

Neural Network

Homework 2

Ning Ma, A50055399

1 Linear Rgression

1. Since $\epsilon \sim \mathcal{N}(\mu = 0, \sigma^2)$, we have $P(t|x; \theta) = \mathcal{N}(f(x, \theta), \sigma^2)$. Thus, for iid samples, we have

$$P(T|X; \theta) = \prod_{i=1}^N \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(t^{(i)} - f(x^{(i)}, \theta))^2}{2\sigma^2}\right) \quad (1)$$

The optimal parameter θ should maximize the above posterior. Since **log** is a monotonically increasing function, it is equivalent to maximize $\log P(T|X; \theta)$

$$\log P(T|X; \theta) \sim -\sum_{i=1}^N (t^{(i)} - f(x^{(i)}, \theta))^2 \quad (2)$$

which is equivalent to minimize $\sum_{i=1}^N (t^{(i)} - f(x^{(i)}, \theta))^2$ which is the SEE. In conclusion, in this special problem, minimize the SSE is equivalent to maximize the posterior of observation.

2 Multilayer Perceptron

(a) The cross entropy loss function for softmax regression is

$$E = -\sum_{l=0}^{K-1} 1_{\{label=l\}} \log y_l \quad (3)$$

where $y_l = \frac{\exp(a_l)}{\sum_{m=0}^{K-1} \exp(a_m)}$

For the output layer, we have

$$\delta_k = -\frac{\partial E}{\partial a_k} = -\sum_l \frac{\partial E}{\partial y_l} \frac{\partial y_l}{\partial a_k} \quad (4)$$

$$= -\sum_l -\frac{1_{\{label=l\}}}{y_l} (y_l \delta_{lk} - y_l y_k) \quad (5)$$

$$= \sum_l 1_{\{label=l\}} (\delta_{lk} - y_k) \quad (6)$$

$$= \sum_l \delta_{lk} 1_{\{label=l\}} - y_k \sum_l 1_{\{label=l\}} \quad (7)$$

$$= 1_{\{label=k\}} - y_k = t_k - y_k \quad (8)$$

For the hidden layer, $y_j = g(a_j)$, we have

$$\delta_j = -\frac{\partial E}{\partial a_j} = -\sum_k \frac{\partial E}{\partial a_k} \frac{\partial a_k}{\partial a_j} \quad (9)$$

$$= \sum_k \delta_k \frac{\partial a_k}{\partial a_j} = \sum_k \delta_k \frac{\partial a_k}{\partial y_j} \frac{\partial y_j}{\partial a_j} \quad (10)$$

$$= \sum_k \delta_k \frac{\partial \sum_l w_{lk} y_l}{\partial y_j} y_j' = \sum_k \delta_k w_{jk} y_j' \quad (11)$$

$$= y_j' \sum_k \delta_k w_{jk} \quad (12)$$

where δ_k has been computed from the output layer.

(b) For the output layer, we have

$$w_{jk} = w_{jk} - \alpha \frac{\partial E}{\partial w_{jk}} = w_{jk} - \alpha \frac{\partial E}{\partial a_k} \frac{\partial a_k}{\partial w_{jk}} \quad (13)$$

$$= w_{jk} + \alpha \delta_k \frac{\partial \sum_l w_{lk} y_l}{\partial w_{jk}} \quad (14)$$

$$= w_{jk} + \alpha \delta_k y_j \quad (15)$$

For the hidden layer, we have

$$w_{ij} = w_{ij} - \alpha \frac{\partial E}{\partial w_{ij}} = w_{ij} - \alpha \frac{\partial E}{\partial a_j} \frac{\partial a_j}{\partial w_{ij}} \quad (16)$$

$$= w_{ij} + \alpha \delta_j \frac{\partial \sum_l w_{lj} x_l}{\partial w_{ij}} \quad (17)$$

$$= w_{ij} + \alpha \delta_j x_i \quad (18)$$

where we have already computed the δ_k and δ_j in part (a).

(c) For the output layer, since $w_{jk} = w_{jk} + \alpha \delta_k y_j$, we have

$$W_{HO} = W_{HO} + \alpha y^{(j)} \otimes \delta^{(k)} \quad (19)$$

where $y^{(j)}$ is a column-vector output from hidden layer, $\delta^{(k)}$ is a column-vector δ from the output layer, and \otimes is an outer product operator.

Similarly, for the hidden layer, since $w_{ij} = w_{ij} + \alpha \delta_j x_i$, we have

$$W_{IH} = W_{IH} + \alpha x^{(i)} \otimes \delta^{(j)} \quad (20)$$

where $x^{(i)}$ is a column-vector input, $\delta^{(j)}$ is a column-vector δ from the hidden layer, and \otimes is an outer product operator.

Since $\delta_j = y'_j \sum_k \delta_k w_{jk}$, we have

$$\delta^{(j)} = (y')^{(j)} \odot (W_{HO} \bullet \delta^{(k)}) \quad (21)$$

where \odot is an element-wise multiplication operator. Thus, we have

$$W_{IH} = W_{IH} + \alpha x^{(i)} \otimes \left((y')^{(j)} \odot (W_{HO} \bullet \delta^{(k)}) \right) \quad (22)$$

(d)

- i. See code 'DataProcess.py' for detail
- ii. I choose a few parameters and the difference is smaller than 10^{-5} . Since I also get fine results in the following questions, I think my gradient is correct.
- iii. We can see from Figure 1 that the training and test accuracy increases rapidly with number of iteration.

(e) From Figure 2, we can see that with regularization, the accuracy also increases rapidly with number of iterations. Large regularization can prevent from overfitting but make the model less powerful. With regularization, the gradient converges faster than the one without any trick. However, as regularization parameter increases, the accuracy decreases a little bit because the model is less powerful.

(f) From Figure 3, the accuracy also increases with number of iterations but increases slower than previous cases. This is because momentum intends to dump big jumps during gradient descent process.

