## Correlaciones relevantes (positivas: +, negativas: -)

* (-): Cuanto mayor es el torque promedio y peak alcanzadas durante la prueba isocinética (tanto para cuádriceps como para isquiotibiales), menor es la actividad muscular evaluada durante la electromiografía en las tres ventanas de medición.
* (-): Una mayor variabilidad (medida como la desviación estándar) del torque del isquiotibial izquierdo se asocia a un menor índice de uso de los brazos en las pruebas de saltos.
* (-): El grado de rodilla al cual ocurre el torque peak en el cuádriceps es inversamente proporcional a la actividad muscular evaluada mediante electromiografía obtenida en la ventana de medición inicial.
* (-): Una mayor altura en el squat jump se asocia a menor actividad muscular en la primera ventana de medición de electromiografía
* (+): Un mayor índice de utilización de brazo se asocia a una mayor actividad electromiográfica en las tres ventanas de medición.
* (+): El grado de rodilla al cual ocurre el torque peak (normalizado) en isquiotibial derecho, se asocia a una mayor altura en el SJ y a una mayor potencia peak en el CMJ
* (+): El torque peak de cuádriceps se relacionó con la potencia media y peak alcanzada en CMJ, y Abalakov.
* (+): El trabajo por kilogramo (normalizado) de cuádriceps derecho se relaciona a una mayor tasa de desarrollo de fuerza en SJ y a una mayor fuerza peak en el abalakov.
* (+): La potencia de cuádriceps (evaluada de la isocinética), se asocia a la potencia en los tres saltos (CMJ, SJ y ABK).
* (+): Un mayor tiempo hasta el torque peak (normalizado) en el cuádricpes e isquiotibiales se asocia a una mayor altura en el SJ

## Correlation Matrix (spearman-method)

* iso\_\*: mediciones de isocinética
* quad\_\*: cuádriceps
* isquio\_\*: isquiotibiales
* deg\_at\_peak\_\*: grado al cual ocurre el torque peak
* sd\_torque\_\*: desviación estándar del torque
* work\_\*: trabajo en joules
* \*\_raw: variable sin normalizar
* \*\_norm: variable normalizada
* time\_to\_peak\_\*: tiempo en segundos hasta el torque peak
* jump\_\*: mediciones de salto
* emg\_\*: mediciones de electromiografía

Nota: Se muestran solo aquellas relaciones significativas al 5%

Correlations. p-value adjustment method: none; Observations: 7-11.

| Parameter1 | Parameter2 | rho | 95% CI | S | p |
| --- | --- | --- | --- | --- | --- |
| iso\_mean\_torque\_quad\_der\_raw | emg\_mean\_1 | -1.00 | [-1.00, -1.00] | 112.00 | < .001\*\*\* |
| iso\_mean\_torque\_quad\_der\_raw | emg\_mean\_2 | -0.96 | [-1.00, -0.76] | 110.00 | < .001\*\*\* |
| iso\_mean\_torque\_quad\_der\_raw | emg\_median\_3 | -0.96 | [-1.00, -0.76] | 110.00 | < .001\*\*\* |
| iso\_peak\_torque\_isquio\_der\_raw | emg\_mean\_2 | -0.96 | [-1.00, -0.76] | 110.00 | < .001\*\*\* |
| iso\_peak\_torque\_isquio\_der\_raw | emg\_median\_3 | -0.96 | [-1.00, -0.76] | 110.00 | < .001\*\*\* |
| iso\_mean\_torque\_isquio\_der\_raw | emg\_mean\_2 | -0.96 | [-1.00, -0.76] | 110.00 | < .001\*\*\* |
| iso\_mean\_torque\_isquio\_der\_raw | emg\_median\_3 | -0.96 | [-1.00, -0.76] | 110.00 | < .001\*\*\* |
| iso\_mean\_torque\_quad\_der\_raw | emg\_mean\_3 | -0.93 | [-0.99, -0.56] | 108.00 | 0.003\*\* |
| iso\_peak\_torque\_isquio\_der\_raw | emg\_mean\_3 | -0.93 | [-0.99, -0.56] | 108.00 | 0.003\*\* |
| iso\_mean\_torque\_isquio\_der\_raw | emg\_mean\_3 | -0.93 | [-0.99, -0.56] | 108.00 | 0.003\*\* |
| iso\_sd\_torque\_isquio\_izq\_raw | jump\_ind\_arm\_usage | -0.90 | [-0.99, -0.44] | 106.45 | 0.006\*\* |
| iso\_peak\_torque\_quad\_der\_raw | emg\_mean\_1 | -0.89 | [-0.99, -0.40] | 106.00 | 0.007\*\* |
