

When an Image Tells a Story: The Role of Visual and Semantic Information for Generating Paragraph Descriptions

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17th December 2020

Describing images with longer sequences¹



People are standing on the grass behind a concrete patch that looks like it was just set. There are two orange cones in front of the concrete and yellow tape surrounding it. There are three people in yellow vests and white hard hats. There are some people sitting on a bench next to them.

¹Krause, J., Johnson, J., Krishna, R., & Fei-Fei, L. (2017). A Hierarchical Approach for Generating Descriptive Image Paragraphs. In Computer Vision and Pattern Recognition (CVPR).

Properties of Image Paragraphs (IP)



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Two Sources of Important Information for IP

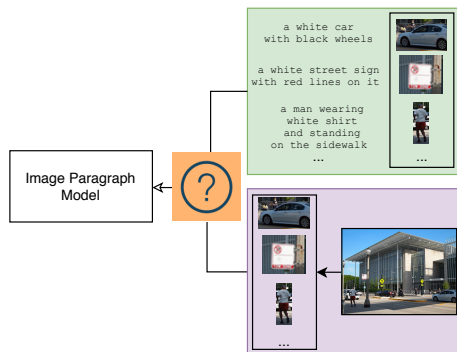


- ① visual features of perceived objects (*what* to refer to)
- ② background knowledge and communicative intent (*when* and *how* to refer)

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Our paper

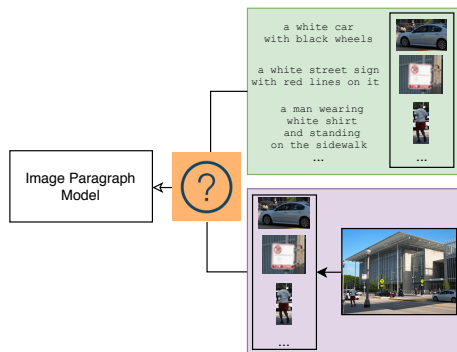
How to improve both *accuracy* and *diversity* of generated image paragraphs?



- **model input:**
unimodal (visual / textual)
vs. multimodal

Our paper

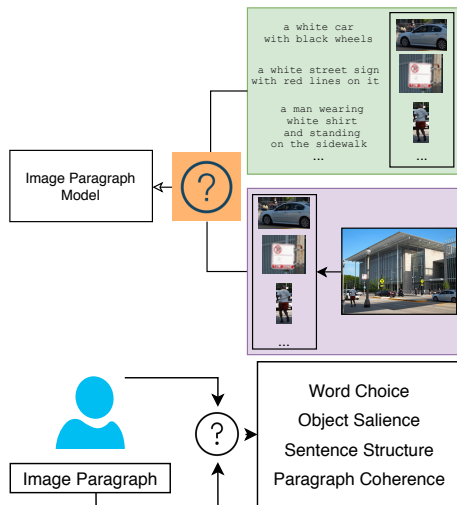
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max-pooling vs. attention

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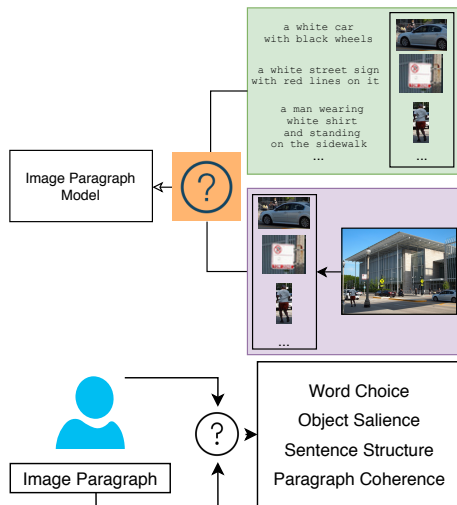
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automatic vs. human

Our paper

How to improve both *accuracy* and *diversity* of generated image paragraphs?

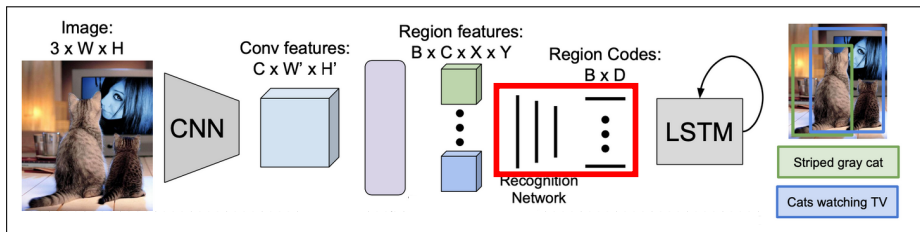


- **model input:**
unimodal (visual / language)
vs. multimodal
- **information fusion:**
max-pooling vs. attention
- **paragraph evaluation:**
automatic vs. human
- **human evaluation:**
accuracy and diversity of
generated paragraphs

Unimodal Features: Vision, Language

We use pre-trained **DenseCap**² model to extract both visual (V) and language (L) features for each image:

