#### **Lecture 6: Data representations - Kernel methods**

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MSA220/MVE441 Statistical Learning for Big Data

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# Kernel-methods

#### Kernels

A **kernel** is a function  $k(\mathbf{x}, \mathbf{y}) : \mathbb{R}^p \times \mathbb{R}^p \to \mathbb{R}$  that maps two elements of the feature space to a real number, such that

$$k(\mathbf{x}, \mathbf{y}) = k(\mathbf{y}, \mathbf{x})$$
 and  $k(\mathbf{x}, \mathbf{y}) \ge 0$ 

Can be seen as a (possibly non-linear) **generalized inner product** without bilinearity.

Kernels measure **similarity** between features vectors.

# **Examples of kernels**

- ► Linear kernel  $k(\mathbf{x}, \mathbf{y}) = \mathbf{x}^{\mathsf{T}} \mathbf{y}$
- **Polynomial kernel**  $k(\mathbf{x}, \mathbf{y}) = (\gamma \mathbf{x}^{\mathsf{T}} \mathbf{y} + r)^m$
- ► Radial basis function (RBF) kernel  $k(\mathbf{x}, \mathbf{y}) = \exp(-\gamma \|\mathbf{x} \mathbf{y}\|_2^2)$
- ► Laplacian kernel  $k(\mathbf{x}, \mathbf{y}) = \exp(-\gamma \|\mathbf{x} \mathbf{y}\|_1)$
- ► Sigmoid kernel  $k(\mathbf{x}, \mathbf{y}) = \tanh(\alpha \mathbf{x}^{\mathsf{T}} \mathbf{y} + c)$

### Mercer/positive definite kernels

For a kernel  $k(\mathbf{x}, \mathbf{y})$ , and a set of features  $\mathbf{x}_1, \dots, \mathbf{x}_n$  define the so-called **Gram** matrix

$$\mathbf{K} = \begin{pmatrix} k(\mathbf{x}_1, \mathbf{x}_1) & \cdots & k(\mathbf{x}_1, \mathbf{x}_n) \\ \vdots & & \vdots \\ k(\mathbf{x}_n, \mathbf{x}_1) & \cdots & k(\mathbf{x}_n, \mathbf{x}_n) \end{pmatrix}$$

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**Note:** All kernels shown on the last slide except for the sigmoid kernel are positive definite.

# Importance of positive definite kernels

If the gram matrix is positive semi-definite there is an orthogonal matrix  $\mathbf{V} \in \mathbb{R}^{n \times n}$  and a diagonal matrix  $\mathbf{\Lambda} \in \mathbb{R}^{n \times n}$  such that

$$\mathbf{K} = \mathbf{V}^{\mathsf{T}} \mathbf{\Lambda} \mathbf{V}.$$

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Define  $\phi(\mathbf{x}_l) = \mathbf{\Lambda}^{1/2} \mathbf{V}^{(:,l)}$ , then

$$\mathbf{K}^{(l,k)} = \boldsymbol{\phi}(\mathbf{x}_l)^{\mathsf{T}} \boldsymbol{\phi}(\mathbf{x}_k)$$

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A result known as Mercer's theorem ensures that for every positive definite kernel  $k(\mathbf{x}, \mathbf{y})$  there is a mapping  $\phi$  from the feature space to some q-dimensional space (with  $q = \infty$  allowed) such that

$$k(\mathbf{x}, \mathbf{y}) = \boldsymbol{\phi}(\mathbf{x})^{\mathsf{T}} \boldsymbol{\phi}(\mathbf{y})$$

# **Example of Mercer's theorem**

Consider the polynomial kernel for  $\gamma=r=1$  and m=2 in a two-dimensional feature space

$$k(\mathbf{x}, \mathbf{y}) = (\mathbf{x}^{\mathsf{T}} \mathbf{y} + 1)^{2} = (1 + x_{1}y_{1} + x_{2}y_{2})^{2}$$
  
= 1 + 2x<sub>1</sub>y<sub>1</sub> + 2x<sub>2</sub>y<sub>2</sub> + (x<sub>1</sub>y<sub>1</sub>)<sup>2</sup> + (x<sub>2</sub>y<sub>2</sub>)<sup>2</sup> + 2x<sub>1</sub>y<sub>1</sub>x<sub>2</sub>y<sub>2</sub>

