

Screening Two Types

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Here: screening two types

- ▶ Impose only quasilinearity

Results

A general characterization of optimal mechanisms

Two applications

- ① Bundling
- ② Vertical and horizontal differentiation

Model

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Two types $\{t_1, t_2\}$, probabilities $1 - q, q$

A set of “alternatives” A

Value $v(t, a)$, $v(t, 0) = 0$

► Payoff $v(t, a) - p$

Cost $c(a)$ normalized to zero normalization

Goal: profit-maximizing IC&IR mechanisms

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To guarantee existence: $\{(v(t_1, a), v(t_2, a))\}_{a \in A}$ closed and bounded.

Application 1: Bundling

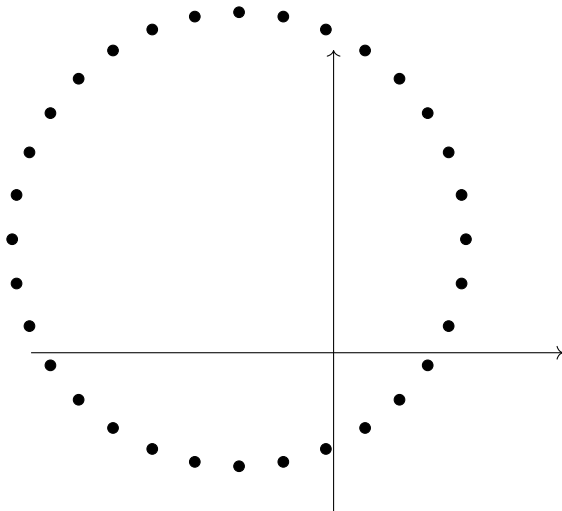
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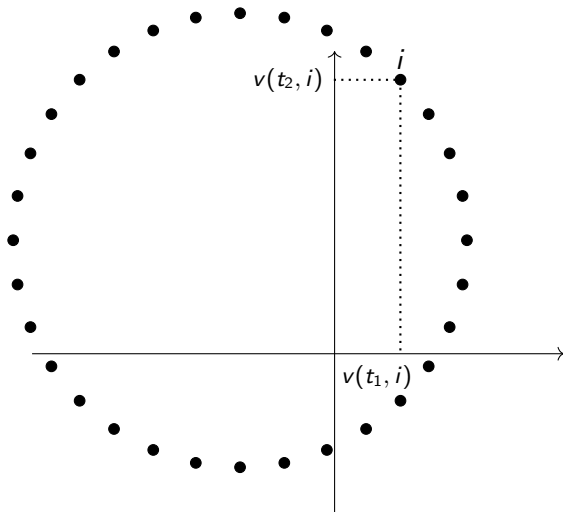
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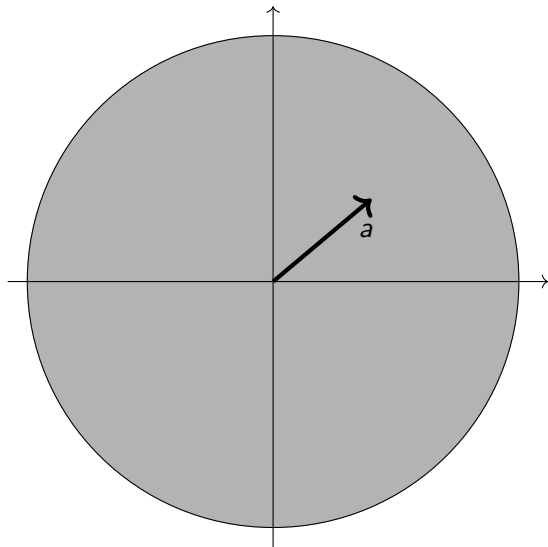
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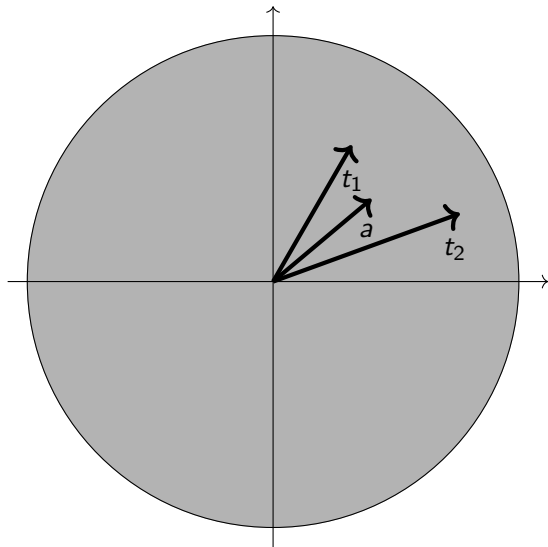
Application 2: Vertical and Horizontal differentiation

A = all points within the circle.