(g) Figure 4 shows how accuracy changes with number of iteration for different functions. We can see that *sigmoid* activation function converges more quickly than *tanh* and *ReLU*, and *tanh* converges quicker than *ReLU*. This is because *ReLU* is a linear increasing function, while *sigmoid* and *tanh* are nonlinear functions and become saturated when input is large

(h)

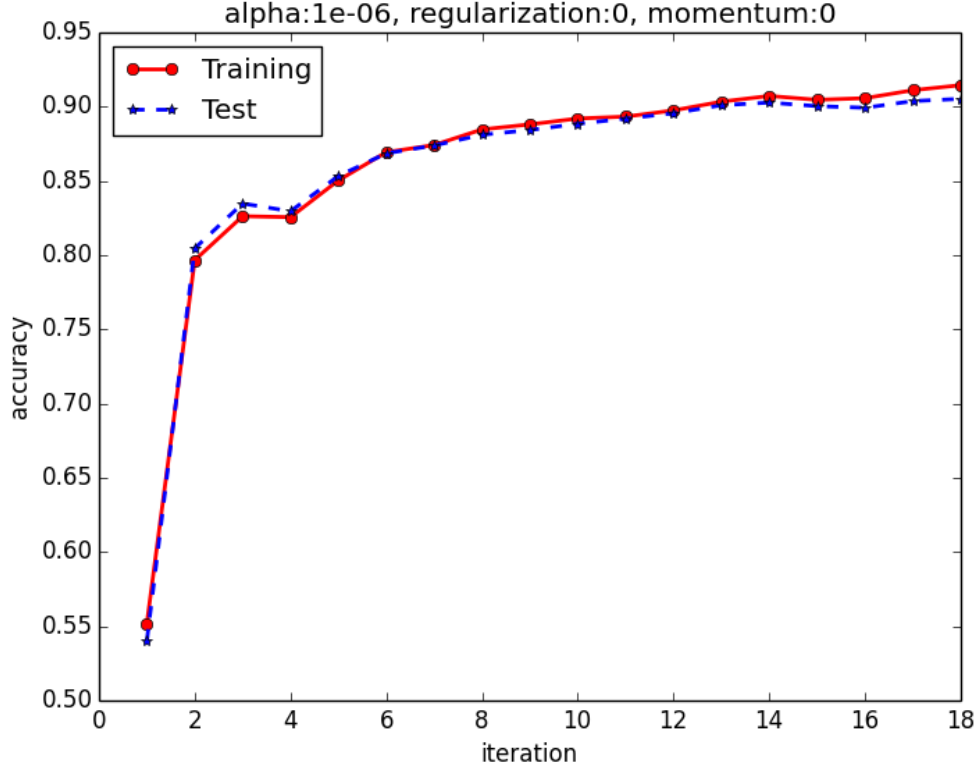
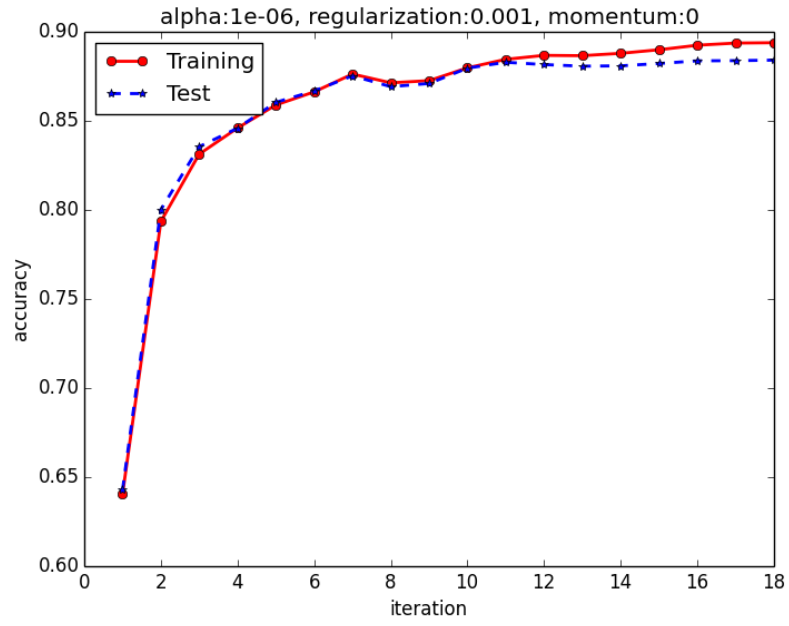
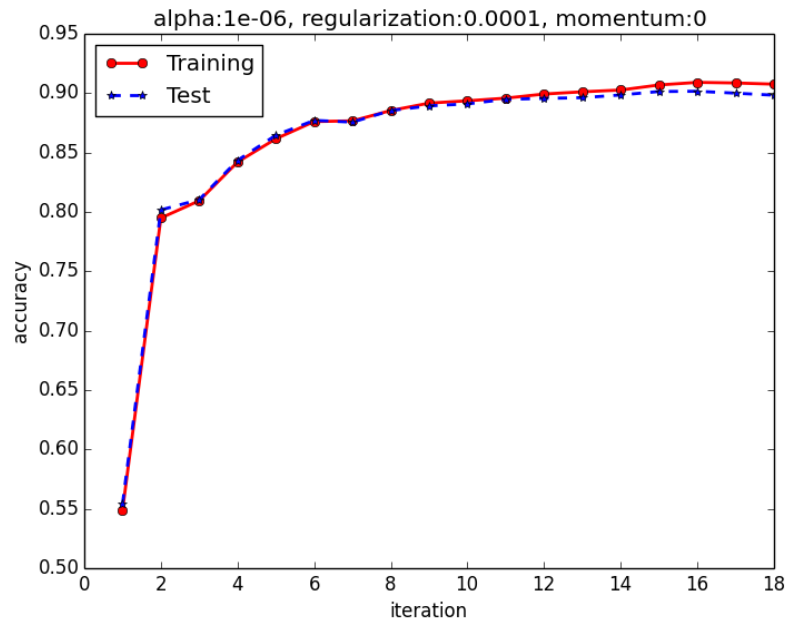


Figure 1: (d).iii. Sigmoid without trick

- i. From Figure 5, we can see that the accuracy increases with number of hidden units. It makes sense because the neural network becomes more powerful when the number of hidden units is larger. However, we can see that the accuracy improvement is very small. So, it is not always necessary to have a very large number of hidden units to increase slight accuracy but sacrifice a lot of computational time.
- ii. From Figure 6, we can see that, though the number of weights are similar, the accuracy increases with number of layers. Although, this double hidden layer network has similar number of weight, it has more complicated structure, and thus provides more powerful representation. So, when increasing hidden units does not increase the accuracy significantly, we can consider changing the structure of the network.