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Define

$$\phi(\mathbf{x}) = (1, \sqrt{2}x_1, \sqrt{2}x_2, x_1^2, x_2^2, \sqrt{2}x_1x_2)^{\mathsf{T}}$$

then

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then

$$k(\mathbf{x}, \mathbf{y}) = \boldsymbol{\phi}(\mathbf{x})^{\mathsf{T}} \boldsymbol{\phi}(\mathbf{y})$$

Using this kernel to measure similarity between **two-dimensional** feature vectors is therefore equivalent to working in a **six-dimensional** feature space.

# Advantages of using kernels

#### **Summary**

Using a positive definite kernel to measure the similarity between m-dimensional feature vectors is equivalent to

- 1. Using a (potentially non-linear) mapping to transform the feature vectors  $\mathbf{x}$  to a q-dimensional vector  $\phi(\mathbf{x})$
- 2. Using the Euclidean scalar product to measure similarity between transformed feature vectors  $\phi(\mathbf{x})$

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**Problem:**  $\phi(x)$  might be hard to compute.

The **kernel-trick** is to replace scalar products with kernel evaluations. Computations are then done implicitly in the higher-dimensional space of the  $\phi(\mathbf{x})$ , but all we need to do is evalute the kernel.

#### **Recap: PCA**

**Recall:** In PCA, the goal was to find the directions of maximum variance of the data matrix  $\mathbf{X} \in \mathbb{R}^{n \times p}$  by decomposing the covariance matrix

$$\widehat{\Sigma} = \frac{\mathbf{X}^{\mathsf{T}} \mathbf{X}}{n-1} = \mathbf{V} \mathbf{D} \mathbf{V}^{\mathsf{T}}$$

where  $\mathbf{V} \in \mathbb{R}^{p \times p}$  is orthgonal and  $\mathbf{D} \in \mathbb{R}^{p \times p}$  is diagonal.

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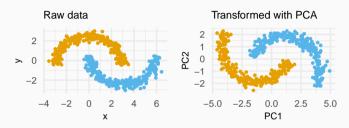
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- ▶ Dimension-reduction (e.g. for visualisation)
- ► Finding important directions in the data relevant to e.g. classification or clustering

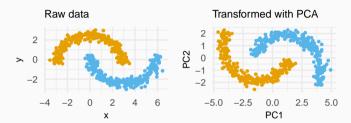
#### **Limitations of PCA**

#### PCA is linear and cannot uncover non-linear structures

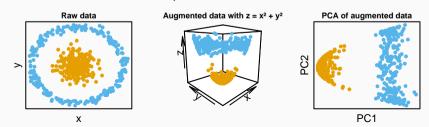


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#### **Augmentation of features** can help



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Given a positive definite kernel  $k(\mathbf{x}, \mathbf{y})$ , how can we perform PCA in the high-dimensional space of  $\phi(\mathbf{x})$ ?

# **Kernels and PCA (I)**

**Idea:** Use the **kernel-trick** to define augmentations implicitly and keep computations manageable.

Given a positive definite kernel  $k(\mathbf{x}, \mathbf{y})$ , how can we perform PCA in the high-dimensional space of  $\phi(\mathbf{x})$ ?

Assume we have access to  $\phi(\mathbf{x}_l)$  for  $l=1,\ldots,n$  and these transformed vectors are centred. Then we can perform PCA on

$$\widehat{\Sigma}^{\phi} = \frac{1}{n} \sum_{l=1}^{n} \phi(\mathbf{x}_l) \phi(\mathbf{x}_l)^{\top} = \mathbf{V} \mathbf{D} \mathbf{V}^{\top}$$

where  $\mathbf{v}_i$  are the principal component axes and  $d_i$  the corresponding variances.

