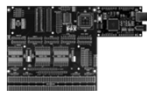




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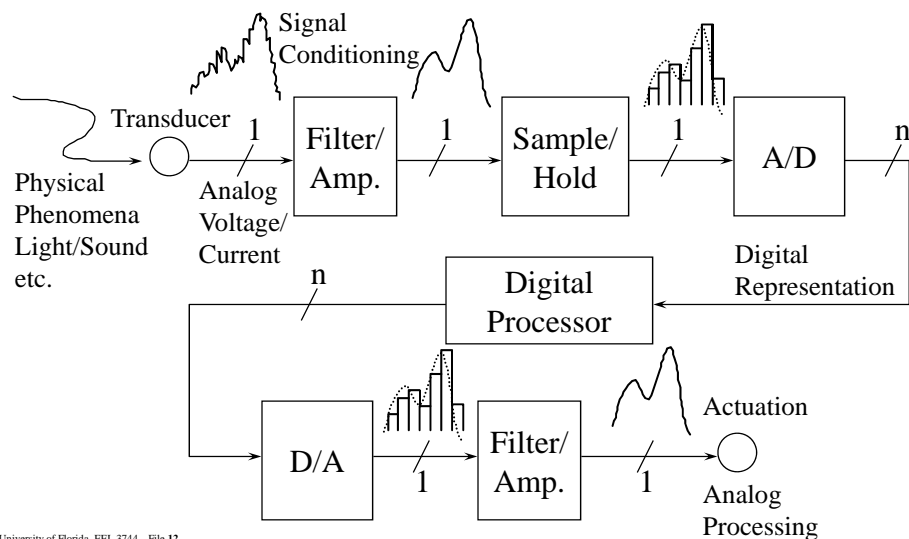
Menu

- A/D-D/A Conversion Processes
 - > Example: “Grandma Singing Hymns”
- Digital Signal Processing
- Analog-to-Digital Conversion
 - > A/D Conversion Methods
- Operational Amplifier in D/A & A/D
- Digital-to-Analog



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A/D and D/A Conversion Process





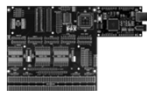
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DSP (Digital Signal Processing) in ECE

- Discussion on Digital Signal Processing
 - > Analog filters introduced in (*EEL 3112*)
 - > Analog Filter Design (*EEL 3308: Electronic Circuits I*), i.e., s-plane design
 - > Digital Analysis of Signals (*EEL 3135: Intro to [Discrete-Time] Signals & Systems*), i.e., z-plane design
 - > Digital Filtering (Analog-->Digital) (*EEL 4712: Digital Design, 4511: Real-time DSP Applications, 4750: Intro to DSP, EEE 5502: Foundations of Digital Signal Processing, 6503: Digital Filtering*)
 - > Implementation as a Recursive Program (CE Stuff)
 - > Advantages of Digital Signal Processing (*EEL 4511 & 4750*)
- The use of D-A/A-D and Digital Processors allows computer engineers to create digital solutions to many engineering problems

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Programming Example

- Example: Recovery of “Grandma Singing Hymns” cassette tapes from the 1950’s
 - > High-pass filter to remove low frequency tape hum (there was no Dolby system in the 1950’s)
 - > Low pass filter to remove high frequency media damage (hiss)
 - > What would it take to do this with Analog circuits?
 - > What would it take to do this with Digital technology?
- The Analog Filter

$$H(s) = Y(s)/X(s) = 1/(s^2 + bs + c)$$

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Programming Example

- The Analog Filter

$$H(s) = Y(s)/X(s) = 1/(s^2 + bs + c)$$
- The Digital Filter

$$H(z) = Y(z)/X(z) = 1/(z^2 + \alpha z + \beta)$$
- This results in the **difference equation**:

$$Y(z) = X(z) / (z^2 + \alpha z + \beta)$$

$$X(z) = Y(z) (z^2 + \alpha z + \beta)$$

$$X(z) = z^2 Y(z) + \alpha z Y(z) + \beta Y(z) \text{ or}$$

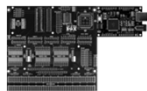
$$z^{-2} X(z) = Y(z) + \alpha z^{-1} Y(z) + \beta z^{-2} Y(z) \text{ or}$$

$$X(n-2) = Y(n) + \alpha Y(n-1) + \beta Y(n-2) \text{ or}$$

$$Y(n) = -\alpha Y(n-1) - \beta Y(n-2) + X(n-2)$$

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Programming Example

- This results in the program (say in Fortran):