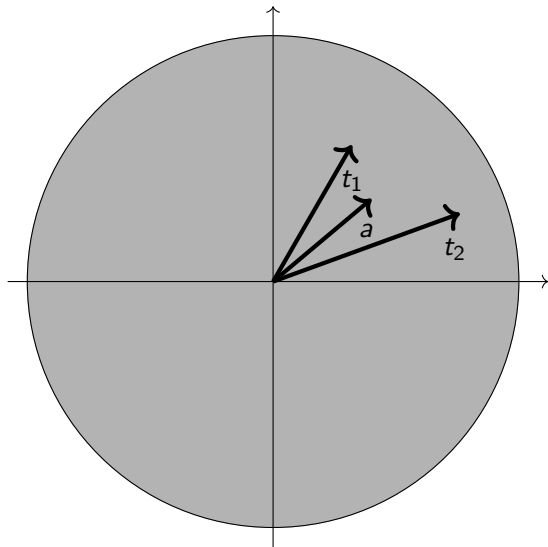
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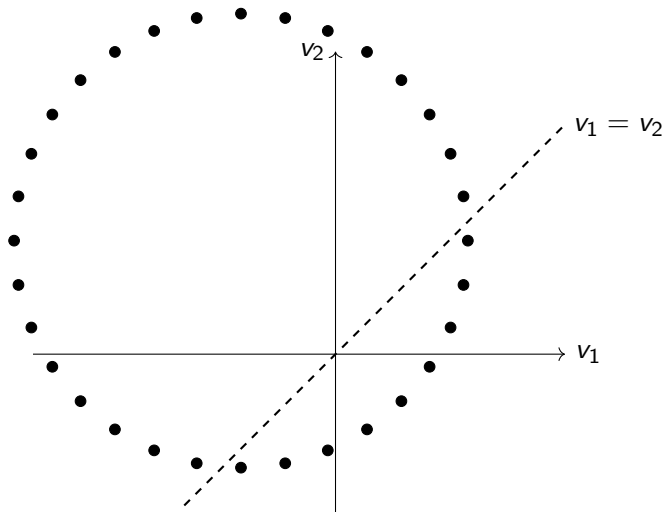
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more

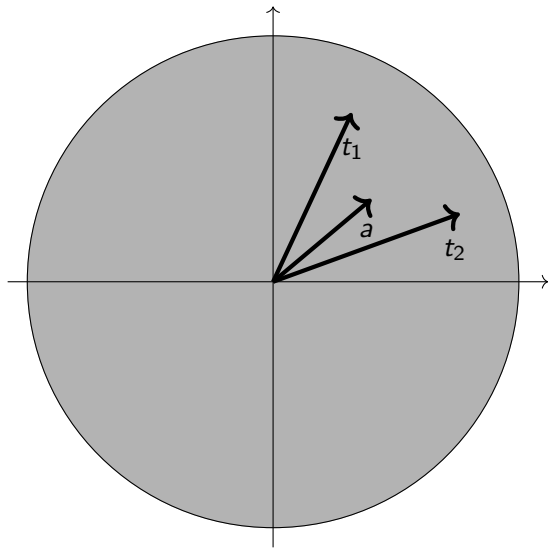
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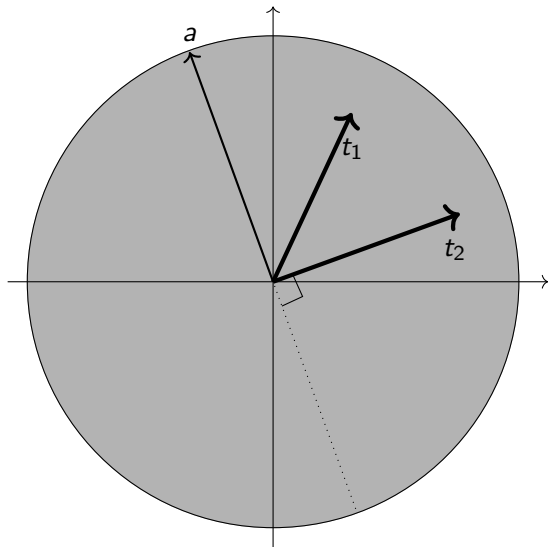
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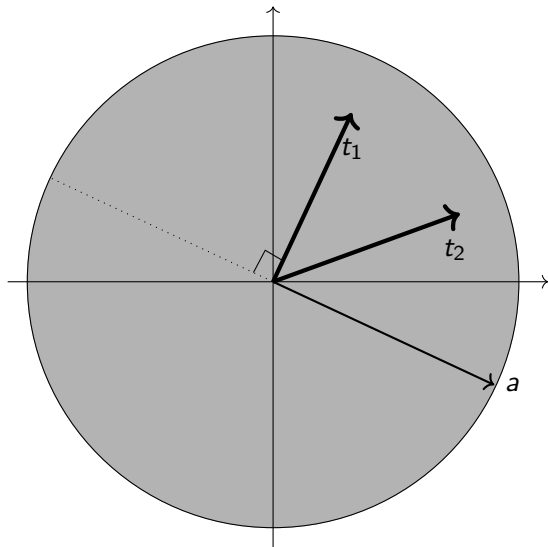
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Back to General Model

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Consider the first-best mechanism:

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Proposition

If (1) \Rightarrow First-best mechanism is feasible and therefore optimal.

If not (1) \Rightarrow see next slide.

Result continued

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Proposition (continued)

Suppose $v(t_2, \bar{a}_1) > v(t_1, \bar{a}_1).$

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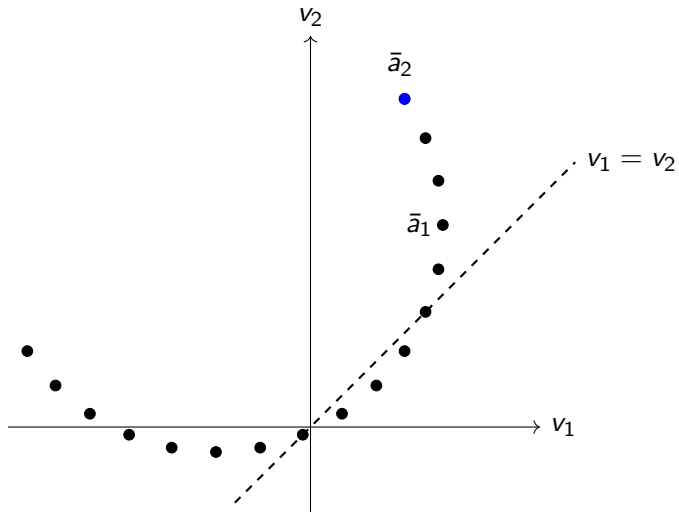
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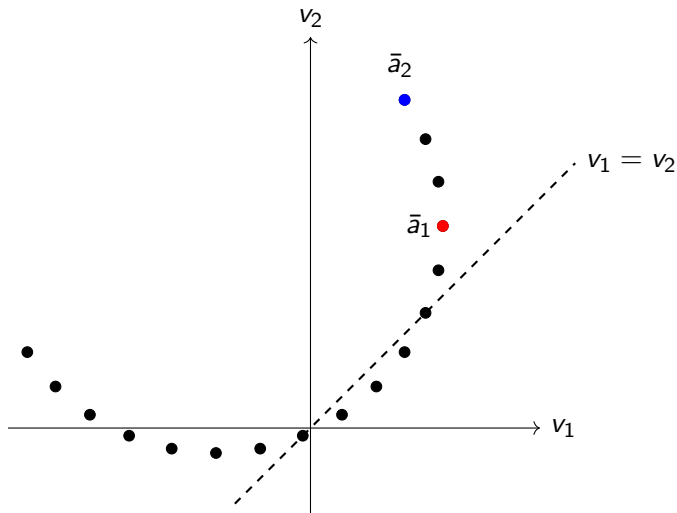
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Allocation of t_1 when $v(t_2, \bar{a}_1) > v(t_1, \bar{a}_1)$



