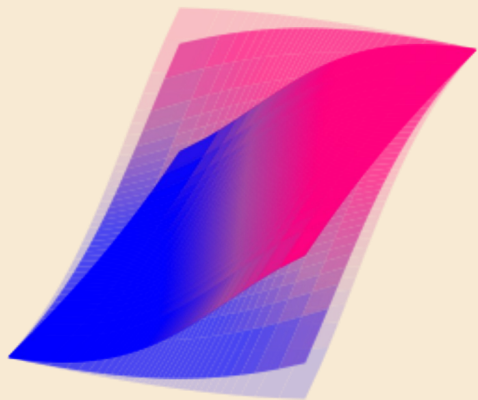


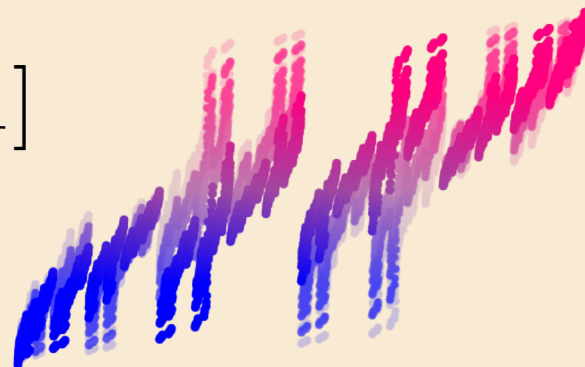
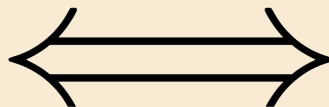
Equivalence of neural field dynamics with different embedding dimensionality

Nicole Vadot
(Supervisor)
Dr. Valentin Schmutz
(Supervisor, LCN director)
Prof. Wulfram Gerstner
(External expert)
Prof. Romain Veltz



Neural field in \mathbb{R}^p

$$S : \mathbb{R}^p \mapsto [0, 1]$$



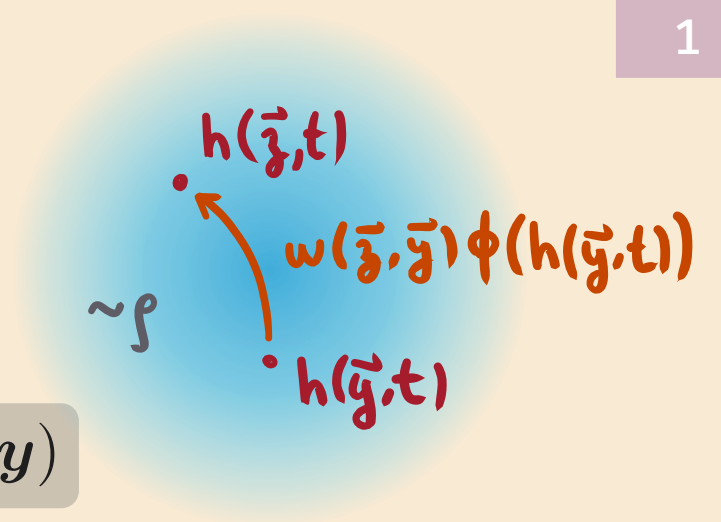
Neural field in $[0, 1]$

Online: <https://ninivert.github.io/lcnthesis/>

recap: neural fields & embedding spaces

$$\partial_t h(\mathbf{z}, t) = -h(\mathbf{z}, t) + \int_{\mathbb{R}^p} w(\mathbf{z}, \mathbf{y}) \phi(h(\mathbf{y}, t)) \rho(d\mathbf{y})$$

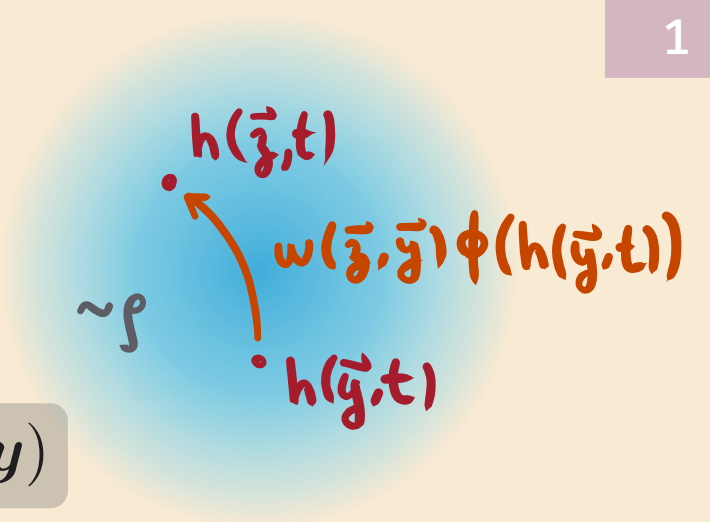
neural field embedding space connectivity kernel activation (firing rate) population density



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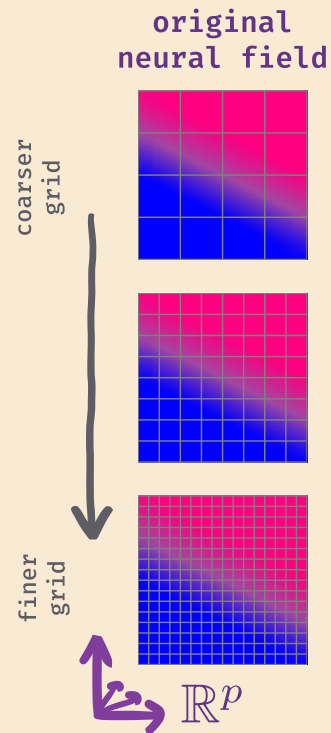
by redefining, we can "hide" the density in the kernel:
 \Rightarrow we get a neural field in $[0, 1]^p$

$$\partial_t h_U(\mathbf{v}, t) = -h_U(\mathbf{v}, t) + \int_{[0, 1]^p} w_U(\mathbf{v}, \mathbf{u}) \phi(h_U(\mathbf{u}, t)) d\mathbf{u}$$

problem statement

neural field in p dimensions

$$\partial_t h_U(t, \mathbf{v}) = -h_U(t, \mathbf{v}) + \int_{[0,1]^p} w_U(\mathbf{v}, \mathbf{u}) \phi(h_U(t, \mathbf{u})) d\mathbf{u}$$



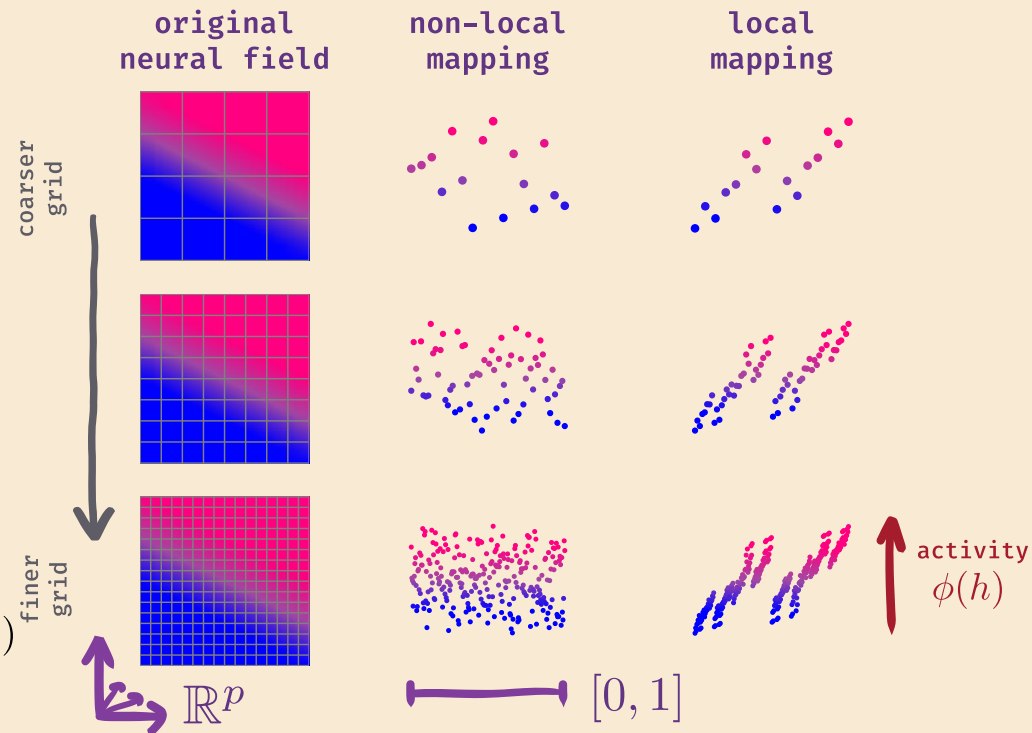
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map to neural field in one dimension?