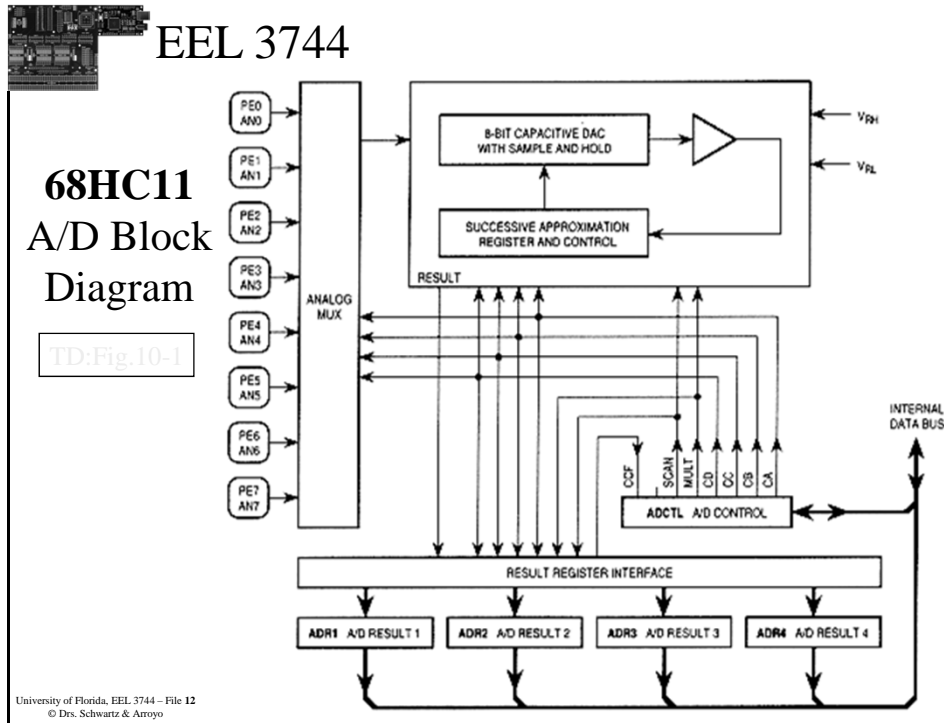
```

C      Y(n) = -αY(n-1) - βY(n-2) + X(n-2)
      Data n/___ /
      DIMENSION Y(0..n), X(0..n)
      READ (5,x) X,alpha,beta,Y(0),Y(1)
      DO 100 i=2,n
100    Y(i) = X(i-2) - (alpha*Y(i-1) + beta*Y(i-2))

```
- Thus, given the parameters α , β and inputs $X(0..n)$ we can calculate the $Y(2..n)$ if we know $Y(0)$ and $Y(1)$
- This program can be implemented easily(?) in any (e.g., XMEGA) assembly language

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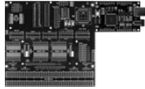


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EEL 3744 Dual slope (Integrator) A/D Converters

- **Components:** Use a counter, analog integrator, voltage comparator, reference voltage and control circuitry
- **Technique:** Integrate over one cycle of the power line frequency (60 Hz) and therefore can ignore 60 Hz noise
- **High points:** Accuracy good, 60 Hz noise immunity
- **Low points:** Relatively slow

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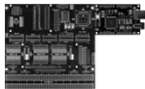
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Flash (Simultaneous) A/D Converters

- **Technique & components:** Uses a tapped resistor to divide a reference voltage into 2^n equal parts, 2^n voltage comparators (to compare the input voltage against each of the tap voltages, and a priority encoder (2^n inputs and n -bit coded output) to output the digital signal
- **High points:** Accuracy very good if use high precision resistors; very fast (fastest); speed depends only on propagation delays (mostly in the encoder)
- **Low points:** Requires a **tremendous** amount of circuitry

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Sigma-Delta A/D Converters

- **Technique & components:** Uses high speed sampling a digital decimation filter. (See class in digital filters.)
- **High points:** Accuracy good
- **Low points:** May be slow
- **Note:** This is now common in many processors (including XMEGA and ATmega)

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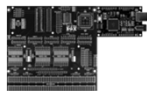
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Successive-Approximation A/D Converters

- **Technique & components:** Uses a D/A converter (DAC), voltage comparator, reference voltage and control circuitry
- **High points:** Relatively fast (not as fast as flash, but much faster than dual-slope)
- **Low points:** Requires a DAC
- **Note:** This has been common in many processors (including 68HC11, 68HC12, TMS320 DSC)

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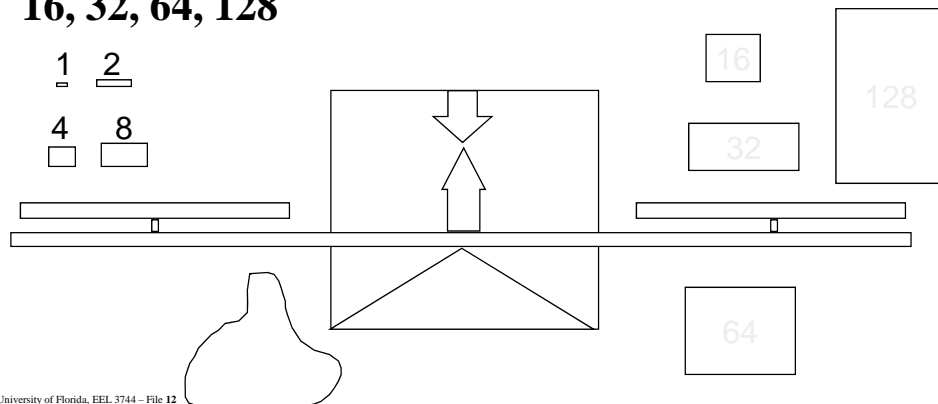
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Successive-Approximation A/D Converter Example

