# MICROPROCESSOR AND INTERFACING LAB MANUAL: 6

## **Execute the following tasks**

### Task 1:

What will be the hexadecimal values of DX, AX, and the Carry flag after the following instructions execute?

mov ax,1234h

mov bx,100h

mul bx

#### **SOURCE CODE:**

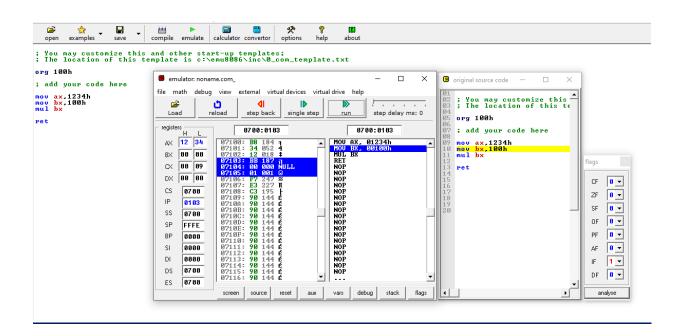
mov ax,1234h mov bx,100h mul bx

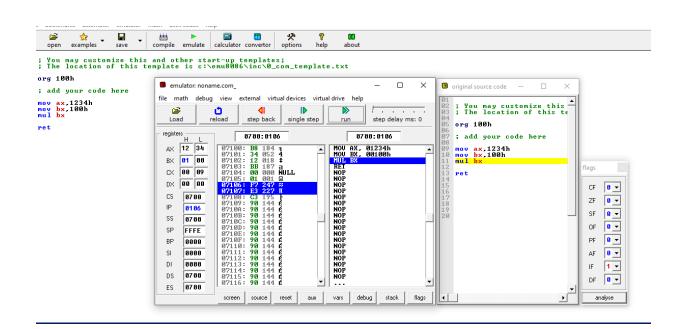
## **EXPALANATION:**

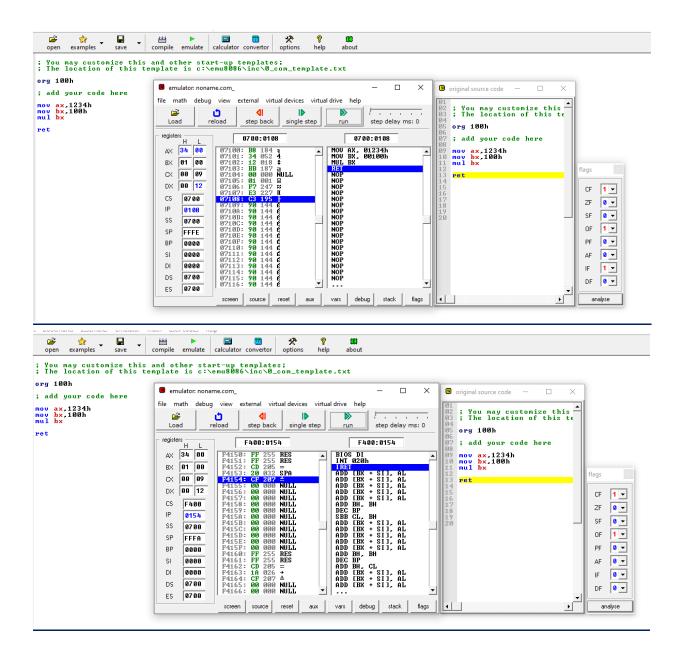
1234h will be copied to the accumulator register.

100h will be copied to the accumulator register and previous content will be removed.

Content of AX will be multiplied with the content of BX which has nothing in it or zero and result will be stored in AX. The result is 0 because anything multiplied by 0 is 0.