| iso\_peak\_torque\_isquio\_der\_raw | emg\_mean\_1 | -0.89 | [-0.99, -0.40] | 106.00 | 0.007\*\* |
| iso\_mean\_torque\_isquio\_der\_raw | emg\_mean\_1 | -0.89 | [-0.99, -0.40] | 106.00 | 0.007\*\* |
| iso\_deg\_at\_peak\_quad\_izq\_norm | emg\_median\_1 | -0.89 | [-0.98, -0.40] | 105.90 | 0.007\*\* |
| iso\_peak\_torque\_quad\_der\_raw | emg\_mean\_2 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_peak\_torque\_quad\_der\_raw | emg\_median\_3 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_peak\_torque\_quad\_der\_norm | emg\_mean\_3 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_mean\_torque\_quad\_der\_raw | emg\_median\_1 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_mean\_torque\_quad\_der\_raw | emg\_median\_2 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_mean\_torque\_quad\_der\_raw | emg\_peak\_2 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_mean\_torque\_quad\_der\_raw | emg\_peak\_3 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_mean\_torque\_quad\_der\_norm | emg\_mean\_3 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_work\_quad\_izq\_norm | emg\_peak\_1 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_peak\_torque\_isquio\_der\_raw | emg\_median\_2 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_peak\_torque\_isquio\_der\_raw | emg\_peak\_2 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_mean\_torque\_isquio\_der\_raw | emg\_median\_2 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_mean\_torque\_isquio\_der\_raw | emg\_peak\_2 | -0.86 | [-0.98, -0.27] | 104.00 | 0.014\* |
| iso\_deg\_at\_peak\_quad\_izq\_norm | emg\_mean\_3 | -0.84 | [-0.98, -0.20] | 102.84 | 0.019\* |
| iso\_sd\_torque\_isquio\_izq\_raw | emg\_median\_1 | -0.83 | [-0.98, -0.17] | 102.42 | 0.021\* |
| iso\_peak\_torque\_quad\_der\_raw | emg\_median\_1 | -0.82 | [-0.97, -0.15] | 102.00 | 0.023\* |
| iso\_peak\_torque\_quad\_der\_norm | emg\_mean\_2 | -0.82 | [-0.97, -0.15] | 102.00 | 0.023\* |
| iso\_peak\_torque\_quad\_der\_norm | emg\_median\_3 | -0.82 | [-0.97, -0.15] | 102.00 | 0.023\* |
| iso\_mean\_torque\_quad\_der\_raw | jump\_ind\_arm\_usage | -0.82 | [-0.97, -0.15] | 102.00 | 0.023\* |
| iso\_mean\_torque\_quad\_der\_norm | emg\_peak\_3 | -0.82 | [-0.97, -0.15] | 102.00 | 0.023\* |
| iso\_time\_to\_peak\_quad\_izq\_norm | jump\_cmj\_time\_to\_peak | -0.82 | [-0.97, -0.15] | 102.00 | 0.023\* |
| iso\_power\_per\_kg\_isquio\_der\_norm | emg\_mean\_2 | -0.82 | [-0.97, -0.15] | 102.00 | 0.023\* |
| iso\_power\_per\_kg\_isquio\_der\_norm | emg\_median\_3 | -0.82 | [-0.97, -0.15] | 102.00 | 0.023\* |
| iso\_deg\_at\_peak\_quad\_izq\_norm | jump\_ind\_arm\_usage | -0.80 | [-0.97, -0.09] | 100.81 | 0.031\* |
| iso\_mean\_torque\_quad\_der\_norm | emg\_mean\_2 | -0.79 | [-0.97, -0.05] | 100.00 | 0.036\* |
| iso\_mean\_torque\_quad\_der\_norm | emg\_median\_2 | -0.79 | [-0.97, -0.05] | 100.00 | 0.036\* |
| iso\_mean\_torque\_quad\_der\_norm | emg\_peak\_2 | -0.79 | [-0.97, -0.05] | 100.00 | 0.036\* |
| iso\_mean\_torque\_quad\_der\_norm | emg\_median\_3 | -0.79 | [-0.97, -0.05] | 100.00 | 0.036\* |
| iso\_work\_per\_kg\_quad\_izq\_norm | emg\_peak\_1 | -0.79 | [-0.97, -0.05] | 100.00 | 0.036\* |
| iso\_peak\_torque\_isquio\_der\_norm | emg\_mean\_3 | -0.79 | [-0.97, -0.05] | 100.00 | 0.036\* |
| iso\_power\_isquio\_der\_norm | emg\_mean\_2 | -0.79 | [-0.97, -0.05] | 100.00 | 0.036\* |
| iso\_power\_isquio\_der\_norm | emg\_median\_3 | -0.79 | [-0.97, -0.05] | 100.00 | 0.036\* |
| iso\_peak\_torque\_isquio\_izq\_raw | emg\_median\_1 | -0.79 | [-0.97, -0.05] | 100.00 | 0.036\* |
