

(1)

Dynamic Programming :-

- Typically apply to optimization problems
- A powerful technique to solve many diff. problems in poly time, for which a naive approach would take an exponential time.
- It is a general approach to solving problems
- ~~Similar to~~ In DP, the subproblems can overlap.
- Basic Idea :-
 * Break a problem in a reasonable number of subproblems s.t. the optimal sol^h to the $\{ \text{may be } n^2 \}$ smaller subproblems can be used to generate the op. sol^h for the whole problem.
- * We ask the same question to the subproblems over and over again, but instead of solving each subproblem, we solve it once and reuse the sol^h.

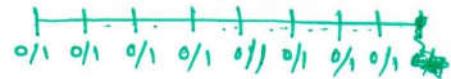
Rod Cutting :-

- Given a rod of length n inches and a table of prices p_i for $i=1, 2, \dots, n$, determine the maximum revenue (r_n) obtainable by cutting the rod & selling the pieces.
 - If the price p_n for a rod of length n is large enough, an optimal sol^h may not require cutting at all.
- Ex:- If $n=4$, How many diff. ways we can the rod of length 4 inches (including no cut at all). The cost table p_i 's as follows:-

rod length l_i	1	2	3	4
cost c_i	1	5	8	9

Diff. ways of cutting the rod of 4 inches		cost
(a)	$1 + 3 = 4$	9
(b)	$2 + 2 = 4$	10
(c)	$3 + 1 = 4$	9
(d)	$1 + 1 + \cancel{2} = 4$	7
(e)	$1 + 2 + 1 = 4$	7
(f)	$2 + 1 + 1 = 4$	7
(g)	$1 + 1 + 1 + 1 = 4$	4

- optimal sol^h is :- cut the rod into two pieces each of 2 inches, to get ~~max~~ profit of 10.
- We can cut up a rod of length n in 2^{n-1} diff ways. why??
- Note, for each $0 \leq i \leq n$, we have an independent option of cutting, or not cutting



- Despite the exponentially large possibility space, we can use DP to solve the problem in $\Theta(n^2)$.
- We can decompose the problem as follows:
 - first, cut a piece off the left end of the rod, & sell it.
 - Then, find the optimal way to cut the remainder of the rod.
 - That is, we try all possible cases:
 - Cut a piece of length 1, combine it with the optimal way of cutting a rod of length $(n-1)$.
 - Cut a piece of length 2, combine it with the optimal way of cutting a rod of length $(n-2)$.
 - so on.
 - We try all the possible lengths & then pick the best one

. We obtain

$$r_n = \max_{1 \leq i \leq n} (p_i + r_{n-i})$$

Naive Algo:- Recursive Top-Down Implementation :-

- CUT-ROD (p, n)

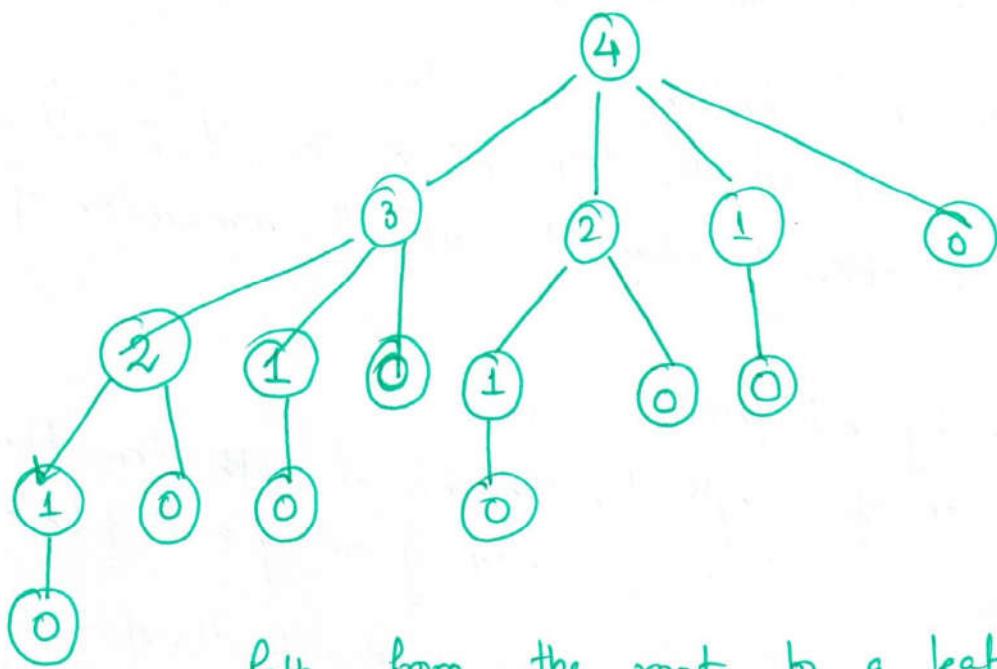
if $n == 0$
return 0

$q = -\infty$

for $i = 1$ to n
 $q = \max(q, p[i] + \text{CUT-ROD}(p, n-i))$

return q .