# Kernels and PCA (II)

Note that

$$\widehat{\Sigma}^{\phi} \mathbf{v}_{i} = \frac{1}{n} \sum_{l=1}^{n} \phi(\mathbf{x}_{l}) \phi(\mathbf{x}_{l})^{\top} \mathbf{v}_{i} = d_{i} \mathbf{v}_{i}$$

$$\Leftrightarrow \mathbf{v}_{i} = \sum_{l=1}^{n} \frac{\phi(\mathbf{x}_{l})^{\top} \mathbf{v}_{i}}{d_{i} n} \phi(\mathbf{x}_{l}) = \sum_{l=1}^{n} \mathbf{a}_{i}^{(l)} \phi(\mathbf{x}_{l})$$

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Multiplying this presentation of  $\mathbf{v}_i$  from the left on both sides with  $\phi(\mathbf{x}_k)^{\mathsf{T}}$  leads to (for all  $k=1,\ldots,n$ )

$$d_i n \mathbf{a}_i^{(k)} = \boldsymbol{\phi}(\mathbf{x}_k)^{\mathsf{T}} \mathbf{v}_i = \sum_{l=1}^n \mathbf{a}_i^{(l)} \boldsymbol{\phi}(\mathbf{x}_k)^{\mathsf{T}} \boldsymbol{\phi}(\mathbf{x}_l) = \sum_{l=1}^n \mathbf{a}_i^{(l)} k(\mathbf{x}_k, \mathbf{x}_l)$$

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In total,  $\mathbf{a}_i$  is a solution to the eigenvalue problem

$$\mathbf{K}\mathbf{a}_i = d_i n \mathbf{a}_i$$

### **Kernels and PCA (III)**

The coefficients  $\mathbf{a}_i$  to determine the principal component directions  $\mathbf{v}_i$  in the space of the  $\phi(\mathbf{x}_i)$  can therefore be found by

ightharpoonup Solving the eigenvalue problem for  $\mathbf{K}\mathbf{a}_i=d_i n\mathbf{a}_i$  requiring that

$$1 = \mathbf{v}_i^{\mathsf{T}} \mathbf{v}_i = \sum_{l,k=1}^n \mathbf{a}_i^{(l)} \mathbf{a}_i^{(k)} \boldsymbol{\phi}(\mathbf{x}_l)^{\mathsf{T}} \boldsymbol{\phi}(\mathbf{x}_k) = \mathbf{a}_i^{\mathsf{T}} \mathbf{K} \mathbf{a}_i$$

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The i-th principal component projection of an arbitrary mapped feature vector  $\phi(\mathbf{x})$  is therefore

$$\boldsymbol{\phi}(\mathbf{x})^{\mathsf{T}}\mathbf{v}_i = \sum_{l=1}^n \mathbf{a}_i^{(l)} k(\mathbf{x}, \mathbf{x}_l)$$

This procedure is called kernel-PCA (kPCA).

# **Centring and kernel PCA**

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- ▶ In the derivation we look at scalar products  $\phi(\mathbf{x}_i)^T \phi(\mathbf{x}_l)$ . Centring in the implicit space leads to

$$\left(\phi(\mathbf{x}_{i}) - \frac{1}{n} \sum_{j=1}^{n} \phi(\mathbf{x}_{j})\right)^{\mathsf{T}} \left(\phi(\mathbf{x}_{l}) - \frac{1}{n} \sum_{j=1}^{n} \phi(\mathbf{x}_{j})\right) = \mathbf{K}^{(i,l)} - \frac{1}{n} \sum_{j=1}^{n} \mathbf{K}^{(i,j)} - \frac{1}{n} \sum_{j=1}^{n} \mathbf{K}^{(j,l)} + \frac{1}{n^{2}} \sum_{j=1}^{n} \sum_{m=1}^{n} \mathbf{K}^{(j,m)}$$