## Task 2:

What will be the hexadecimal values of DX and AX after the following instructions execute?

mov dx,0087h mov ax,6000h mov bx,100h div bx

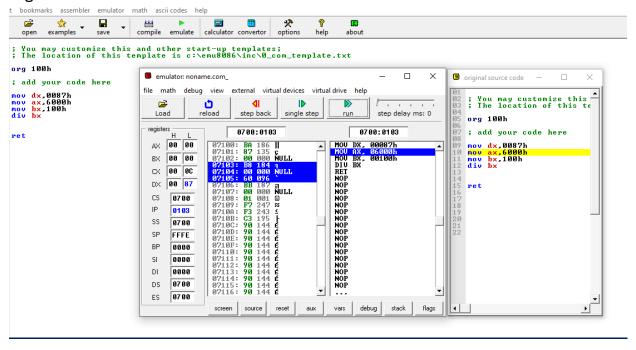
#### **SOURCE CODE:**

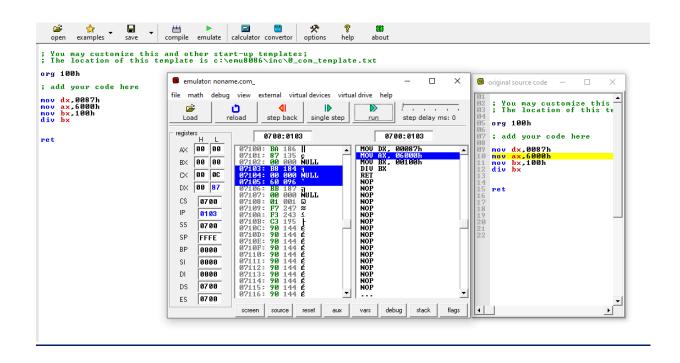
mov dx,0087h mov ax,6000h mov bx,100h div bx

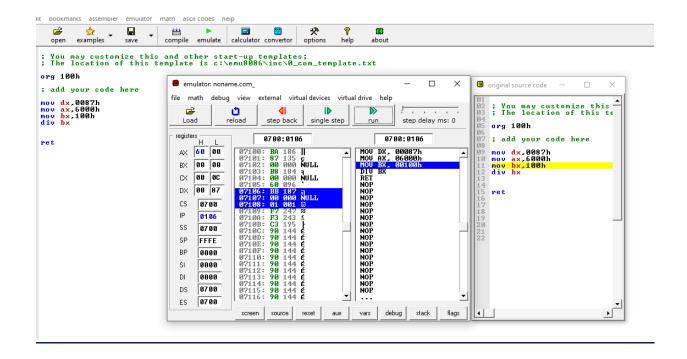
#### **Explanation:**

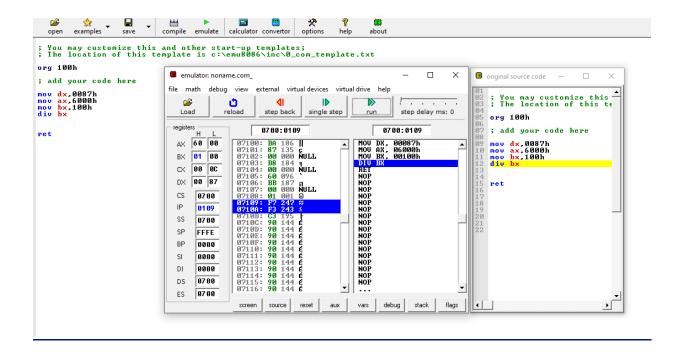
0087h will be copied to DX, 6000h will be copied to AX and 100h to BX register. Content of AX is dividend and content of BX is divisor.

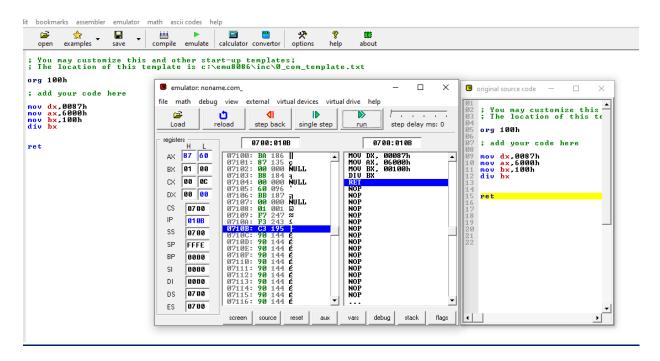
The result after division: Remainder will be stored in DX and Quotient in AX register











## Task 3:

Take two binary numbers such as 11111111

#### 11111111

Perform two's complement of the first number and save it to one of the register. Then, reverse the bits of second binary number and save it to the other register.

