

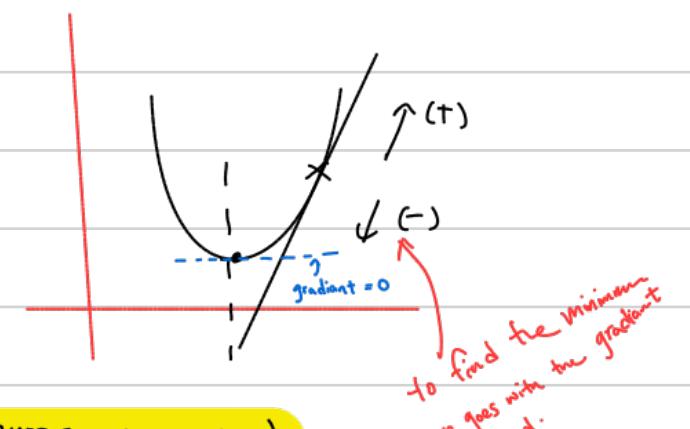
Tenes ← data contours
Autograd ← Numerical diffi - -
Optimum ← Optimizer

Find the optimal

$$f(w) = w^2$$

$$f'(w) = 2w$$

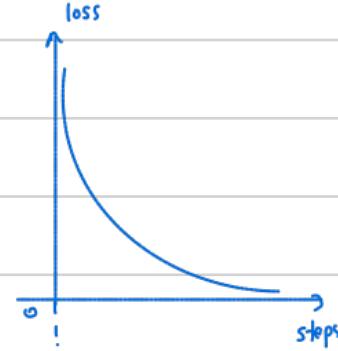
$$\text{moving down hill} \Rightarrow w_{\text{new}} = w - \eta \cdot f'(w) \\ = w - \eta(2w)$$



* use a threshold to find the minimal point.

Why we not taking gradient = 0? (points may be overfitted / There can be a function which goes through all points)

learning process -



```
# -----
# starting point
w = -3.0
lr = 0.3
# learning rate
# number of iterations
steps = 25
thresh = 0.001

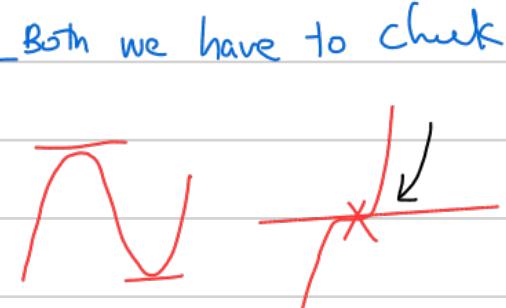
for i in range(steps):
    gradient = grad_loss(w)
    w_next = w - lr * gradient

    # Plot the frame
    plot_step(w, w_next, gradient)

# STUDENT TASK: Add your stopping criteria here
# =====
# OPTION CORRECT
if (abs(w_next-w) < thresh) and (abs(gradient) < thresh):
    print(i)
    print("Stopping criteria met!")
    break

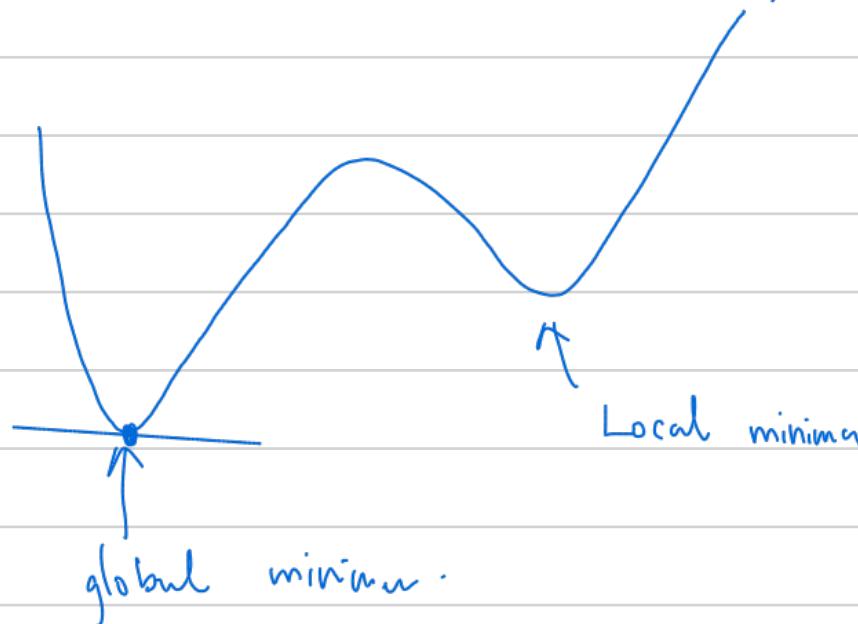
# Update w
w = w_next

time.sleep(0.4) # smooth pacing
```



Importance of the learning Rate

"changing Learning rate we can find the global minima"



pytorch optimizers

SGD (Stochastic Gradient Descent)

Vanilla gradient Desent SGD with (batch size = full-dataset)

Mini batch SGD

Momentum.

Adam.

RM Sprop

Adagrad.

} automatical track all parameters
update using gradients
apply learning rate scaling &
other things