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▶ Using the **centring matrix**  $J = I_n - \frac{1}{n} \mathbf{1} \mathbf{1}^T$ , centring in the implicit space is equivalent to transforming K as

$$K' = JKJ$$

### General algorithm for kPCA

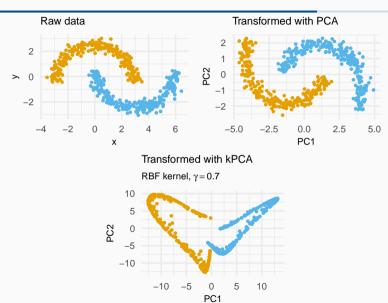
- 1. Choose a kernel  $k(\cdot, \cdot)$  and possible hyper-parameters
- 2. Compute the Gram matrix  $\mathbf{K} \in \mathbb{R}^{n \times n}$  for the data  $\mathbf{x}_1, \dots, \mathbf{x}_n$
- 3. Centre **K** using  $\mathbf{J} = \mathbf{I}_n \frac{1}{n} \mathbf{1} \mathbf{1}^\mathsf{T}$  to get

$$K' = JKJ$$

- 4. Perform a normal linear PCA on  $\mathbf{K}' = \mathbf{A} \mathbf{\Lambda} \mathbf{A}^{\mathsf{T}}$ .
- 5. The columns of **A** are the vectors  $\mathbf{a}_i$  and set  $d_i = \lambda_i/n$ .
- 6. The projection of the *l*-th observation onto the *i*-th principal component axis is computed as

$$\eta_l^{(i)} = \mathbf{K'}^{(l,:)} \mathbf{a}_i \in \mathbb{R}$$

# **Example: kPCA**



Kernel trick in other algorithms

# **Recap: Ridge regression**

Ridge regression solves the problem

$$\widehat{\pmb{\beta}} = \mathop{\arg\min}_{\pmb{\beta}} \|\mathbf{y} - \mathbf{X} \pmb{\beta}\|_2^2 + \lambda \|\pmb{\beta}\|_2^2$$

with analytical solution

$$\widehat{\boldsymbol{\beta}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X} + \lambda \mathbf{I}_p)^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}.$$

The kernel trick requires scalar products between feature vectors. Note that

$$(\mathbf{X}\mathbf{X}^{\mathsf{T}})^{(i,j)} = \mathbf{x}_i^{\mathsf{T}}\mathbf{x}_j$$

but here we have  $\mathbf{X}^{\mathsf{T}}\mathbf{X}$ .

Assume that matrices  $\mathbf{A} \in \mathbb{R}^{p \times p}$  and  $\mathbf{C} \in \mathbb{R}^{n \times n}$  are invertible and let  $\mathbf{U} \in \mathbb{R}^{p \times n}$  and  $\mathbf{V} \in \mathbb{R}^{n \times p}$ . The Woodbury matrix identity then holds

$$(A + UCV)^{-1} = A^{-1} - A^{-1}U(C^{-1} + VA^{-1}U)^{-1}VA^{-1}$$

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$$(\mathbf{X}^{\top}\mathbf{X} + \lambda \mathbf{I}_p)^{-1} \mathbf{X}^{\top} = \left(\frac{1}{\lambda}\mathbf{I}_p - \frac{1}{\lambda}\mathbf{I}_p \mathbf{X}^{\top} \left(\mathbf{I}_n + \mathbf{X}\frac{1}{\lambda}\mathbf{I}_p \mathbf{X}^{\top}\right)^{-1} \mathbf{X}\frac{1}{\lambda}\mathbf{I}_p\right) \mathbf{X}^{\top}$$

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$$\begin{split} \left(\mathbf{X}^{\mathsf{T}}\mathbf{X} + \lambda\mathbf{I}_{p}\right)^{-1}\mathbf{X}^{\mathsf{T}} &= \left(\frac{1}{\lambda}\mathbf{I}_{p} - \frac{1}{\lambda}\mathbf{I}_{p}\mathbf{X}^{\mathsf{T}}\left(\mathbf{I}_{n} + \mathbf{X}\frac{1}{\lambda}\mathbf{I}_{p}\mathbf{X}^{\mathsf{T}}\right)^{-1}\mathbf{X}\frac{1}{\lambda}\mathbf{I}_{p}\right)\mathbf{X}^{\mathsf{T}} \\ &= \frac{1}{\lambda}\mathbf{X}^{\mathsf{T}}\left(\mathbf{I}_{n} - \left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\mathsf{T}}\right)^{-1}\mathbf{X}\mathbf{X}^{\mathsf{T}}\right) \\ &= \frac{1}{\lambda}\mathbf{X}^{\mathsf{T}}\left(\left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\mathsf{T}}\right)^{-1}\left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\mathsf{T}}\right) - \left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\mathsf{T}}\right)^{-1}\mathbf{X}\mathbf{X}^{\mathsf{T}}\right) \\ &= \frac{1}{\lambda}\mathbf{X}^{\mathsf{T}}\left(\left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\mathsf{T}}\right)^{-1}\left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\mathsf{T}} - \mathbf{X}\mathbf{X}^{\mathsf{T}}\right)\right) \end{split}$$