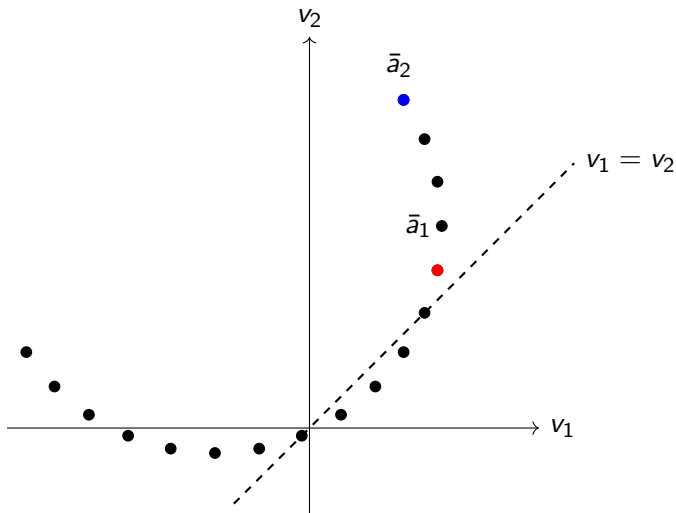
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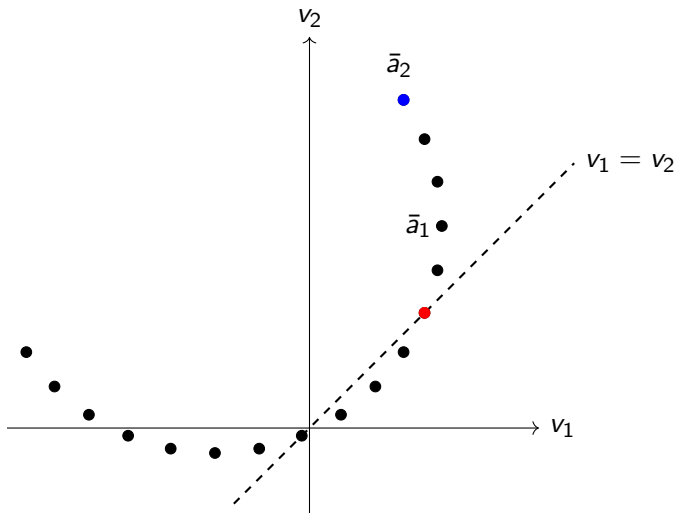
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Suppose FSE impossible: $v(t_2, \bar{a}_1) > v(t_1, \bar{a}_1)$

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- ▶ Then $u(t_2) >_{IC2} v(t_2, \bar{a}_1) - p(t_1) \geq_{IR1} v(t_2, \bar{a}_1) - v(t_1, \bar{a}_1) > 0$. Can't be!

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④ Solve problem subject to IR_2 : $\max_a v(t_1, a) - qv(t_2, a)$ s.t. $v(t_2, a) \geq v(t_1, a)$

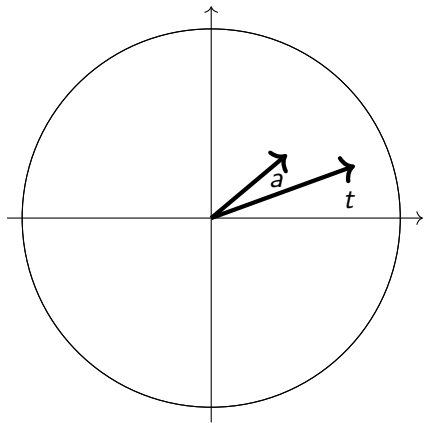
Next

Two applications:

- ① Vertical + horizontal differentiation
- ② Bundling

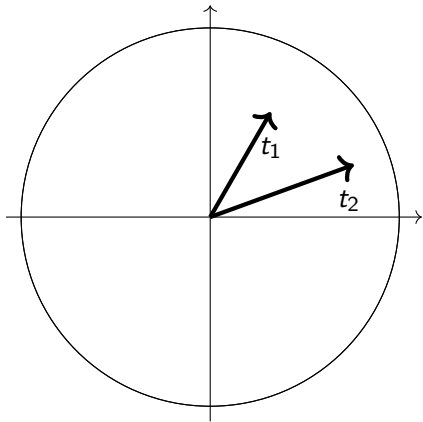
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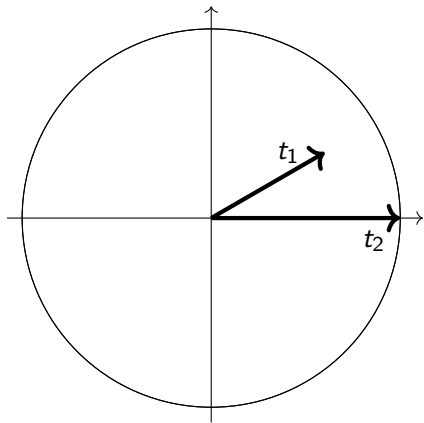
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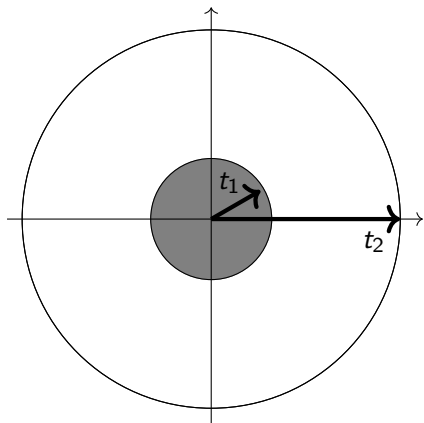