- **Given:** Ancient balance scale, some “boxes” of sand of known weight (in *talanton* units): 1, 2, 4, 8, 16, 32, 64, 128



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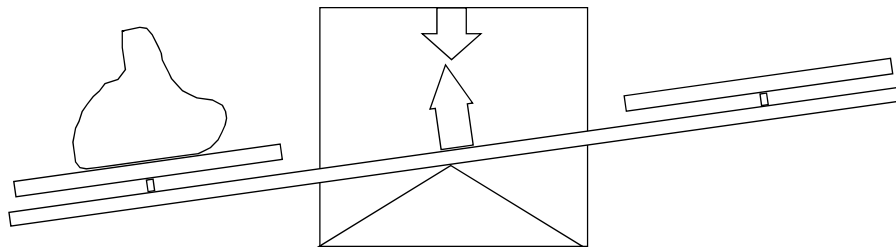


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Successive-Approximation A/D

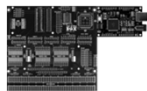
Converter Example

- **Find the weight of a sack of salt (worth its weight in gold).**



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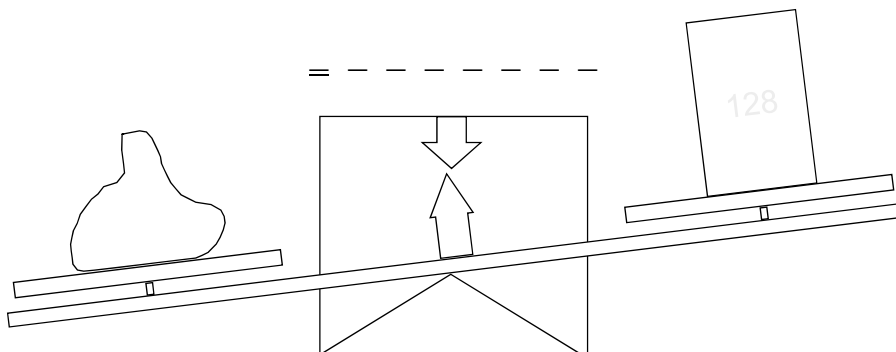


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Successive-Approximation A/D

Converter Example

- **First try the maximum weight (128 talatons)**



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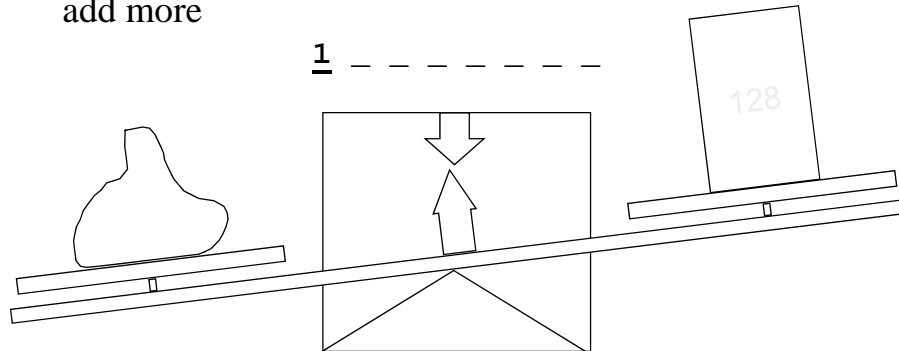


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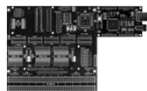
Successive-Approximation A/D

Converter Example

- **First try the maximum weight (128 talatons)**
 > Too light, so keep this weight (put 1 in the MSB) and add more

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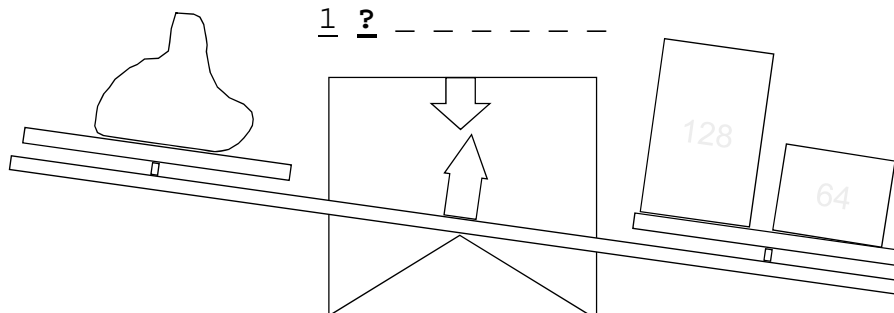


