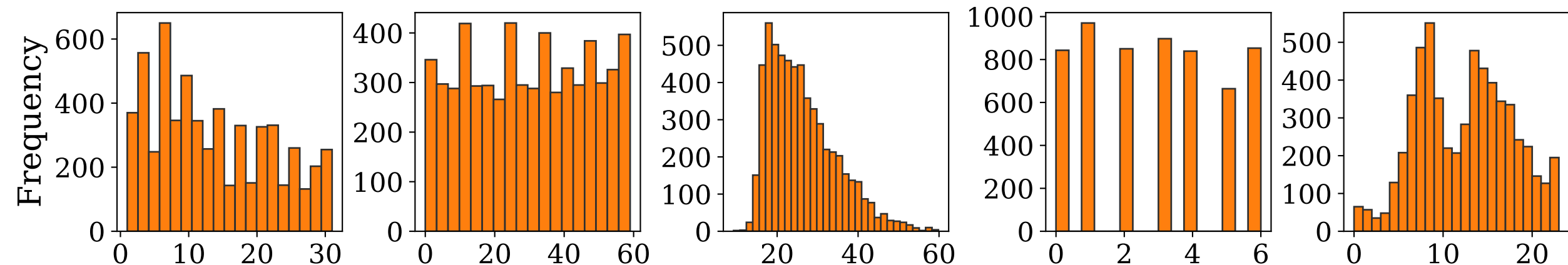


## Distribution of filtered features (not gaussianized)



## Distribution of filtered and partially gaussianized features

