



**Nilay SHETH**  
Embedded | Control Systems

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## PROFESSIONAL EXPERIENCE

<a href="#">zepp solutions</a> Delft, Netherlands Feb 2021 - current	<b>EMBEDDED AND CONTROL SOFTWARE ENGINEER</b> 2½ years at zepp solutions, an H <sub>2</sub> fuel cell systems company prominent in the automotive industry. <ul style="list-style-type: none"> <li>&gt; Safety critical drivers for 30 onboard sensors, control and diagnostics for 15 pumps/motors/valves.</li> <li>&gt; Adding state estimators, kalman observers, J1939-21 communication and J1939-73 diagnostics stack.</li> <li>&gt; Realizing software architectures for safety critical ISO26262 ECUs (engine control units).</li> <li>&gt; 4G telemetry pipeline for on field vehicles, data analysis tools, build tools for embedded firmware.</li> <li>&gt; Expanding zepp's fuel cell test bench system, system integration testing, factory acceptance testing.</li> <li>&gt; Onboarding zepp's firmware team to the V-model, build processes and software architectures.</li> </ul> MISRA C python Jenkins CI/CD J1939/CAN Infineon Aurix V-model static/dynamic/docs tools 4G telemetry
<a href="#">AlphaPilot</a> Lockheed Martin, USA Jan2021 - Jan2019	<b>ROBOTICS PERCEPTION AND CONTROL ENGINEER</b> 2 years at <a href="#">AlphaPilot/AI Robotic Racing</a> with TU Delft MAVLab, Lockheed Martin, MIT Aerospace. <ul style="list-style-type: none"> <li>&gt; Won the AI racing world championship against 432 research teams, with a prize of \$1M <a href="#">(highlights)</a>.</li> <li>&gt; Designed the race drone's state estimation/localization, control and trajectory planning pipeline.</li> <li>&gt; Firmware for <a href="#">PercEvite</a>, Sense-and-Avoid air traffic control (European Single-Skies initiative).</li> </ul> C++ computer-vision linux-preemptive RT ROS Matlab Python UAV HiL
<a href="#">Espressif Systems</a> , Shanghai, China Aug2017 - Jul2016	<b>FIRMWARE APPLICATIONS ENGINEER</b> A year at Espressif, prominent in the IoT space with inexpensive and feature packed WiFi chips. <ul style="list-style-type: none"> <li>&gt; Developed applications in <a href="#">esp-idf</a> and Amazon Web Services for embedded platforms.</li> <li>&gt; Speech analysis and audio processing with FFT and LAPACK in C on ESP32's tensilica Processor.</li> <li>&gt; Motor control drivers: BLDC/brushed/servo and I2C/SPI/UART drivers for LCDs for HMI applications.</li> </ul> C FreeRTOS ESP32 ESP8266 esp-idf Matlab git AWS
<a href="#">SRA, VJTI</a> Society of Robotics and Automation, Mumbai Mar2016 - Nov2013	<b>GENERAL SECRETARY AND TEAM CAPTAIN</b> Robocon poses an annual semi-autonomous robotics challenge for countries in the Asia Pacific region. <ul style="list-style-type: none"> <li>&gt; Finalists in 2014 &amp; 2016: taking our university international, winning the Panasonic Award for Innovation.</li> <li>&gt; Mentored India's debut FIRST Robotics FRC6026 team to finish in the top 10 of Australian regionals.</li> <li>&gt; Undertook workshops on embedded robotics for 300+ students around Mumbai (ARM, AVR, ESP32).</li> <li>&gt; Won GridWarrior with the fastest grid solving robot at TechFest 2014, IIT-Bombay.</li> </ul> C/C++ STM32 AtMega1280 motor driver harness management NI Rio

## ACADEMICS AND CO-CURRICULARS

TU Delft, Netherlands Sep2019 - Aug2017	<b>MASTERS IN CONTROL AND EMBEDDED SYSTEMS</b> <ul style="list-style-type: none"> <li>&gt; Satellite Orbit Determination: GPS, non linear least squares, orbit dynamics, tracking and prediction.</li> <li>&gt; Implemented detumbling on the <a href="#">Attitude Control subsystem</a> of Delft's PocketCube satellite.</li> <li>&gt; Networked &amp; Distributed Control: convex optimization, sampling + synchronization algorithms.</li> <li>&gt; Vehicle Dynamics: ABS, path planning algorithms, localization with Particle Filters.</li> </ul>
Veermata Jijabai Technological Institute (VJTI) May2016 - Aug2012	<b>BACHELOR OF TECHNOLOGY IN ELECTRONICS ENGINEERING</b> <ul style="list-style-type: none"> <li>&gt; Graded 'A+' on Bachelor thesis on <a href="#">Swarm Robots</a> in Closed Loop Visual Odometry system, using Li-Fi.</li> <li>&gt; Courses on numerical techniques, applied math, digital signal processing, op-amps and filters, wireless communication, electromagnetic wave theory, VLSI design, control systems.</li> <li>&gt; MIT Media Labs: <a href="#">wrist watch camera</a>, Texas Instruments Challenge: <a href="#">wrist watch multimeter</a></li> </ul>

## PUBLICATIONS

Dec 2019	<a href="#">Research</a> in drone racing featured at <a href="#">Business Insider</a> <a href="#">Nature</a> <a href="#">Wired</a> <a href="#">Bloomberg</a> <a href="#">BBC</a> .
Sep 2019	<a href="#">Thesis on state estimation and optimal control for racing drones.</a>
Sep 2017	Advances in Intelligent Systems and Computing (Springer, Germany) on <a href="#">LiFi Swarm Robots</a> .
Dec 2015	<a href="#">MOSFET based motor drivers</a> with closed loop control at the 12th International IEEE Conference, Indicon.
Jun 2015	Hindustan Times, India: Tech students engineer fixes for health-care issues: reference: SRA, VJTI.
Aug 2014	NHK Japan, Hindustan Times, Times of India: City College VJTI representing India internationally, ref-RoboCon 2014.

## SKILLS

Programming	Git, C/C++, SafeRTOS, FreeRTOS, PxCOS, MATLAB, Python, OpenCV, ROS, multi-threading.
Controls	PID, Kalman filters, state estimation, system identification, LAPACK, closed loop motor-control.
Embedded	Infineon Aurix, STM32, ESP32, NI-Rio, MQTT, PCB design, oscilloscope.
Languages	English (fluent), Hindi (fluent), Gujarati (fluent), Dutch (A2).