- following tree shows the recursive calls made for $n=4$,



- Path from the root to a leaf corresponds to one of the 2^{n-1} ways of cutting the rod of length n .
- In general, this recursion tree has 2^n nodes and 2^{n-1} leaves.
- From the recurrence recursion tree, we see that we are actually doing a lot of extra work.

↳ Computing the same thing again & again
- like fibonacci numbers (recursive implementation)

— a —

Memoization (Top down approach) :-

- Idea :- Store the result of recursive calls, reuse it if needed.

↳ subproblems

MEMOIZED-CUT-ROD (p, n)

Let $r[0 \dots n]$ be a new array

[for $i = 0$ to n

$r[i] = -\infty$

initialize a new auxiliary array

return MEMOIZED-CUT-ROD-Aux (p, n, r)

MEMOIZED-CUT-ROD-Aux (p, n, r)

- memoized version of CUT-ROD algo.

[if $r[n] \geq 0$ }

return $r[n]$

[if $n == 0$

$q = 0$;

else $q = -\infty$

for $i = 1$ to n

$q = \max(q, p[i] + \text{MEMOIZED-CUT-ROD-Aux}(p, n-i, r))$

checks to see if the designed value is already known

$r[n] = q$

return q

= Runtime : $\Theta(n^2)$

- Solves each subproblem exactly once.

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bottom up approach

- iteratively computes the value for smaller rod first; assuming that they will be used later to solve for large rod.
- Algo :-

```
→ BOTTOM-UP-CUT-ROD (p, n)
  let r[0...n] be a new array
  r[0] = 0
  for j = 1 to n
    q = -∞
    for i = 1 to j
      q = max(q, p[i] + r[j-i])
    r[j] = q
  return r[n]
```

- Time complexity = $\Theta(n^2)$; double "for" loop.
- No recursion
- The problem Algo solves subproblems of size $j = 0, 1, \dots, n$ in that order.
- Example :- Assume that we have a rod of size 4. (say)
Prices of diff sizes of rod is shown below:-

length	1	2	3	4	5	6	7	8
price	1	5	8	9	10	17	17	20

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- if the rod is size 4, then possible combinations are:-
 - $1+1+1+1 = 4 \rightarrow \text{cost} = 4.$
 - $2+2 = 4 \rightarrow \text{cost} = 10 \leftarrow \text{most value}$
 - $1+3 = 4 \rightarrow \text{cost} = 8$
 - $1+1+2 = 4 \rightarrow \text{cost} = 7$
 - $4 = 4 \rightarrow \text{cost} = 9$
- Remaining ways of cutting the rod is some permutation of the above.

— x —

Optimal substructure of rod-cutting problem:-

Substructure: Optimal solⁿ to the problem incorporate optimal solⁿ⁻¹ to related subproblems, which can be solved independently.

→ Proof by contradiction

— x —

Solⁿ In the algo., $r[i]$ is the price of the optimal cut until i .

i	0	1	2	3	4	5	6	7	8
p_i	0	1	5	8	9	10	17	17	20
r_i	0	1	5	8	10	13	17	18	22

if we have an optimal solⁿ

↓

rod

i

k

$k+1$

optimal

$r[1] = \max(-\infty, 1 + r[0]) = 1$

$r[2] = \max \{ p[1] + r[2-1] = 2, p[2] + r[2-2] = 5 \}$

$r[3] = \max \{ p[1] + r[3-1] = 6, p[2] + r[3-2] = 6, p[3] = 8 \}$

$r[4] = \max \{ p[1] + r[4-1] = 9, p[2] + r[4-2] = 10, p[3] + r[4-3] = 9, p[4] = 9 \}$

$$c[5] = \max \left\{ \begin{array}{l} p[1] + r[4] = 11 \\ p[2] + r[3] = 13 \leftarrow \\ p[3] + r[2] = 13 \\ p[4] + r[1] = 10 \\ p[5] = 10 \end{array} \right.$$

$$c[6] = \max \left\{ \begin{array}{l} p[1] + r[5] = 14 \\ p[2] + r[4] = 15 \\ p[3] + r[3] = 16 \\ p[4] + r[2] = 14 \\ p[5] + r[1] = 11 \\ p[6] + r[0] = 17 \leftarrow \end{array} \right.$$

no cut
optimal for
node of size 6

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Matrix-chain Multiplication :-

→ Assume we have two matrices $A_{4 \times 6}$ and $B_{6 \times 3}$

→ So, if we multiply the two :-

$$C_{4 \times 3} = A_{4 \times 6} \times B_{6 \times 3}$$

→ Total number of multiplications :- $4 \times 6 \times 3 = 72$

→ Now, consider the problem of multiplying the following :-

$$\begin{array}{c} A_1 \\ 10 \times 100 \end{array} \quad \begin{array}{c} A_2 \\ 100 \times 5 \end{array} \quad \begin{array}{c} A_3 \\ 5 \times 50 \end{array}$$

• If we multiply these matrices in the following order.

