

tf.keras and tf.estimator

TensorFlow has now integrated the popular Keras object-oriented frontend into the core TensorFlow library. Keras includes a Layer class definition that closely matches the Layer objects you've just learned about in this section. In fact, the Layer objects here were adapted from the DeepChem library, which in turn adapted them from an earlier version of Keras.

It's worth noting, though, that tf.keras has not yet become the standard higher-level interface to TensorFlow. The tf.estimator module provides an alternative (albeit less rich) high-level interface to raw TensorFlow.

Regardless of which frontend eventually becomes standard, we think that understanding the fundamental design principles for building your own frontend is instructive and worthwhile. You might need to build a new system for your organization that requires an alternative design, so a solid grasp of design principles will serve you well.

Defining a Graph of Layers

We mentioned briefly in the previous section that a deep architecture could be visualized as a directed graph of Layer objects. In this section, we transform this intuition into the TensorGraph object. These objects are responsible for constructing the underlying TensorFlow computation graph.

A TensorGraph object is responsible for maintaining a tf.Graph, a tf.Session, and a list of layers (self.layers) internally (Example 8-9). The directed graph is represented implicitly, by the in_layers belonging to each Layer object. TensorGraph also contains utilities for saving this tf.Graph instance to disk and consequently assigns itself a directory (using tempfile.mkdtemp() if none is specified) to store checkpoints of the weights associated with its underlying TensorFlow graph.

Example 8-9. The TensorGraph contains a graph of layers; TensorGraph objects can be thought of as the "model" object holding the deep architecture you want to train

```
learning rate=0.001,
           model dir=None,
           **kwarqs):
.....
Parameters
------
batch size: int
 default batch size for training and evaluating
graph: tensorflow.Graph
 the Graph in which to create Tensorflow objects. If None, a new Graph
  is created.
learning rate: float or LearningRateSchedule
  the learning rate to use for optimization
kwargs
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# Layer Management
self.layers = dict()
self.features = list()
self.labels = list()
self.outputs = list()
self.task weights = list()
self.loss = None
self.built = False
self.optimizer = None
self.learning_rate = learning_rate
# Singular place to hold Tensor objects which don't serialize
# See TensorGraph._get_tf() for more details on lazy construction
self.tensor objects = {
    "Graph": graph,
    #"train_op": None,
}
self.global_step = 0
self.batch size = batch size
self.random_seed = random_seed
if model_dir is not None:
 if not os.path.exists(model_dir):
    os.makedirs(model_dir)
else:
 model_dir = tempfile.mkdtemp()
 self.model_dir_is_temp = True
self.model dir = model dir
self.save_file = "%s/%s" % (self.model_dir, "model")
self.model class = None
```

The private method _add_layer does bookkeeping work to add a new Layer obect to the TensorGraph (Example 8-10).

Example 8-10. The add layer method adds a new Layer object

```
def _add_layer(self, layer):
 if layer.name is None:
   layer.name = "%s_%s" % (layer.__class__.__name__, len(self.layers) + 1)
 if layer.name in self.layers:
 if isinstance(layer, Input):
   self.features.append(layer)
 self.layers[layer.name] = layer
 for in layer in layer.in layers:
   self._add_layer(in_layer)
```

The layers in a TensorGraph must form a directed acyclic graph (there can be no loops in the graph). As a result, we can topologically sort these layers. Intuitively, a topological sort "orders" the layers in the graph so that each Layer object's in layers precede it in the ordered list. This topological sort is necessary to make sure all input layers to a given layer are added to the graph before the layer itself (Example 8-11).

Example 8-11. The topsort method orders the layers in the TensorGraph

```
def topsort(self):
 def add layers to list(layer, sorted layers):
   if layer in sorted_layers:
      return
   for in layer in layer.in layers:
      add_layers_to_list(in_layer, sorted_layers)
    sorted layers.append(layer)
 sorted_layers = []
 for l in self.features + self.labels + self.task weights + self.outputs:
   add_layers_to_list(l, sorted_layers)
 add layers to list(self.loss, sorted layers)
 return sorted_layers
```

The build() method takes the responsibility of populating the tf.Graph instance by calling layer.create_tensor for each layer in topological order (Example 8-12).

