#### Lecture 3: A first look at dimension reduction

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**Dimension reduction and Predictive** 

Modeling

# One version of the curse of dimensionality

### Samples tend to be further away from the origin

Let  $\mathbf{x} \in [-1, 1]^p$  be a uniformly distributed random variable. For  $0 \le t \le 1$  consider

$$q = \mathbb{P}(-t \le x^{(1)} \le t, \dots, -t \le x^{(p)} \le t) = \left(\frac{2t}{2}\right)^p$$

$$\Rightarrow \quad t = q^{1/p}$$

In a large enough sample about q percent of observations will be in  $[-t, t]^p$ .

In high dimensions, most data points are far away from the origin.

How should t be chosen so that about q percent of observations lie in  $[-t,t]^p$ ?

p	q = 1%	q = 10%
2	$t \approx 0.01$	$t \approx 0.32$
3	$t \approx 0.22$	$t \approx 0.46$
10	$t \approx 0.63$	$t \approx 0.79$
100	$t \approx 0.95$	$t \approx 0.98$

# Another version of the curse of dimensionality

## Pairwise distances grow with dimension

If  $\mathbf{x}, \mathbf{y} \in [0, 1]^p$  uniformly distributed, then their pairwise distance  $\|\mathbf{x} - \mathbf{y}\|_2$  grow with p.

The last column suggests that the mean pairwise distance grows as  $O(\sqrt{p})$ .

The standard deviations stay constant suggesting that observations have increasingly similar pairwise distances in high dimensions.

Mean and standard deviation of the pairwise distances of n = 500 simulated observations.

p	Mean	SD	Mean / $\sqrt{p}$
2	0.52	0.25	0.37
3	0.66	0.25	0.38
10	1.28	0.25	0.40
100	4.07	0.24	0.41
500	9.13	0.25	0.41
1000	12.91	0.24	0.41
	2 3 10 100 500	2 0.52 3 0.66 10 1.28 100 4.07 500 9.13	2 0.52 0.25 3 0.66 0.25 10 1.28 0.25 100 4.07 0.24 500 9.13 0.25

What does a predictive model do? The methods we have discussed so far try to capture some type of local, average behaviour - meaning, observations that are close borrow information from each other to come to a decision regarding the value of the outcome variable (numerical or class label). [.5em]

In high-dimensional settings, the notion of neighborhood breaks down.

In addition, many of the methods we have discussed will either be numerically unstable or ill-defined (i.e., can't estimate parameters) if the data dimension is to large.

- 1. Feature selection: Deciding on a subset of the original features
  - We will talk a lot about feature selection later in class
  - Simplest strategy is some kind of pre-processing or filtering
  - ► Example: max variance features, features that are statistically associated with the label (t-test, ANOVA, correlation)

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  - ► Example: max variance features, features that are statistically associated with the label (t-test, ANOVA, correlation)
- 2. Feature transformation: Combining existing features while reducing dimension (e.g. PCA)
  - ► The feature transformation might destroy/obscure relationships in the original data that it cannot capture
  - Since features are transformed, it is not guaranteed that uninformative features are actually filtered out

When p is large

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- discriminant analysis: ill-defined/multicollinearity or numerically unstable model

# Principal Component Analysis

# **Projection onto a subspace**

Assume  $\mathbf{x} \in \mathbb{R}^p$ . Given **orthonormal vectors**  $\mathbf{b}_1, \dots, \mathbf{b}_m$ , i.e.

$$\|\mathbf{b}_j\| = 1$$
 and  $\mathbf{b}_j^{\mathsf{T}} \mathbf{b}_k = 0$  for  $j \neq k$ 

where m < p, the projection of x onto the m-dimensional linear subspace

$$V_m = \operatorname{span}(\mathbf{b}_1, \dots, \mathbf{b}_m)$$
 is

$$\hat{\mathbf{x}} = \sum_{j=1}^{m} (\mathbf{x}^{\mathsf{T}} \mathbf{b}_{j}) \mathbf{b}_{j} = \underbrace{\left(\sum_{j=1}^{m} \mathbf{b}_{j} \mathbf{b}_{j}^{\mathsf{T}}\right)}_{\text{Projection}} \mathbf{x}$$

matrix

The projection is orthogonal, i.e.

$$(\mathbf{x} - \hat{\mathbf{x}})^{\mathsf{T}} \mathbf{b}_j = 0$$

for all  $\mathbf{b}_j$ .