(a) $((A_1 A_2) A_3)$ \longrightarrow # of multiplications

$$\begin{array}{l} \xrightarrow{\quad} (10 \times 100 \times 5) = 5000 \\ \xrightarrow{\quad} (10 \times 5 \times 50) = 2500 \end{array} \left. \begin{array}{l} \\ \end{array} \right\} = 7500 \text{ mult.}$$

$$\begin{array}{l} (b) (A_1 (A_2 A_3)) \longrightarrow 100 \times 5 \times 50 + 10 \times 100 \times 50 \\ \qquad\qquad\qquad = 25,000 + 50,000 \\ \qquad\qquad\qquad = 75,000 \text{ mult.} \end{array}$$

Matrix Chain Multiplication Problem :-

→ Given a chain of n matrices $\langle A_1, A_2, \dots, A_n \rangle$, where for $i = 1, 2, \dots, n$, matrix A_i has dimension $p_{i-1} \times p_i$.

→ full parenthesis the product A_1, A_2, \dots, A_n s.t. it minimizes the total number of multiplication.

Optimal Substructure for Matrix chain Multiplication

Lemma:-

Suppose, we have an optimal sol^b for ~~A_{i+1}~~ multiplying matrices from A_i, A_{i+1}, \dots, A_j .

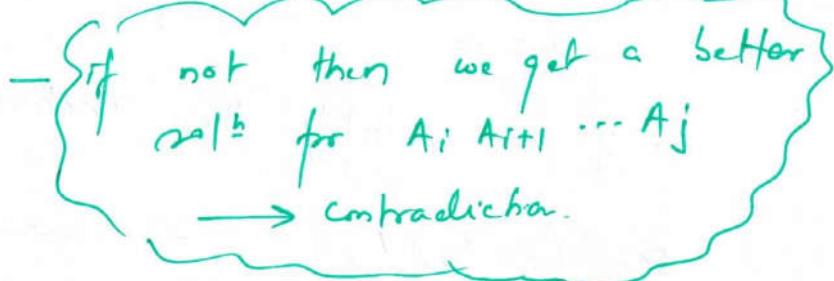
Also assume that that sol^b has the following parentheses

$$(A_i A_{i+1} \dots A_k) (A_{k+1} \dots A_j)$$

Then, the way we parenthesize the prefix subchain $A_i \dots A_k$ within this optimal parenthesization of $A_i A_{i+1} \dots A_j$ must be the optimal parenthesization of $A_i A_{i+1} \dots A_k$.

Proof:- - By contradiction.

-  Homework

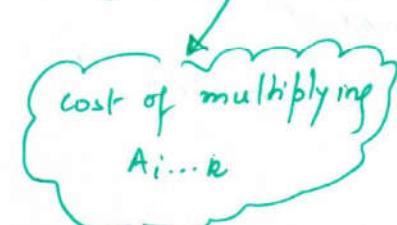
 If not then we get a better sol^b for $A_i A_{i+1} \dots A_j$
→ contradiction.

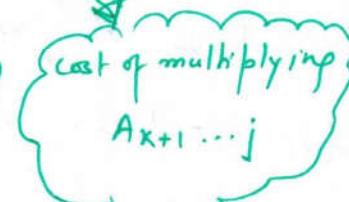
Recursive Solution :-

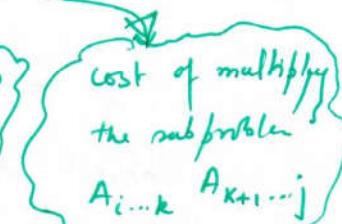
- Let $m[i, j]$ be the min number of multiplications required to compute $A_i \dots j$
- We define $m[i, j]$ recursively, as follows:-

$$m[i, j] = 0 \quad \text{if } i=j$$

$$m[i, j] = \min_{i \leq k < j} \{ m[i, k] + m[k+1, j] + p_{i-1} p_k p_j \} \quad \text{if } i < j$$

 cost of multiplying $A_i \dots k$

 cost of multiplying $A_{k+1} \dots j$

 cost of multiplying the subproblem $A_{i \dots k} A_{k+1 \dots j}$

- ~~Since~~, we don't know the value of 'k'.
- There are only $j-i$ possible values of k , i.e., $k = i, i+1, \dots, j-1$.
- We need to check them all to find the best.