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$c(a) = c \cdot s(a)$, $v(t, a) = a \cdot t$. Suppose $c < 1$.

t_2 's efficient alternative: unit horizontal vector.

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- 2 $|t_1| > c$: unit vector in t_1 's direction.



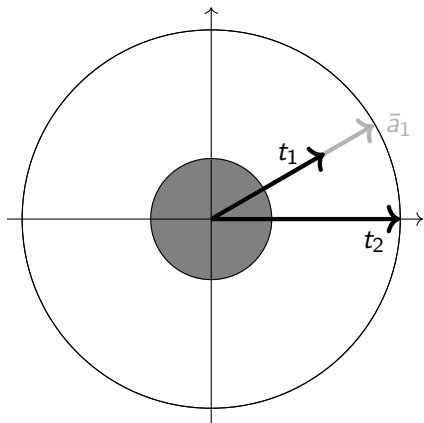
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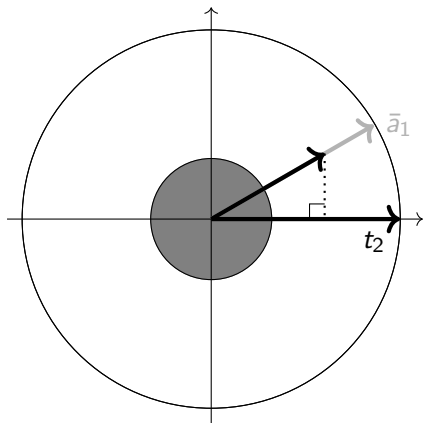


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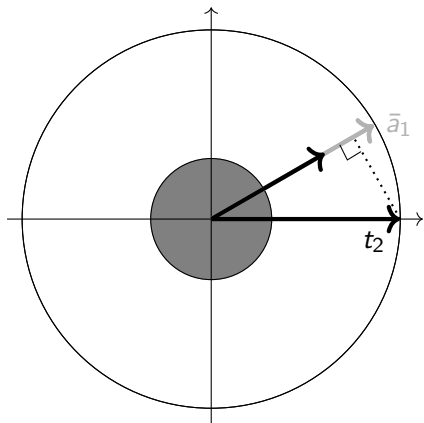
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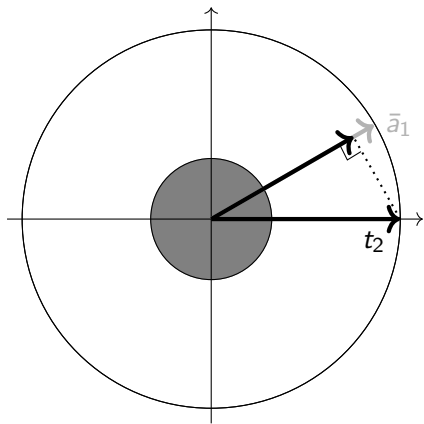
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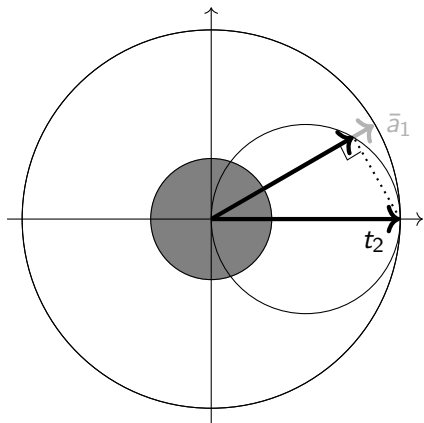
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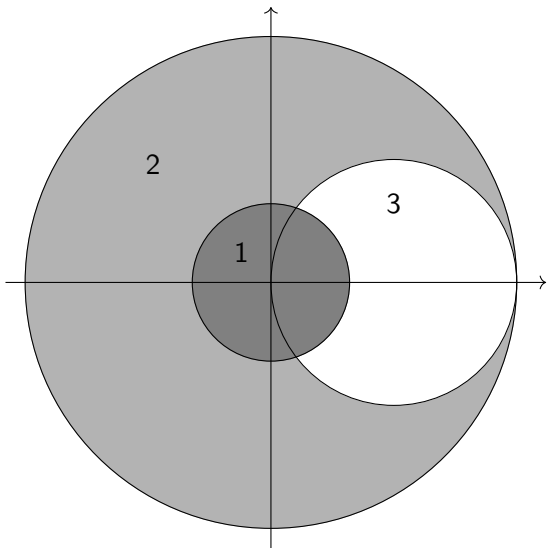
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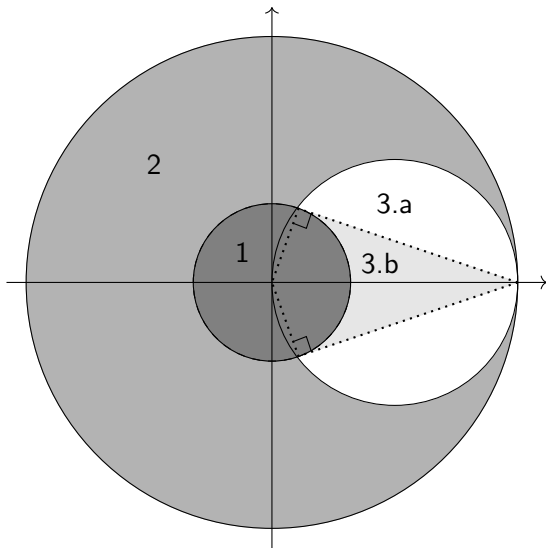
Vertical + Horizontal differentiation result

1 & 2: FSE. 3?



