

# Nilesh Kulkarni

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EDUCATION	<u>University of Michigan</u> , Ann Arbor, USA Ph.D. in Computer Science, EECS • Advisors: David Fouhey, Justin Johnson <u>Carnegie Mellon University</u> , Pittsburgh, USA Masters in Robotics, Robotics Institute, School of Computer Science • CGPA: 4.05/4.0 • Advisor: Abhinav Gupta <u>Indian Institute of Technology Bombay</u> , Mumbai, India Bachelor of Technology (B.Tech), Computer Science and Engineering with Honours • CGPA: 8.77/10 • Minor in Electrical Engineering • Advisor: Suyash Awate, Ganesh Ramakrishnan	Sept. 2019 -  Aug. 2017 - Aug. 2019  Jul. 2011 - Jul. 2015
INTERESTS	My research interests are to understand and learn the 3D structure in the visual world with minimal supervision from images, and raw data. Topics: <i>Computer Vision, Machine Learning</i>	

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PUBLICATIONS	<a href="#">Collision Replay: What does bumping into things tell you about the scene geometry?</a> Alexander Raistrick, <b>Nilesh Kulkarni</b> , David Fouhey BMVC, 2021 (Oral)  <a href="#">Implicit mesh reconstruction from unannotated image collections</a> Shubham Tulsiani, <b>Nilesh Kulkarni</b> , Abhinav Gupta Preprint, 2021  <a href="#">Articulation-Aware Canonical Surface Mapping</a> <b>Nilesh Kulkarni</b> , Abhinav Gupta, David Fouhey, Shubham Tulsiani CVPR, 2020  <a href="#">Canonical Surface Mapping via Geometric Cycle Consistency</a> <b>Nilesh Kulkarni</b> , Abhinav Gupta*, Shubham Tulsiani* ICCV, 2019  <a href="#">3D-RelNet: Joint Object and Relational Network for 3D Prediction</a> <b>Nilesh Kulkarni</b> , Ishan Misra, Shubham Tulsiani, Abhinav Gupta ICCV, 2019  <a href="#">On-Device Neural Language Model based Word Prediction</a> Seunghak Yu*, <b>Nilesh Kulkarni</b> *, Haejun Lee, Jihie Kim 27th International Conference on Computational Linguistics: System Demonstrations (COLING 2018)  <a href="#">Syllable-level Neural Language Model for Agglutinative Language</a> Seunghak Yu*, <b>Nilesh Kulkarni</b> *, Haejun Lee, Jihie Kim Empirical Methods in Natural Language Processing, Workshop on Subword and Character Level Models, (EMNLP 2017)  <a href="#">Robust Kernel Principal Nested Spheres</a> Suyash Awate*, Manik Dhar*, <b>Nilesh Kulkarni</b> * 23rd International Conference on Pattern Recognition (ICPR 2016)  <a href="#">Research and Development of Matsya 4.0, Autonomous Underwater Vehicle</a> Technical Report, International Robosub Competition, 2015  * – Shared Authorship
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ACHIEVEMENTS	<ul style="list-style-type: none"><li>• Secured an <b>All India Rank 77</b> in IITJEE-2011 (amongst 0.5 million students)</li><li>• Certified as among the <b>Top 1%</b> in India, in the Indian National Chemistry Olympiad and Indian National Physics Olympiad, 2011</li><li>• Awarded Institute Technical Color (<b>7</b> among 9000), 2014</li><li>• Awarded Institute Technical Special Mention (<b>15</b> among 9000), 2013</li><li>• Awarded the Tata Welfare Trust Scholarship for Graduate Studies, 2017</li></ul>
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PROFESSIONAL SERVICE	<u>Reviewer</u> 3DV 2019, CVPR 2020, ECCV 2020, NeurIPS 2020, CVPR 2021, NeurIPS 2021, ICLR 2021
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PROFESSIONAL EXPERIENCE	<u>Samsung Research, Seoul, South Korea</u> Sept. 2015 - Jun. 2017 <u>Research Engineer, AI Lab</u> Jihie Kim <u>Samsung Research, Seoul, South Korea</u> May 2014 - Jul. 2014 <u>Research Intern, AI Lab</u> Choonoh Lee <u>Technical University of Braunschweig, Braunschweig, Germany</u> May 2013 - Jul. 2013 <u>Research Intern, Algorithms Group</u> Sándor P. Fekete