$$\partial_t \tilde{h}(\alpha, t) = -\tilde{h}(\alpha, t) + \int_{[0,1]} \tilde{w}(\alpha, \beta) \phi(\tilde{h}(\beta, t)) [\lambda \circ S^{-1}] (d\beta)$$



problem statement

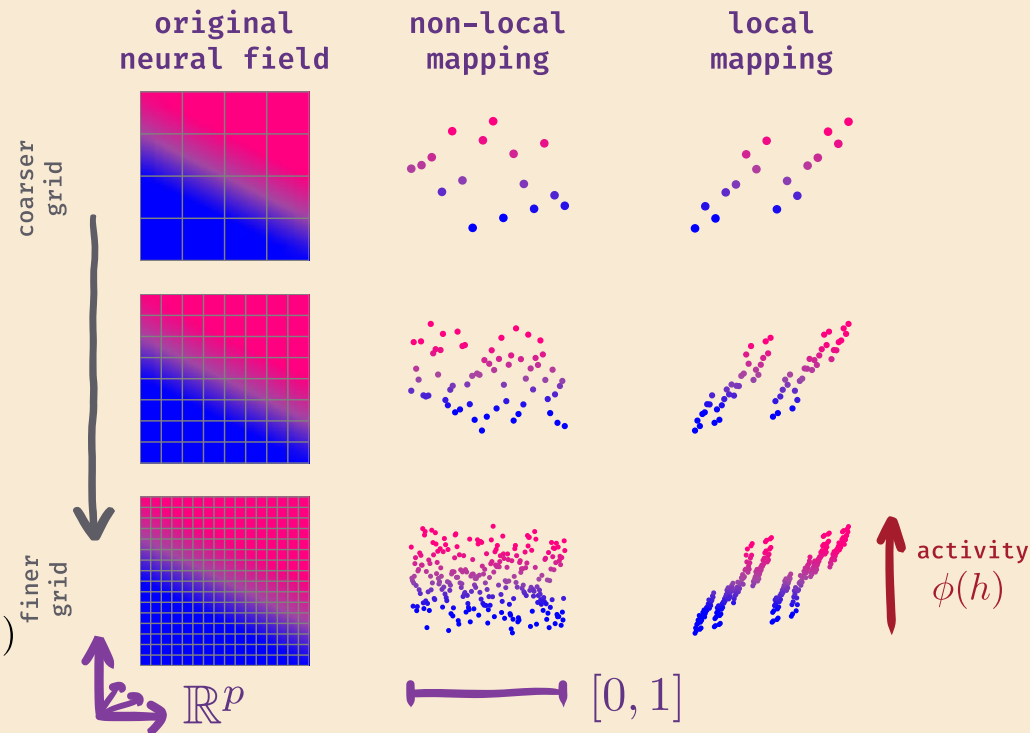
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→ "regularity" of the activity is what allows writing the neural field



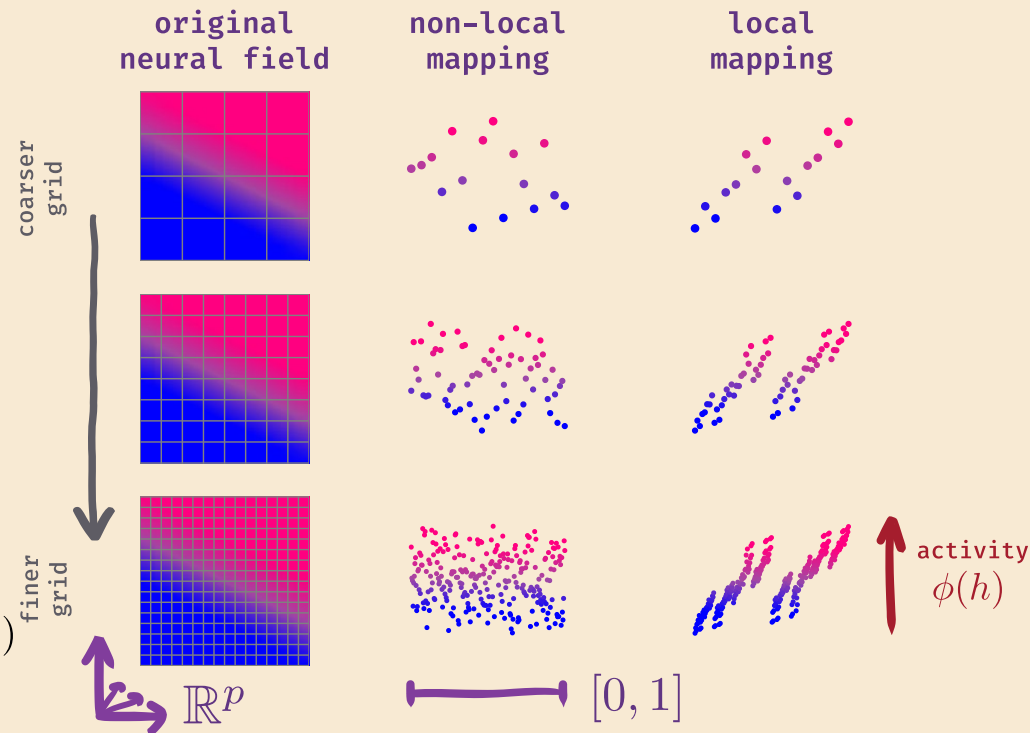
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→ "regularity" of the activity is what allows writing the neural field

→ can an equivalent neural field in $[0,1]$ also be regular?
 → what conditions on mapping S to preserve regularity? (→ locality)

smoothness of the kernel: what properties on S^{-1} can we hope for?

$$\partial_t \tilde{h}(\alpha, t) = -\tilde{h}(\alpha, t) + \int_{[0,1]} \tilde{w}(\alpha, \beta) \phi(\tilde{h}(\beta, t)) [\lambda \circ S^{-1}] (d\beta)$$

kernel of the $[0,1]$ embedding

defined as: $\tilde{w}(\alpha, \beta) = w_U(S^{-1}(\alpha), S^{-1}(\beta))$

→ w_U is highly regular, but
 \tilde{w} might not be, it depends on S^{-1}

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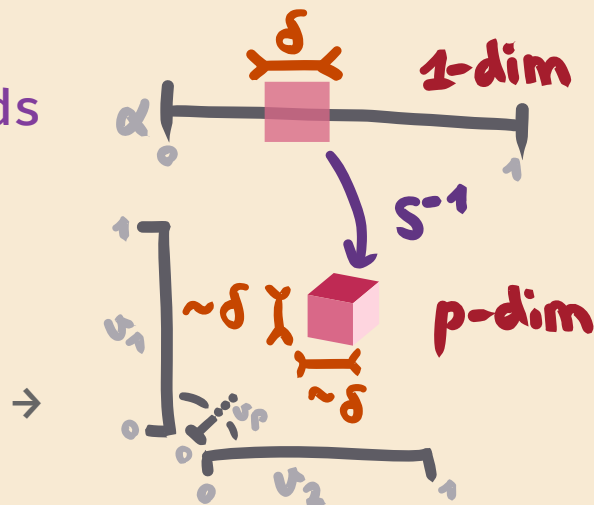
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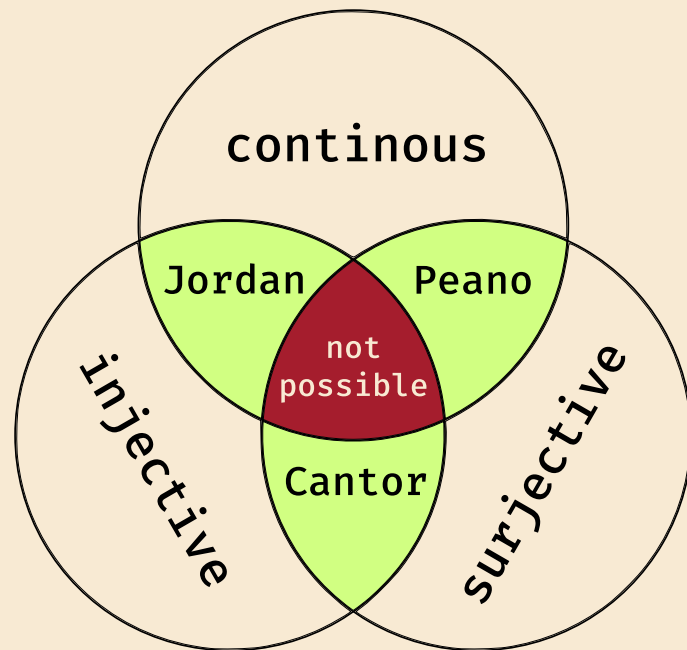
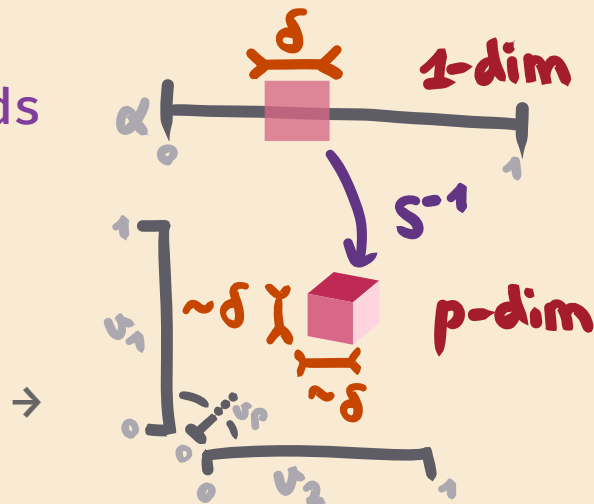
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↑ Netto's theorem states
there are no continuous
bijections $S^{-1}: [0,1] \mapsto [0,1]^2$

S as the limit of a sequence of mappings S^n

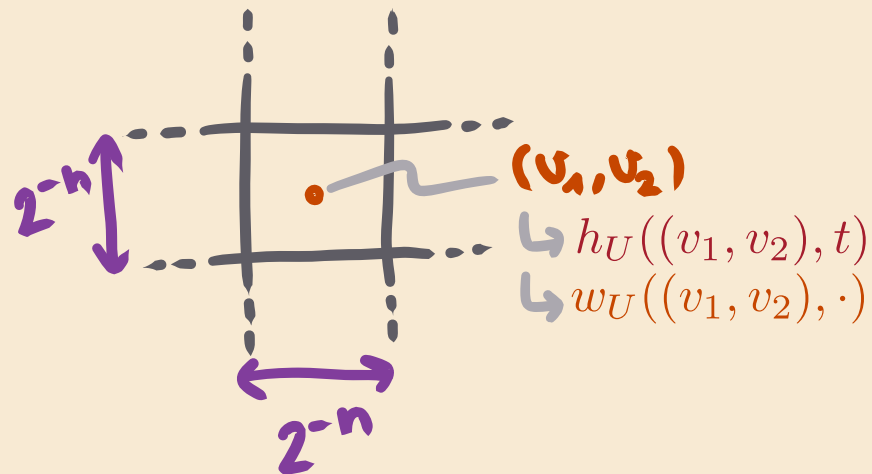
- motivation

why? → grid discretization of the neural field in p dimensions

→ 2^n bins along each dimension

→ case $p=2$, positions of bins given by: $\mathbf{v}_i = (v_{1,i}, v_{2,i}), i \in \{1, \dots, 4^n\}$

