

BFS and DFS reference – CLRS 4th edition algorithms

Input: Graph $G = (V, E)$, either directed or undirected, and *source vertex* $s \in V$.

Output:

- $v.d$ = distance (smallest # of edges) from s to v , for all $v \in V$.
- $v.\pi$ is v 's **predecessor** on a shortest path (smallest # of edges) from s .
 (u, v) is last edge on shortest path $s \rightsquigarrow v$.

Predecessor subgraph contains edges (u, v) such that $v.\pi = u$.

The predecessor subgraph forms a tree, called the **breadth-first tree**.

BFS(V, E, s)

for each vertex $u \in V - \{s\}$

$u.d = \infty$

$u.\pi = \text{NIL}$

$s.d = 0$

$Q = \emptyset$

 ENQUEUE(Q, s)

while $Q \neq \emptyset$

$u = \text{DEQUEUE}(Q)$

for each vertex v in $G.\text{Adj}[u]$ // search the neighbors of u

if $v.d == \infty$ // is v being discovered now?

$v.d = u.d + 1$

$v.\pi = u$

 ENQUEUE(Q, v) // v is now on the frontier

 // u is now behind the frontier.

Input: $G = (V, E)$, directed or undirected. No source vertex given.

Output:

- 2 *timestamps* on each vertex:

- $v.d = \textit{discovery time}$
- $v.f = \textit{finish time}$

These will be useful for other algorithms later on.

- $v.\pi$ is v 's predecessor in the *depth-first forest* of ≥ 1 *depth-first trees*.
If $u = v.\pi$, then (u, v) is a *tree edge*.

DFS(G)

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for each vertex  $u \in G.V$ 
     $u.color = \text{WHITE}$ 
     $u.\pi = \text{NIL}$ 
time = 0
for each vertex  $u \in G.V$ 
    if  $u.color == \text{WHITE}$ 
        DFS-VISIT( $G, u$ )
```

DFS-VISIT(G, u)

```
time = time + 1           // white vertex  $u$  has just been discovered
 $u.d = \text{time}$ 
 $u.color = \text{GRAY}$ 
for each vertex  $v$  in  $G.Adj[u]$  // explore each edge  $(u, v)$ 
    if  $v.color == \text{WHITE}$ 
         $v.\pi = u$ 
        DFS-VISIT( $G, v$ )
time = time + 1
 $u.f = \text{time}$ 
 $u.color = \text{BLACK}$        // blacken  $u$ ; it is finished
```