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if $i=j$

$$\text{So, } m[i, j] = \begin{cases} 0 & \text{if } i=j \\ \min_{i \leq k < j} \{ m[i, k] + m[k+1, j] + p_{i-1} p_k p_j \} & \text{if } i < j \end{cases}$$

Example:- Consider the following matrices :-

$$\begin{array}{ccccc}
 & A_1 & A_2 & A_3 & A_4 & A_5 \\
 & 4 \times 10 & 10 \times 3 & 3 \times 12 & 12 \times 20 & 20 \times 7 \\
 & p_0 \times p_1 & p_1 \times p_2 & p_2 \times p_3 & p_3 \times p_4 & p_4 \times p_5
 \end{array}$$

- We start with the case when $i=j$.
- Then we compute $m[i, j]$ for $i < j$ where the diff between $i < j$ is 1.
- Next, we do the same for when $i < j$ has a spread of 2
- and so on.

i	1	2	3	4	5
1	0	120	264	1080	1344
2	x	0	360	1320	1350
3	x	x	0	720	1140
4	x	x	x	0	1680
5	x	x	x	x	0

cases where $|i-j|=2$

cases where $|i-j|=1$

cases when $i=j$

cases when $i > j$

spread ($i < j$) of 1

$$m[1, 2] = \min_{1 \leq k < 2} \{ m[1, 1] + m[2, 2] + 4 \times 10 \times 3 = 0 + 0 + 4 \times 10 \times 3 = 120 \}$$

$$m[2, 3] = \min_{2 \leq k < 3} \{ m[2, 2] + m[3, 3] + 10 \times 3 \times 12 = 0 + 0 + 360 = 360 \}$$

$$m[3, 4] = \min \{ 0 + 0 + 3 \times 12 \times 20 = 720 \}$$

$$m[4, 5] = \min_{4 \leq k < 5} \{ 0 + 0 + 12 \times 20 \times 7 = 1680 \}$$

Spread of 2 :-

$$m[1,3] = \min_{1 \leq k \leq 3} \begin{cases} m[1,1] + m[2,3] + 4 \times 10 \times 12 = 840 \\ m[1,2] + m[3,3] + 4 \times 3 \times 12 = 264. \end{cases}$$

$$m[2,4] = \min_{2 \leq k \leq 4} \begin{cases} m[2,2] + m[3,4] + 10 \times 3 \times 20 = 0 + 720 + 10 \times 2 \times 20 = 1320. \\ m[2,3] + m[4,4] + 10 \times 12 \times 20 = 360 + 0 = 2760 \end{cases}$$

$$m[3,5] = \min_{3 \leq k \leq 5} \begin{cases} m[3,3] + m[4,5] + 3 \times 12 \times 7 = 1932 \\ m[3,4] + m[5,5] + 3 \times 20 \times 7 = 1140. \end{cases}$$

— \times —

Spread of 3

$$m[1,4] = \min_{1 \leq k \leq 4} \begin{cases} m[1,1] + m[2,4] + 4 \times 10 \times 20 = 2420 \\ m[1,2] + m[3,4] + 4 \times 20 \times 20 = 1080 \\ m[1,3] + m[4,4] + 4 \times 12 \times 20 = 1224 \end{cases}$$

$$m[2,5] = \min_{2 \leq k \leq 5} \begin{cases} m[2,2] + m[3,5] + 10 \times 3 \times 7 = 1350 \\ m[2,3] + m[4,5] + 10 \times 12 \times 7 = 2880 \\ m[2,4] + m[5,5] + 10 \times 20 \times 7 = 2720. \end{cases}$$

Similarly, spread of 4

$$m[1,5] = \min_{1 \leq k \leq 5} \begin{cases} m[1,1] + m[2,5] + 4 \times 10 \times 7 = 1430 \\ m[1,2] + m[3,5] + 4 \times 3 \times 7 = 1344 \\ m[1,3] + m[4,5] + 4 \times 12 \times 7 = 2280 \\ m[1,4] + m[5,5] + 4 \times 20 \times 7 = 1640 \end{cases}$$

— \times —

— So we can multiply A_1 to A_5 in 1344 multiplications.

— In which order ??

→ we need to keep track of the 'k' value.

for example :-

- When we solve for $m[1,5]$, we find that the optimal sol^b is for $k=2$.

i.e., $m[1,5] = m[1,2] + m[3,5] + k_1 p_2 p_5$
So, we put a bracket between $A_2 \& A_3$, i.e.,

$$(A_1 \ A_2) \ (A_3 \ A_4 \ A_5)$$

- Then, we look for subproblems $m[1,2]$ & $m[3,5]$ used for solving $m[1,5]$.

- Can we put a bracket in subproblem $m[1,2]$.

- → no, only two matrices.
- what about $m[3,5]$.

- see, the sol^b to find we find a min fat $k=4$.

- we have :-

$$- (A_1 \ A_2) ((A_3 \ A_4) \ A_5)$$

- Check the above sol^b :-

$$(A_1 \ A_2) \overbrace{(A_3 \ A_4)}^{\downarrow} \overbrace{A_5}^{\downarrow}$$

$\cdot 120$ 720
 84 420

⇒ Total multiplication

$$\underline{\underline{1344}}$$

- Algo :-

MATRIX-CHAIN-ORDER (\mathbf{p})

$$n = \mathbf{p}.\text{length} - 1$$

Let $m[1..n, 1..n]$ and $s[1..n-1, 2..n]$ be new tables.