↓ each bin "samples" the neural field and kernel



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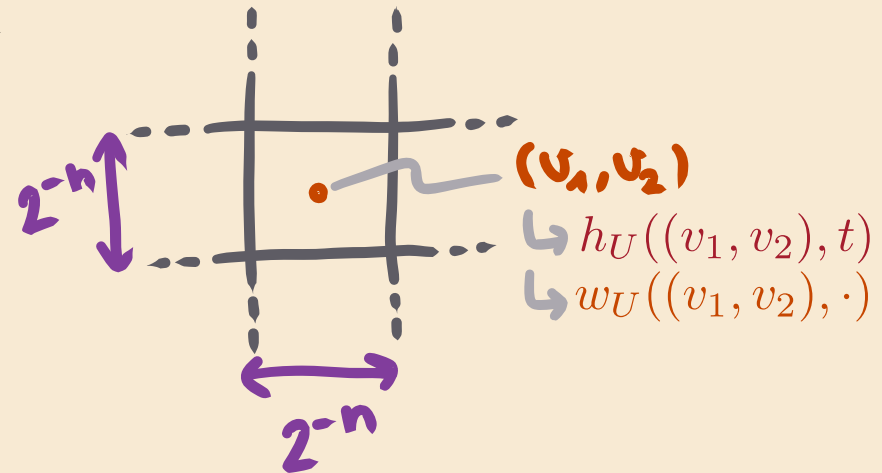
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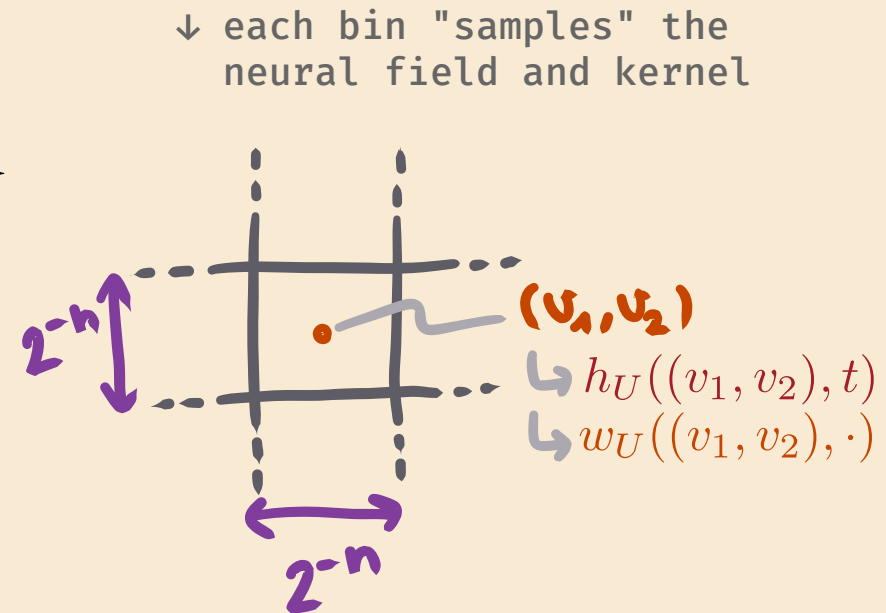
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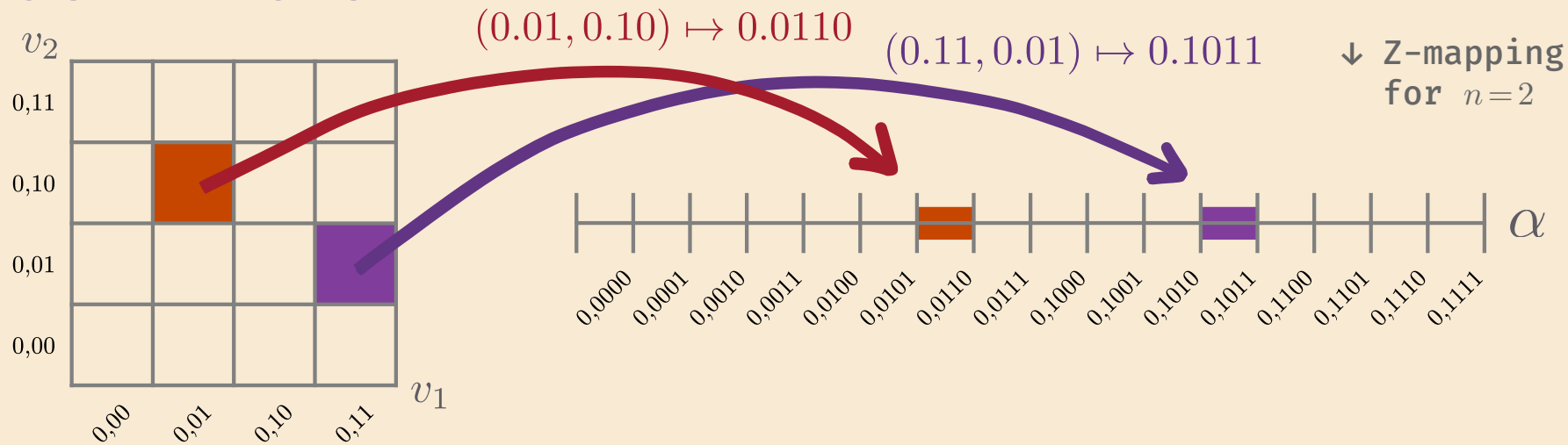
- 2^n bins along each dimension
- case $p=2$, positions of bins given by: $\mathbf{v}_i = (v_{1,i}, v_{2,i})$, $i \in \{1, \dots, 4^n\}$
- numerical kernel: $J_{ij} = w_U(\mathbf{v}_i, \mathbf{v}_j)$
- we simulate the discretized neural field

$$\frac{d}{dt}h_i(t) = -h_i(t) + \sum_{j=1}^{4^n} J_{ij}\phi(h_j(t))$$



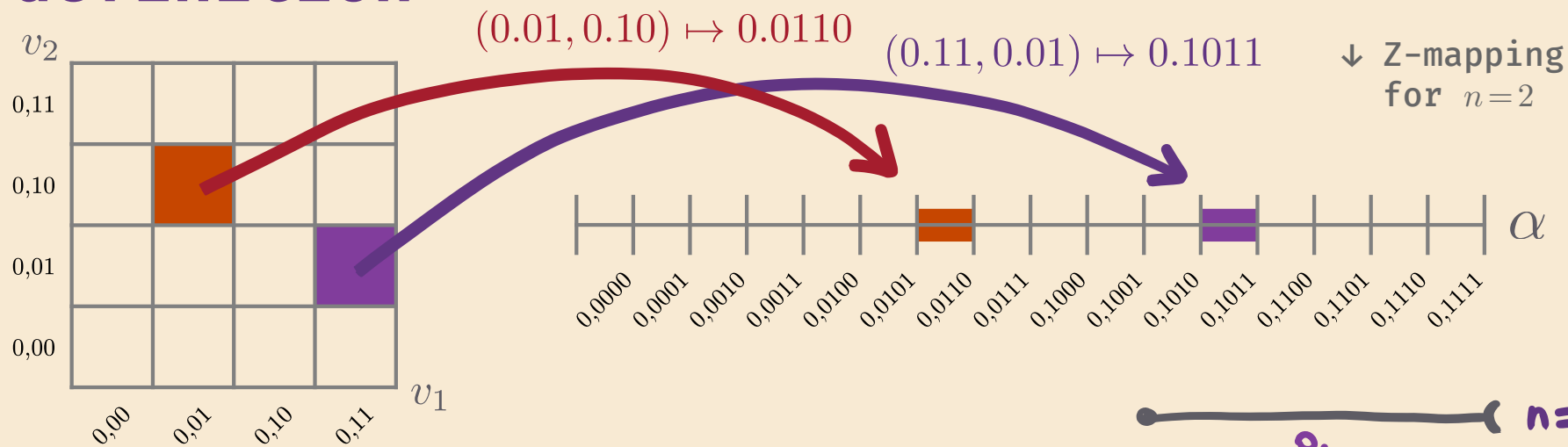
S as the limit of a sequence of mappings S^n

- definition



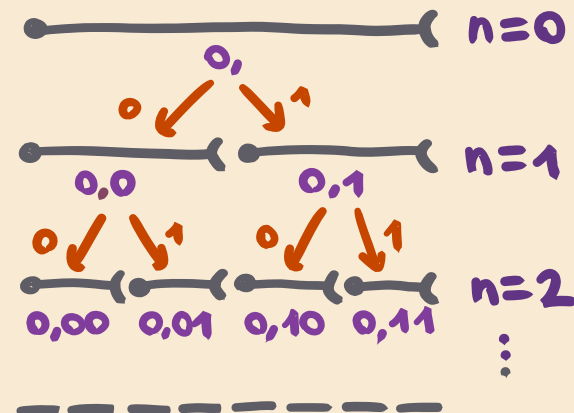
S as the limit of a sequence of mappings S^n

- definition



- S^n maps 4^n squares of size $2^{-n} \times 2^{-n}$ to 4^n segments of size 4^{-n}
- bins are located using binary expansions →