(a) regularization: 0.001



(b) regularization: 0.0001

Figure 2: (e). Different regularization

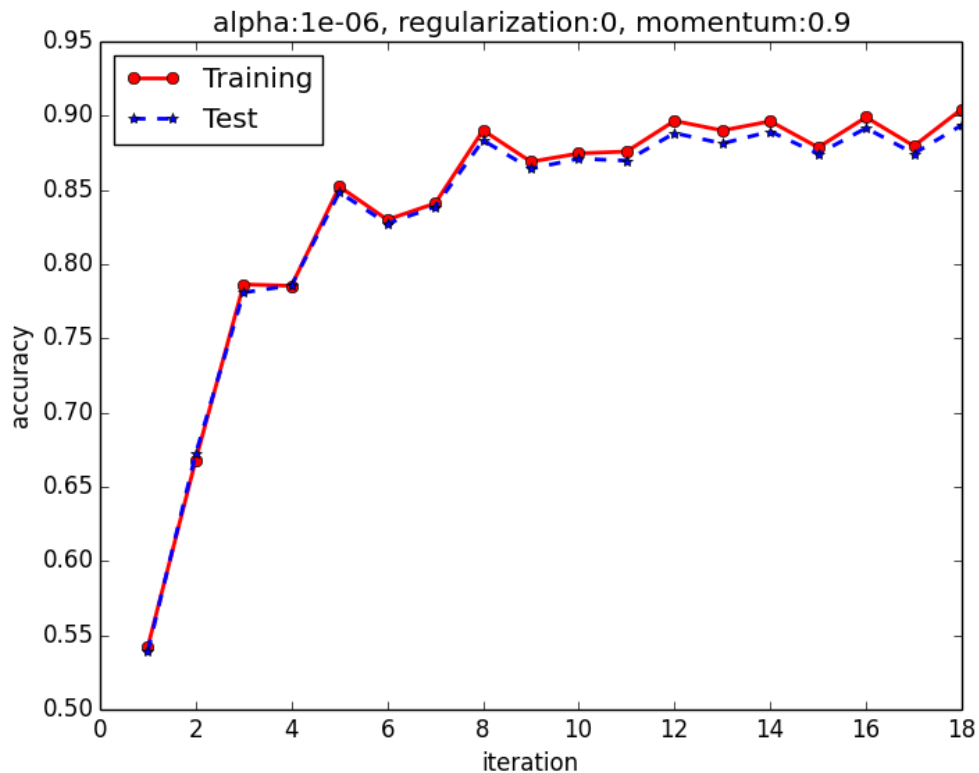


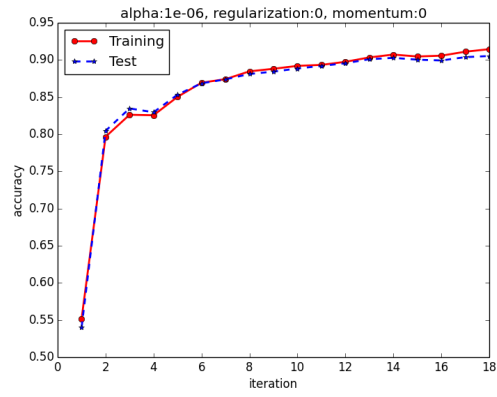
Figure 3: (f). With momentum

3 Appendix

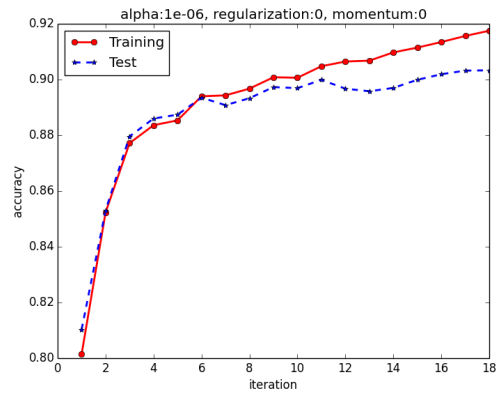
The following is the source code

```
##### DataProcess.py #####
import os, struct
import numpy as np
from array import array as pyarray
from numpy import append, array, int8, uint8, zeros
from scipy import stats

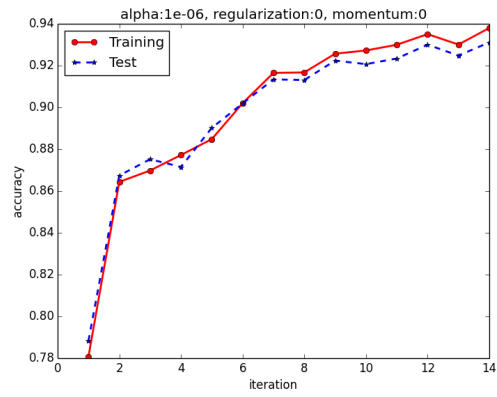
def load_mnist(dataset="training", digits=None, path=None,
               asbytes=False, selection=None,
               return_labels=True, return_indices=False, zscore=True,
               appendOne=True, isShuffle=True):
```