| iso\_mean\_torque\_isquio\_izq\_raw | emg\_mean\_1 | -0.79 | [-0.97, -0.05] | 100.00 | 0.036\* |
| iso\_deg\_at\_peak\_quad\_izq\_norm | emg\_mean\_1 | -0.78 | [-0.97, -0.04] | 99.79 | 0.038\* |
| iso\_deg\_at\_peak\_quad\_izq\_norm | emg\_peak\_3 | -0.78 | [-0.97, -0.04] | 99.79 | 0.038\* |
| jump\_sj\_altura\_m | emg\_median\_1 | -0.69 | [-0.92, -0.14] | 372.00 | 0.019\* |
| jump\_ind\_arm\_usage | emg\_mean\_2 | 0.61 | [-0.01, 0.89] | 86.00 | 0.047\* |
| jump\_ind\_arm\_usage | emg\_median\_3 | 0.61 | [-0.01, 0.89] | 86.00 | 0.047\* |
| jump\_ind\_arm\_usage | emg\_peak\_3 | 0.68 | [ 0.12, 0.91] | 70.00 | 0.021\* |
| jump\_ind\_arm\_usage | emg\_peak\_2 | 0.69 | [ 0.14, 0.92] | 68.00 | 0.019\* |
| jump\_ind\_arm\_usage | emg\_mean\_1 | 0.75 | [ 0.26, 0.94] | 54.00 | 0.007\*\* |
| iso\_deg\_at\_peak\_isquio\_der\_norm | jump\_cmj\_power\_peak | 0.76 | [-0.02, 0.96] | 13.62 | 0.049\* |
| iso\_deg\_at\_peak\_isquio\_der\_norm | jump\_sj\_altura\_m | 0.76 | [-0.02, 0.96] | 13.62 | 0.049\* |
| iso\_deg\_at\_peak\_quad\_izq\_norm | jump\_sj\_altura\_m | 0.78 | [ 0.04, 0.97] | 12.21 | 0.038\* |
| iso\_peak\_torque\_quad\_der\_raw | jump\_abkv\_power\_mean | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_mean\_torque\_quad\_der\_raw | jump\_cmj\_power\_peak | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_mean\_torque\_quad\_der\_raw | jump\_abkv\_power\_mean | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_work\_per\_kg\_quad\_der\_norm | jump\_sj\_rdf\_mean | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_work\_per\_kg\_quad\_der\_norm | jump\_abkv\_fuerza\_peak | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_power\_quad\_der\_norm | jump\_abkv\_power\_mean | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_peak\_torque\_quad\_izq\_raw | jump\_cmj\_power\_peak | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_time\_to\_peak\_quad\_izq\_norm | jump\_cmj\_rdf\_mean | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_power\_quad\_izq\_norm | jump\_cmj\_fuerza\_peak | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_power\_per\_kg\_quad\_izq\_norm | jump\_sj\_fuerza\_peak | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_power\_per\_kg\_quad\_izq\_norm | jump\_abkv\_fuerza\_peak | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_work\_isquio\_der\_norm | jump\_sj\_fuerza\_peak | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_work\_per\_kg\_isquio\_der\_norm | jump\_ind\_elasticidad | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_work\_per\_kg\_isquio\_der\_norm | jump\_sj\_power\_mean | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_power\_isquio\_der\_norm | jump\_cmj\_power\_peak | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_power\_isquio\_der\_norm | jump\_sj\_rdf\_mean | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_mean\_torque\_isquio\_izq\_raw | jump\_cmj\_fuerza\_peak | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_time\_to\_peak\_isquio\_izq\_norm | jump\_sj\_rdf\_peak | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_time\_to\_peak\_isquio\_izq\_norm | jump\_abkv\_rdf\_mean | 0.79 | [ 0.05, 0.97] | 12.00 | 0.036\* |
| iso\_work\_isquio\_izq\_norm | jump\_cmj\_power\_peak | 0.79 | [ 0.07, 0.97] | 11.60 | 0.033\* |
| jump\_ind\_arm\_usage | emg\_median\_1 | 0.81 | [ 0.39, 0.95] | 42.00 | 0.003\*\* |