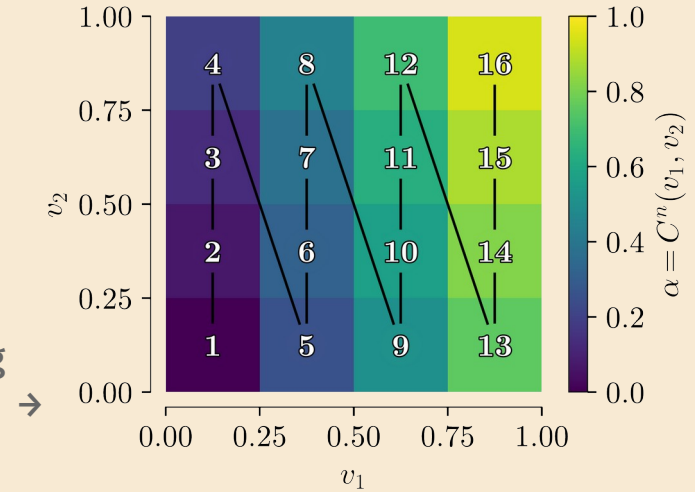
$$S^n : (v_1^{(n)}, v_2^{(n)}) = (0.b_1^1 b_2^1 \cdots b_n^1, 0.b_1^2 b_2^2 \cdots b_n^2) \\ \mapsto \alpha^{(n)} = 0.b_1 b_2 \cdots b_{2n}$$



a naive mapping: Column mapping

→ enumerate the populations columnwise

Column mapping
for $n=2$



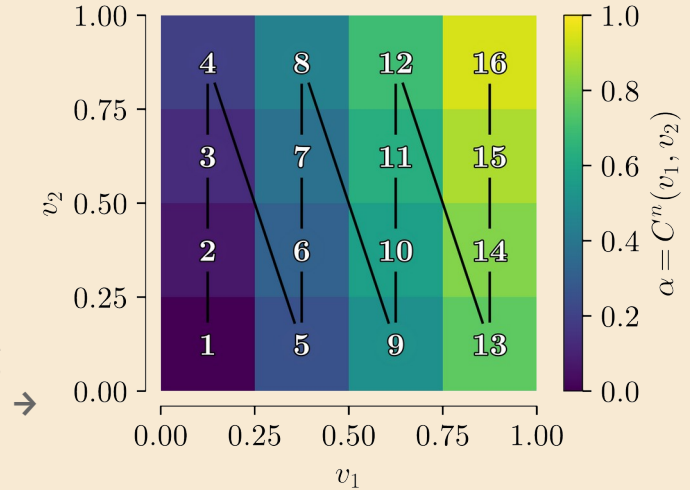
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$$\alpha^{(n)} = C(v_1^{(n)}, v_2^{(n)}) = 0.b_1^1 b_2^1 \cdots b_n^1 b_1^2 b_2^2 \cdots b_n^2$$

$$= \sum_{k=1}^n b_k^1 2^{-k} + b_k^2 2^{-(n+k)}$$

Column mapping
for $n=2$

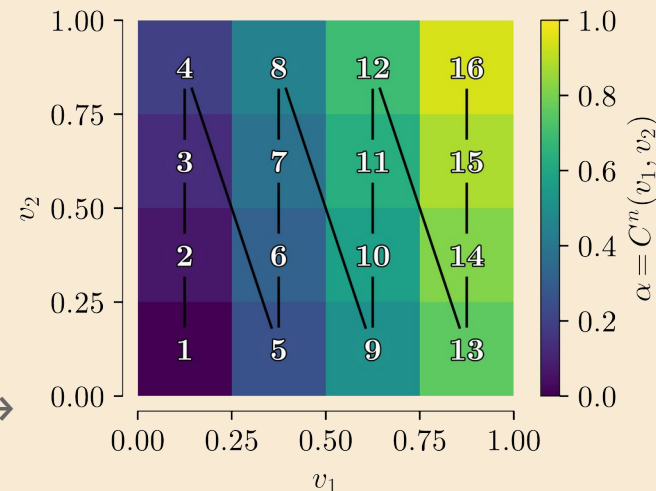


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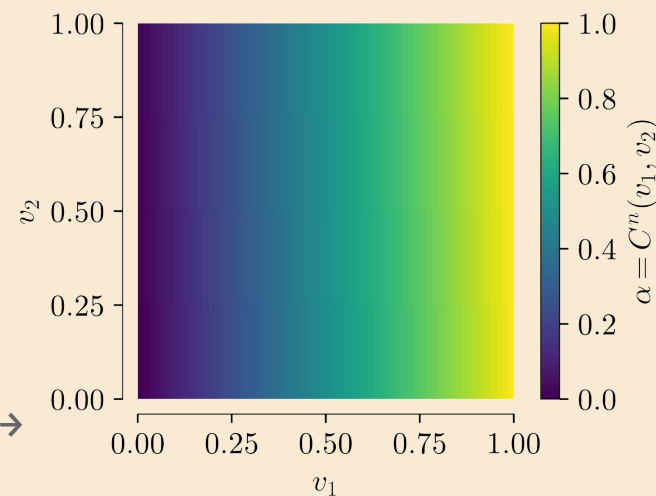
→ at finite- n , inverse is

$$v_1^{(n)} = C_1^{-1}(\alpha^{(n)}) = 0.b_1 b_2 \cdots b_n = \sum_{k=1}^n b_k 2^{-k}$$

$$v_2^{(n)} = C_2^{-1}(\alpha^{(n)}) = 0.b_{n+1} b_{n+2} \cdots b_{2n} = \sum_{k=1}^n b_{n+k} 2^{-k}$$

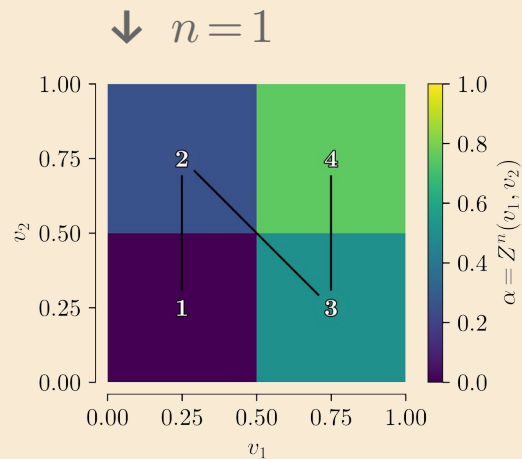
→ converges to a projection
on the first axis

Column mapping
for $n \rightarrow \infty$



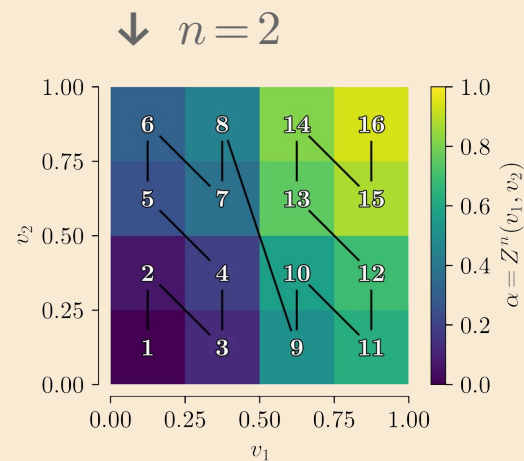
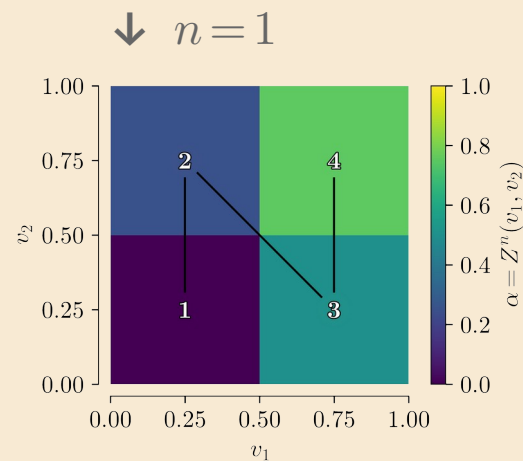
a less naive mapping: Z-mapping

