

Figure 4-28. Customizing errorbars

In addition to these options, you can also specify horizontal errorbars (`xerr`), one-sided errorbars, and many other variants. For more information on the options available, refer to the docstring of `plt.errorbar`.

## Continuous Errors

In some situations it is desirable to show errorbars on continuous quantities. Though Matplotlib does not have a built-in convenience routine for this type of application, it's relatively easy to combine primitives like `plt.plot` and `plt.fill_between` for a useful result.

Here we'll perform a simple *Gaussian process regression* (GPR), using the Scikit-Learn API (see “[Introducing Scikit-Learn](#)” on page 343 for details). This is a method of fitting a very flexible nonparametric function to data with a continuous measure of the uncertainty. We won't delve into the details of Gaussian process regression at this point, but will focus instead on how you might visualize such a continuous error measurement:

```
In[4]: from sklearn.gaussian_process import GaussianProcess

# define the model and draw some data
model = lambda x: x * np.sin(x)
xdata = np.array([1, 3, 5, 6, 8])
ydata = model(xdata)

# Compute the Gaussian process fit
gp = GaussianProcess(corr='cubic', theta0=1e-2, thetaL=1e-4, thetaU=1E-1,
                    random_start=100)
gp.fit(xdata[:, np.newaxis], ydata)

xfit = np.linspace(0, 10, 1000)
yfit, MSE = gp.predict(xfit[:, np.newaxis], eval_MSE=True)
dyfit = 2 * np.sqrt(MSE) # 2*sigma ~ 95% confidence region
```

We now have `xfit`, `yfit`, and `dyfit`, which sample the continuous fit to our data. We could pass these to the `plt.errorbar` function as above, but we don't really want to plot 1,000 points with 1,000 errorbars. Instead, we can use the `plt.fill_between` function with a light color to visualize this continuous error (Figure 4-29):

```
In[5]: # Visualize the result
plt.plot(xdata, ydata, 'or')
plt.plot(xfit, yfit, '-', color='gray')

plt.fill_between(xfit, yfit - dyfit, yfit + dyfit,
                 color='gray', alpha=0.2)
plt.xlim(0, 10);
```

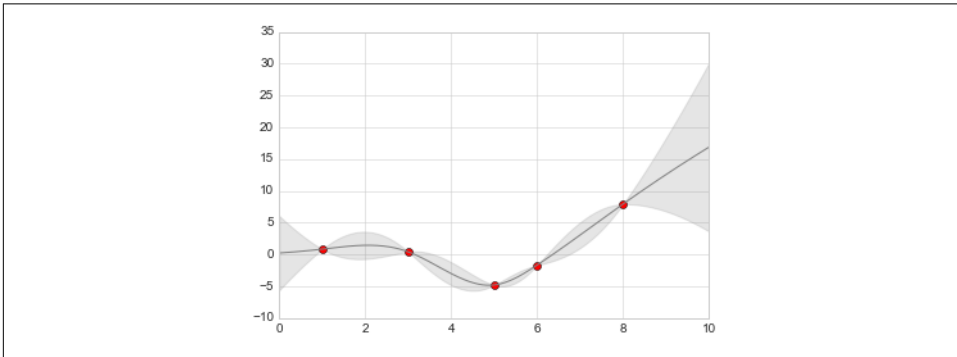


Figure 4-29. Representing continuous uncertainty with filled regions

Note what we've done here with the `fill_between` function: we pass an `x` value, then the lower `y`-bound, then the upper `y`-bound, and the result is that the area between these regions is filled.

The resulting figure gives a very intuitive view into what the Gaussian process regression algorithm is doing: in regions near a measured data point, the model is strongly constrained and this is reflected in the small model errors. In regions far from a measured data point, the model is not strongly constrained, and the model errors increase.

For more information on the options available in `plt.fill_between()` (and the closely related `plt.fill()` function), see the function docstring or the Matplotlib documentation.

Finally, if this seems a bit too low level for your taste, refer to “[Visualization with Seaborn](#)” on page 311, where we discuss the Seaborn package, which has a more streamlined API for visualizing this type of continuous errorbar.

# Density and Contour Plots

Sometimes it is useful to display three-dimensional data in two dimensions using contours or color-coded regions. There are three Matplotlib functions that can be helpful for this task: `plt.contour` for contour plots, `plt.contourf` for filled contour plots, and `plt.imshow` for showing images. This section looks at several examples of using these. We'll start by setting up the notebook for plotting and importing the functions we will use:

```
In[1]: %matplotlib inline
import matplotlib.pyplot as plt
plt.style.use('seaborn-white')
import numpy as np
```

## Visualizing a Three-Dimensional Function

We'll start by demonstrating a contour plot using a function  $z = f(x, y)$ , using the following particular choice for  $f$  (we've seen this before in “[Computation on Arrays: Broadcasting](#)” on page 63, when we used it as a motivating example for array broadcasting):

```
In[2]: def f(x, y):
        return np.sin(x) ** 10 + np.cos(10 + y * x) * np.cos(x)
```

A contour plot can be created with the `plt.contour` function. It takes three arguments: a grid of  $x$  values, a grid of  $y$  values, and a grid of  $z$  values. The  $x$  and  $y$  values represent positions on the plot, and the  $z$  values will be represented by the contour levels. Perhaps the most straightforward way to prepare such data is to use the `np.meshgrid` function, which builds two-dimensional grids from one-dimensional arrays:

```
In[3]: x = np.linspace(0, 5, 50)
        y = np.linspace(0, 5, 40)

        X, Y = np.meshgrid(x, y)
        Z = f(X, Y)
```

Now let's look at this with a standard line-only contour plot ([Figure 4-30](#)):

```
In[4]: plt.contour(X, Y, Z, colors='black');
```