| iso\_time\_to\_peak\_quad\_der\_norm | jump\_cmj\_altura\_m | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_power\_quad\_der\_norm | jump\_sj\_fuerza\_peak | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_peak\_torque\_quad\_izq\_raw | jump\_abkv\_power\_mean | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_mean\_torque\_quad\_izq\_raw | jump\_sj\_rdf\_mean | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_mean\_torque\_quad\_izq\_norm | jump\_cmj\_power\_mean | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_time\_to\_peak\_quad\_izq\_norm | jump\_sj\_time\_to\_peak | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_work\_quad\_izq\_norm | jump\_abkv\_power\_mean | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_power\_quad\_izq\_norm | jump\_abkv\_fuerza\_peak | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_peak\_torque\_isquio\_der\_raw | jump\_sj\_fuerza\_peak | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_mean\_torque\_isquio\_der\_raw | jump\_sj\_fuerza\_peak | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_mean\_torque\_isquio\_der\_norm | jump\_cmj\_rdf\_mean | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_mean\_torque\_isquio\_izq\_raw | jump\_sj\_rdf\_mean | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_time\_to\_peak\_isquio\_izq\_norm | jump\_cmj\_altura\_m | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_power\_isquio\_izq\_norm | jump\_cmj\_power\_mean | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_power\_isquio\_izq\_norm | jump\_sj\_fuerza\_peak | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_power\_isquio\_izq\_norm | jump\_abkv\_fuerza\_peak | 0.82 | [ 0.15, 0.97] | 10.00 | 0.023\* |
| iso\_deg\_at\_peak\_quad\_der\_norm | jump\_sj\_rdf\_peak | 0.85 | [ 0.23, 0.98] | 8.57 | 0.016\* |
| iso\_sd\_torque\_isquio\_izq\_raw | jump\_abkv\_power\_peak | 0.85 | [ 0.23, 0.98] | 8.57 | 0.016\* |
| iso\_peak\_torque\_quad\_der\_raw | jump\_sj\_rdf\_mean | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_mean\_torque\_quad\_der\_raw | jump\_sj\_fuerza\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_peak\_torque\_quad\_izq\_raw | jump\_sj\_rdf\_mean | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_mean\_torque\_quad\_izq\_raw | jump\_cmj\_fuerza\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_mean\_torque\_quad\_izq\_raw | jump\_abkv\_fuerza\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_work\_per\_kg\_quad\_izq\_norm | jump\_sj\_power\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_power\_quad\_izq\_norm | jump\_sj\_fuerza\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_power\_quad\_izq\_norm | jump\_sj\_rdf\_mean | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_power\_per\_kg\_quad\_izq\_norm | jump\_cmj\_fuerza\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_peak\_torque\_isquio\_der\_raw | jump\_sj\_power\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_mean\_torque\_isquio\_der\_raw | jump\_sj\_power\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_sd\_torque\_isquio\_der\_raw | jump\_cmj\_power\_mean | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_work\_isquio\_der\_norm | jump\_sj\_power\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_power\_per\_kg\_isquio\_der\_norm | jump\_sj\_fuerza\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_power\_per\_kg\_isquio\_der\_norm | jump\_sj\_power\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_peak\_torque\_isquio\_izq\_raw | jump\_sj\_fuerza\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_mean\_torque\_isquio\_izq\_raw | jump\_cmj\_power\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_power\_isquio\_izq\_norm | jump\_cmj\_power\_peak | 0.86 | [ 0.27, 0.98] | 8.00 | 0.014\* |
| iso\_sd\_torque\_isquio\_izq\_raw | jump\_cmj\_altura\_m | 0.88 | [ 0.36, 0.98] | 6.56 | 0.008\*\* |