# **Rayleigh Quotient**

Let  $\mathbf{A} \in \mathbb{R}^{k \times k}$  be a symmetric matrix. For  $\mathbf{0} \neq \mathbf{x} \in \mathbb{R}^k$  define

$$J(\mathbf{x}) = \frac{\mathbf{x}^{\mathsf{T}} \mathbf{A} \mathbf{x}}{\mathbf{x}^{\mathsf{T}} \mathbf{x}}$$

 $J(\mathbf{x})$  is called the **Rayleigh Quotient** for **A**.

#### **Maximizing the Rayleigh Quotient**

The maximization problem

$$\max_{\mathbf{x}} J(\mathbf{x}) \quad \text{subject to} \quad \mathbf{x}^{\mathsf{T}} \mathbf{x} = 1$$

is solved by a **unit eigenvector**  $\mathbf{x}$  of  $\mathbf{A}$  corresponding to the **largest eigenvalue**  $\lambda$  of  $\mathbf{A}$ .

**Note:** -x is also a solution.

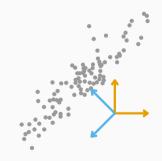
# Principal Component Analysis (PCA) (I)

**Goal:** Given continuous data, find an orthogonal coordinate system such that the variance of the data is maximal along each direction.

Given data points  $x_1, ..., x_n$  and a unit vector  $\mathbf{r}$ , the variance of the data along  $\mathbf{r}$  is

$$S(\mathbf{r}) = \sum_{l=1}^{n} (\mathbf{r}^{\mathsf{T}} (\mathbf{x}_{l} - \overline{\mathbf{x}}))^{2} = (n-1)\mathbf{r}^{\mathsf{T}} \widehat{\mathbf{\Sigma}} \mathbf{r}$$

where  $\widehat{\Sigma}$  is the empirical covariance matrix.



Axes

Cartesian Principal Component

# Principal Component Analysis (PCA) (II)

**Direction with maximal variance:** Find **r** such that

$$\max_{\mathbf{r}} S(\mathbf{r}) \quad \text{subject to} \quad \|\mathbf{r}\|^2 = \mathbf{r}^{\mathsf{T}}\mathbf{r} = 1$$

- ▶ This is the same problem as maximizing the **Rayleigh Quotient** for the matrix  $\hat{\Sigma}$ .
- ▶ The solution is the eigenvector  $\mathbf{r}_1$  of  $\hat{\Sigma}$  corresponding to the largest eigenvalue  $\lambda_1$ .

#### How do we find the other directions?

Project data on orthogonal complement of  $\mathbf{r}_1$ , i.e.

$$\hat{\mathbf{x}}_l = \left(\mathbf{I}_p - \mathbf{r}_1 \mathbf{r}_1^{\mathsf{T}}\right) \mathbf{x}_l$$

and repeat the procedure above.

# **Intermezzo: Pre-processing**

Data is often pre-processed before it is used in computational methods.

Given a data matrix  $\mathbf{X} \in \mathbb{R}^{n \times p}$ , let

- ▶  $\mathbf{m}_r \in \mathbb{R}^n$  be the vector of row-means,
- $ightharpoonup \mathbf{m}_c \in \mathbb{R}^p$  be the vector of column-means, and
- $\mathbf{s} \in \mathbb{R}^p$  be the vector of per-column standard deviations.

Then (with  $\mathbf{1}_n = (1, \dots, 1)^T \in \mathbb{R}^n$ )

- ▶ the matrix  $\mathbf{X} \mathbf{m}_r \mathbf{1}_p^{\mathsf{T}}$  has row means zero (row-centred),
- ▶ the matrix  $\mathbf{X} \mathbf{1}_n \mathbf{m}_r^{\mathsf{T}}$  has column means zero (**column-centred**), and
- ► the matrix **X** diag(1/**s**) has column standard deviations one (**standardised columns**)

# Principal Component Analysis (PCA) (III)

#### **Computational Procedure:**

- 1. Centre (and possibly standardise) the columns of the data matrix  $\mathbf{X} \in \mathbb{R}^{n \times p}$
- 2. Calculate the **empirical covariance matrix**  $\widehat{\Sigma} = \frac{1}{n-1} \mathbf{X}^T \mathbf{X}$
- 3. Determine the **eigenvalues**  $\lambda_j$  and corresponding orthonormal **eigenvectors**  $\mathbf{r}_j$  of  $\widehat{\boldsymbol{\Sigma}}$  for  $j=1,\ldots,p$  and order them such that

$$\lambda_1 \ge \lambda_2 \ge \dots \ge \lambda_p \ge 0$$

4. The vectors  $\mathbf{r}_j$  give the direction of the principal components (PC)  $\mathbf{r}_j^{\mathsf{T}} \mathbf{x}$  and the eigenvalues  $\lambda_j$  are the variances along the PC directions

