative weights given by  $w : E^2 \to \mathbb{R}_{\geq 0}$ . If G is unweighted, we simply treat G as a weighted graph with weights of all edges as 1. Define  $d_{ij}$  to be the weighted length of the shortest path from vertex i to j. The Wasserstein metric  $W_G$  based on graph G is defined to be the Wasserstein metric  $W_d$  based on d.

Corresponding to the abovementioned Wasserstein metric  $W_G$ , its unit ball in  $H_{n-1}$  will be denoted by  $B_G$ .

Example 2.2. The metric induced by an unweighted line graph on n vertices is said to be the  $L_1$  metric on [n]. Let's look at n=3. So G is 1—2—3. The corresponding metric is given by  $d_{ij}=|i-j|$ . According to Equation (3),  $B_G$  is the convex hull of the points  $\mathbf{u}_{\pm}=\pm(1,-1,0), \mathbf{v}_{\pm}=\pm(0,1,-1), \mathbf{w}_{\pm}=\pm(0.5,0,-0.5)$ . But  $\mathbf{w}_{\pm}=\frac{1}{2}\mathbf{u}_{\pm}+\frac{1}{2}\mathbf{v}_{\pm}$  hence not vertices. The vertices of  $B_G$  turn out to be exactly  $\mathbf{u}_{\pm}, \mathbf{v}_{\pm}$ ; so total 4 in number. Again observe that the number of vertices of  $B_G$  is double the number of edges in G.

Next we will turn towards the key result in this section, namely the phenomenon we observed both for the discrete and  $L_1$  metric.

**Theorem 2.3.** Let G = ([n], E) be a connect unweighted undirected graph without self loops on n vertices. Then the unit ball  $B_G$  of the Wasserstein metric induced by G has precisely |E| vertices.

Before starting the proof right away, we present an observation that was key in the examples of discrete and  $L_1$  metrics. Our graph G is connected, unweighted and undirected. If shortest path from i to j is  $i = x_1 \to x_2 \to \cdots \to x_p = j$  then  $d_{ij} = p - 1$  and  $\frac{\mathbf{e}_j - \mathbf{e}_i}{d_{ij}} = \frac{\mathbf{e}_j - \mathbf{e}_i}{p - 1} = \frac{\mathbf{e}_j - \mathbf{e}_i}{p - 1}$ 

$$\frac{1}{p-1}\sum_{t=1}^{p-1}(\boldsymbol{e}_{t+1}-\boldsymbol{e}_t) = \frac{1}{p-1}\sum_{t=1}^{p-1}\frac{\boldsymbol{e}_{x_{t+1}}-\boldsymbol{e}_{x_t}}{d_{x_tx_{t+1}}}.$$
 In other words,  $\frac{\boldsymbol{e}_j-\boldsymbol{e}_i}{d_{ij}}$  is never a vertex of  $B_G$  because it is a convex combination of some other points in  $B_G$  corresponding to edges in  $G$ .

If we want to determine a d, for given n and number of vertices  $2\alpha$ , for which the constraint matrix M satisfies that its rank is  $2\alpha$ , we want to find a rank 2 matrix M with the rows being  $\frac{e_i-e_j}{d_{ij}}$ , such that its rank is  $2\alpha$ , then equivalently we want to search for a matrix  $X = M^{\top}M \succeq 0$  with rank  $2\alpha$ .

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