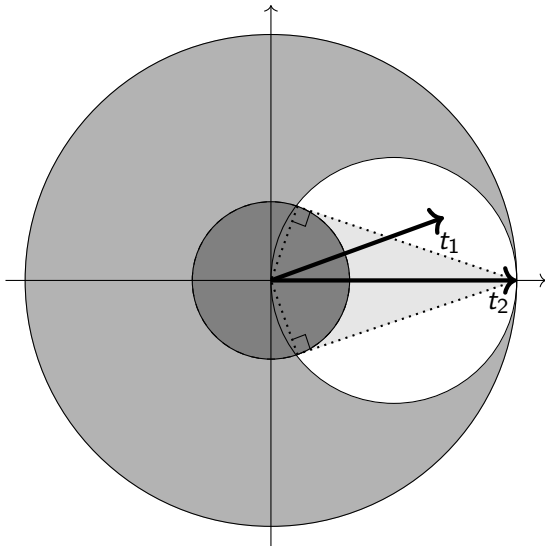
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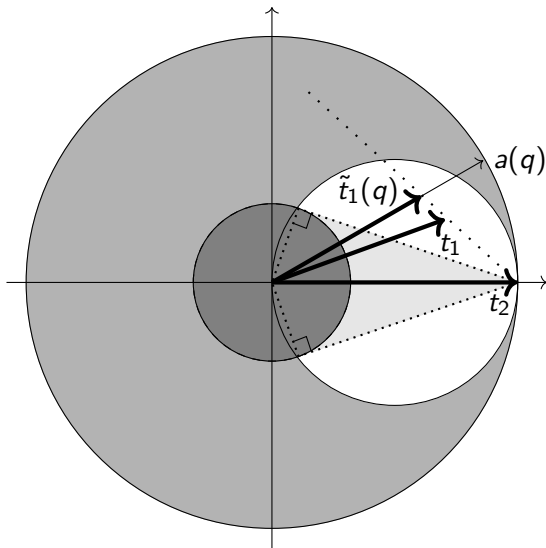
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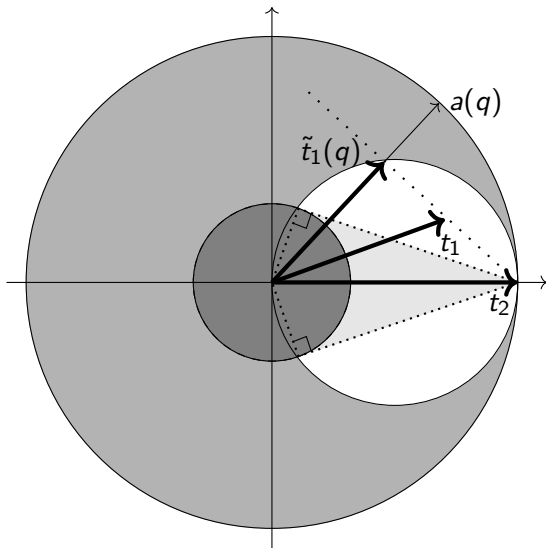
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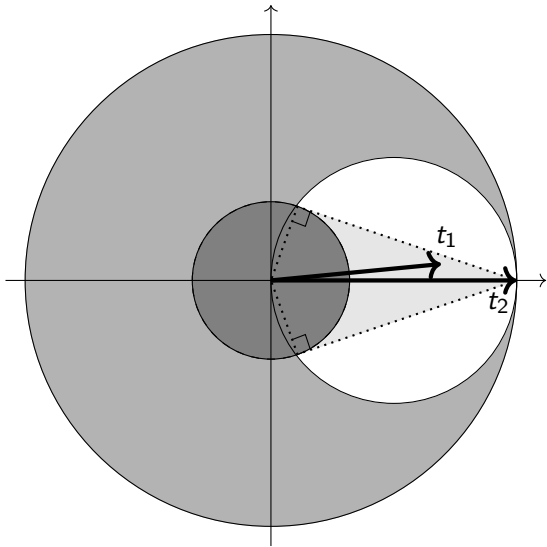
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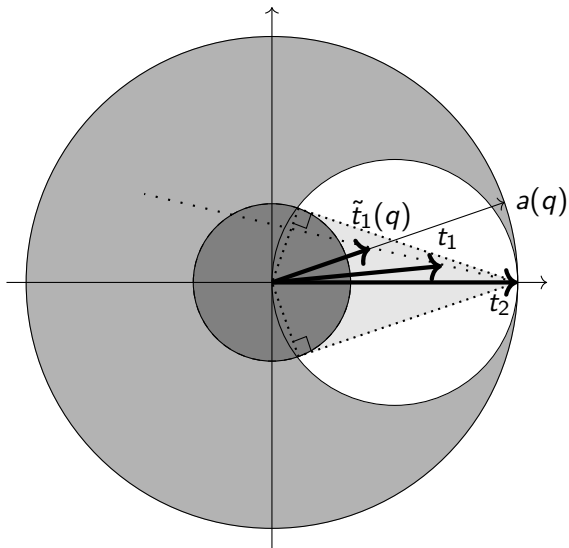
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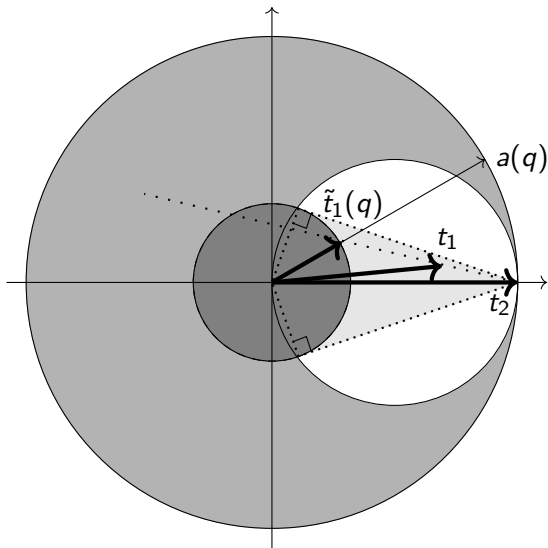
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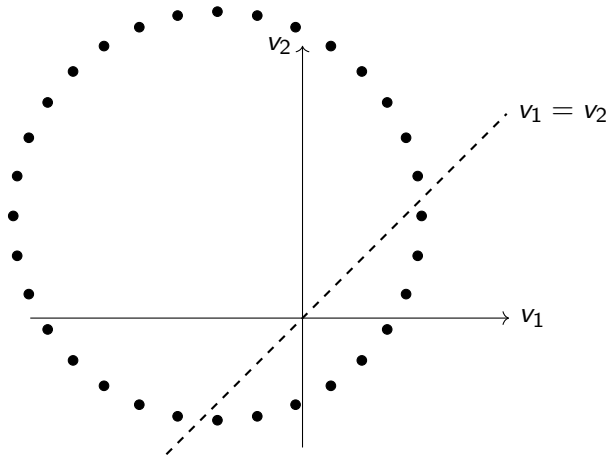
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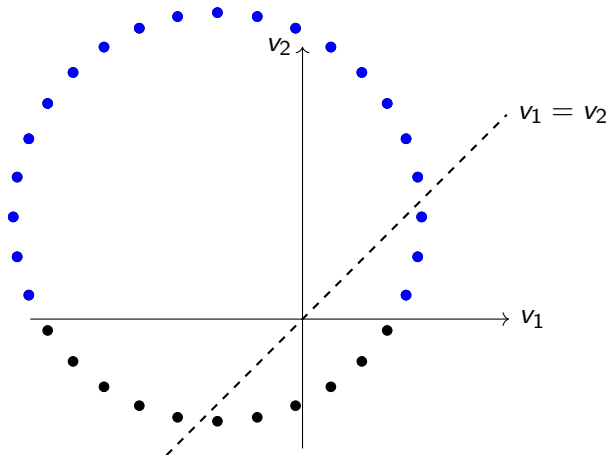