- 1. Take the value 0 in third register and perform the AND operation with both of the results computed above.
- 2. Take the value 1 in third register and perform the AND operation with both of the results computed above.

#### **SOURCE CODE:**

MOV AX,11111111B

MOV BX,11111111B

**NEG AX** 

**NOT BX** 

MOV CX,0

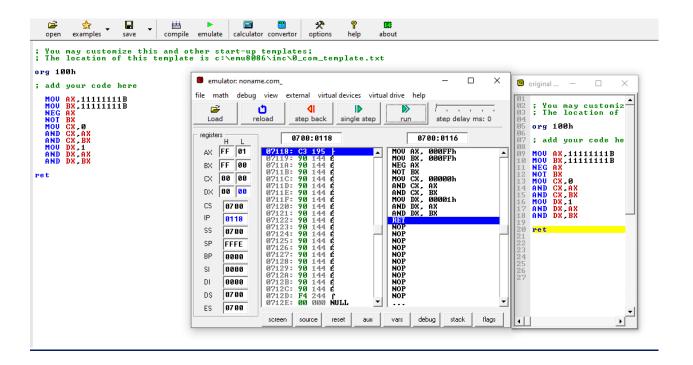
AND CX,AX

AND CX,BX

MOV DX,1

AND DX,AX

AND DX,BX



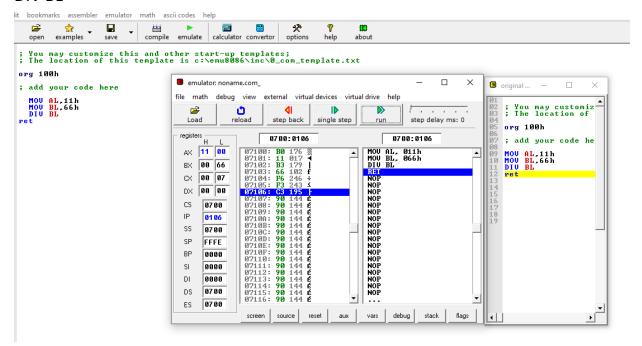
## Task 4:

Division of 8 bit numbers using immediate addressing mode?

#### **SOURCE CODE:**

MOV AL,11h MOV BL,66h

DIV BL



Write a code to perform multiplication on 16 bit numbers in consecutive memory locations?

## **SOURCE CODE:**

MOV SI, 0100H

MOV [SI], 1234H

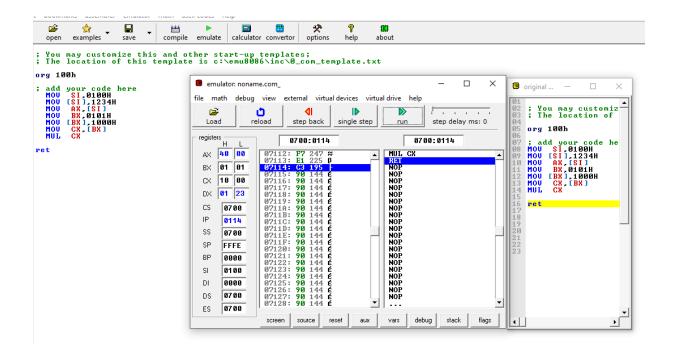
MOV AX, [SI]

MOV BX, 0101H

MOV [BX], 1000H

MOV CX, [BX]

MUL CX



Write a code to add 16 bit numbers and find the average of numbers?