[for $i = 1$ to n

$$m[i, i] = 0$$

[for $l = 2$ to n // l is the chain length.

[for $i = 1$ to $n-l+1$

$$j = i + l - 1$$

$$m[i, j] = \infty$$

[for $k = i$ to $j-1$

$$q = m[i, k] + m[k+1, j] + p_{i-1} p_k p_j$$

[if $q < m[i, j]$

$$m[i, j] = q$$

$$s[i, j] = k$$

] return m and s .

- Runtime is $\Theta(n^3)$. Algo is nested three deep, and each loop (indexed (l, i , and k)) takes on at most $n-1$ values
- space complexity is $\Theta(n^2)$.

(1)

Longest Common Subsequence :-

- A subsequence of a string s_1 is a set of characters that appear in left-to-right order, but not necessarily consecutively.

Example :-

ACTTGCG

- ACT, ATTC, T, ACTTGC are all subsequences.
- TTA is not a subsequence.

- A common subsequence of two strings is a subsequence that appears in both strings.
- A longest common subsequence is a common subsequence of maximum length.
- Example :-

s_1 = AAACCGTGAGTTATTCTGTTCTAGAA

s_2 = CACCCCTAAGGTACCTTTGGTTC

LCS is ACCTAGTACTTG

- Has applications in many areas including biology.
- Brute-force solⁿ :- Try all possible subsequence from one string, and search for matches in the other string.
 - # of ~~the~~ substring subsequence of a string is 2^m . (m is the length of the string.)
 - Exponential number of possible subsequence.

Optimal substructure of an LCS :-

Theorem :- Let $X = \langle x_1, x_2, \dots, x_m \rangle$ and $Y = \langle y_1, y_2, \dots, y_n \rangle$ be sequences, and let $Z = \langle z_1, z_2, \dots, z_k \rangle$ be any LCS of X and Y .

1. If $x_m = y_n$, then $z_k = x_m = y_n$ and Z_{k-1} is an LCS of X_{m-1} and Y_{n-1} .
2. If $x_m \neq y_n$, in this case $x_m \neq y_n$ cannot both be in the LCS. Thus, either x_m is not part of the LCS, or y_n is not part of the LCS (or possibly both are not part of LCS).
 - (a) if $x_m \neq y_n$, then $z_k \neq x_m$ implies that Z is an LCS of X_{m-1} and Y .
 - (b) if $x_m \neq y_n$, then $z_k \neq y_n$ implies that Z is an LCS of X and Y_{n-1} .

Proof (1) :- If $z_k \neq x_m$, then we could append $x_m = y_n$ to Z to obtain a common subsequence of X and Y of length $k+1$.
→ contradiction to our assumption that Z (of length k) is the LCS of X and Y .

Thus, we must have $z_k = x_m = y_n$.

Next :- the prefix Z_{k-1} is a length $(k-1)$ common subsequence of X_{m-1} and Y_{n-1} . We have to show that it is ~~an~~ LCS.

Suppose, for the purpose of contradiction that there is a common subsequence W of X_{m-1} and Y_{n-1} with length greater than $k-1$.

Then, appending $x_m = y_n$ to W produces a common subsequence of X and Y , whose length is greater than k , which is a contradiction.

(2)

Proof (2) :- If $z \neq x_m$, then z is a common subsequence of x_{m-1} and Y .

If there were a common ^{sub}seq. W of x_{m-1} and Y with length greater than k , then W would also be a common subsequence of x_m and Y , contradicting the assumption that z is an LCS of X and Y .

Proof (3) :- Proof is symmetric to (2).

— X —

Recursive Solution :-

- from the above theorem, to find the LCS of $X = \langle x_1, x_2, \dots, x_n \rangle$ and $Y = \langle y_1, y_2, \dots, y_n \rangle$
- we should either examine one subproblem,
i.e., if $x_m = y_n \rightarrow$ we find LCS of $x_{m-1} \& Y_{n-1}$
- OR examine two subproblems
i.e., if $x_m \neq y_n \rightarrow$ we find LCS of x_{m-1} and Y
and LCS of X and Y_{n-1}
and find the max LCS of the two
- The optimal substructure of LCS problem gives the following recursive formula:-