| iso\_peak\_torque\_quad\_der\_raw | jump\_abkv\_fuerza\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_power\_per\_kg\_quad\_der\_norm | jump\_abkv\_fuerza\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_peak\_torque\_quad\_izq\_raw | jump\_sj\_fuerza\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_time\_to\_peak\_quad\_izq\_norm | jump\_cmj\_altura\_m | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_work\_quad\_izq\_norm | jump\_sj\_power\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_work\_quad\_izq\_norm | jump\_abkv\_fuerza\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_peak\_torque\_isquio\_der\_raw | jump\_cmj\_fuerza\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_mean\_torque\_isquio\_der\_raw | jump\_cmj\_fuerza\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_work\_isquio\_der\_norm | jump\_abkv\_fuerza\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_work\_per\_kg\_isquio\_der\_norm | jump\_sj\_power\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_power\_isquio\_der\_norm | jump\_cmj\_fuerza\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_power\_isquio\_der\_norm | jump\_abkv\_fuerza\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_peak\_torque\_isquio\_izq\_raw | jump\_cmj\_power\_peak | 0.89 | [ 0.40, 0.99] | 6.00 | 0.007\*\* |
| iso\_work\_isquio\_izq\_norm | jump\_sj\_rdf\_mean | 0.90 | [ 0.44, 0.99] | 5.55 | 0.006\*\* |
| iso\_peak\_torque\_quad\_der\_raw | jump\_cmj\_power\_peak | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_peak\_torque\_quad\_izq\_raw | jump\_abkv\_fuerza\_peak | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_peak\_torque\_quad\_izq\_norm | jump\_cmj\_power\_mean | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_mean\_torque\_quad\_izq\_raw | jump\_sj\_fuerza\_peak | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_work\_per\_kg\_quad\_izq\_norm | jump\_sj\_power\_mean | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_time\_to\_peak\_isquio\_der\_norm | jump\_sj\_altura\_m | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_work\_isquio\_der\_norm | jump\_cmj\_fuerza\_peak | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_work\_per\_kg\_isquio\_der\_norm | jump\_cmj\_fuerza\_peak | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_peak\_torque\_isquio\_izq\_raw | jump\_abkv\_fuerza\_peak | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_mean\_torque\_isquio\_izq\_raw | jump\_sj\_fuerza\_peak | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_work\_per\_kg\_isquio\_izq\_norm | jump\_cmj\_power\_mean | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_power\_isquio\_izq\_norm | jump\_sj\_rdf\_mean | 0.93 | [ 0.56, 0.99] | 4.00 | 0.003\*\* |
| iso\_work\_isquio\_izq\_norm | jump\_cmj\_power\_mean | 0.94 | [ 0.61, 0.99] | 3.53 | 0.002\*\* |
| iso\_peak\_torque\_quad\_der\_raw | jump\_sj\_fuerza\_peak | 0.96 | [ 0.76, 1.00] | 2.00 | < .001\*\*\* |
| iso\_time\_to\_peak\_quad\_der\_norm | jump\_sj\_altura\_m | 0.96 | [ 0.76, 1.00] | 2.00 | < .001\*\*\* |
| iso\_work\_quad\_der\_norm | jump\_abkv\_fuerza\_peak | 0.96 | [ 0.76, 1.00] | 2.00 | < .001\*\*\* |
| iso\_power\_isquio\_der\_norm | jump\_sj\_fuerza\_peak | 0.96 | [ 0.76, 1.00] | 2.00 | < .001\*\*\* |
| iso\_mean\_torque\_isquio\_izq\_raw | jump\_abkv\_fuerza\_peak | 0.96 | [ 0.76, 1.00] | 2.00 | < .001\*\*\* |
| iso\_power\_quad\_der\_norm | jump\_abkv\_fuerza\_peak | 1.00 | [ 1.00, 1.00] | 1.24e-14 | < .001\*\*\* |
| iso\_power\_per\_kg\_isquio\_der\_norm | jump\_cmj\_fuerza\_peak | 1.00 | [ 1.00, 1.00] | 1.24e-14 | < .001\*\*\* |