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For a data matrix  $\mathbf{X} \in \mathbb{R}^{n \times p}$ , let  $\mathbf{U} = \mathbf{X}^{\mathsf{T}}$ ,  $\mathbf{V} = \mathbf{X}$ ,  $\mathbf{A} = \lambda \mathbf{I}_p$  for  $\lambda > 0$ , and  $\mathbf{C} = \mathbf{I}_n$ .

$$\begin{split} \left(\mathbf{X}^{\top}\mathbf{X} + \lambda\mathbf{I}_{p}\right)^{-1}\mathbf{X}^{\top} &= \left(\frac{1}{\lambda}\mathbf{I}_{p} - \frac{1}{\lambda}\mathbf{I}_{p}\mathbf{X}^{\top}\left(\mathbf{I}_{n} + \mathbf{X}\frac{1}{\lambda}\mathbf{I}_{p}\mathbf{X}^{\top}\right)^{-1}\mathbf{X}\frac{1}{\lambda}\mathbf{I}_{p}\right)\mathbf{X}^{\top} \\ &= \frac{1}{\lambda}\mathbf{X}^{\top}\left(\mathbf{I}_{n} - \left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\top}\right)^{-1}\mathbf{X}\mathbf{X}^{\top}\right) \\ &= \frac{1}{\lambda}\mathbf{X}^{\top}\left(\left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\top}\right)^{-1}\left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\top}\right) - \left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\top}\right)^{-1}\mathbf{X}\mathbf{X}^{\top}\right) \\ &= \frac{1}{\lambda}\mathbf{X}^{\top}\left(\left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\top}\right)^{-1}\left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\top} - \mathbf{X}\mathbf{X}^{\top}\right)\right) \\ &= \mathbf{X}^{\top}\left(\lambda\mathbf{I}_{n} + \mathbf{X}\mathbf{X}^{\top}\right)^{-1} \end{split}$$

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$$\widehat{\boldsymbol{\beta}} = \mathbf{X}^{\mathsf{T}} (\mathbf{X} \mathbf{X}^{\mathsf{T}} + \lambda \mathbf{I}_n)^{-1} \mathbf{y}.$$

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Using the dual variables, computed with a chosen kernel, as weights for the observations to compute the primal variables is called **kernel ridge regression**.

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Standard ridge regression is recovered when using the linear kernel

$$k(\mathbf{x}, \mathbf{y}) = \mathbf{x}^{\mathsf{T}} \mathbf{y}.$$

# Prediction in kernel ridge regression

In normal ridge ression, we predict for unseen test data  ${\bf x}$  as

$$\widehat{f}(\mathbf{x}) = \widehat{\boldsymbol{\beta}}^{\mathsf{T}} \mathbf{x} = \sum_{l=1}^{n} \widehat{\boldsymbol{\alpha}}^{(l)} \mathbf{x}_{l}^{\mathsf{T}} \mathbf{x}$$

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Using the **kernel trick** and replacing scalar products with kernel evaluations leads to

$$\widehat{f}(\mathbf{x}) = \sum_{l=1}^{n} \widehat{\alpha}^{(l)} k(\mathbf{x}_l, \mathbf{x})$$

for kernel ridge regression.

#### Take-home message

- ► Kernels in combination with Mercer's theorem are a powerful tool to make high-dimensional computation manageable
- ▶ kPCA is a first example demonstrating the power of kernels
- ► The kernel trick can also be used in other established methods like ridge regression

## KRR and gradient descent

$$y = K\alpha + \epsilon$$

$$L(y, \alpha, K) = \frac{1}{2}||y - K\alpha||^2 + \lambda \alpha' K\alpha$$