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RESEARCH PROJECTS	<b>Articulation Canonical Surface Mapping</b> Jun. 2019 - Dec 2019 Research Assistant, University of Michigan Advisor: David Fouhey <ul style="list-style-type: none"><li>• Designing a method to recover shape and pose without keypoint supervision</li><li>• Uses the structure of template category shape to get the articulated versions of the template shape</li></ul> <b>Canonical Surface Mapping</b> Oct. 2018 - Mar 2019 Research Assistant, Robotics Institute Advisor: Abhinav Gupta <ul style="list-style-type: none"><li>• Designing a method to perform correspondence matching without keypoint or multi-view supervision</li><li>• Uses the structure of mean category shape to map pixels in the image to mean-shape in 3D</li></ul> <b>3DRelNet, Joint Object and Relationship Network for 3D</b> Mar. 2018 - Sept 2018 Research Assistant, Robotics Institute Advisor: Abhinav Gupta <ul style="list-style-type: none"><li>• Improved 3D Reconstruction given a single image of the scene on standard metrics by 6 mAP points on the SUNCG dataset and by 3 mAP points on the NYUv2 dataset</li><li>• Designed a method to incorporate inductive biases set in indoor-scenes.</li></ul> <b>Conversational Modelling, Customer Care Assistant</b> Dec. 2016 - Jun. 2017 Samsung Research, Seoul, South Korea <ul style="list-style-type: none"><li>• Designed a siamese network with multi-objective cost to improve classification for in-domain data along increasing robustness to out-of-domain data</li><li>• Researched on various deep learning conversational models to improve conversation contexts</li></ul> <b>Natural Language Modelling, Smart Input Panel</b> Mar. 2016 - Nov. 2017 Samsung Research, Seoul, South Korea <ul style="list-style-type: none"><li>• Designed language models for English and Korean using Recurrent Neural Nets (RNNs)</li><li>• Optimized the model for memory and inference time constraints on mobile devices</li><li>• Obtained better on-device keyboard predictions benchmarks than existing solutions and was rolled out to millions of users and deployed on all Samsung smart phones <a href="#">paper1</a> <a href="#">paper2</a></li></ul> <b>Distributed Linear Programming Boost (LPBoost)</b> Jul. 2014 - May 2015 Undergraduate Dissertation, IIT Bombay Advisor: Ganesh Ramakrishnan <ul style="list-style-type: none"><li>• Designed a distributed LP Boost (D-LPBoost) algorithm</li><li>• Implemented the algorithm using two paradigms: data and hypothesis space parallelism</li><li>• Formulated a master-slave solution with each slave working on a subset of hypotheses. <a href="#">report</a> <a href="#">code</a></li></ul> <b>Kernel Principal Nested Sphere (KPNS)</b> Jul. 2014 - May 2015 Undergraduate Research Project, IIT Bombay Advisor: Suyash Awate <ul style="list-style-type: none"><li>• Designed KPNS, a kernel space statistical procedure</li><li>• KPNS transforms data to independent un-correlated modes of variation called Principal Spheres</li><li>• Achieved better results on downstream tasks of model-compactness, dimensionality reduction, classification <a href="#">paper</a></li></ul> <b>Online Triangulation using a Swarm of simple Robots</b> May 2013 - Jun. 2013 Research Intern, Technical University of Braunschweig Advisor: Sándor P. Fekete <ul style="list-style-type: none"><li>• Improved algorithms for exploring unknown areas using a swarm of simple robots</li><li>• Minimized overall error in navigation and localization, allowing for complicated maneuvers</li></ul> <b>Matsya, a Autonomous Underwater Vehicle(AUV)</b> Jun. 2012 - Jul. 2015 IIT Bombay & Naval Research Board, India Advisor: Leena Vachhani
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- Developed an Autonomous Underwater Vehicle to compete at International Robosub
- Team Leader - 2014: Led a 40 member team across three sub-divisions: Electronics, Software & Mechanical
- Software Leader - 2013: Led a sub-division of 5 members, to ensure full-stack software development for the AUV
- Three time semi-finalist at Robosub - 2013, 2014, 2015

[paper website](#)

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TEACHING  
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MENTORING

- Teaching Assistant CS 210 Logic Design, IIT Bombay
  - Teaching Assistant Workshop on Parallel Programming conducted by NVIDIA at IIT Bombay
  - Technical Mentor mentored 4 teams on technical projects
  - Department Academic Mentor mentored 9 sophomores
  - Electronics Club Coordinator club catering to hobby electronics at IIT Bombay
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SALIENT  
COURSES

- **CMU**: Introduction to Machine Learning (10701), Visual Learning and Recognition (16824), Computer Vision (16720), Math Fundamentals for Robotics (16811)
- **IITB**: Topics in Machine Learning, Digital Image processing, Artificial Intelligence, Algorithms, Signal processing, Medical Image Processing