(a) sigmoid

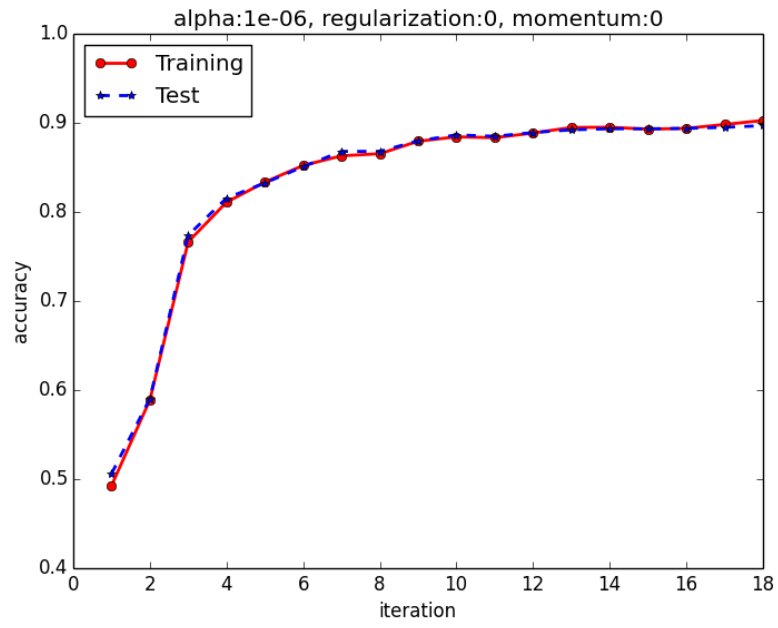


(b) tanh

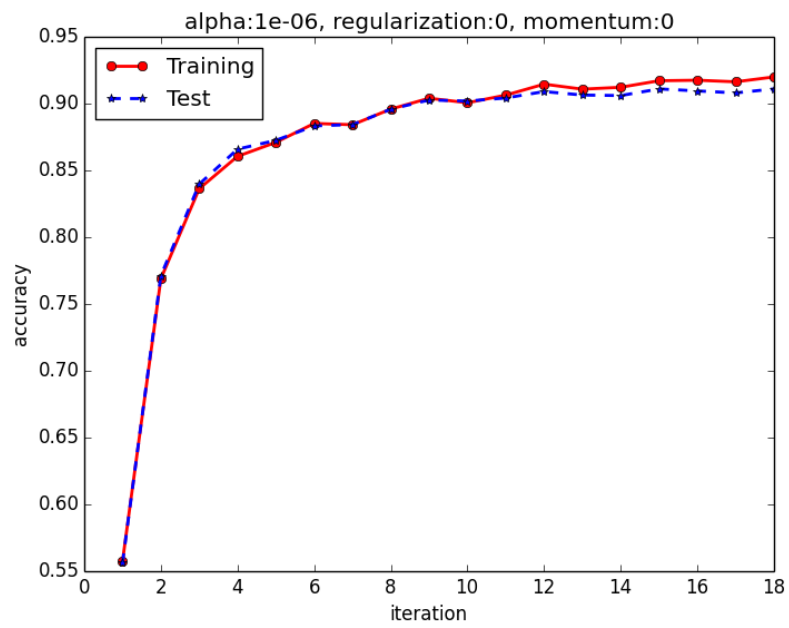


(c) ReLu

Figure 4: (g). Different activation functions



(a) Half hidden units



(b) Double hidden units

Figure 5: (h).i. Different number of hidden units

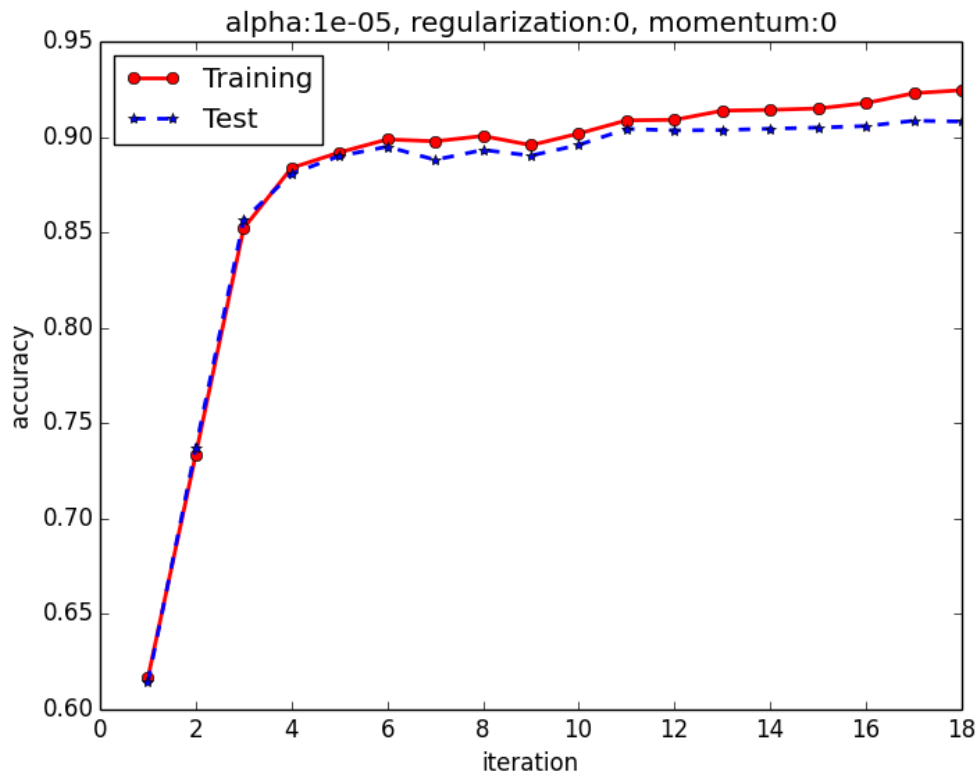


Figure 6: (h).ii. Two Hidden Layer

”””

Loads MNIST files into a 3D numpy array.

You have to download the data separately from [MNIST]_.

It is recommended to set the environment variable ‘‘MNIST’’ to point to the folder where you put the data, so that you don’t have to select path. On a Linux+bash setup, this is done by adding the following to your ‘‘.bashrc
‘‘::

export MNIST=/path/to/mnist

Parameters

dataset : str
Either "training" or "testing", depending on which dataset you want to load.

digits : list
Integer list of digits to load. The entire database is loaded if set to "None". Default is "None".

path : str
Path to your MNIST datafiles. The default is "None", which will try to take the path from your environment variable "MNIST". The data can be downloaded from <http://yann.lecun.com/exdb/mnist/>.

asbytes : bool
If True, returns data as "numpy.uint8" in [0, 255] as opposed to "numpy.float64" in [0.0, 1.0].

selection : slice
Using a "slice" object, specify what subset of the dataset to load. An example is "slice(0, 20, 2)", which would load every other digit until—but not including—the twentieth.

return_labels : bool
Specify whether or not labels should be returned. This is also a speed performance if digits are not specified, since then the labels file does not need to be read at all.

return_indicies : bool
Specify whether or not to return the MNIST indices that were fetched. This is valuable only if digits is specified, because in that case it can be valuable to know how far in the database it reached.

zscore : boolean

if True, do the zscore transformation for the raw image data. Default is true.
appendOne : boolean
if True, append one in the front of the image data representing the input to the bias node
isShuffle : boolean
if True, shuffle the data set.