- 1 $V \in \mathbb{R}^{M \times D}$: the output of the recognition network (two fully connected layers, within the red box)



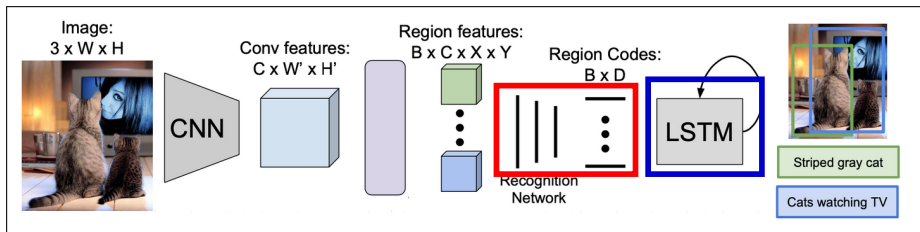
Notations: $M = 50$, $D = 4096$, $H = 512$.

²Johnson, J., Karpathy, A., & Fei-Fei, L. (2016). DenseCap: Fully Convolutional Localization Networks for Dense Captioning. In Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition.

Unimodal Features: Vision, Language

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- 1 $V \in \mathbb{R}^{M \times D}$: the output of the recognition network (two fully connected layers, within the red box)
- 2 $L \in \mathbb{R}^{M \times H}$: the sequence of *hidden states* used to generate the region descriptions (within the blue box)

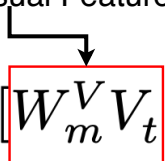


Notations: $M = 50$, $D = 4096$, $H = 512$.

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Multimodal Features: Vision **and** Language

Mapping Visual Features


$$mult_t = [W_m^V V_t \oplus W_m^L L_t \oplus W_h h_{t-1}^\delta]$$

Multimodal Features: Vision **and** Language

Mapping Visual Features

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Mapping Language Features

Multimodal Features: Vision **and** Language

Mapping Visual Features

Mapping Sentence LSTM
last hidden state

$$mult_t = [W_m^V V_t \oplus W_m^L L_t \oplus W_h h_{t-1}^\delta]$$

Mapping Language Features

The diagram illustrates the construction of a multimodal feature vector $mult_t$. It consists of three components combined via element-wise addition (\oplus):

- Visual Features:** $W_m^V V_t$ (highlighted with a red box). An arrow from "Mapping Visual Features" points to this term.
- Language Features:** $W_m^L L_t$ (highlighted with a blue box). An arrow from "Mapping Language Features" points to this term.
- Sentence LSTM State:** $W_h h_{t-1}^\delta$ (highlighted with a green box). An arrow from "Mapping Sentence LSTM last hidden state" points to this term.

Multimodal Features: Vision **and** Language

Mapping Visual Features

Mapping Sentence LSTM last hidden state

$$mult_t = [W_m^V V_t \oplus W_m^L L_t \oplus W_h h_{t-1}^\delta]$$

Mapping Language Features

The diagram illustrates the construction of the multimodal feature vector $mult_t$. It is composed of three concatenated components: $W_m^V V_t$ (visual features, highlighted with a red box), $W_m^L L_t$ (language features, highlighted with a blue box), and $W_h h_{t-1}^\delta$ (Sentence LSTM last hidden state, highlighted with a green box). Arrows indicate the mapping from their respective sources to these components.

Note: passing multimodal features through a linear layer $FC(mult_t)$ did not affect the automatic metric scores.

Information Fusion: Max-Pooling

For uni-modal experiments, we use max-pooling on either mapped visual features $x = W_m^V V_t$ or mapped language features $x = W_m^L L_t$:

$$x_s^\zeta = \max_{i=1}^M(x) \quad (1)$$

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For multimodal experiments, we concatenate max-pooled vectors of both modalities:

$$x_s^\zeta = [\max_{i=1}^M(W_m^L L_t) \oplus \max_{i=1}^M(W_m^V V_t)] \quad (2)$$

Information Fusion: Late Attention

We applied **additive****concat** attention on either unimodal or multimodal features (F_t):

$$\alpha_t^{mult} = softmax(W_a^A tanh(F_t \oplus W_h h_{t-1}^\delta)) \quad (3)$$

$$f_t = [\alpha_t^{mult} \odot F_t] \quad (4)$$

Information Fusion: Late Attention

We applied **additive****concat** attention on either unimodal or multimodal features (F_t):

$$\alpha_t^{mult} = softmax(W_a^A tanh(F_t \oplus W_h h_{t-1}^\delta)) \quad (5)$$

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Note: Although some work on multimodal machine translation has shown that early attention improves quality of text generations⁴, using **modality-dependent** / **early** attention (unique W_a^A and, therefore, unique α_t^{mult} for each modality) provided us with worse automatic metric scores.

⁴Ozan Caglayan, Pranava Madhyastha, Lucia Specia, & Loïc Barrault. (2019). Probing the Need for Visual Context in Multimodal Machine Translation.

Image Paragraph Model