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- Machine Learning is about making machines get better at some task by learning from data, instead of having to explicitly code rules.
- There are many different types of ML systems: supervised or not, batch or online, instance-based or model-based, and so on.
- In a ML project you gather data in a training set, and you feed the training set to a learning algorithm. If the algorithm is model-based it tunes some parameters to fit the model to the training set (i.e., to make good predictions on the training set itself), and then hopefully it will be able to make good predictions on new cases as well. If the algorithm is instance-based, it just learns the examples by heart and uses a similarity measure to generalize to new instances.
- The system will not perform well if your training set is too small, or if the data is not representative, noisy, or polluted with irrelevant features (garbage in, garbage out). Lastly, your model needs to be neither too simple (in which case it will underfit) nor too complex (in which case it will overfit).

There's just one last important topic to cover: once you have trained a model, you don't want to just "hope" it generalizes to new cases. You want to evaluate it, and finetune it if necessary. Let's see how.

Testing and Validating

The only way to know how well a model will generalize to new cases is to actually try it out on new cases. One way to do that is to put your model in production and monitor how well it performs. This works well, but if your model is horribly bad, your users will complain—not the best idea.

A better option is to split your data into two sets: the training set and the test set. As these names imply, you train your model using the training set, and you test it using the test set. The error rate on new cases is called the generalization error (or out-ofsample error), and by evaluating your model on the test set, you get an estimation of this error. This value tells you how well your model will perform on instances it has never seen before.

If the training error is low (i.e., your model makes few mistakes on the training set) but the generalization error is high, it means that your model is overfitting the training data.



It is common to use 80% of the data for training and hold out 20% for testing.

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So evaluating a model is simple enough: just use a test set. Now suppose you are hesitating between two models (say a linear model and a polynomial model): how can you decide? One option is to train both and compare how well they generalize using the test set.

Now suppose that the linear model generalizes better, but you want to apply some regularization to avoid overfitting. The question is: how do you choose the value of the regularization hyperparameter? One option is to train 100 different models using 100 different values for this hyperparameter. Suppose you find the best hyperparameter value that produces a model with the lowest generalization error, say just 5% error.

So you launch this model into production, but unfortunately it does not perform as well as expected and produces 15% errors. What just happened?

The problem is that you measured the generalization error multiple times on the test set, and you adapted the model and hyperparameters to produce the best model *for that set*. This means that the model is unlikely to perform as well on new data.

A common solution to this problem is to have a second holdout set called the *validation set*. You train multiple models with various hyperparameters using the training set, you select the model and hyperparameters that perform best on the validation set, and when you're happy with your model you run a single final test against the test set to get an estimate of the generalization error.

To avoid "wasting" too much training data in validation sets, a common technique is to use *cross-validation*: the training set is split into complementary subsets, and each model is trained against a different combination of these subsets and validated against the remaining parts. Once the model type and hyperparameters have been selected, a final model is trained using these hyperparameters on the full training set, and the generalized error is measured on the test set.

No Free Lunch Theorem

A model is a simplified version of the observations. The simplifications are meant to discard the superfluous details that are unlikely to generalize to new instances. However, to decide what data to discard and what data to keep, you must make *assumptions*. For example, a linear model makes the assumption that the data is fundamentally linear and that the distance between the instances and the straight line is just noise, which can safely be ignored.

In a famous 1996 paper,¹¹ David Wolpert demonstrated that if you make absolutely no assumption about the data, then there is no reason to prefer one model over any other. This is called the *No Free Lunch* (NFL) theorem. For some datasets the best

^{11 &}quot;The Lack of A Priori Distinctions Between Learning Algorithms," D. Wolperts (1996).

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model is a linear model, while for other datasets it is a neural network. There is no model that is a priori guaranteed to work better (hence the name of the theorem). The only way to know for sure which model is best is to evaluate them all. Since this is not possible, in practice you make some reasonable assumptions about the data and you evaluate only a few reasonable models. For example, for simple tasks you may evaluate linear models with various levels of regularization, and for a complex problem you may evaluate various neural networks.

Exercises

In this chapter we have covered some of the most important concepts in Machine Learning. In the next chapters we will dive deeper and write more code, but before we do, make sure you know how to answer the following questions:

- 1. How would you define Machine Learning?
- 2. Can you name four types of problems where it shines?
- 3. What is a labeled training set?
- 4. What are the two most common supervised tasks?
- 5. Can you name four common unsupervised tasks?
- 6. What type of Machine Learning algorithm would you use to allow a robot to walk in various unknown terrains?
- 7. What type of algorithm would you use to segment your customers into multiple groups?
- 8. Would you frame the problem of spam detection as a supervised learning problem or an unsupervised learning problem?
- 9. What is an online learning system?
- 10. What is out-of-core learning?
- 11. What type of learning algorithm relies on a similarity measure to make predictions?
- 12. What is the difference between a model parameter and a learning algorithm's hyperparameter?
- 13. What do model-based learning algorithms search for? What is the most common strategy they use to succeed? How do they make predictions?
- 14. Can you name four of the main challenges in Machine Learning?
- 15. If your model performs great on the training data but generalizes poorly to new instances, what is happening? Can you name three possible solutions?
- 16. What is a test set and why would you want to use it?