Returns

images : ndarray
Image data of shape ‘(N, rows, cols)’, where ‘N’ is the number of images. If neither labels nor indices are returned, then this is returned directly, and not inside a 1-sized tuple.
labels : ndarray
Array of size ‘N’ describing the labels. Returned only if ‘return_labels’ is ‘True’, which is default.
indices : ndarray
The indices in the database that were returned.

Examples

Assuming that you have downloaded the MNIST database and set the environment variable ‘\$MNIST’ point to the folder, this will load all images and labels from the training set:

```
>>> images, labels = ag.io.load_mnist('training') #
doctest: +SKIP
```

Load 100 sevens from the testing set:

```
>>> sevens = ag.io.load_mnist('testing', digits=[7],
selection=slice(0, 100), return_labels=False) #
doctest: +SKIP
```

"""

```

# The files are assumed to have these names and should
be found in 'path'
files = {
    'training': ('train-images-idx3-ubyte', 'train-
                labels-idx1-ubyte'),
    'testing': ('t10k-images-idx3-ubyte', 't10k-labels-
                idx1-ubyte'),
}

if path is None:
    try:
        path = os.environ['MNIST']
    except KeyError:
        raise ValueError("Unspecified_path_requires_
                           environment_variable_$MNIST_to_be_set")

try:
    images_fname = os.path.join(path, files[dataset
][0])
    labels_fname = os.path.join(path, files[dataset
][1])
except KeyError:
    raise ValueError("Data_set_must_be_'testing'_or_'
training'")

# We can skip the labels file only if digits aren't
specified and labels aren't asked for
if return_labels or digits is not None:
    flbl = open(labels_fname, 'rb')
    magic_nr, size = struct.unpack(">II", flbl.read(8))
    labels_raw = pyarray("b", flbl.read())
    flbl.close()

fimg = open(images_fname, 'rb')
magic_nr, size, rows, cols = struct.unpack(">IIII",
fimg.read(16))
images_raw = pyarray("B", fimg.read())
fimg.close()

```

```

indices = range(size)
N = len(indices)

images = zeros((N, rows*cols), dtype=uint8)

if return_labels:
    labels = zeros((N), dtype=int8)
for i, index in enumerate(indices):
    images[i] = array(images_raw[ indices[i]*rows*cols
        : (indices[i]+1)*rows*cols ]).reshape(1,rows*
        cols)
    if return_labels:
        labels[i] = labels_raw[indices[i]]

if not asbytes:
    images = images.astype(float)/255.0

if zscore:
    images = zscoreTransform(images);
#numpy.insert(arr, index, values, axis=None)
if appendOne:
    images = np.insert(images, 0, 1, axis=1)

#shuffle the images
if isShuffle:
    np.random.shuffle(indices)
    images = images[indices]
    labels = labels[indices]

#choose images from shuffled images
indices = range(size)
if digits:
    indices = [k for k in range(size) if labels[k] in
        digits]

if selection:
    indices = indices[selection]

images = images[indices]

```

```

labels = labels[indices]

ret = (images,)
if return_labels:
    ret += (labels,)
if return_indices:
    ret += (indices,)
if len(ret) == 1:
    return ret[0] # Don't return a tuple of one
else:
    return ret

def zscoreTransform(data):
    """
    Do a z-score transformation for the data such that the
    mean is 0 and variance is 1.
    """
    zscoreData = stats.zscore(data);
    #convert NaN to zero. NaN mean this feacture is a
    constant. So this feature is zero after centering
    zscoreData[np.isnan(zscoreData)] = 0;
    return zscoreData

if __name__ == '__main__':
    myTrainData = load_mnist(dataset="training", path='../'
        , digits = None, selection = None, zscore = True,
        isShuffle = True)
    import matplotlib.pyplot as plt

    images = myTrainData[0]
    for i in range(4):
        print i
        image = images[i]
        image = image[1:].reshape(28,28)
        plt.imshow(image, cmap=plt.get_cmap('gray'))
        plt.show()

```

```
##### FunctionGradient #####
import numpy as np

def SoftMaxFunc(inputValue):
    return np.exp(inputValue) / sum(np.exp(inputValue))

def tanh(inputValue):
    return np.tanh(inputValue)

def tanhGradient(inputValue):
    return 1 - np.multiply(tanh(inputValue), tanh(
        inputValue))

def sigmoid(inputValue):
    return 1.0 / (1 + np.exp(-inputValue))

def sigmoidGradient(inputValue):
    return np.multiply(sigmoid(inputValue), 1 - sigmoid(
        inputValue))

def ReLu(inputValue):
    return np.maximum(0, inputValue)

def ReLuGradient(inputValue):
    slope = np.ones(inputValue.shape)
    slope[inputValue <= 0] = 0
    return slope

##### multilayer.py #####
import numpy as np
from FunctionGradient import SoftMaxFunc, tanh,
    tanhGradient, sigmoid, sigmoidGradient, ReLu,
    ReLuGradient
from DataProcess import load_mnist
import matplotlib.pyplot as plt
import timeit

class SoftmaxTopLayer(object):
    def __init__(self, rng, n_in, n_out):
        self.W = np.asarray( rng.uniform(
```

```

        low = -np.sqrt(6.0 / (n_in + n_out)
        ),
        high = np.sqrt(6.0 / (n_in + n_out)
        ),
        size = (n_in, n_out)
    )
    # $W(t) - W(t - 1)$ 
    self.deltaW = np.zeros((n_in, n_out))

    self.delta = np.zeros(n_out)
    # $\partial E / \partial W$ 
    self.weightGradient = np.zeros((n_in, n_out))
    self.inputValue = np.zeros(n_in)
    self.y = SoftMaxFunc(np.dot(self.inputValue, self.W))
    self.predict = np.argmax(self.y)
    self.params = self.W