Example 8-12. The build method populates the underlying TensorFlow graph

```
def build(self):
 if self.built:
 with self._get_tf("Graph").as_default():
    self. training placeholder = tf.placeholder(dtype=tf.float32, shape=())
    if self.random_seed is not None:
      tf.set_random_seed(self.random_seed)
    for layer in self.topsort():
```

```
with tf.name scope(layer.name):
   layer.create tensor(training=self. training placeholder)
self.session = tf.Session()
self.built = True
```

The method set_loss() adds a loss for training to the graph. add_output() specifies that the layer in question might be fetched from the graph. set_optimizer() specifies the optimizer used for training (Example 8-13).

Example 8-13. These methods add necessary losses, outputs, and optimizers to the computation graph

```
def set loss(self, layer):
  self._add_layer(layer)
 self.loss = layer
def add_output(self, layer):
  self. add layer(layer)
  self.outputs.append(layer)
def set optimizer(self, optimizer):
  """Set the optimizer to use for fitting."""
  self.optimizer = optimizer
```

The method get_layer_variables() is used to fetch the learnable tf.Variable objects created by a layer. The private method _get_tf is used to fetch the tf.Graph and optimizer instances underpinning the TensorGraph, get global step is a convenience method for fetching the current step in the training process (starting from 0 at construction). See Example 8-14.

Example 8-14. Fetch the learnable variables associated with each layer

```
def get_layer_variables(self, layer):
  """Get the list of trainable variables in a layer of the graph."""
  if not self.built:
    self.build()
 with self._get_tf("Graph").as_default():
    if layer.variable scope == "":
      return []
    return tf.get collection(
        tf.GraphKeys.TRAINABLE VARIABLES, scope=layer.variable scope)
def get_global_step(self):
  return self._get_tf("GlobalStep")
def get tf(self, obj):
  """Fetches underlying TensorFlow primitives.
```

```
Parameters
_____
obj: str
 If "Graph", returns tf. Graph instance. If "Optimizer", returns the
 optimizer. If "train op", returns the train operation. If "GlobalStep" returns
  the global step.
Returns
TensorFlow Object
if obj in self.tensor objects and self.tensor objects[obj] is not None:
 return self.tensor_objects[obj]
if obj == "Graph":
  self.tensor objects["Graph"] = tf.Graph()
elif obj == "Optimizer":
  self.tensor objects["Optimizer"] = tf.train.AdamOptimizer(
      learning_rate=self.learning_rate,
      beta1=0.9.
      beta2=0.999,
      epsilon=1e-7)
elif obj == "GlobalStep":
 with self._get_tf("Graph").as_default():
    self.tensor_objects["GlobalStep"] = tf.Variable(0, trainable=False)
return self. get tf(obj)
```

Finally, the restore() method restores a saved TensorGraph from disk (Example 8-15). (As you will see later, the TensorGraph is saved automatically during training.)

Example 8-15. Restore a trained model from disk

```
def restore(self):
  """Reload the values of all variables from the most recent checkpoint file."""
 if not self.built:
    self.build()
  last checkpoint = tf.train.latest checkpoint(self.model dir)
  if last_checkpoint is None:
    raise ValueError("No checkpoint found")
 with self._get_tf("Graph").as_default():
    saver = tf.train.Saver()
    saver.restore(self.session, last_checkpoint)
```

The A3C Algorithm

In this section you will learn how to implement A3C, the asynchronous reinforcement learning algorithm you saw earlier in the chapter. A3C is a significantly more complex training algorithm than those you have seen previously. The algorithm requires running gradient descent in multiple threads, interspersed with game rollout