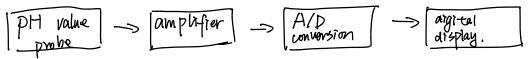
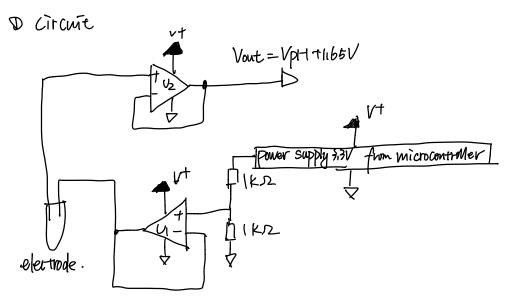
Aim: to measure the pH value of solution and make it stay in an optimum range

System introduction:



1. Measure the PH value.



Power supply to appear is from microcontraler 5V potential divider: $\frac{33}{2} = 1.65V$

01: adds offset directly to the pH-reference electrode \Rightarrow stay constant. (because the PH value sensor has a large Third Timpedance).

Uz: add5 7t5 Individual offset voltage to the output of FH-massuring.

(because voltage signed provided by the PH value. Sonsor is too small).

transfer function of PH electrode: digital conversion? T is temperature of solution TNK D = 1.65 - 0,001386T voltage C= 1.65 +0.00/3867 $\frac{D-0}{313} = \frac{A-0}{1024} \qquad A = \frac{1024}{33} D$ PH Value $\frac{C-0}{3.3} = \frac{B-0}{(924)}$ B= $\frac{1024}{3.3}$ C range $A-B \Rightarrow range.$ of PH $(\frac{1024}{33} \, \text{C}, 0)$ prt (1024D, (4) $M = \frac{1024}{335} C - \frac{1024}{335} D$ y=mx+b $b = -\frac{1024}{33} cm$. y=mx+b y=pH x=digital

2- motor

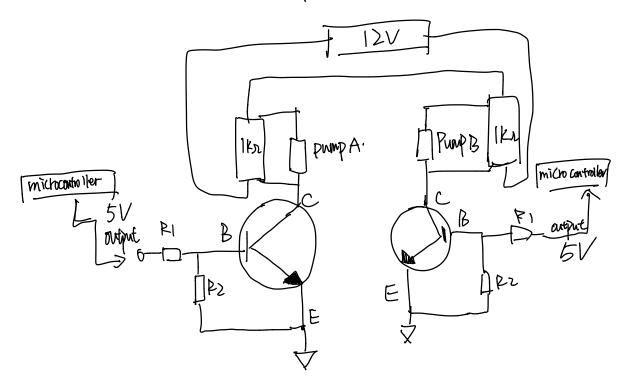
DIF the pH <45, pump on to add bose, microcontroller output 5V, transister on's so pump on.

If PH=5, pump Stop, microcontroller output OV. transister off, so pump off,

DIF the pH > 5.5, pump on to add oxid, microcontroller output 5v, transister on's so pump on,

If PH=5, pump stop, microcontroller output ov. transister off, so pump off,

Circuit : + Vawistor & MPN BIT (27X450)



PI: limit the current.

Pz: prevent the transistor working because of the bias current.

(noise).