```

```

class HiddenLayer(object):
    def __init__(self, rng, n_in, n_out, activation,
        activationGradient):
        self.W = np.asarray( rng.uniform(
            low = -np.sqrt(6.0 / (n_in + n_out)
            ),
            high = np.sqrt(6.0 / (n_in + n_out)
            ),
            size = (n_in, n_out)
        )
        self.W[:,0] = 0
        # $W(t) - W(t - 1)$ 
        self.deltaW = np.zeros((n_in, n_out))

        #print self.W
        self.activation = activation

```



```

self.activationGradient =
    activationGradient

#the derivative at bias unit is zero
self.delta = np.zeros(n_out)
self.weightGradient = np.zeros((n_in, n_out
    ))
self.inputValue = np.zeros(n_in)
self.linearOutput = np.dot(self.inputValue,
    self.W)
#add bias unit
self.y = activation(self.linearOutput)
self.y[0] = 1

self.yPrime = activationGradient(self.
    linearOutput)
self.yPrime[0] = 0

self.params = self.W

```

```

class MultiLayerPerceptron(object):
    def __init__(self, rng, n_in, n_hidden, n_out,
        activation = tanh,
        activationGradient =
        tanhGradient, learningRate =
        10**(-6), regularization = 0,
        momentum = 0):
self.labelRange = np.array(range(10))

self.hiddenLayer = HiddenLayer(
    rng = rng, n_in = n_in, n_out =
    n_hidden + 1, activation =
    activation, activationGradient =
    activationGradient
)

self.softmaxTopLayer = SoftmaxTopLayer(
    rng = rng, n_in = n_hidden + 1,
    n_out = n_out

```

```

)

self.params = [self.hiddenLayer.params] + [
    self.softmaxTopLayer.params]
self.learningRate = learningRate
self.regularization = regularization
self.momentum = momentum

def forwardPropagate(self, inputValue, output):
    outputVec = 1*(self.labelRange == output)

    #propagate to the hidden layer, bias
    corresponds to a unit with constant
    output 1
    self.hiddenLayer.inputValue = inputValue
    self.hiddenLayer.linearOutput = np.dot(self
        .hiddenLayer.inputValue, self.
        hiddenLayer.W)
    self.hiddenLayer.y = self.hiddenLayer.
        activation(self.hiddenLayer.linearOutput
        )
    self.hiddenLayer.y[0] = 1

    self.hiddenLayer.yPrime = self.hiddenLayer.
        activationGradient(self.hiddenLayer.
        linearOutput)
    self.hiddenLayer.yPrime[0] = 0

    #propagate to the top layer, bias
    corresponds to a unit with constant
    output 1
    self.softmaxTopLayer.inputValue = self.
        hiddenLayer.y
    self.softmaxTopLayer.linearOutput = np.dot(
        self.softmaxTopLayer.inputValue, self.
        softmaxTopLayer.W)
    self.softmaxTopLayer.y = SoftMaxFunc(self.
        softmaxTopLayer.linearOutput)

```

```

self.softmaxTopLayer.predict = np.argmax(
    self.softmaxTopLayer.y)

self.softmaxTopLayer.delta = outputVec -
    self.softmaxTopLayer.y
self.softmaxTopLayer.weightGradient = self.
    softmaxTopLayer.weightGradient - \
        np.outer(self.softmaxTopLayer.
            inputValue, self.softmaxTopLayer.
                delta)

def backwardPropagate(self):
    self.hiddenLayer.delta = np.multiply(self.
        hiddenLayer.yPrime,
        np.dot(self.softmaxTopLayer.W, self.
            softmaxTopLayer.delta))

    self.hiddenLayer.weightGradient = self.
        hiddenLayer.weightGradient - \
            np.outer(self.hiddenLayer.
                inputValue, self.hiddenLayer.
                    delta)

def updateWeight(self):
    preW = self.softmaxTopLayer.W
    self.softmaxTopLayer.W = preW - \
        self.learningRate*self.
            softmaxTopLayer.weightGradient +
            \
            2*self.regularization*preW + self.
                momentum*self.softmaxTopLayer.
                    deltaW
    self.softmaxTopLayer.deltaW = self.
        softmaxTopLayer.W - preW

preHiddenW = self.hiddenLayer.W

```

```

        self.hiddenLayer.W = preHiddenW - \
            self.learningRate*self.hiddenLayer.
                weightGradient + \
            2*self.regularization*preHiddenW +
                self.momentum*self.hiddenLayer.
                    deltaW
        self.hiddenLayer.deltaW = self.hiddenLayer.
            W - preHiddenW

    def accuracy(self, INPUT, OUTPUT):
        count = 0
        for inputValue, output in zip(INPUT,OUTPUT)
            :
                linearOutputHidden = np.dot(
                    inputValue, self.hiddenLayer.W)
                yHidden = self.hiddenLayer.
                    activation(linearOutputHidden)
                yHidden[0] = 1

                linearOutput = np.dot(yHidden, self
                    .softmaxTopLayer.W)
                y = SoftMaxFunc(linearOutput)
                predict = np.argmax(y)

                if predict == output:
                    count = count + 1

        return (float(count) / len(OUTPUT))

def test_MLP(MLP, trainImage, trainLabel, validImage,
    validLabel, testImage, testLabel, fileName, nEpochs=18):
    batchSize = 500
    numBatch = trainImage.shape[0] / batchSize

    trainingAccuracy = []
    testAccuracy = []
    preValidAccuracy = 0.05

    for k in range(nEpochs):

