Download from finelybook www.finelybook.com off between these two objectives. This gives us the constrained optimization problem in Equation 5-4.

Equation 5-4. Soft margin linear SVM classifier objective

$$\begin{aligned} & \underset{\mathbf{w},b,\zeta}{\text{minimize}} & & \frac{1}{2}\mathbf{w}^T \cdot \mathbf{w} + C \sum_{i=1}^m \zeta^{(i)} \\ & \text{subject to} & & t^{(i)} \Big(\mathbf{w}^T \cdot \mathbf{x}^{(i)} + b\Big) \geq 1 - \zeta^{(i)} & \text{and} & & \zeta^{(i)} \geq 0 & \text{for } i = 1,2,\cdots,m \end{aligned}$$

Quadratic Programming

The hard margin and soft margin problems are both convex quadratic optimization problems with linear constraints. Such problems are known as Quadratic Programming (QP) problems. Many off-the-shelf solvers are available to solve QP problems using a variety of techniques that are outside the scope of this book.⁵ The general problem formulation is given by Equation 5-5.

Equation 5-5. Quadratic Programming problem

$$\begin{array}{lll} \text{Minimize} & \frac{1}{2}\mathbf{p}^T\cdot\mathbf{H}\cdot\mathbf{p} & + & \mathbf{f}^T\cdot\mathbf{p} \\ \text{subject to} & \mathbf{A}\cdot\mathbf{p} \leq \mathbf{b} \\ & \begin{bmatrix} \mathbf{p} & \text{is an } n_p\text{-dimensional vector } (n_p = \text{number of parameters}), \\ \mathbf{H} & \text{is an } n_p \times n_p \text{ matrix,} \\ \mathbf{f} & \text{is an } n_p\text{-dimensional vector,} \\ \mathbf{A} & \text{is an } n_c \times n_p \text{ matrix } (n_c = \text{number of constraints}), \\ \mathbf{b} & \text{is an } n_c\text{-dimensional vector.} \\ \end{array}$$

Note that the expression $\mathbf{A} \cdot \mathbf{p} \leq \mathbf{b}$ actually defines n_c constraints: $\mathbf{p}^T \cdot \mathbf{a}^{(i)} \leq b^{(i)}$ for i = 11, 2, ..., n_c , where $\mathbf{a}^{(i)}$ is the vector containing the elements of the ith row of \mathbf{A} and $b^{(i)}$ is the ith element of **b**.

You can easily verify that if you set the QP parameters in the following way, you get the hard margin linear SVM classifier objective:

• $n_p = n + 1$, where *n* is the number of features (the +1 is for the bias term).

⁵ To learn more about Quadratic Programming, you can start by reading Stephen Boyd and Lieven Vandenberghe, Convex Optimization (Cambridge, UK: Cambridge University Press, 2004) or watch Richard Brown's series of video lectures.

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- $n_c = m$, where m is the number of training instances.
- **H** is the $n_p \times n_p$ identity matrix, except with a zero in the top-left cell (to ignore the bias term).
- $\mathbf{f} = \mathbf{0}$, an n_p -dimensional vector full of 0s.
- $\mathbf{b} = \mathbf{1}$, an n_c -dimensional vector full of 1s.
- $\mathbf{a}^{(i)} = -t^{(i)} \dot{\mathbf{x}}^{(i)}$, where $\dot{\mathbf{x}}^{(i)}$ is equal to $\mathbf{x}^{(i)}$ with an extra bias feature $\dot{\mathbf{x}}_0 = 1$.

So one way to train a hard margin linear SVM classifier is just to use an off-the-shelf QP solver by passing it the preceding parameters. The resulting vector \mathbf{p} will contain the bias term $b = p_0$ and the feature weights $w_i = p_i$ for $i = 1, 2, \dots, m$. Similarly, you can use a QP solver to solve the soft margin problem (see the exercises at the end of the chapter).

However, to use the kernel trick we are going to look at a different constrained optimization problem.

The Dual Problem

Given a constrained optimization problem, known as the *primal problem*, it is possible to express a different but closely related problem, called its *dual problem*. The solution to the dual problem typically gives a lower bound to the solution of the primal problem, but under some conditions it can even have the same solutions as the primal problem. Luckily, the SVM problem happens to meet these conditions,⁶ so you can choose to solve the primal problem or the dual problem; both will have the same solution. Equation 5-6 shows the dual form of the linear SVM objective (if you are interested in knowing how to derive the dual problem from the primal problem, see Appendix C).

Equation 5-6. Dual form of the linear SVM objective

$$\begin{aligned} & \underset{\alpha}{\text{minimize}} \ \frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \alpha^{(i)} \alpha^{(j)} t^{(i)} t^{(j)} \mathbf{x}^{(i)}^T \cdot \mathbf{x}^{(j)} & - \sum_{i=1}^{m} \alpha^{(i)} \\ & \text{subject to} \quad \alpha^{(i)} \geq 0 \quad \text{for } i = 1, 2, \cdots, m \end{aligned}$$

⁶ The objective function is convex, and the inequality constraints are continuously differentiable and convex functions.