→ (recursively) draw Z shapes



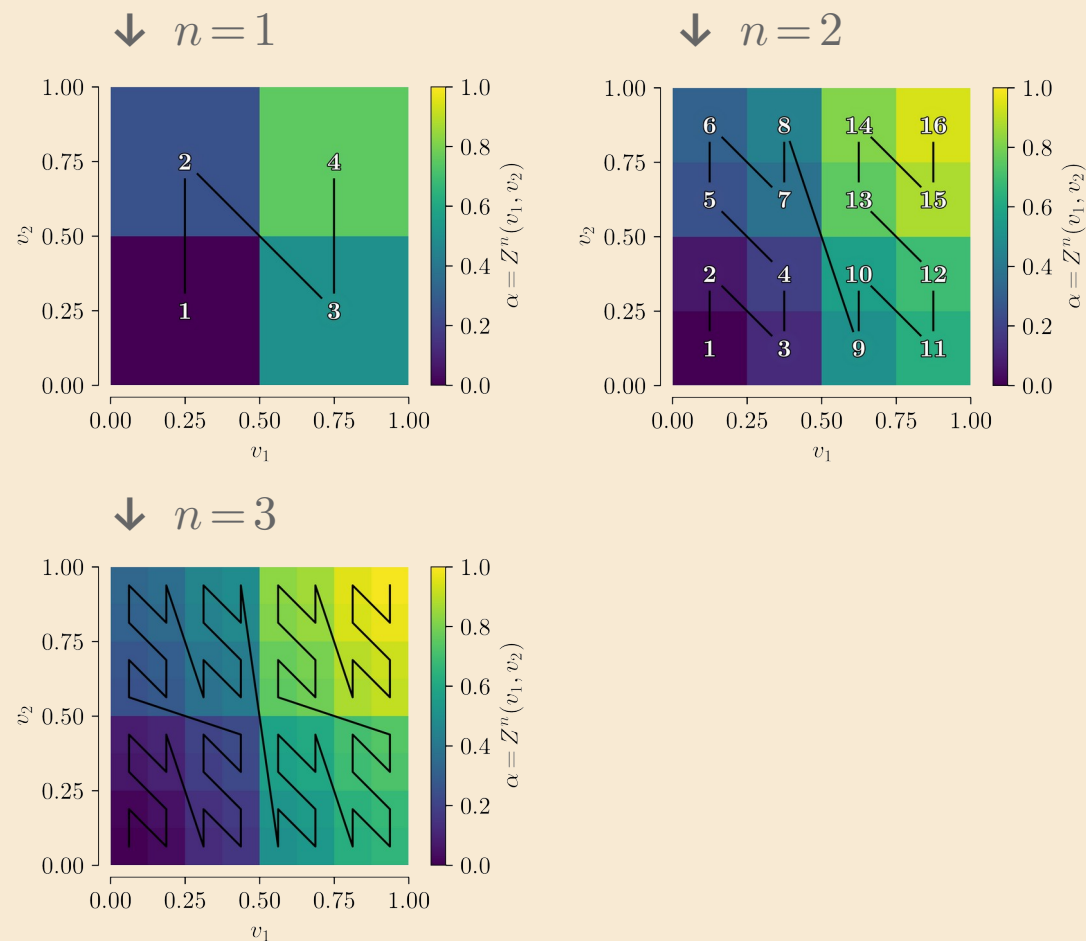
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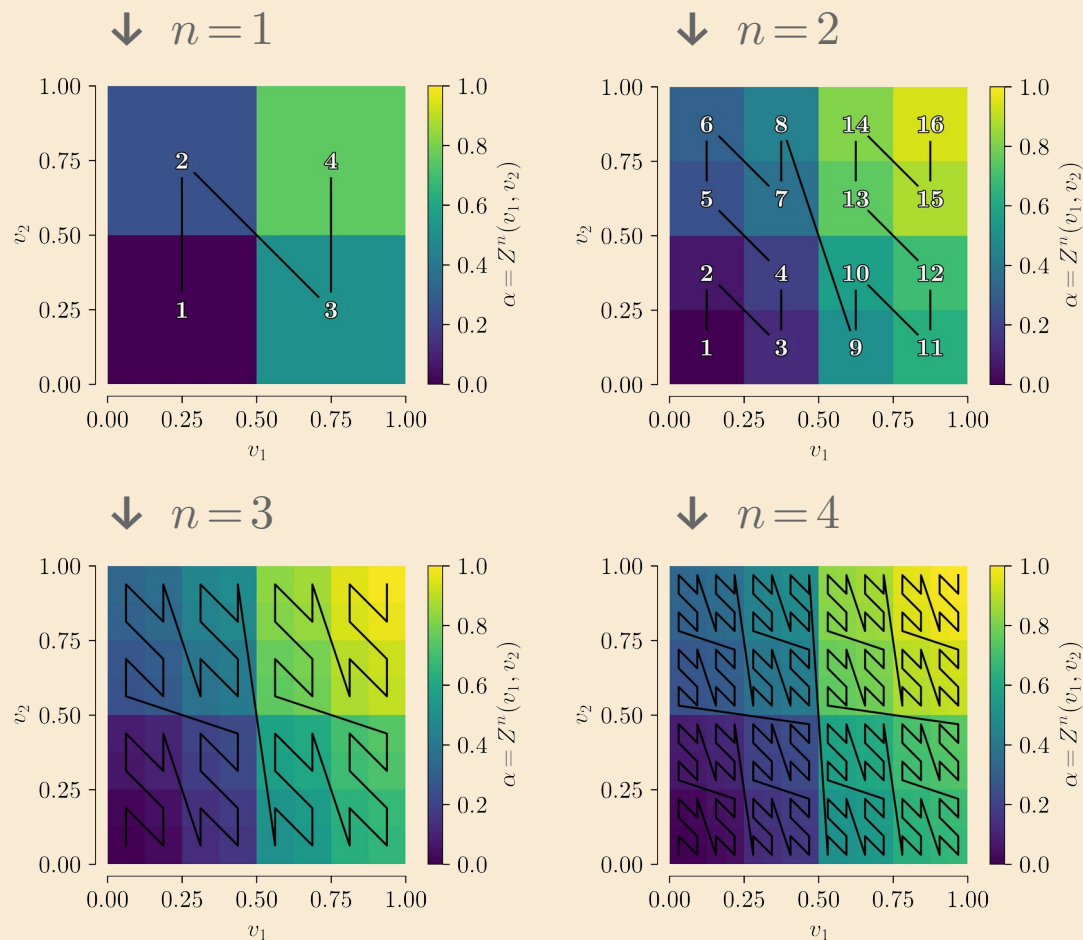
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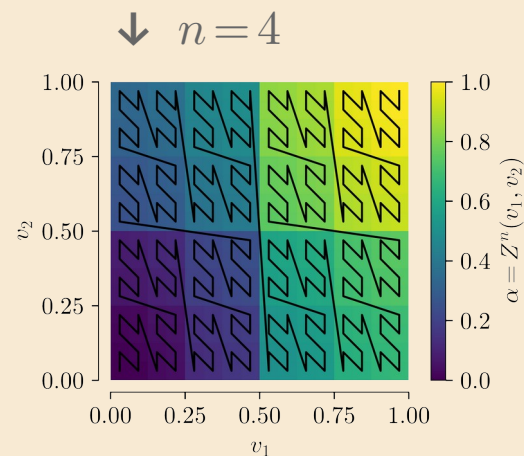
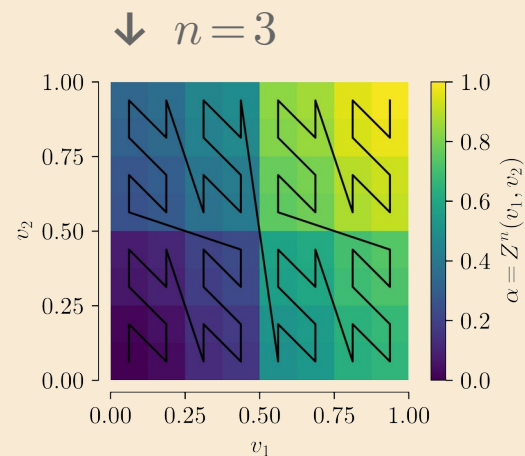
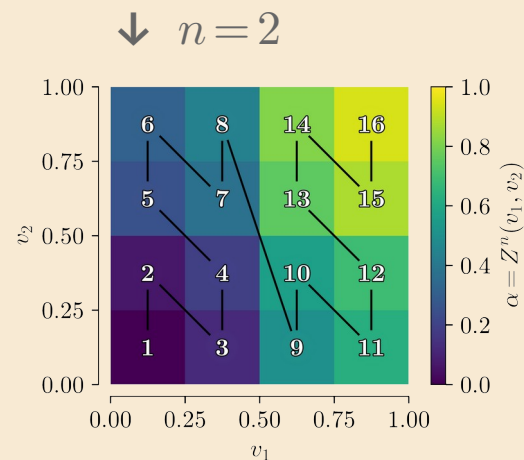
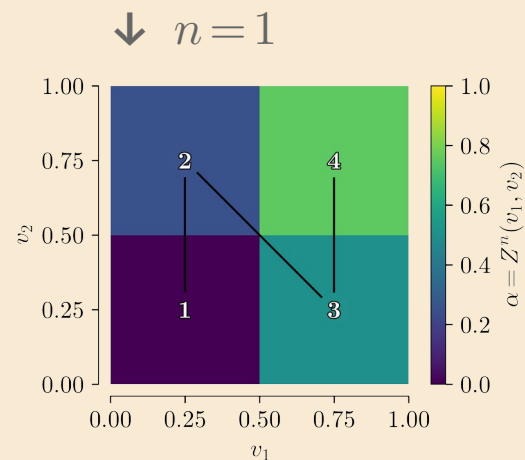
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$$\begin{aligned}\alpha^{(n)} &= Z(v_1^{(n)}, v_2^{(n)}) \\ &= 0.b_1^1 b_1^2 b_2^1 b_2^2 \cdots b_n^1 b_n^2\end{aligned}$$



a less naive mapping: Z-mapping

→ (recursively) draw Z shapes

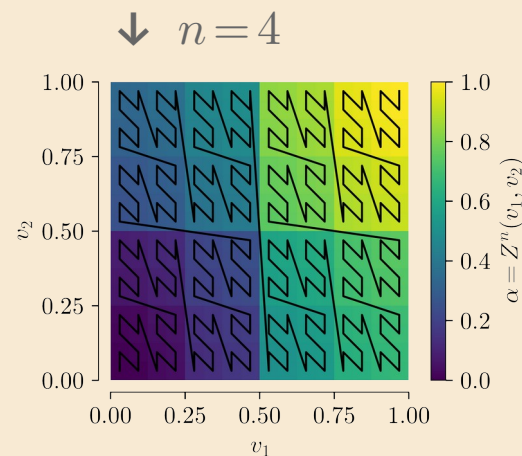
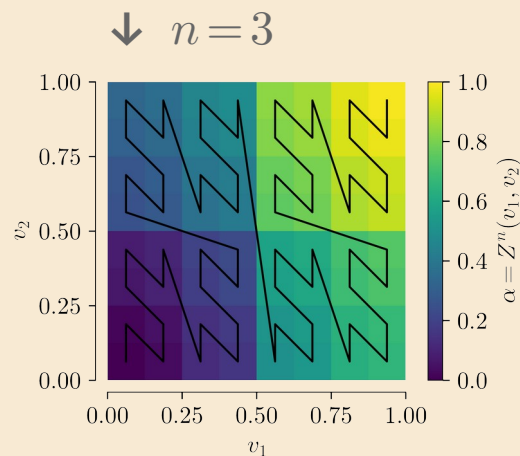
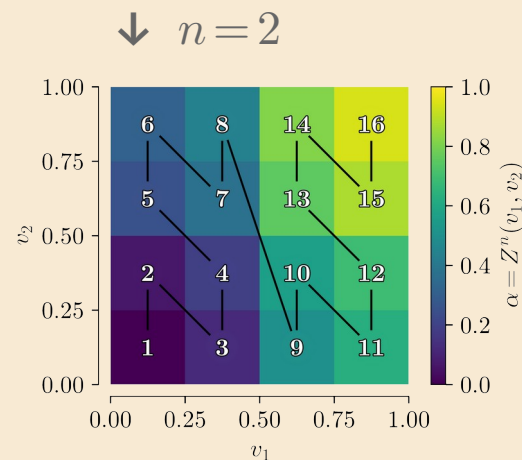
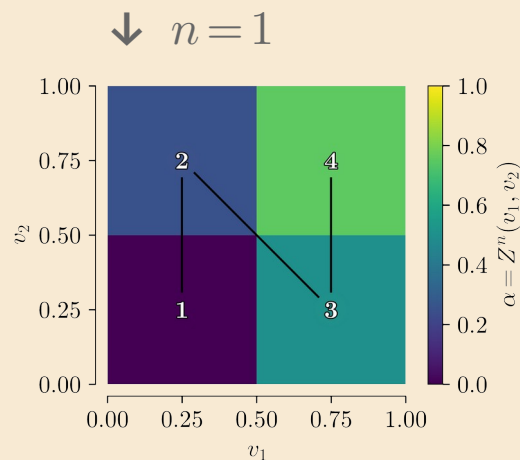
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→ again, inverse is

$$v_1^{(n)} = Z_1^{-1}(\alpha^{(n)}) = 0.b_1 b_3 \cdots b_{2n-1}$$

$$v_2^{(n)} = Z_2^{-1}(\alpha^{(n)}) = 0.b_2 b_4 \cdots b_{2n}$$

→ converges to a bijection between the segment and the square



coarse-graining: how to simulate the 1-dimensional neural field

→ naive numerical kernel for $[0,1]$

$$\begin{aligned}\tilde{w}(\alpha_i, \beta_j) &= \tilde{J}_{\alpha_i, \beta_j} \\ &= \tilde{J}_{S(i), S(j)} \\ &\stackrel{\text{def}}{=} J_{ij} \\ &= w_U(\mathbf{v}_i, \mathbf{v}_j)\end{aligned}$$

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⇒ identical dynamics indep. of the mapping!