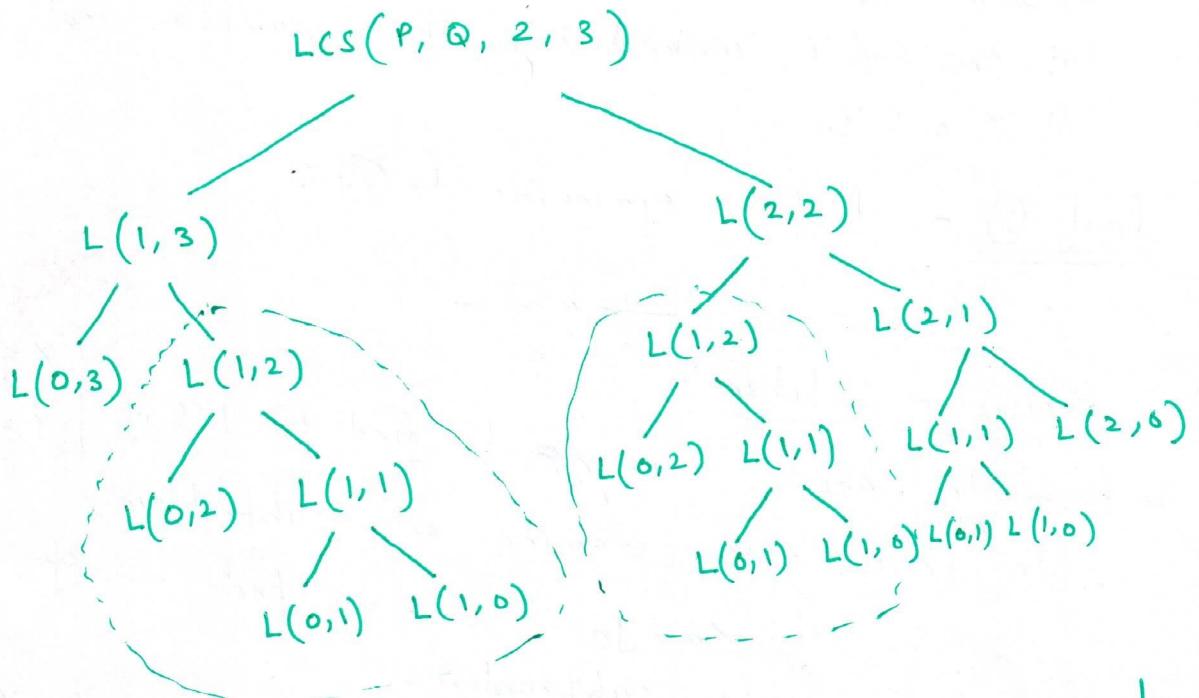
$$c[i, j] = \begin{cases} 0 & \text{if } i=0 \text{ or } j=0 \\ c[i-1, j-1] + 1 & \text{if } i, j > 0 \text{ and } x_i = y_j \\ \max(c[i, j-1], c[i-1, j]) & \text{if } i, j > 0 \text{ and } x_i \neq y_j \end{cases}$$

→ The length of an LCS of the sequences $x_i \& y_i$

Overlapping subproblems :-

Ex:- Let's consider two strings

$$P = "A A" \quad Q = "B B B."$$



- We could easily write an exponential-time recursive algo to compute the length of an LCS of two ~~same~~ sequences.
- However, LCS has only $\Theta(m \cdot n)$ distinct subproblems.
- so use dynamic programming. to compute the solution bottom-up.
- Memoization can improve the performance. to $\Theta(m \cdot n)$.

// initialize arr[n][m] to undefined.

LCS-Memoized(X, Y, n, m) {

 m = X.length;
 n = Y.length;

 if arr[n][m] != undefined
 return arr[n][m].

 if (n == 0) or (m == 0) return 0;
 else if (X[n] == Y[m]) return 1 + LCS-Memoized(
 X, Y, n-1, m-1);
 else return max(LCS-Memo(X, Y, n-1, m), LCS-Memo(X, Y, n, m-1))

$\Theta(m \cdot n)$

LCS using Dynamic Programming (Bottom-up).

Algo:

LCS-LENGTH (X, Y)

$m = X.length$

$n = Y.length$

let $b[1..m, 1..n]$ and $c[0..m, 0..n]$ be new tables.

[for $i = 1$ to m
 $c[i, 0] = 0$

[for $j = 0$ to n
 $c[0, j] = 0$

[for $i = 1$ to m

[for $j = 1$ to n

[if $x_i == y_j$

$c[i, j] = c[i-1, j-1] + 1$

$b[i, j] = "↖"$

[else if $c[i-1, j] \geq c[i, j-1]$

$c[i, j] = c[i-1, j]$

$b[i, j] = "↑"$

[else $c[i, j] = c[i, j-1]$

$b[i, j] = " "$

] return c and b .

Run-time complexity is $\Theta(m \cdot n)$

↳ each table entry takes $\Theta(1)$ to compute.