Bundling result

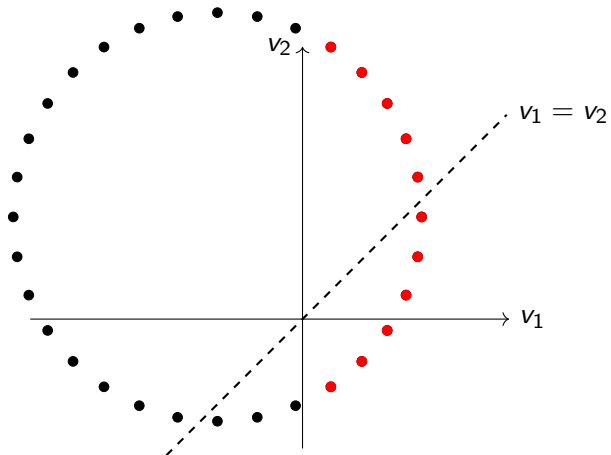
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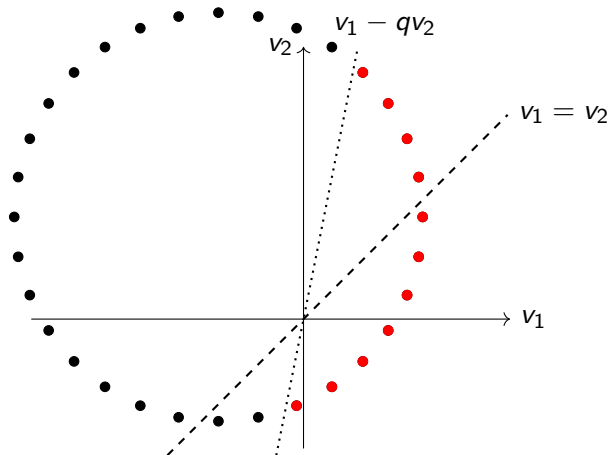


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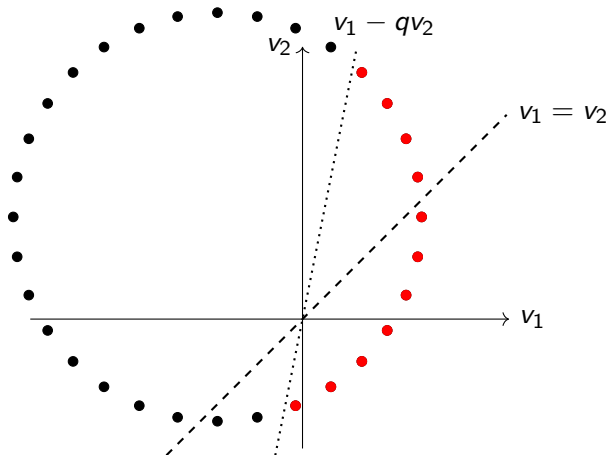
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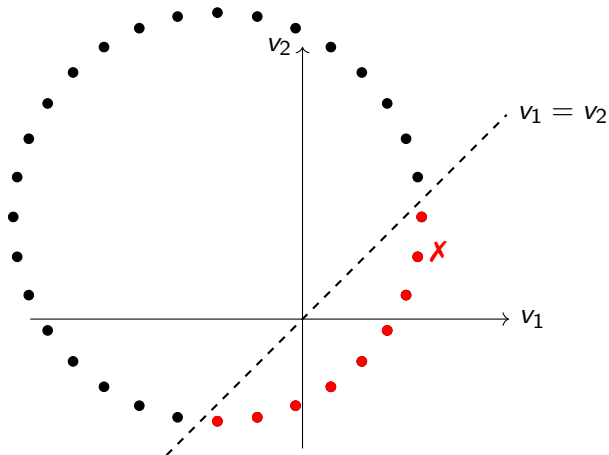
As $q \uparrow$, $u(t_2) = v(t_2, \textcolor{red}{S}) - v(t_1, \textcolor{red}{S})$ decreases