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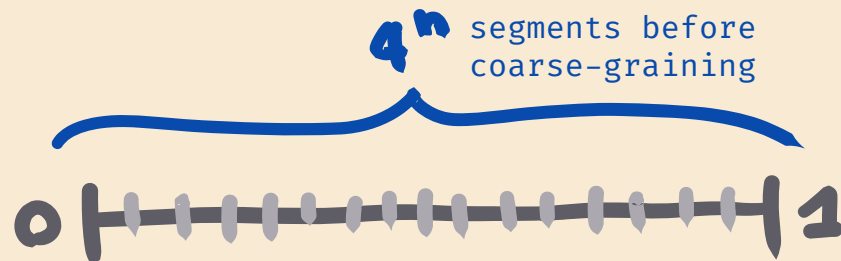
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- in 2D: 2^n bins per dimension
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→ problem: **permutation invariance**
 \Rightarrow identical dynamics indep. of the mapping!

→ in 2D: 2^n bins per dimension
 in 1D: 4^n bins per dimension

→ reduce to 2^n bins in 1D by **coarse-graining**

↑ coarse-graining averages 2^n consecutive populations in 1D, forming effective bins of size 2^{-n}

coarse-graining: how to simulate the 1-dimensional neural field

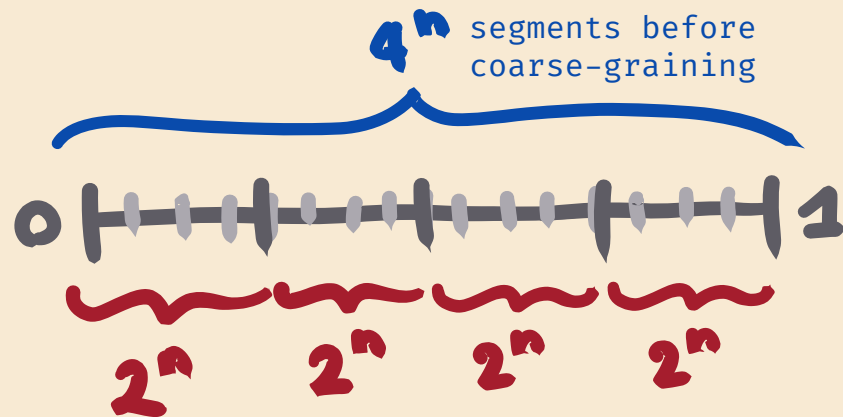
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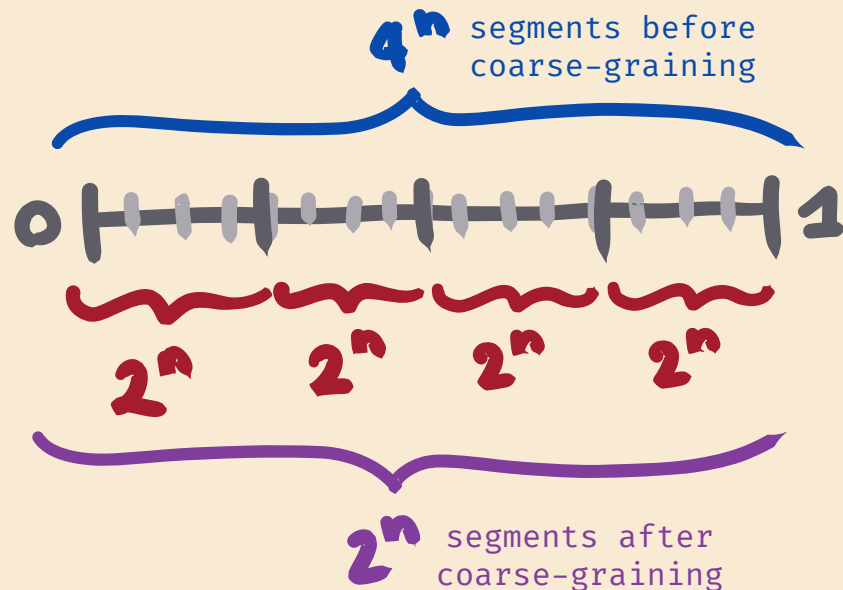
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let's simulate!

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... , but first, we'll need a toy model

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 → low-rank cycling gaussian neural field

kernel has rank p


$$\partial_t h(\mathbf{z}, t) = -h(\mathbf{z}, t) + \sum_{\mu=1}^p \int_{\mathbb{R}^p} z_{\mu+1} \tilde{\phi}(y_\mu) \phi(h(\mathbf{y}, t - \delta)) \mathcal{N}^p(d\mathbf{y})$$

"rolling" induces recurrent drive to the next pattern

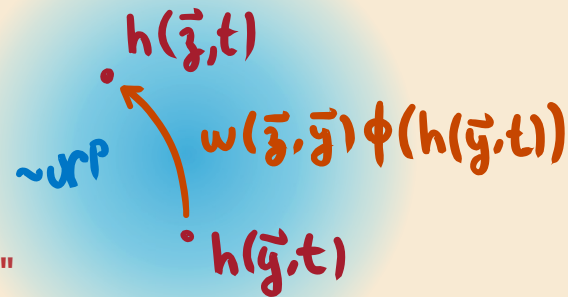
"delay"

population density follows a p -dimensional Gaussian (zero mean, no covariance)

$$w(\mathbf{z}, \mathbf{y}) = \sum_{\mu=1}^p z_\mu \tilde{\phi}(y_\mu)$$

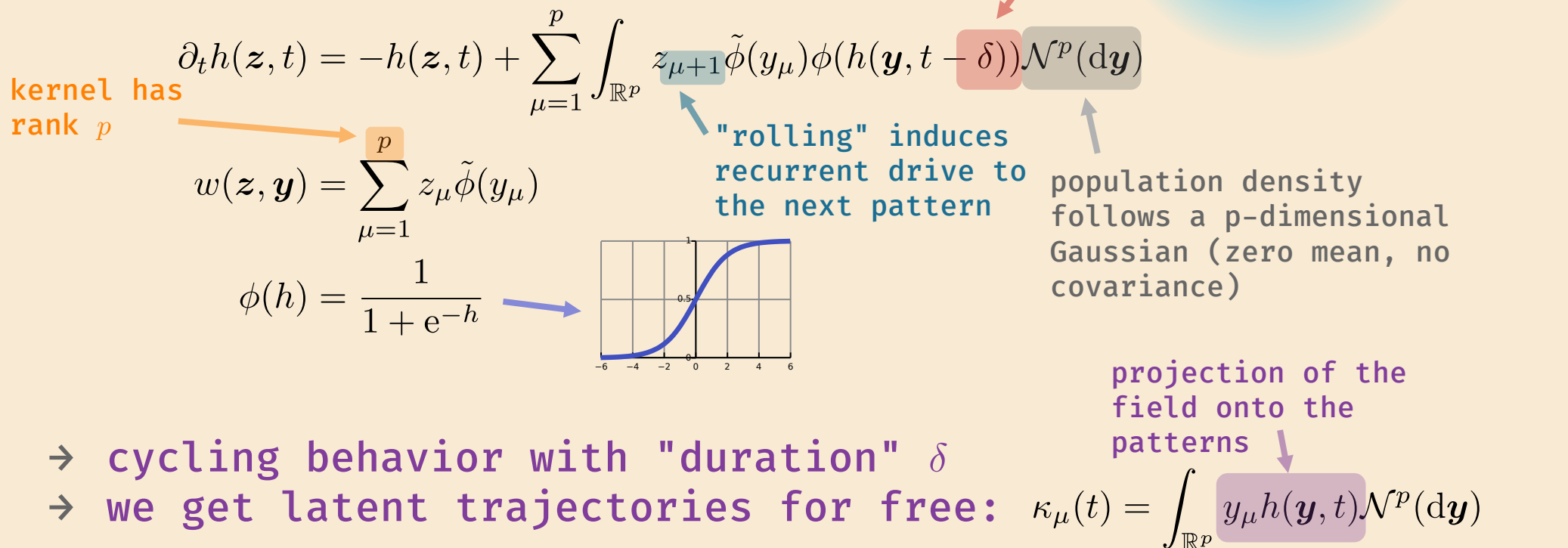
$$\phi(h) = \frac{1}{1 + e^{-h}}$$


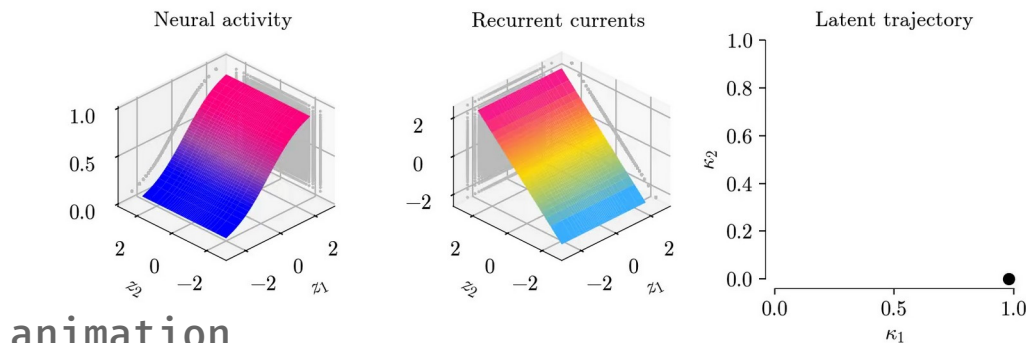
→ cycling behavior with "duration" δ



let's simulate!