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Successive-Approximation A/D

Converter Example

- **Now try the next weight down (64 talatons)**

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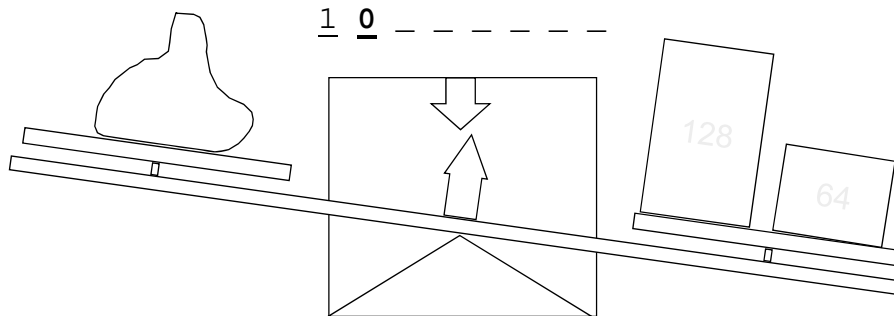


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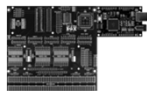
Successive-Approximation A/D

Converter Example

- **Now try the next weight down (64 talatons)**
 - > Too heavy, so remove the 64 talaton weight and put a 0 below

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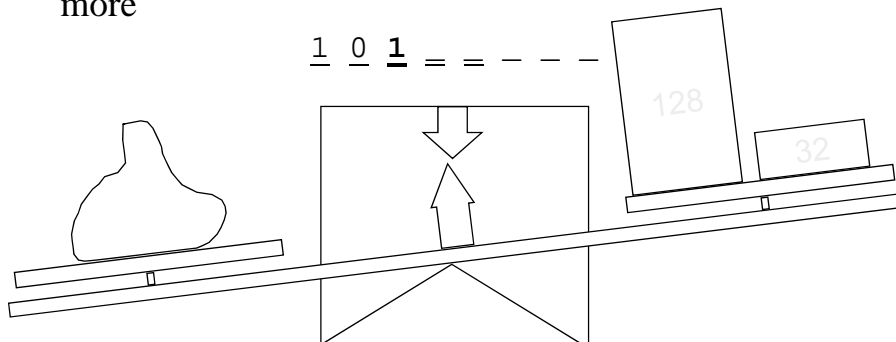


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Successive-Approximation A/D

Converter Example

- **Try 32 talaton weight**
 - > Still too light, so keep this weight (put 1 below) and add more

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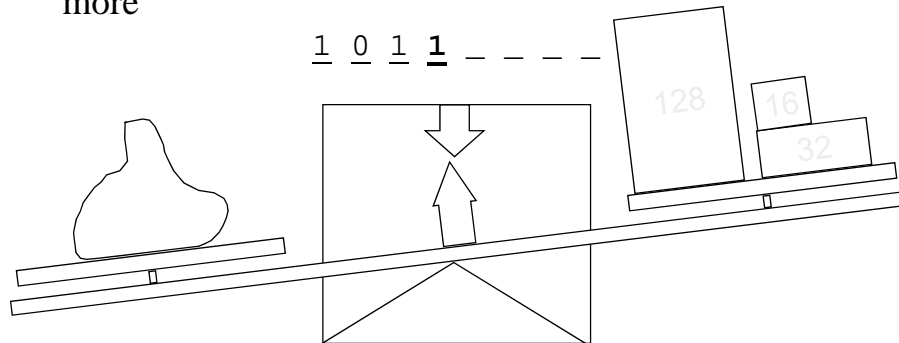
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Successive-Approximation A/D

Converter Example

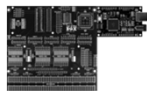
- **Try 16 talaton weight**

> Still too light, so keep this weight (put 1 below) and add more



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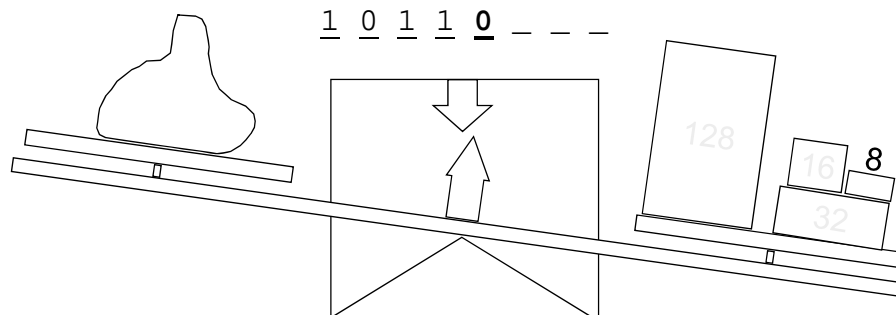
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Successive-Approximation A/D