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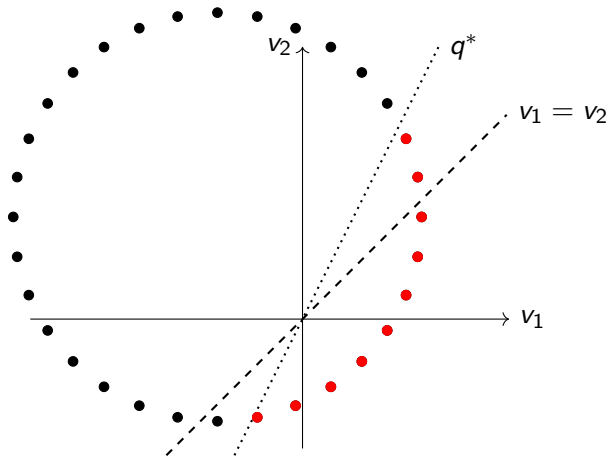


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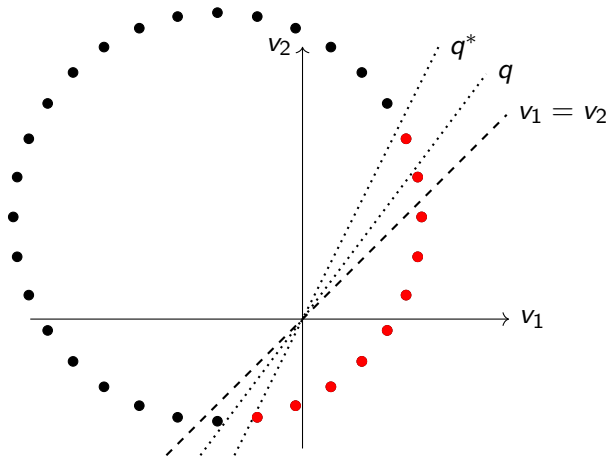


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Related Literature

Classic models only consider vertically differentiated products

- ▶ Mussa and Rosen (1978), Maskin and Riley (1984)

Imperfect competition of single-product firms

- ▶ Horizontal differentiation: Hotelling (1929), Salop (1979)
- ▶ Horizontal + vertical differentiation: Villas-Boas (1999), Armstrong and Vickers (2001), and Rochet and Stole (2002)

Multi-product bundling: optimal mechanisms are complex and difficult to characterize

- ▶ Even with two products with additive and independently drawn values (Daskalakis et al., 2014, Thirumulanathan et al., 2019)

Applications that don't satisfy single-crossing, study two types

- ▶ Selling information: Bergemann, Bonatti, Smolin (2018)
- ▶ Screening with self-control: Galperti (2015)

More in the paper

- ① A more general model that doesn't require randomization [here](#)
- ② Use the result to characterize when randomization helps [here](#)

Conclusion

A general characterization of optimal mechanisms with two types

- ▶ A **simple comparison** specifies **which type is high and which is low**

Two applications

- 1 Bundling
 - ▶ Products might be **added** to distort allocation
- 2 Vertical and horizontal differentiation
 - ▶ Allocation is distorted **away** from the low type

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Thanks!

Normalizing costs and value of outside option to zero

$$\begin{aligned} \max_{a_1, a_2 \in \Delta(A) \quad p_1, p_2 \in \mathbb{R}} \quad & (1 - q)(p_1 - c(a_1)) + q(p_2 - c(a_2)) \\ \text{subject to} \quad & v_1(a_1) - p_1 \geq v_1(0), \\ & v_2(a_2) - p_2 \geq v_2(0), \\ & v_1(a_1) - p_1 \geq v_1(a_2) - p_2, \\ & v_2(a_2) - p_2 \geq v_2(a_1) - p_1. \end{aligned}$$

Define $\tilde{v}_t(a) = v_t(a) - c(a) - v_t(0)$, $r_t = p_t - c(a_t)$.

$$\begin{aligned} \max_{a_1, a_2 \in \Delta(A) \quad r_1, r_2 \in \mathbb{R}} \quad & (1 - q)r_1 + qr_2 \\ \text{subject to} \quad & \tilde{v}_1(a_1) - r_1 \geq 0, \\ & \tilde{v}_2(a_2) - r_2 \geq 0, \\ & \tilde{v}_1(a_1) - r_1 \geq \tilde{v}_1(a_2) - r_2, \\ & \tilde{v}_2(a_2) - r_2 \geq \tilde{v}_2(a_1) - r_1. \end{aligned}$$

“Weak” Increasing Differences

$$\cancel{A \subset \mathbb{R}_+} \quad A \subset \mathbb{R}, 0 \in A$$

$$\blacktriangleright \forall a > a', v(t_2, a) - v(t_2, a') > v(t_1, a) - v(t_1, a')$$

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- ▶ $\forall a > a', v(t_2, a) - v(t_2, a') > v(t_1, a) - v(t_1, a')$
- ▶ ~~when $a' = 0 : v(t_2, a) > v(t_1, a), \forall a \neq 0.$~~

Then

- ① ~~IR2 is implied by IR1 and IC2 and can be relaxed~~
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- 2 With two types: IC1, IC2, IR1, IR2 might all bind.

