

nilay994.github.io @ nilay\_994@hotmail.com in linkedin.com/in/legorative • Delft, Netherlands Embedded systems at fuel cell tech

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### Professional Experience

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☑ zepp solutions	EMBEDDED SYSTEMS ENGINEER   CONTROL AND SOFTWARE TEAM
Feb2021-current	> Firmware for the Engine Control Units (ECU) of zepp solutions, a hydrogen fuel-cell company.
	> Filtering sensor data, implementing Kalman observers, controlling various automotive valves and pumps.
	> Detection of various failure modes, facilitating a dashboard visualizing key-metrics of the system.
	MISRA C CAN J1939 (IEC61508) ISO 26262 (unit & HiL tests) CI builds (Infineon AURIX) grafana
MAVLab Delft	CONTROL AND EMBEDDED TEAM, AEROSPACE FACULTY, TU DELFT
AlphaPilot	> Finished as world champions at AIRR amongst 432 research teams, with a prize of \$1M 🗹 (highlights).
Lockheed Martin	> AlphaPilot ☑ Al Robotic Racing (AIRR) is about autonomous racing against human pilots and was men-
Jan2019-Jan2021	tored by experts from Lockheed Martin, Drone Racing League and MIT's Aerospace lab.
	> Designed the race drone's state estimation, control and trajectory planning pipeline.
	> Firmware for PercEvite, Sense-and-Avoid air traffic control (European Single-Skies initiative).
_	Matlab/Python C/C++ ESP32 UAV HiL ROS threading computer-vision linux-preemptive RT
Espressif	FIRMWARE DEVELOPER   APPLICATIONS ENGINEERING
Systems,	> Added Linear Algebra (LAPACK) and FFT support, MIPS and FLOPS profiling for matrix inversion.
Shanghai	➤ Developed parts of the famous 🗹 esp-idf alongwith Amazon Web Services for embedded platforms.
Jul2016-Aug2017	> Audio Processing for Speech Analysis using Fixed point arithmetic on ESP-32's Tensilica Processor.
	> Motor control drivers: BLDC/brushed/servo and I2C/SPI/UART drivers for LCDs for HMI applications.
<b>5</b> 1	Embedded C FreeRTOS ESP32 ESP8266 esp-idf Matlab git
☑ FIRST	TEAM MENTOR FRC-6024   CONTROL SYSTEMS
Robotics, Sydney	> Layed out the control system and drive-train over the CAN bus of NI-Rio (credits to WPI-lib).
Jan2015-Mar2016	Mentored India's debut FRC team to finish in the top 10 of Australian regionals.
	NI-RoboRio (labview) C++/java
ABU Robocon,	TEAM CAPTAIN ABU-ROBOCON   SECRETARY, ROBOTICS AND AUTOMATION CHAPTER VJTI
Asia Pacific	> Competition for prototyping mechatronic systems addressing novel problem statements in robotics.
region	> Quarter-Finalist at Robocon 2016, Semi-Finalist at Robocon 2014: promoting VJTI to internationals.
Nov2013-Mar2016	> Represented India at the International ABU-RoboCon, winning the Panasonic Award for Innovation.
	Embedded C AtMega1280 motor driver designs harness management motor control

#### ACADEMICS AND CO-CURRICULARS

TU Delft,	MASTERS IN CONTROL AND EMBEDDED SYSTEMS
	> Satellite Orbit Determination: GPS, non linear least squares, orbit dynamics, tracking and prediction.
Aug 2017-Sep2019	> Implemented detumbling on the 🗹 Attitude Control subsystem of Delft's PocketCube satellite.
	> Networked & Distributed Control: convex optimization, sampling + synchronization algorithms.
	> Vehicle Dynamics: ABS, path planning algorithms, localization with Particle Filters.
Veermata Jijabai	BACHELOR OF TECHNOLOGY IN ELECTRONICS ENGINEERING
Technological	> Graded 'A+' on Bachelor thesis on 🗹 Swarm Robots in Closed Loop Visual Odometry system, using Li-Fi.
Institute (VJTI)	> Product ideas: 🗹 Hybrid HID ARM Cortex and wrist-watch multimeter at Texas Instruments Challenge.
Aug2012-May2016	
	> Undertook workshops on embedded robotics for 300+ students around Mumbai (ARM, AVR, ESP32).
	> MIT Media Labs DI: Open Sourced and prototyped a 🗹 wrist band for taking 360°panoramas.
	> numerical techniques, applied math, digital signal processing, op-amps and filters, VLSI design.

## PUBLICATIONS

Dec 2019	🛮 🗗 Research in drone racing was featured at 🗹 Business Insider 🗹 Nature 🗹 Wired 🗹 Bloomberg 🗹 BBC .
Sept 2019	Study during M.Sc., 🗹 Thesis on state estimation and optimal control for racing drones.
Sept 2017	Published in Advances in Intelligent Systems and Computing (Springer, Germany) on 🗹 LiFi Swarm Robots .
Dec 2015	Published 🗹 MOSFET based motor drivers with closed loop control at the 12th International IEEE Conference, Indicon.
Jun 2015	Hindustan Times, India: Tech students engineer fixes for health-care issues: reference: SRA, VJTI.
Aug 2014	NHK Japan, Hindustan Times, Times of India: City College VJTI representing India internationally, ref-RoboCon 2014.

# SKILLS

	Programming	Embedded C, C++, FreeRTOS, Keil, MATLAB, Python, Labview, OpenCV, ROS, multi-threading.
O,	Controls	LAPACK for uCs, HiL tests, Adaptive control laws, Kalman and RANSAC filtering, system identification.
4	Embedded	STM32, MSP432, ESP32, closed loop motor-control, NI-Rio, Multisim, KiCad, oscilloscope, soldering.
	Softwares	Git-scm, Eclipse, Photoshop, CorelDraw, Latex.
•	Languages	English (fluent), Hindi (fluent), Mandarin (limited proficiency).