Converter Example

- **Now try the 8 talaton weight**

> Too heavy, so remove the 8 talaton weight and put a 0 below



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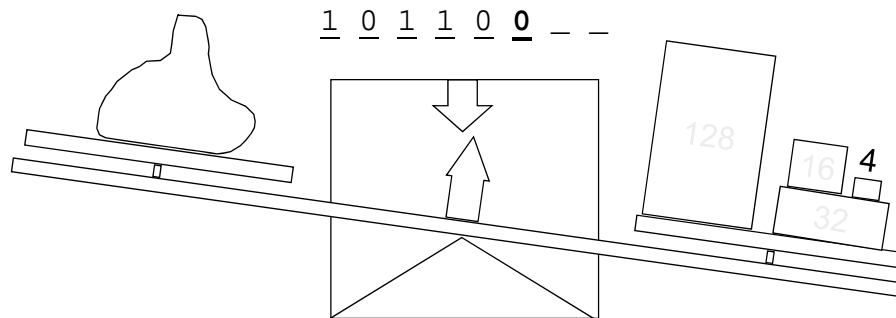
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Successive-Approximation A/D

Converter Example

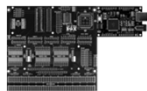
- **Now try the 4 talaton weight**

> Too heavy, so remove the 4 talaton weight and put a 0 below



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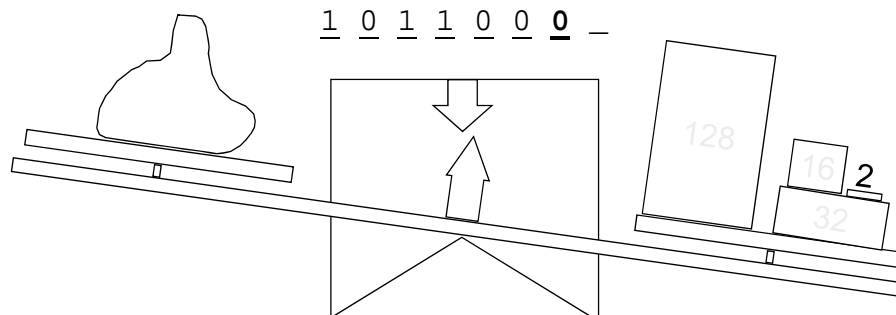
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Successive-Approximation A/D

Converter Example

- **Now try the 2 talaton weight**

> Too heavy, so remove the 2 talaton weight and put a 0 below



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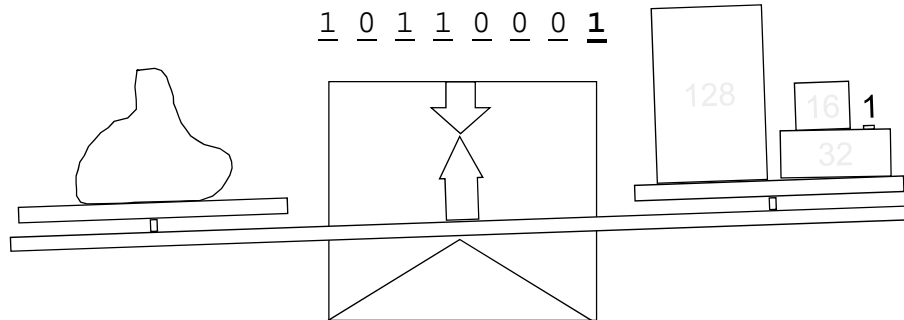


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Successive-Approximation A/D Converter Example

- **Now try the 1 talaton weight**

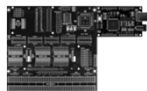
>Not quite heavy enough, so keep this weight and put a 1 below



Q: What is the range of **possible** weights for **this** bag?

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Successive-Approximation A/D Converter

- The above algorithm is called a **binary search** (since the known weights were 2^n talatons)
- The electronic successive-approximation A/D works with the same principles as the ancient balance, comparing the unknown quantity (voltage) with a succession of known quantities (voltages) with binary weights
- All Successive-Approximation A/D converters have D/A converters (DACs) inside

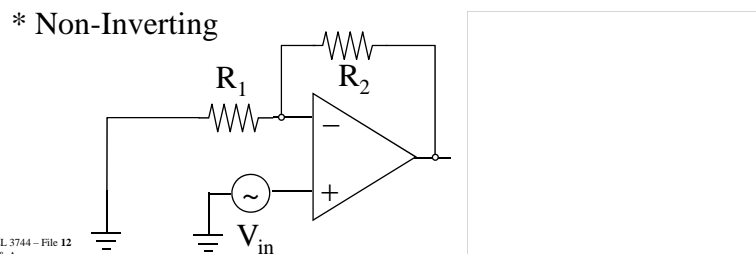
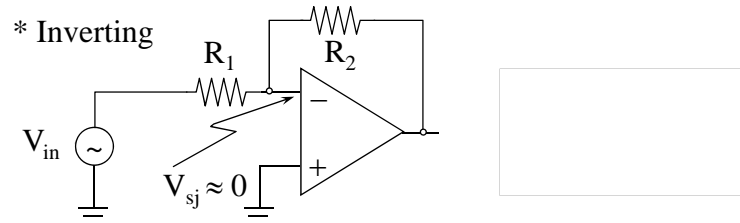
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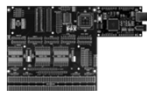