**Note:** Set 
$$\mathbf{R}=(\mathbf{r}_1,\dots,\mathbf{r}_p)$$
 and  $\mathbf{D}=\mathrm{diag}(\lambda_1,\dots,\lambda_p)$  then 
$$\widehat{\boldsymbol{\Sigma}}=\mathbf{R}\mathbf{D}\mathbf{R}^{\mathsf{T}}\quad\text{and}\quad\mathbf{R}^{\mathsf{T}}\mathbf{R}=\mathbf{R}\mathbf{R}^{\mathsf{T}}=\mathbf{I}_p$$

#### **PCA** and Dimension Reduction

**Recall:** For a matrix  $\mathbf{A} \in \mathbb{R}^{k \times k}$  with eigenvalues  $\lambda_1, \dots, \lambda_k$  it holds that

$$\operatorname{tr}(\mathbf{A}) = \sum_{j=1}^{k} \lambda_j$$

For the empirical covariance matrix  $\widehat{\Sigma}_p$  and the variance of the j-th feature  $\operatorname{Var}[x_j]$ 

$$\operatorname{tr}(\widehat{\Sigma}) = \sum_{j=1}^{r} \operatorname{Var}[x_j] = \sum_{j=1}^{r} \lambda_j$$

is called the total variation.

Using only the first m < p principal components leads to

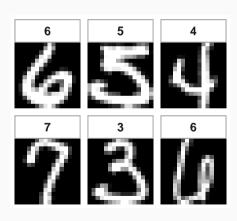
$$\frac{\lambda_1 + \cdots + \lambda_m}{\lambda_1 + \cdots + \lambda_n} \cdot 100\%$$
 of explained variance

# PCA and Dimension Reduction: Example (I)

#### Variant of the MNIST handwritten digits dataset

 $(n = 7291, 16 \times 16 \text{ greyscale images, i.e. } p = 256)$ 

Digit	Frequency
0	0.16
1	0.14
2	0.10
3	0.09
4	0.09
5	0.08
6	0.09
7	0.09
8	0.07
9	0.09



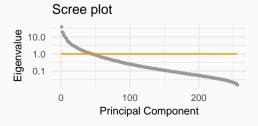
# PCA and Dimension Reduction: Example (II)

For standardized variables

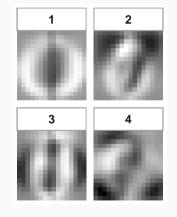
$$\operatorname{tr}(\widehat{\boldsymbol{\Sigma}}) = p$$

Typical selection rule: Components with

$$\lambda_j \ge \frac{1}{p} \operatorname{tr}(\widehat{\Sigma}) \quad (= 1)$$



Visualisations of the first four principal components

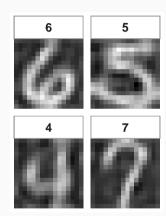


# PCA and Dimension Reduction: Example (III)

Using the selection rule leads to 44 components. Using the projection

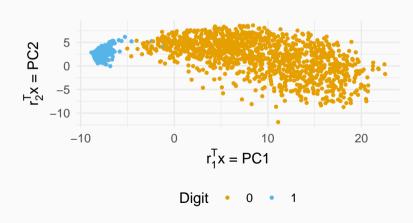
$$\hat{\mathbf{x}} = \left(\sum_{j=1}^{44} \mathbf{r}_j \mathbf{r}_j^{\mathsf{T}}\right) \mathbf{x}$$

creates a **reconstruction** of x.



# PCA and Dimension Reduction: Example (IV)

Projecting the digits onto the first two principal component directions gives a very clear distinction of digits 0 and 1.



# Importance of standardisation (I)

#### The overall issue: Subjectivity vs Objectivity

(Co-)variance is scale dependent: If we have a sample (size n) of variables x and y, then their empirical covariance is

$$s_{xy} = \frac{1}{n-1} \sum_{l=1}^{n} (x_l - \overline{x})(y_l - \overline{y})$$

If x is scaled by a factor c, i.e.  $z = c \cdot x$ , then

$$s_{zy} = \frac{1}{n-1} \sum_{l=1}^{n} (z_l - \overline{z})(y_l - \overline{y})$$
$$= \frac{1}{n-1} \sum_{l=1}^{n} (c \cdot x_l - c \cdot \overline{x})(y_l - \overline{y}) = c \cdot s_{xy}$$

