```
#include <unistd.h>
#include <sys/types.h>
#include <sys/stat.h>
#include <time.h>
#include <stdlib.h>
#include <dirent.h>
#include <stdio.h>
#include <string.h>
#include <getopt.h>
#include <stdbool.h>
#include <ctype.h>
#include <sys/wait.h>
#include <signal.h>
#include <sys/mman.h>
#include <sys/time.h>
#define INTERVAL 2
int t=0;
void display_message()
  kill(0,SIGKILL);
  t=1;
}
```

```
void calling2()
{
  sleep(3);
}
void calling()
{
  signal(SIGALRM, display_message);
  int i;
  for(i=0;i<3;i++)
  {
    pid_t pID = fork();
    if (pID == 0)
                        // child
    {
      calling2();
      if(t==1)
      {
         printf("killing the process");
         kill(0,SIGKILL);
        exit(0);
      }
      exit(0);
    }
```

```
else if(pID>0)
    {
      if(t==1)
      {
         printf("killing the process");
         kill(0,SIGKILL);
         exit(0);
      }
      printf("\nhello from the father");
    }
  }
}
int main()
{
  signal(SIGALRM, display_message);
  alarm(2);
  calling();
  // wait until alarm callback before terminating main thread
  sleep(15);
}
```

Output

hello from the father

hello from the father