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Generalized Model

Two types $\{t_1, t_2\}$, probabilities $1 - q, q$

A set of “alternatives” A

Value $v(t, a)$, $v(t, 0) = 0$

► Payoff $v(t, a) - p$

Cost $c(a)$ normalized to zero

Mechanisms: $(x, p) : \{t_1, t_2\} \rightarrow A \times \mathbb{R}$

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Result

$$0 \geq v(t_1, \bar{a}_2) - v(t_2, \bar{a}_2); 0 \geq v(t_2, \bar{a}_1) - v(t_1, \bar{a}_1) \quad (1)$$

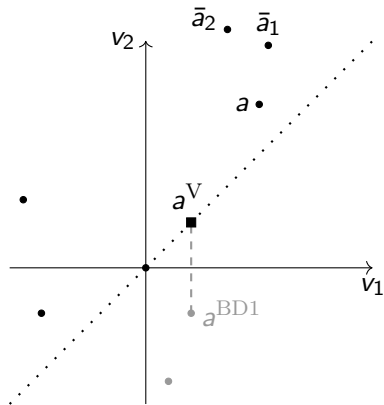
Proposition

If (1) \Rightarrow FSE is feasible.

Otherwise suppose (WLOG) $v(t_2, \bar{a}_1) > v(t_1, \bar{a}_1)$. Then for all distributions

- ① t_2 is “the high type”:
 - Ⓐ Its allocation is *efficient*: it gets \bar{a}_2
 - Ⓑ ~~Its IC binds~~
- ② t_1 is “the low type”:
 - Ⓒ Its *IR binds* (pins down payment given t_1 's allocation)
 - Ⓓ Allocation: see next slide. It determines whether IC2 or IR2 binds.

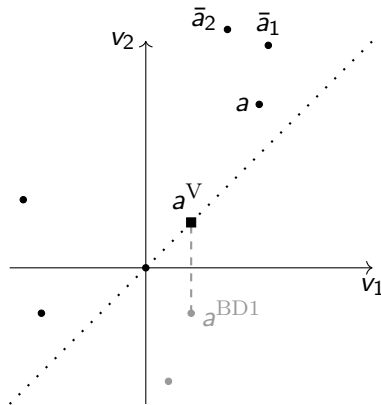
Allocation of t_1 when $v(t_2, \bar{a}_1) > v(t_1, \bar{a}_1)$



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Maximize $v_1 - qv_2$ over $\{a | v_2 \geq v_1\} + a^V$.

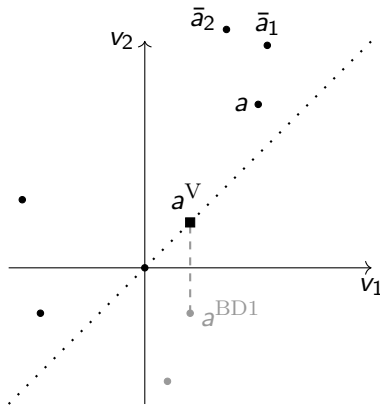
- ▶ Maximizer is a^V : Give t_1 alternative a^{BD1} . IR2 binds.
- ▶ Maximizer is not a^V : Give t_1 the maximizer. IC2 binds.



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General Proof: Suppose FSE impossible: $v(t_2, \bar{a}_1) > v(t_1, \bar{a}_1)$

Previously

- 1 IC2 binds
- 2 t_2 's allocation is efficient
- 3 IR_1 binds
- 4 Solve problem subject to IR2: $\max_a v(t_1, a) - qv(t_2, a)$ s.t. $v(t_2, a) \geq v(t_1, a)$

Now:

- 1 ~~IC2 binds~~
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 - ▶ Either IC2 binds or IR2 binds.
 - ▶ If IC2 binds: same as before.
 - ▶ If IR2 binds:
 - ▶ make t_2 's allocation efficient and keep her utility at 0
 - ▶ IC1 not violated because $v_1(a_1) - p_1 \geq 0 > v(t_1, \bar{a}_1) - v(t_2, \bar{a}_1)$.
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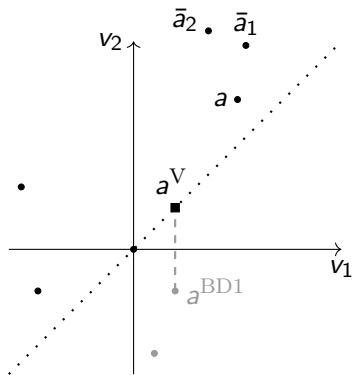
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Notice that $(1 - q)v(t_1, a^{\text{BD1}}) = v(t_1, a^{\text{V}}) - qv(t_2, a^{\text{V}})$.

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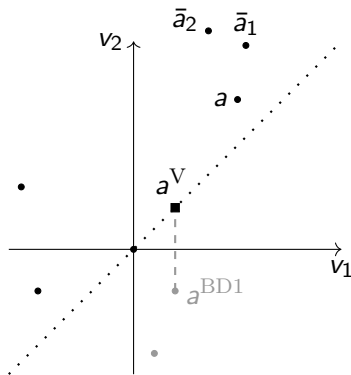


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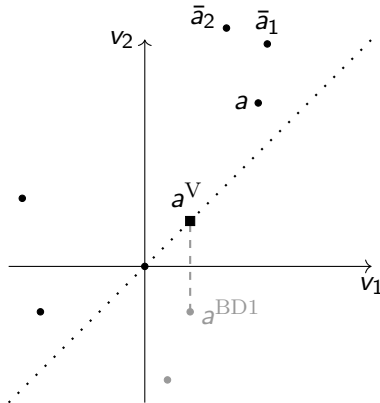
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Randomization helps (for some q) if and only if a^{BD1} is on the diagonal.



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