... , but first, we'll need a toy model
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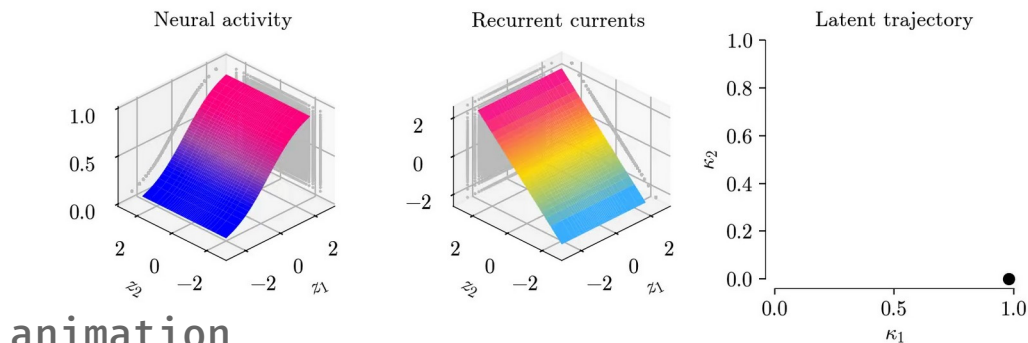




animation

← original neural field
for $p=2, \delta=6, h(z_1, z_2, 0) = z_1$

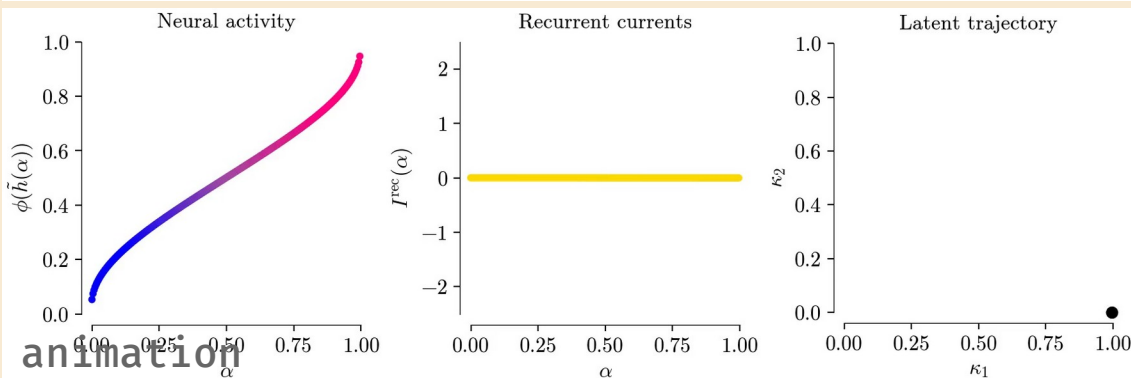
⇒ cycling behavior



animation

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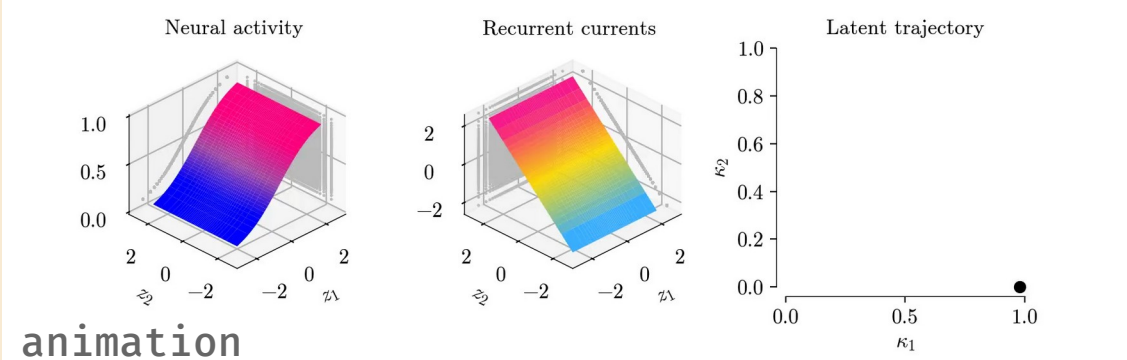
⇒ cycling behavior



animation

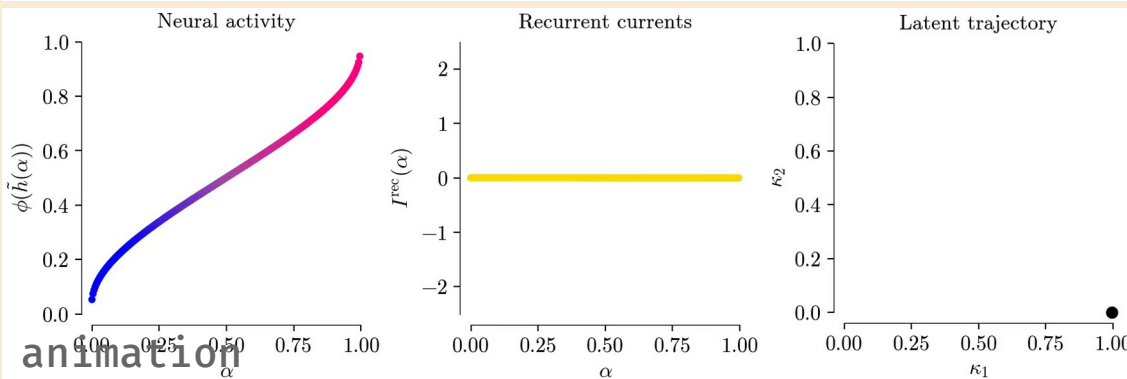
← mapped with Column mapping,
then coarse-grained

⇒ quick decay



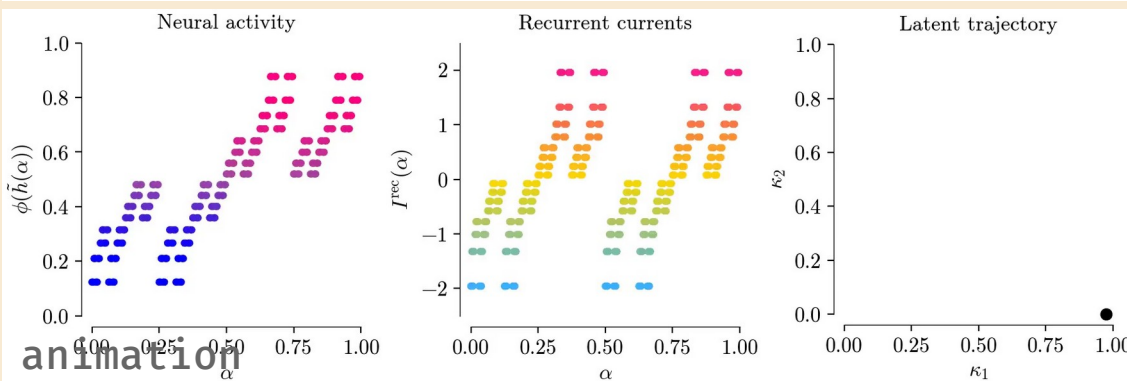
← original neural field
for $p=2, \delta=6, h(z_1, z_2, 0) = z_1$

⇒ cycling behavior



← mapped with Column mapping,
then coarse-grained

⇒ quick decay

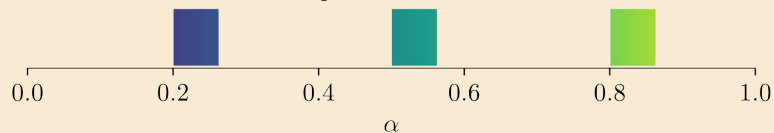


← mapped with Z-mapping, then
coarse-grained

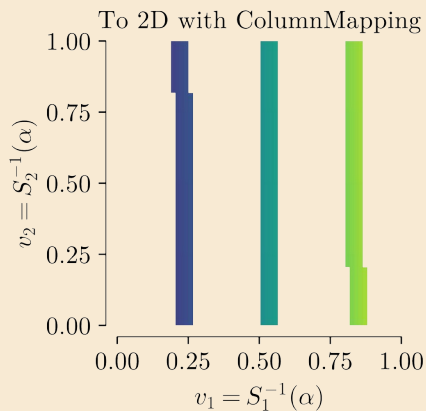
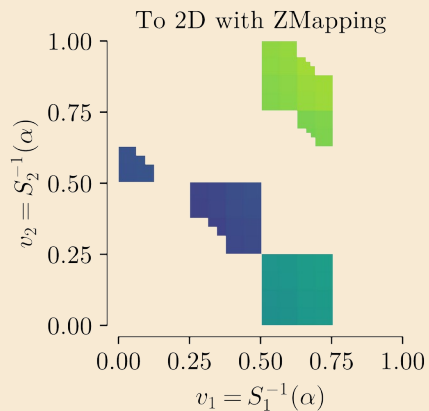
⇒ identical cycling
behavior

the notion of locality - motivation

Populations in 1D



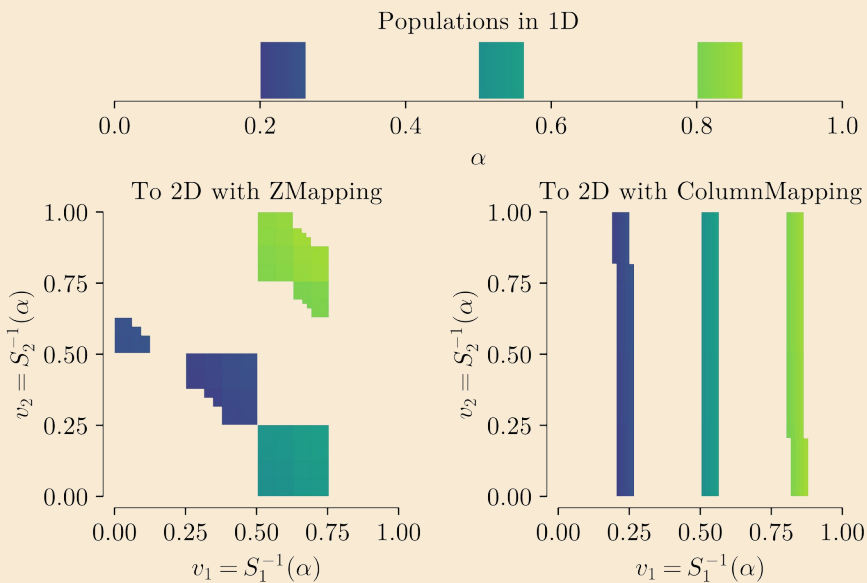
→ are populations close in 1D
also close in 2D ?