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OP Amps Circuits used in A/D & D/A Circuits

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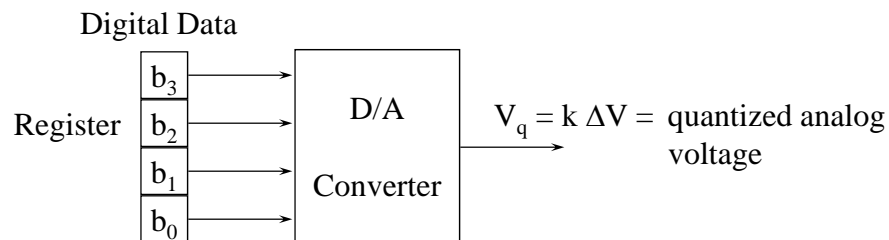
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Digital/Analog Conversion

Binary integer: $k = b_3 2^3 + b_2 2^2 + b_1 2^1 + b_0$



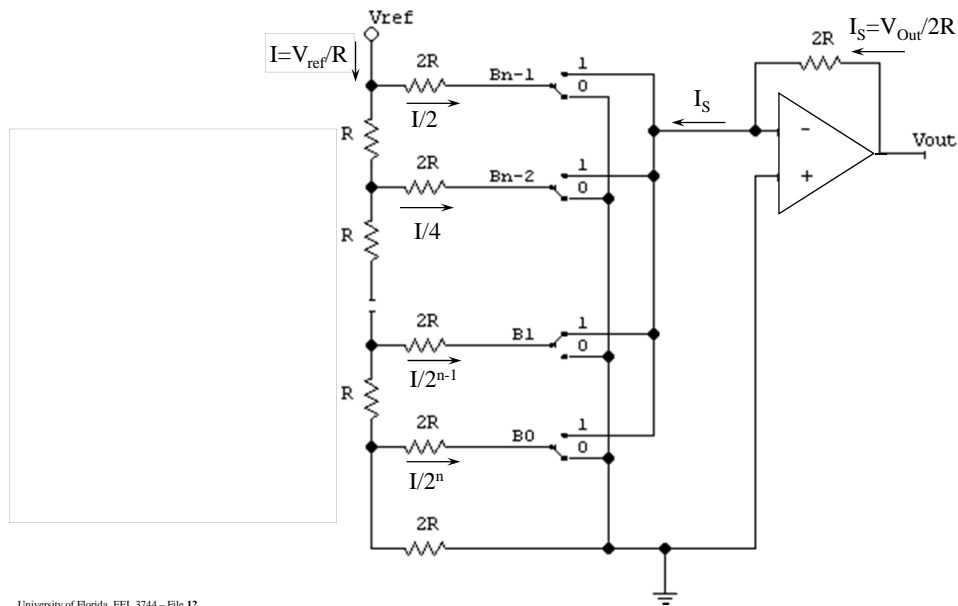
$\Delta V = \text{quantized voltage proportionality constant}$

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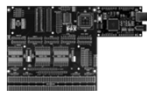


EEL 3744 DAC: Inverted R-2R Ladder Circuit



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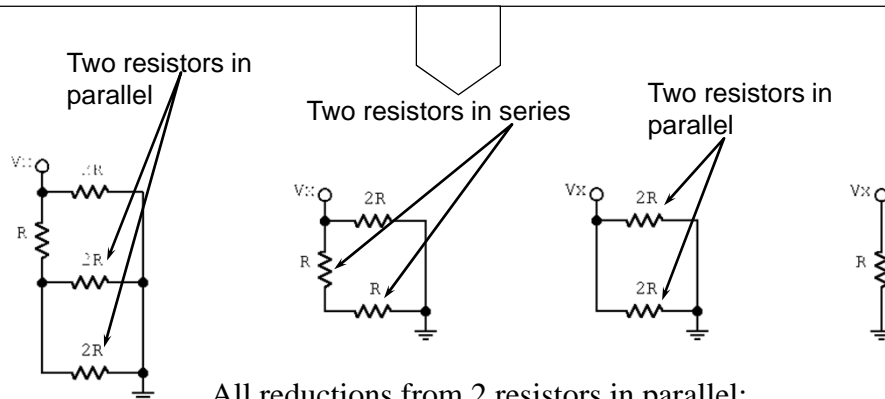
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DAC: Inverted R-2R Ladder Circuit