#### **SOURCE CODE:**

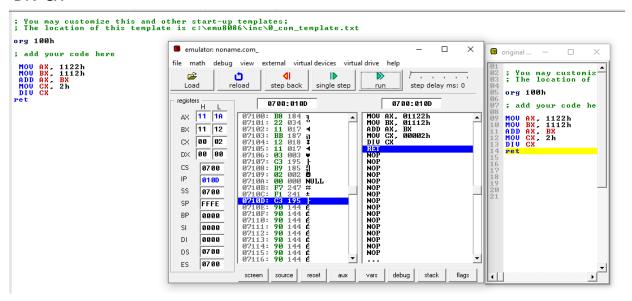
MOV AX, 1122h

MOV BX, 1112h

ADD AX, BX

MOV CX, 2h

**DIV CX** 



## Task 5:

Translate the high-level language assignment statement: A=5×A+12×B Let A and B be word variables, and suppose there is no overflow.

#### **SOURCE CODE:**

MOV AX, 5h

MOV BX, A

**MUL BX** 

MOV BX,AX

MOV AX,12h

MOV DX,B

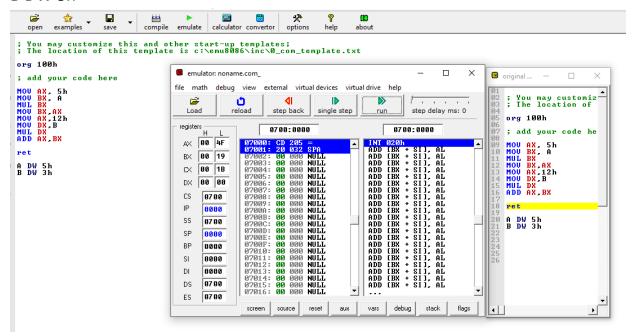
**MUL DX** 

ADD AX,BX

ret

A DW 5h

B DW 3h



## Task 6:

## Try the example no 7 with different numbers for AL and BL, open flags by clicking on flags button, use single step and see what happens SOURCE CODE:

```
MOV AL, 77h; set al to 25

MOV BL, 77h; set bl to 10.

CMP AL,BL; compare al - bl

JE equal; jump if al = bl (zf = 1).

Mov CX, BX; if it gets here, then al <> bl,

JMP stop; so print 'n', and jump to stop

equal:; if gets here,

Mov CX, AX; then al = bl, so print 'y'

stop:
```

ret

```
; You may customize this and other start-up templates;
; The location of this template is c:\emu8086\inc\0_com_template.txt
; add your code here
                                                                                        mulator: noname.com
                                                                                                                                                                                                             📵 original ...
MOU AL, 77h; set al to 25
MOU BL, 77h; set bl to 10.
                                                                                                                                                                                                                   ; You may customized; The location of
CMP AL,BL ; compare al - bl
                       ; jump if al = bl (zf = 1).
                                                                                                                                                                               step delay ms: 0
                                                                                                                                                                                                                   org 100h
                                                                                         registers —
Mov CX, BX ; if it gets here, then al <> bl,
JMP stop ; so print 'n', and jump to stop
                                                                                                                           0700:010E
                                                                                                                                                                     0700:010E
                                                                                                                                                                                                                   ; add your code he
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                                                                                                                  97198: 88 176 

97198: 89 176 

97198: 77 119 

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97198: 93 37 5
                                                                                                                                                                                                                   MOV AL, 77h; set
MOV BL, 77h; set
equal: ; if gets here,
Mov CX, AX ; then al = bl, so print 'y'
                                                                                            BX 00 77
                                                                                                                                                                                                                                               ; c
stop:
                                                                                           CX 00 77
                                                                                                                                                                                                                   JE equal
                                                                                                                                                                                                                                               ; j
                                                                                           DX 88 88
                                                                                                                                                                                                                   Mov CX, BX
JMP stop
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                                                                                                  9799
                                                                                                  01 0E
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Mov CX, AX
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                                                                                           DS
                                                                                                  0700
                                                                                                 0700
                                                                                                                   screen source reset aux vars debug stack flags
```

-----THE END------