recall: $\tilde{w}(\alpha, \beta) = w_U(S^{-1}(\alpha), S^{-1}(\beta))$

← 2D populations corresponding to
three small segments (each of length 1/16)
of 1D populations

the notion of locality - motivation

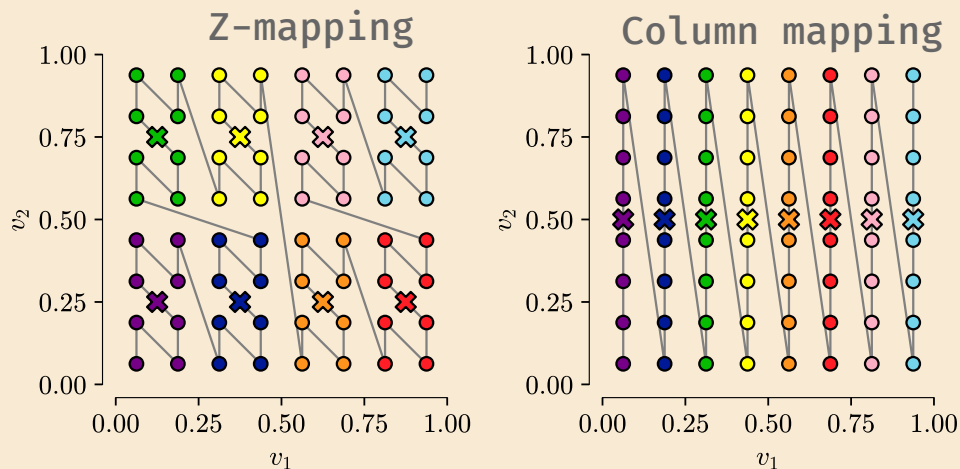


→ are populations close in 1D also close in 2D ?

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← 2D populations corresponding to three small segments (each of length 1/16) of 1D populations

→ what positions in 2D get "averaged together" ?



the notion of locality - formalism

→ average variation inside each coarse-graining bin

$$V_n(S^{-1}) = \frac{1}{2^n} \sum_{i=1}^{2^n} \sup_{\alpha, \alpha' \in \left[\frac{i-1}{2^n}, \frac{i}{2^n}\right]^2} \|S^{-1}(\alpha') - S^{-1}(\alpha)\|_1$$

average over all bins

every pair of positions inside each bin

distance in the p -dimensional embedding

→ if f is continuous, then $V_n(f) \rightarrow 0$

the notion of locality - formalism

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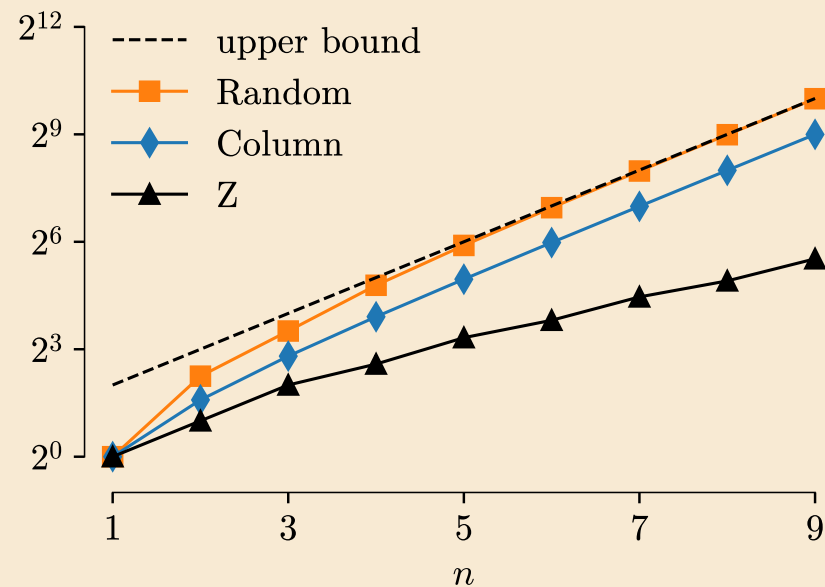
distance in the p -dimensional embedding

→ if f is continuous, then $V_n(f) \rightarrow 0$

→ scaling behavior of numerator

- Random mapping saturates bound
- Column mapping $\sim 2^n \Rightarrow V_n(C^{-1}) > 0$
- Z-mapping $\sim 2^{n/2} \Rightarrow V_n(Z^{-1}) \rightarrow 0$

↓ (numerator of the) average binned variation as a function of n



locality guarantees simulation accuracy

- \tilde{w} is regular enough that the integral on $[0,1]$ can be numerically evaluated. sketch of proof:

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3) bound integrand by supremum and use locality

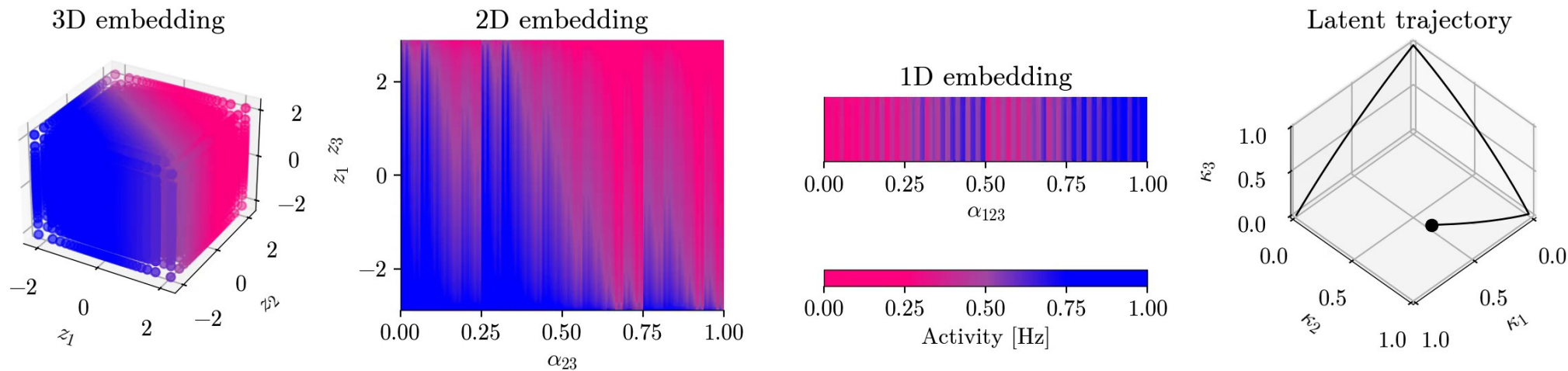
$$|\text{NI}_n - \text{AI}| \leq L(\alpha) V_n(S^{-1}) \xrightarrow{n \rightarrow \infty} 0$$

(bonus) iterating mapping and coarse-graining from p-dim to 1-dim

- \tilde{w} is regular enough that we can again apply a mapping and do coarse-graining
- "local mappings conserve regularity"

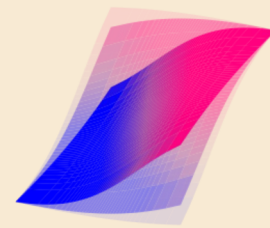
(bonus) iterating mapping and coarse-graining from p-dim to 1-dim

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- numerical demo with $p=3$: from $[0,1]^3$ to $[0,1]^2$ to $[0,1]$



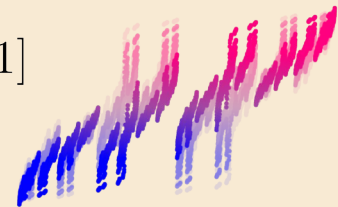
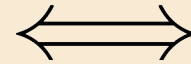
summary & conclusion

- example of neural fields in p dimensions that can be mapped to **equivalent neural fields in $[0,1]$**
- locality quantifies the **conservation of "regularity"**
- **coarse-graining** numerically enforces the notion of locality: non local mappings are destroyed
- the Z-mapping can be **approximated numerically**, and the numerical integral on $[0,1]$ approaches the analytical integral on $[0,1]$



Neural field in \mathbb{R}^p

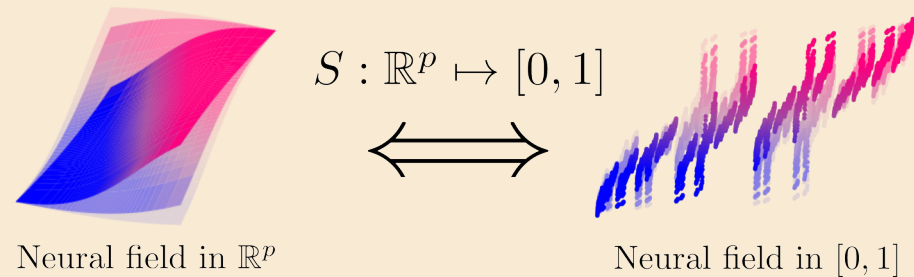
$$S : \mathbb{R}^p \mapsto [0, 1]$$



Neural field in $[0, 1]$

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Thank you!