Demonstration that equivalent resistance of network is **always** R



All reductions from 2 resistors in parallel:

$$R_p = R_1 R_2 / (R_1 + R_2)$$

Or two resistors in series: $R_s = R_1 + R_2$

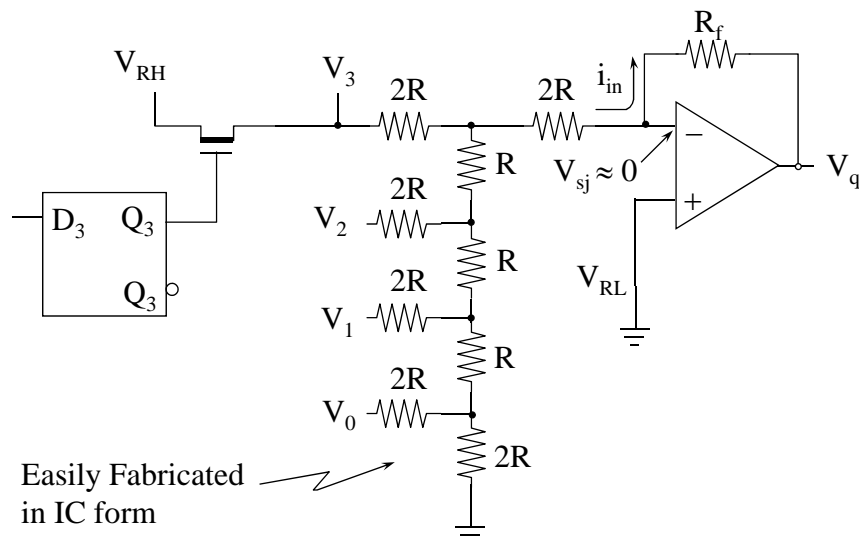
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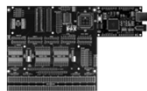


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DAC: R-2R Ladder Network

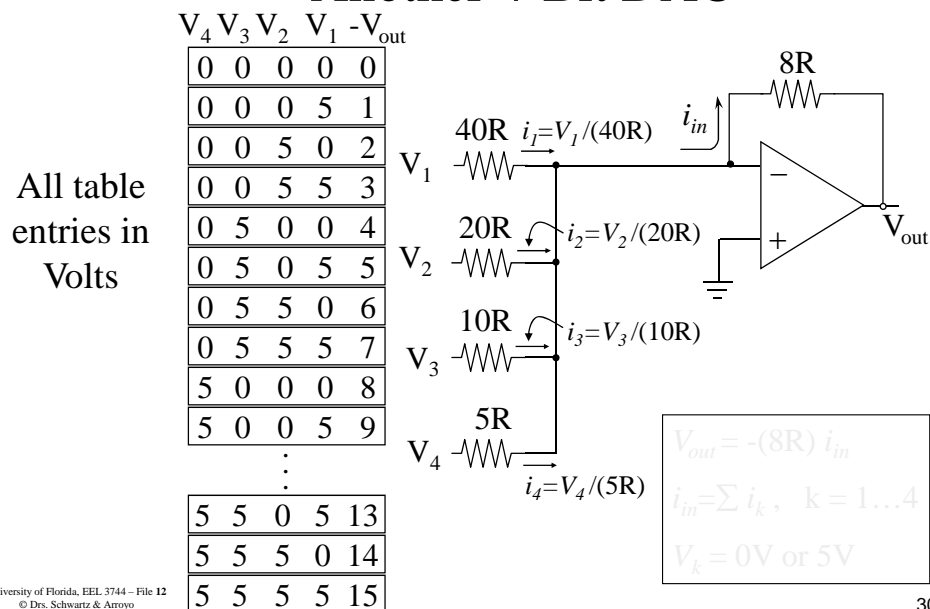
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Another 4-Bit DAC

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Analog/Digital Conversion

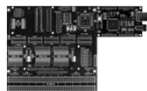
- A/D Conversion Methods

- > Successive Approximation

- > Flash Conversion

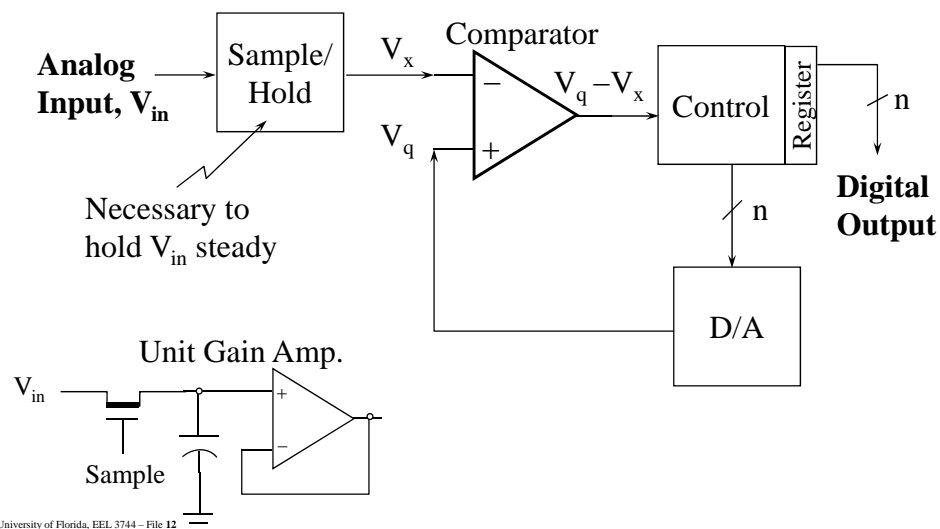
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Successive Approximation