```

```

start_time = timeit.default_timer()
for i in range(numBatch):
    #miniBatch
    for j in range(batchSize):
        index = i*batchSize + j
        MLP.forwardPropagate(
            trainImage[index,:],
            trainLabel[index])
        MLP.backwardPropagate()

        MLP.updateWeight()
    validAccuracy = MLP.accuracy(validImage,
        validLabel)

    if validAccuracy > 0.95 and (abs(
        validAccuracy - preValidAccuracy) /
        preValidAccuracy < 0.0005):
        break
    preValidAccuracy = validAccuracy

end_time = timeit.default_timer()
print "one_pass_takes_" + str(end_time -
    start_time) + 's'
trainingAccuracy.append(MLP.accuracy(
    trainImage, trainLabel))
testAccuracy.append(MLP.accuracy(testImage,
    testLabel))

plt.plot(range(1, len(trainingAccuracy) + 1,1),
    trainingAccuracy, 'ro-', linewidth=2)
plt.plot(range(1, len(testAccuracy) + 1,1),
    testAccuracy, 'b*--', linewidth=2)
plt.legend(["Training", "Test"], loc = 2 )
plt.xlabel('iteration')
plt.ylabel('accuracy')
plt.title('alpha:' + str(MLP.learningRate) + ", \
    regularization:" + str(MLP.regularization) + \
    ", \momentum:" + str(MLP.momentum))
plt.savefig(' ./ ' + str(fileName))

```

```

plt.show()

if __name__ == '__main__':
    allTrain = load_mnist(dataset="training", path='../'
                          ')

    trainImage = allTrain[0][0:49999,:]
    trainLabel = allTrain[1][0:49999]

    validImage = allTrain[0][50000:,:]
    validLabel = allTrain[1][50000:]

    allTest = load_mnist(dataset="testing", path='../')
    testImage = allTest[0]
    testLabel = allTest[1]

    rng = np.random.RandomState(1234)

    #(D)
    MLP = MultiLayerPerceptron(rng, n_in = 28*28 + 1,
                                n_hidden = 50, n_out = 10,
                                activation = sigmoid, activationGradient =
                                    sigmoidGradient, learningRate = 10*(-6)
                                )
    test_MLP(MLP, trainImage, trainLabel, validImage,
             validLabel, testImage, testLabel, "sigmoid.png")

    #(E) /over flow occur
    MLPRegul = MultiLayerPerceptron(rng, n_in = 28*28 +
                                     1, n_hidden = 50, n_out = 10,
                                     activation = sigmoid, activationGradient =
                                         sigmoidGradient, learningRate = 10*(-6)
                                     , regularization = 0.001)
    test_MLP(MLPRegul, trainImage, trainLabel,
             validImage, validLabel, testImage, testLabel, "
             regularization1.png")

    MLPRegu2 = MultiLayerPerceptron(rng, n_in = 28*28 +
                                     1, n_hidden = 50, n_out = 10,

```

```

        activation = sigmoid, activationGradient =
            sigmoidGradient, learningRate = 10**(-6)
            , regularization = 0.0001)
test_MLP(MLPRegu2, trainImage, trainLabel,
        validImage, validLabel, testImage, testLabel, "
        regularization2.png")

```

#(F)

```

MLPMomentum = MultiLayerPerceptron(rng, n_in =
    28*28 + 1, n_hidden = 50, n_out = 10,
        activation = sigmoid, activationGradient =
            sigmoidGradient, learningRate = 10**(-6)
            , momentum = 0.9)
test_MLP(MLPMomentum, trainImage, trainLabel,
        validImage, validLabel, testImage, testLabel, "
        momentum.png")

```

#(G)

```

MLPTanh = MultiLayerPerceptron(rng, n_in = 28*28 +
    1, n_hidden = 50, n_out = 10,
        activation = tanh, activationGradient =
            tanhGradient, learningRate = 10**(-6))
test_MLP(MLPTanh, trainImage, trainLabel,
        validImage, validLabel, testImage, testLabel, "
        tanh.png")

```

```

MLPReLU = MultiLayerPerceptron(rng, n_in = 28*28 +
    1, n_hidden = 50, n_out = 10,
        activation = ReLu, activationGradient =
            ReLuGradient, learningRate = 10**(-6))
test_MLP(MLPReLU, trainImage, trainLabel,
        validImage, validLabel, testImage, testLabel, "
        ReLu.png", nEpochs=14)

```

#(H)

```

MLPHalf = MultiLayerPerceptron(rng, n_in = 28*28 +
    1, n_hidden = 25, n_out = 10,
        activation = sigmoid, activationGradient =
            sigmoidGradient, learningRate = 10**(-6)
        )

```

```

test_MLP(MLPHalf, trainImage, trainLabel,
         validImage, validLabel, testImage, testLabel,"
         HalfHiddenUnits.png")

MLPDouble = MultiLayerPerceptron(rng, n_in = 28*28
    + 1, n_hidden = 100, n_out = 10,
    activation = sigmoid, activationGradient =
    sigmoidGradient, learningRate = 10*(-6)
    )
test_MLP(MLPDouble, trainImage, trainLabel,
         validImage, validLabel, testImage, testLabel,"
         DoubleHiddenUnits.png")

##### twoHiddenLayerNN.py #####
import numpy as np
from FunctionGradient import SoftMaxFunc, tanh,
    tanhGradient, sigmoid, sigmoidGradient, ReLu,
    ReLuGradient
from DataProcess import load_mnist
import matplotlib.pyplot as plt
import timeit
from multilayerNN import SoftmaxTopLayer, HiddenLayer,
    test_MLP

class twoHiddenLayerPerceptron(object):
    def __init__(self, rng, n_in, n_hidden1, n_hidden2,
        n_out,
            activation = sigmoid,
            activationGradient =
            sigmoidGradient, learningRate =
            10*(-5), regularization = 0,
            momentum = 0):
        self.labelRange = np.array(range(10))

        self.hiddenLayer1 = HiddenLayer(
            rng = rng, n_in = n_in, n_out =
            n_hidden1 + 1, activation =
            activation, activationGradient =
            activationGradient
        )

