# Nilesh Kulkarni

Bob Betty Byester Building, 2260 Hayward St, Ann Arbor, USA nileshk@umich.edu https://nileshkulkarni.github.io/ +1-412-583-0992

**EDUCATION** 

University of Michigan, Ann Arbor, USA

Sept. 2019 - April 2024 (Expected)

Ph.D. in Computer Science, EECS

• Advisors: Prof. David Fouhey, Prof. Justin Johnson

Carnegie Mellon University, Pittsburgh, USA

Aug. 2017 - Aug. 2019

Masters in Robotics, Robotics Institute, School of Computer Science

• CGPA: 4.05/4.0

• Advisor: Prof. Abhinav Gupta

Indian Institute of Technology Bombay, Mumbai, India

Jul. 2011 - Jul. 2015

Bachelor of Technology (B.Tech), Computer Science and Engineering with Honours

- CGPA: 8.77/10
- Minor in Electrical Engineering
- Advisor: Prof. Suyash Awate, Prof. Ganesh Ramakrishnan

Interests

My research interests are to understand and learn the 3D structure and human-object (and robot) interactions in the visual world with minimal supervision from images, and raw data.

Professional Experience

Waymo Research, Mountain View, CA

Research Intern, Preception Research
Google Research, Mountain View, CA

Research Intern, Scene Understanding Team Samsung Research, Seoul, South Korea

Research Engineer, AI Lab

Jun. 2023 - Aug 2023

Xinchen Yan and Charles Qi

May. 2022 - Dec 2022 Prof. Leonidas Guibas

Sept. 2015 - Jun. 2017

Prof. Jihie Kim

Publications

NIFTY: Neural Object Interaction Fields for Guided Human Motion Synthesis

Nilesh Kulkarni, Davis Rempe, Kyle Genova, Abhijit Kundu, Justin Johnson, David F. Fouhey, Leonidas Guibas

Arxiv, 2023

Learning to Predict Scene-Level Implicit 3D from Posed RGBD Data

Nilesh Kulkarni, Linyi Jin, Justin Johnson, David F. Fouhey

CVPR, 2023

What's Behind the Couch? Directed Ray Distance Functions (DRDF) for 3D Scene Reconstruction

Nilesh Kulkarni, Justin Johnson, David F. Fouhey

ECCV, 2022

Collision Replay: What does bumping into things tell you about the scene geometry?

Alexander Raistrick, Nilesh Kulkarni, David F. Fouhev

BMVC, 2021 (Oral)

Implicit mesh reconstruction from unannotated image collections

Shubham Tulsiani, Nilesh Kulkarni, Abhinav Gupta

Preprint, 2021

Articulation-Aware Canonical Surface Mapping

Nilesh Kulkarni, Abhinav Gupta, David F. Fouhey, Shubham Tulsiani

CVPR, 2020

Canonical Surface Mapping via Geometric Cycle Consistency

Nilesh Kulkarni, Abhinav Gupta\*, Shubham Tulsiani\*

ICCV, 2019

3D-RelNet: Joint Object and Relational Network for 3D Prediction

Nilesh Kulkarni, Ishan Misra, Shubham Tulsiani, Abhinav Gupta

ICCV, 2019

On-Device Neural Language Model based Word Prediction

Seunghak Yu\*, Nilesh Kulkarni\*, Haejun Lee, Jihie Kim

27th International Conference on Computational Linguistics: System Demonstrations (COLING 2018)

Syllable-level Neural Language Model for Agglutinative Language

Seunghak Yu\*, Nilesh Kulkarni\*, Haejun Lee, Jihie Kim

Empirical Methods in Natural Language Processing, Workshop on Subword and Character Level Models, (EMNLP 2017)

Robust Kernel Principal Nested Spheres

Suyash Awate\*, Manik Dhar\*, Nilesh Kulkarni\*

23rd International Conference on Pattern Recognition (ICPR 2016)

Research and Development of Matsya 4.0, Autonomous Underwater Vehicle

Technical Report, International Robosub Competition, 2015

\* - Shared Authorship

- ACHIEVEMENTS Secured an All India Rank 77 in IITJEE-2011 (amongst 0.5 million students)
  - Certified as among the Top 1% in India, in the Indian National Chemistry Olympiad and Indian National Physics Olympiad, 2011
  - Awarded Institute Technical Color (7 among 9000), 2014
  - Awarded Institute Technical Special Mention (15 among 9000), 2013
  - Awarded the Tata Welfare Trust Scholarship for Graduate Studies, 2017

## Professional Reviewer

### SERVICE

- CVPR 2020, 2021, 2022, 2023
- ECCV/ICCV 2019, 2020, 2022
- NeurIPS 2020, 2021
- 3DV 2019, 2022
- AI4ALL 2021