Example:-

Let $x = A B C B D A B$ find .LCS.
 $y = B D C A B A .$

y_j	B	D	C	A	B	A	
x_i	0	0	0	0	0	0	0
A	0	0	0	0	1	1	1
B	0	1	1	1	1	2	2
C	0	1	1	2	2	2	2
B	0	1	1	2	2	3	3
D	0	1	2	2	2	3	3
A	0	1	2	2	3	3	4
B	0	1	2	2	3	4	4

- if $x_i = y_j \rightarrow$ top left diagonal + 1.
 \rightarrow max of (top and left).
- else

- Constructing LCS :- (Algo. from the book)
- whenever we encounter " \nwarrow " $\Rightarrow x_i = y_j$ is an element in LCS.
- We encounter the elements of LCS in reverse order.
- Move from bottom right (i.e. 4) to top-left (0) and print the char corresponding to " \nwarrow ".
- LCS :- $\langle B C B A \rangle$
- The procedure takes $O(m+n)$ time!

as it decrements
one of i & j in
each recursive
call

Bellman-Ford Algorithm

5

- Richard Bellman and Lester Ford, Jr., published the algo worked on the same problem, and published it in 1958 and 1956, respectively. *separately*
- Solves the shortest-path problem in the general case in which edge weights may be negative.
- Algorithm returns a boolean value indicating whether or not there is a -ve weight cycle that is reachable from the source.
 - ↳ In such a case, (i.e., -ve weight cycles) the algo indicates no solution.
 - Else, algo. produces the shortest path & their weights.

- Algo:-

BELLMAN-FORD (G, w, s)

INITIALIZE (G, s);

for $i = 1$ to $|V| - 1$ $\dots \dots \dots O(V)$

 for each edge $(u, v) \in E$ $\dots \dots \dots O(E)$

 RELAX (u, v, w)

 for each edge $(u, v) \in E$

 if $v.d > u.d + w(u, v)$

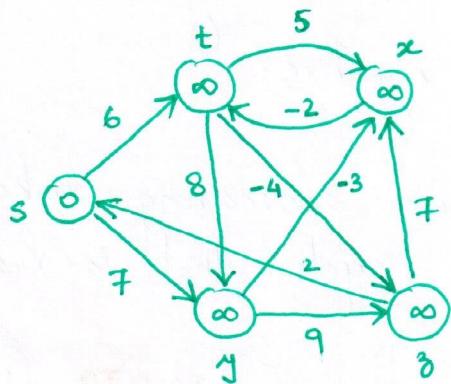
 return FALSE

return TRUE

RELAX (u, v, w)

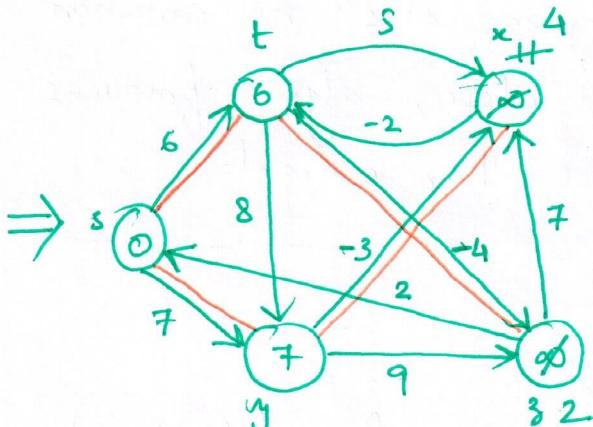
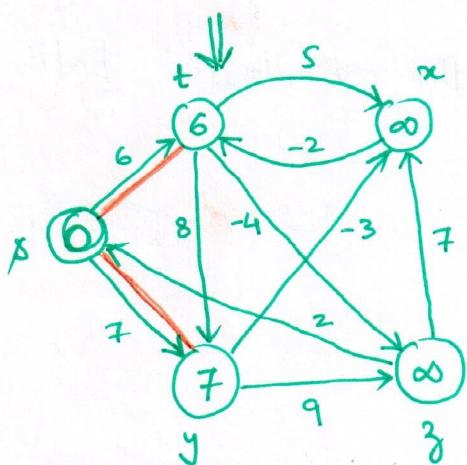
 if $(d[v] > d[u] + w(u, v))$
 $d[v] =$
 $\pi[v] = u$

- Total complexity : $O(VE + E) = O(VE)$
- It is slower than Dijkstra's algorithm for the same problem, but ~~can~~ can handle -ve weight edges in a graph.
- follows Dynamic Programming :- Try out all possible sol^h & pick the best one.
- Example :- Relax all edges. (for $V-1$ times)