```



```

self.hiddenLayer2 = HiddenLayer(
    rng = rng, n_in = n_hidden1 + 1,
    n_out = n_hidden2 + 1,
    activation = activation,
    activationGradient =
        activationGradient
)

self.softmaxTopLayer = SoftmaxTopLayer(
    rng = rng, n_in = n_hidden2 + 1,
    n_out = n_out
)

self.params = [self.hiddenLayer1.params] +
    [self.hiddenLayer2.params] + [self.
        softmaxTopLayer.params]
self.learningRate = learningRate
self.regularization = regularization
self.momentum = momentum

def forwardPropagate(self, inputValue, output):
    outputVec = 1*(self.labelRange == output)

    #propagate to the hidden layer, bias
    corresponds to a unit with constant
    output 1
    self.hiddenLayer1.inputValue = inputValue
    self.hiddenLayer1.linearOutput = np.dot(
        self.hiddenLayer1.inputValue, self.
            hiddenLayer1.W)
    self.hiddenLayer1.y = self.hiddenLayer1.
        activation(self.hiddenLayer1.
            linearOutput)
    self.hiddenLayer1.y[0] = 1
    self.hiddenLayer1.yPrime = self.
        hiddenLayer1.activationGradient(self.
            hiddenLayer1.linearOutput)
    self.hiddenLayer1.yPrime[0] = 0

```

```

#propagate to the second hidden layer,
    bias corresponds to a unit with constant
    output 1
self.hiddenLayer2.inputValue = self.
    hiddenLayer1.y
self.hiddenLayer2.linearOutput = np.dot(
    self.hiddenLayer2.inputValue, self.
    hiddenLayer2.W)
self.hiddenLayer2.y = self.hiddenLayer2.
    activation(self.hiddenLayer2.
    linearOutput)
self.hiddenLayer2.y[0] = 1
self.hiddenLayer2.yPrime = self.
    hiddenLayer2.activationGradient(self.
    hiddenLayer2.linearOutput)
self.hiddenLayer2.yPrime[0] = 0

#propagate to the top layer, bias
    corresponds to a unit with constant
    output 1
self.softmaxTopLayer.inputValue = self.
    hiddenLayer2.y
self.softmaxTopLayer.linearOutput = np.dot(
    self.softmaxTopLayer.inputValue, self.
    softmaxTopLayer.W)
self.softmaxTopLayer.y = SoftMaxFunc(self.
    softmaxTopLayer.linearOutput)
self.softmaxTopLayer.predict = np.argmax(
    self.softmaxTopLayer.y)

self.softmaxTopLayer.delta = outputVec -
    self.softmaxTopLayer.y
self.softmaxTopLayer.weightGradient = self.
    softmaxTopLayer.weightGradient - \

```

```

def backwardPropagate(self):
    self.hiddenLayer2.delta = np.multiply(self.
        hiddenLayer2.yPrime,
        np.dot(self.softmaxTopLayer.W, self.
            softmaxTopLayer.delta))

    self.hiddenLayer2.weightGradient = self.
        hiddenLayer2.weightGradient - \
        np.outer(self.hiddenLayer2.
            inputValue, self.hiddenLayer2.
            delta)

    self.hiddenLayer1.delta = np.multiply(self.
        hiddenLayer1.yPrime,
        np.dot(self.hiddenLayer2.W, self.
            hiddenLayer2.delta))

    self.hiddenLayer1.weightGradient = self.
        hiddenLayer1.weightGradient - \
        np.outer(self.hiddenLayer1.
            inputValue, self.hiddenLayer1.
            delta)

def updateWeight(self):
    preW = self.softmaxTopLayer.W
    self.softmaxTopLayer.W = preW - \

```

```

        self.learningRate*self.
            softmaxTopLayer.weightGradient +
            \
        2*self.regularization*preW + self.
            momentum*self.softmaxTopLayer.
            deltaW
self.softmaxTopLayer.deltaW = self.
    softmaxTopLayer.W - preW

```

```

preHiddenW2 = self.hiddenLayer2.W
self.hiddenLayer2.W = preHiddenW2 - \
    self.learningRate*self.hiddenLayer2
        .weightGradient + \
    2*self.regularization*preHiddenW2 +
        self.momentum*self.hiddenLayer2
        .deltaW
self.hiddenLayer2.deltaW = self.
    hiddenLayer2.W - preHiddenW2

```

```

preHiddenW1 = self.hiddenLayer1.W
self.hiddenLayer1.W = preHiddenW1 - \
    self.learningRate*self.hiddenLayer1
        .weightGradient + \
    2*self.regularization*preHiddenW1 +
        self.momentum*self.hiddenLayer1
        .deltaW
self.hiddenLayer1.deltaW = self.
    hiddenLayer1.W - preHiddenW1

```

```

def accuracy(self, INPUT, OUTPUT):
    count = 0
    for inputValue, output in zip(INPUT,OUTPUT)
        :
        linearOutputHidden1 = np.dot(
            inputValue, self.hiddenLayer1.W)
        yHidden1 = self.hiddenLayer1.
            activation(linearOutputHidden1)

```

```

yHidden1[0] = 1

linearOutputHidden2 = np.dot(
    yHidden1, self.hiddenLayer2.W)
yHidden2 = self.hiddenLayer2.
    activation(linearOutputHidden2)
yHidden2[0] = 1

linearOutput = np.dot(yHidden2,
    self.softmaxTopLayer.W)
y = SoftMaxFunc(linearOutput)
predict = np.argmax(y)

if predict == output:
    count = count + 1

return (float(count) / len(OUTPUT))

if __name__ == '__main__':
    allTrain = load_mnist(dataset="training", path='../
        ')

    trainImage = allTrain[0][0:49999,:]
    trainLabel = allTrain[1][0:49999]

    validImage = allTrain[0][50000:,:]
    validLabel = allTrain[1][50000:]

    allTest = load_mnist(dataset="testing", path='../ ')
    testImage = allTest[0]
    testLabel = allTest[1]

    rng = np.random.RandomState(1234)

    #(D)
    MLP = twoHiddenLayerPerceptron(rng, n_in = 28*28 +
        1, n_hidden1 = 43, n_hidden2 = 43, n_out = 10,
        activation = sigmoid, activationGradient =
        sigmoidGradient, learningRate = 10**(-5))

```

```
)  
test_MLP(MLP, trainImage, trainLabel, validImage,  
         validLabel, testImage, testLabel, "twoHiddenLayer  
         .png")
```