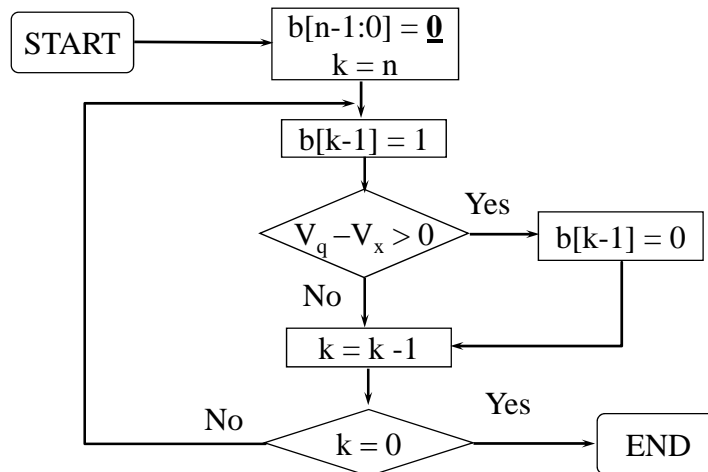


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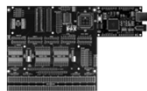


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Successive Approximation Algorithm A.K.A. Binary Search

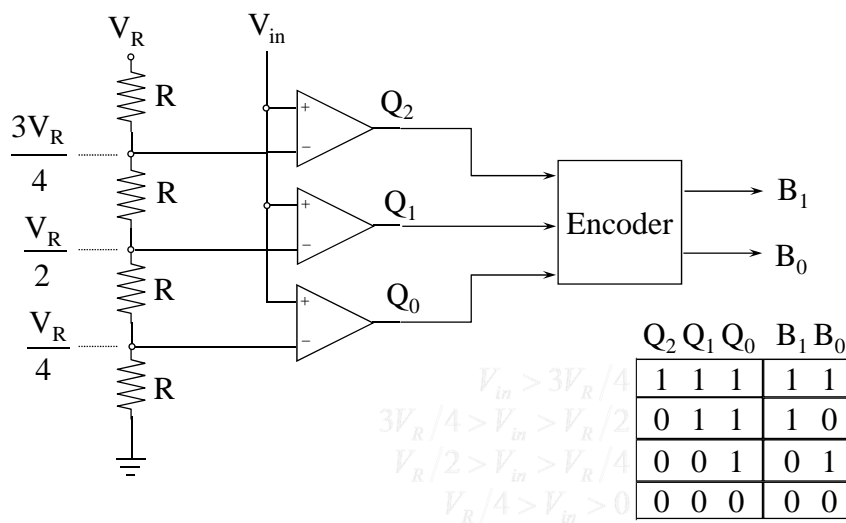
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Flash Conversion

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Analog/Digital Conversion

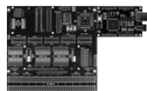
- A/D Conversion Method in the 68HC11

- > Charge Distribution A/D

- See 68HC11 RM Chapter 12

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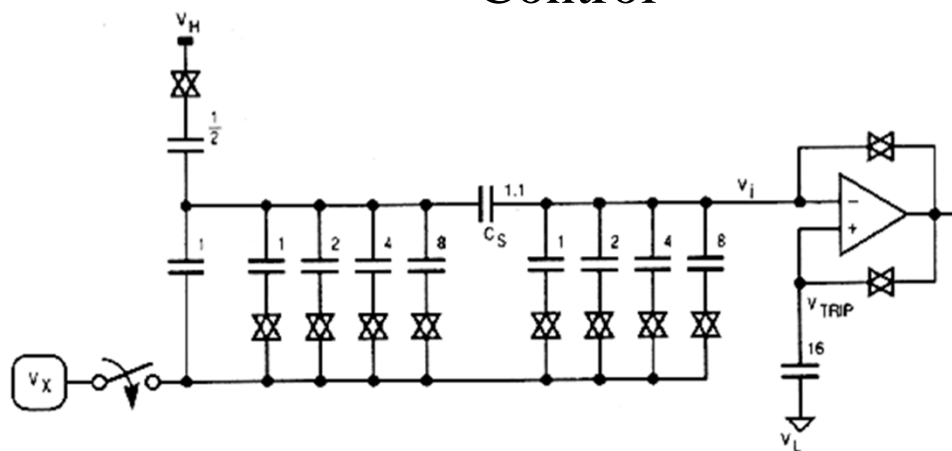
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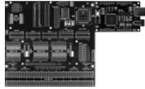
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A/D Successive-Approximation Control

68HC11 RM: Fig. 12-3

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The End!