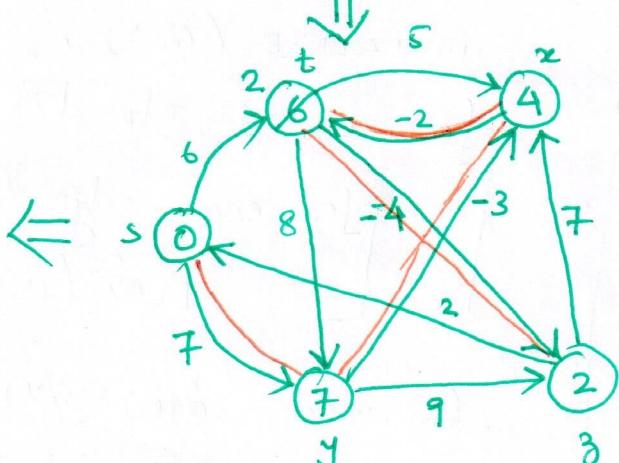
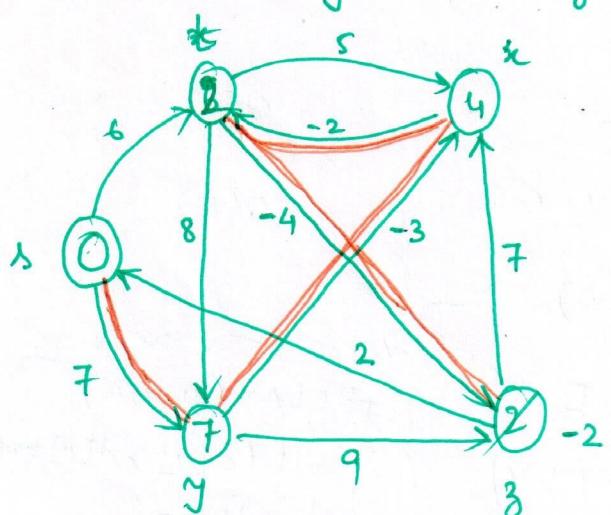


(a) Initialize (G, δ)

- Relax all edges in the following sequence.
- Keep the edges starting from s at the last, (to help the iteration).



$$\begin{aligned}
 (s, t) &= 6 \\
 (s, y) &= 7 \\
 (s, z) &= 3 \\
 (t, x) &= 5 \\
 (t, y) &= 8 \\
 (t, z) &= 2 \\
 (y, x) &= 9 \\
 (y, z) &= 7 \\
 (z, x) &= 2 \\
 (z, t) &= 4 \\
 (z, y) &= 3
 \end{aligned}$$



- # iterations = $V-1 = 5-1 = 4$.
- Complexity = $O(VE)$.

Lemma :- Let $G(V, E)$ be a weighted, directed graph with source 's' and weight function $w: E \rightarrow \mathbb{R}$, and assume G contains no negative-weight cycles that are reachable from 's'.

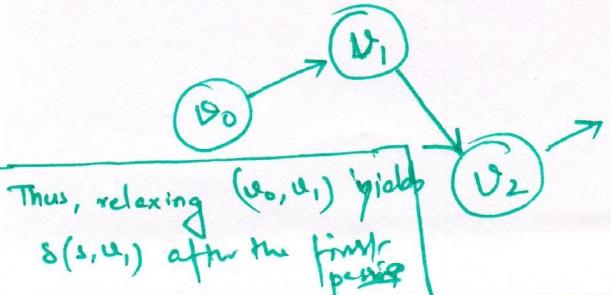
Then, after $|V|-1$ iteration of the for loop of BF-Algo, we have $d[v] = \delta(s, v)$ for all vertices v that are reachable from 's'.

Corollary :- If a value for each vertex $v \in V$, there is a \dagger If the value $d[v]$ fails to converge after $|V|-1$ passes, then \exists a -ve edge cycle reachable from 's'.

Proof B (of Lemma) :-

- Use path relaxation property.
- Consider any vertex v , that is reachable from 's'.
- and let, $\beta = \langle v_0, v_1, \dots, v_k \rangle$ where $v_0 = s$ and $v_k = v$. by any shortest path from 's' to 'v'.
- As, shortest path are simple (no loop), β has at most $|V|-1$ edges, i.e., $k \leq |V|-1$.
- Each of the $|V|-1$ iterations of the "for" loop in BF-algo relaxes all $|E|$ edges.

Otherwise we will have loop



At some pt in iter 1, we will relax edge (v_0, v_1) . Due to optimal strategy, if $(v_0 \dots v_k)$ is the SP, then v_0, v_1 is also a SP.

Idea of BF :- At each pass we move closer to v_k , while constructing the SP.

i.e., Iter. 1 $\Rightarrow \delta(s, v_1)$
Iter 2 $\Rightarrow \delta(s, v_2)$
... so on ...

- Thus, after 1st iteration of all edges E , we have
 $d[v_1] = \delta(s, v_1)$, as we will relax ^{edge} $(v_0, v_1) \in E$ in this pass.
 - Similarly in the second iteration we get
 $d[v_2] = \delta(s, v_2)$ as we relax the edge (v_1, v_2) .
 - After k passes, $d[v_k] = \delta(s, v_k)$
 - so, after $|V|-1$ passes, all reachable vertices will have a δ value.
- x —

Proof (Corollary):

- If \exists an edge in the graph ~~and~~ that can be relaxed after $|V|-1$ passes...
 - It implies that the current shortest path from s to v is not simple, as we have a repeating vertex.
 - found a cycle of -ve weight.
- x —