Recorded at time: 1604586225.513 panda\_link0 Broadcaster: /robot\_state\_publisher Average rate: 30.204 Hz Most recent transform: 1604586225.471 (0.042 sec old) Buffer length: 4.900 sec panda\_link1 Broadcaster: /robot\_state\_publisher Average rate: 30.204 Hz Most recent transform: 1604586225.471 ( 0.042 sec old) Buffer length: 4.900 sec panda\_link2 Broadcaster: /robot\_state\_publisher Average rate: 30.204 Hz Most recent transform: 1604586225.471 ( 0.042 sec old) Buffer length: 4.900 sec panda\_link3 Broadcaster: /robot\_state\_publisher Average rate: 30.204 Hz Most recent transform: 1604586225.471 ( 0.042 sec old) Buffer length: 4.900 sec panda\_link4 Broadcaster: /robot\_state\_publisher Average rate: 30.204 Hz Most recent transform: 1604586225.471 (0.042 sec old) Buffer length: 4.900 sec panda\_link5 Broadcaster: /robot\_state\_publisher Average rate: 30.204 Hz Most recent transform: 1604586225.471 (0.042 sec old) Buffer length: 4.900 sec panda\_link6 Broadcaster: /robot\_state\_publisher Average rate: 30.204 Hz Most recent transform: 1604586225.471 ( 0.042 sec old) Buffer length: 4.900 sec panda\_link7 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1604586225.513 sec old) Most recent transform: 0.000 ( 1604586225.513 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec panda\_fake\_probe panda\_link8 Broadcaster: /robot\_state\_publisher Broadcaster: /franka\_control Average rate: 29.611 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1604586225.513 sec old) Most recent transform: 1604586225.481 (0.032 sec old) Buffer length: 0.000 sec Buffer length: 4.897 sec panda\_ar\_marker panda\_EE Broadcaster: /franka\_control Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 29.611 Hz Most recent transform: 0.000 ( 1604586225.513 sec old) Most recent transform: 1604586225.481 (0.032 sec old) Buffer length: 0.000 sec Buffer length: 4.897 sec panda\_K panda\_ar\_camera\_frame

view\_frames Result