# Importance of standardisation (II)

# (Co-)variance is scale dependent: $s_{zy} = c \cdot s_{xy}$ where $z = c \cdot x$

- By scaling variables we can therefore make them as large/influential or small/insignificant as we want, which is a very subjective process
- By standardising variables we can get of rid of scaling and reach an objective point-of-view
- ▶ Do we get rid of information?
  - ► The **typical range** of a variable is compressed
  - ▶ The overall shape of the data is preserved
  - Outliers will still be outliers

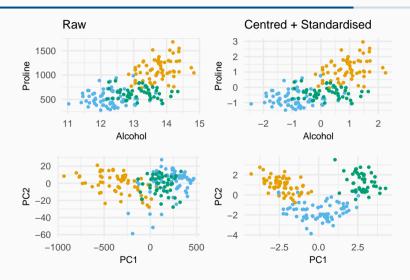
#### **UCI Wine Data Set**

#### **UCI Wine Data Set<sup>1</sup>**

- Results of a chemical analysis on multiple samples from three different origins of wine
- ightharpoonup p = 13 features
  - e.g. alcohol in %, ash, colour intensity, magnesium, ...

¹https://archive.ics.uci.edu/ml/datasets/Wine

# Importance of standardisation (III)



# Singular Value Decomposition

# Singular Value Decomposition (SVD)

The singular value decomposition (SVD) of a matrix  $X \in \mathbb{R}^{n \times p}$ ,  $n \ge p$ , is

$$X = UDV^{T}$$

where  $\mathbf{U} \in \mathbb{R}^{n \times p}$  and  $\mathbf{V} \in \mathbb{R}^{p \times p}$  with

$$\mathbf{U}^{\mathsf{T}}\mathbf{U} = \mathbf{I}_p$$
 and  $\mathbf{V}^{\mathsf{T}}\mathbf{V} = \mathbf{V}\mathbf{V}^{\mathsf{T}} = \mathbf{I}_p$ 

and  $\mathbf{D} \in \mathbb{R}^{p \times p}$  is diagonal. Usually

$$d_{11} \ge d_{22} \ge \dots \ge d_{pp}$$

Note: Due to the orthogonality conditions on  ${f U}$  and  ${f V}$ 

$$\mathbf{X}\mathbf{X}^{\mathsf{T}}\mathbf{U} = \mathbf{U}\mathbf{D}^{2}$$

$$\mathbf{X}^{\mathsf{T}}\mathbf{X}\mathbf{V} = \mathbf{V}\mathbf{D}^2$$

#### **SVD** and **PCA**

In PCA the empirical covariance matrix  $\widehat{\Sigma}$  is in focus, whereas SVD focuses on the data matrix X directly.

**Connection:** For centred variables

$$\widehat{\Sigma} = \frac{\mathbf{X}^{\mathsf{T}} \mathbf{X}}{n-1} = \frac{\mathbf{V} \mathbf{D} \mathbf{U}^{\mathsf{T}} \mathbf{U} \mathbf{D} \mathbf{V}^{\mathsf{T}}}{n-1} = \mathbf{V} \left( \frac{\mathbf{D}^2}{n-1} \right) \mathbf{V}^{\mathsf{T}}$$

The PC directions are in **V** and the eigenvalues of  $\widehat{\Sigma}$  are  $d_{jj}^2/(n-1)$ .

**Note:** This is how PCA is typically calculated. SVD is a **more general tool** and is used in many other contexts as well.

# SVD and best rank-q-approximation / dimension reduction

Write  $\mathbf{u}_j$  and  $\mathbf{v}_j$  for the columns of  $\mathbf{U}$  and  $\mathbf{V}$ , respectively. Then

$$\mathbf{X} = \mathbf{U}\mathbf{D}\mathbf{V}^{\mathsf{T}} = \sum_{j=1}^{p} d_{jj} \underbrace{\mathbf{u}_{j}\mathbf{v}_{j}^{\mathsf{T}}}_{\mathsf{rank-1-matrix}}$$

**Best rank**-q-approximation: For q < p

$$\mathbf{X}_{\mathbf{q}} = \sum_{j=1}^{\mathbf{q}} d_{jj} \mathbf{u}_j \mathbf{v}_j^{\mathsf{T}}$$

with approximation error

$$\left\| \mathbf{X} - \mathbf{X}_q \right\|_F^2 = \left\| \sum_{j=q+1}^p d_{jj} \mathbf{u}_j \mathbf{v}_j^\mathsf{T} \right\|_F^2 = \sum_{j=q+1}^p d_j^2$$

## **Cautionary Remarks**

- ▶ PCA with leading eigenvectors may not preserve the signal in your data about the outcome *Y* alternatives like PLS (partial least squares), CCA (canonical correlation analysis), etc.
- ▶ Pre-processing (centring and standardisation) is important if data is collected on different scales...
- but.... Is the relative scale of features a nuisance or informative?
- ► What about binary or categorical data?
  - Binary may be misleading careful about centering as well
  - Categorical/Ordinal use one-shot encoding
  - ► Generalized PCA (MSE loss replaced with Deviance for the distribution family) or MCA (multiple correspondence analysis) looking for co-occurences of factor levels.
  - Lot's of packages even for mixed type data.

