NILE CAMAI

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EDUCATION

University of Washington

Sep 2020 - Jun 2024

Bachelor of Science, Computer Science | GPA: 3.96

Seattle, WA

- Direct-to-major admission into the Paul G. Allen School of Computer Science and Engineering.
- CSE Coursework: Computer Programming I & II, Software Design and Implementation, Foundations of Computing I, Hardware/Software Interface

SKILLS

Java, JavaScript, Python, Android, Node.js, Swift, HTML, CSS, Bash/Shell, Git

EXPERIENCE

Paul G. Allen School of Computer Science and Engineering

Jan 2021 – Present

Seattle, WA

CSE 14x Undergraduate Teaching Assistant

• Assisting the instruction of CSE 143 (Computer Programming II). Responsibilities include teaching Java programming, leading weekly sections, grading, and helping students with lecture concepts at the Introductory Programming Lab.

Advanced Robotics at the University of Washington

Jan 2021 - Present

Controls Team Member

Seattle, WA

• Competing in the DJI RoboMaster University Championship. Working on C++ control systems as a software team member.

Skyline Spartabots Robotics Team

Jan 2017 - May 2020

President (2019 - 2020), Vice President (2018 - 2019), Build Lead (2017 - 2018), Member (2017)

Sammamish, WA

· Managed and mentored a team of over sixty active members competing in the FIRST Robotics Competition.

MIT Lincoln Laboratory

Jul 2018 - Aug 2018

Beaver Works Summer Institute Student

Cambridge, MA

- Worked on a team of five to research and develop a UAV-SAR (Unmanned Aerial Vehicle Synthetic-Aperture Radar) system.
- Responsible for assembling the hexacopter drone and for developing a data visualization desktop application.

PROJECTS

FaceMe Python, OpenCV, Google Cloud API

https://devpost.com/software/facecentric

- Developed on-screen visual cues for a desktop interface that improves the accessibility of video calls.
- Worked on a team of five and won the Best Use of Google Cloud API and Best First-Time Hack awards at DubHacks 2020.

TelloMapper Android Studio, Java, Go

https://github.com/nilecamai/TelloMapper

- Independently built a mobile Android application which allows a user to draw flight paths for a DJI Tello drone to perform.
- · Saved flight instructions for a wirelessly-connected drone could be executed from the Android device.

Synthetic Aperture Radar GUI Python

https://github.com/nilecamai/UAV-SAR/

• Programmed a graphical user interface that visualized synthetic-aperture radar scan data using back-projection scripts.

AWARDS

Best Use of Google Cloud API, Best First-Time Hack

Oct 2020

DubHacks

World Championship Winners

Apr 2018

FIRST Robotics Competition