**Connections to Discriminant Analysis** 

# Discriminant Analysis and the Inverse Covariance Matrix

From PCA or SVD we get  $\widehat{\Sigma} = \mathbf{V}\mathbf{D}\mathbf{V}^{\mathsf{T}}$  where  $\mathbf{V}^{\mathsf{T}}\mathbf{V} = \mathbf{V}\mathbf{V}^{\mathsf{T}} = \mathbf{I}_p$  and  $d_{11} \geq \cdots \geq d_{pp} \geq 0$ . Then

$$\widehat{\mathbf{\Sigma}}^{-1} = \mathbf{V}\mathbf{D}^{-1}\mathbf{V}^{\mathsf{T}} = \mathbf{V}\mathbf{D}^{-1/2}\mathbf{D}^{-1/2}\mathbf{V}^{\mathsf{T}} = \left(\widehat{\mathbf{\Sigma}}^{-1/2}\right)^{\mathsf{T}}\widehat{\mathbf{\Sigma}}^{-1/2}$$

where  $(\mathbf{D}^{-1/2})_{jj}:=1/\sqrt{d_{jj}}$  and  $\widehat{\mathbf{\Sigma}}^{-1/2}:=\mathbf{D}^{-1/2}\mathbf{V}^{\mathsf{T}}.$ 

In LDA the term involving the inverse covariance matrix is then

$$(\mathbf{x} - \widehat{\boldsymbol{\mu}})^{\mathsf{T}} \widehat{\boldsymbol{\Sigma}}^{-1} (\mathbf{x} - \widehat{\boldsymbol{\mu}}) = (\mathbf{x} - \widehat{\boldsymbol{\mu}})^{\mathsf{T}} \left(\widehat{\boldsymbol{\Sigma}}^{-1/2}\right)^{\mathsf{T}} \widehat{\boldsymbol{\Sigma}}^{-1/2} (\mathbf{x} - \widehat{\boldsymbol{\mu}})$$
$$= \left(\mathbf{V}^{\mathsf{T}} (\mathbf{x} - \widehat{\boldsymbol{\mu}})\right)^{\mathsf{T}} \mathbf{D}^{-1} \left(\mathbf{V}^{\mathsf{T}} (\mathbf{x} - \widehat{\boldsymbol{\mu}})\right)$$
$$= \sum_{j=1}^{\infty} \frac{1}{d_{jj}} (\widetilde{x}_j - \widetilde{\mu}_j)^2$$

Inverse of the eigenvalues can lead to numerical instability.

# Regularised Discriminant Analysis (RDA)

The empirical covariance matrix used by LDA can be **stabilized**:

$$\widehat{\mathbf{\Sigma}}_{\lambda} := \widehat{\mathbf{\Sigma}} + \lambda \mathbf{I}_{p} = \mathbf{V}(\mathbf{D} + \lambda \mathbf{I}_{p})\mathbf{V}^{\mathsf{T}}$$

where  $\lambda > 0$  is a tuning parameter.

- ▶ Using  $\widehat{\Sigma}_{\lambda}$  in LDA is called **regularised discriminant analysis (RDA)**.
- ▶ Instead of  $1/d_{ij}$  the scaling factors are now  $1/(d_{ij} + \lambda)$ .
- ▶ For small  $d_{jj}$  this can lead to **numerical stability**, whereas large  $d_{jj}$  are not much affected.
- ▶ For increasingly large  $\lambda$  the  $d_{jj}$  will have diminishing impact and RDA starts to become **nearest centroids**.
- ▶ RDA can be used with QDA as well by considering:

$$\widehat{\Sigma}_{i,\lambda} := \widehat{\Sigma}_{i} + \lambda \widehat{\Sigma}_{LDA}$$

# Take-home message

- ► Principal component analysis gives a convenient decomposition of the variance of the data
- ▶ Pre-processing (centring and standardisation) is important if data is collected on different scales
- Singular value decomposition is a universal workhorse for in numerical methods