

Classification of Algorithms

Distinctive Characteristics



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Important Definitions

- Correctness: The correctness for an algorithm in a distributed system is defined on two different metrics.
 - Liveness: The right must eventually occur
 - Safety: The wrong must not occur
- An algorithm is correct if and only if it ensures both liveness and safety.

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Fairness



- Fairness property generally means that the processes are executed in the order of their arrival in the system
- Each process gets a fair chance to execute the CS.
- Does fairness cause priority inversion?

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Common Performance Metrics



- Message complexity: The number of control messages required to be exchanged per execution of an algorithm
- Synchronization delay: The time required between two successive executions
 - e.g., it is the time required between a process leaves its CS and the next one enters its CS.

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Common Performance Metrics



- Response time: The time interval that a request waits before the result is computed
- Throughput: The rate at which the algorithms are executed.
 - $\text{Throughput} = 1/(\text{SD} + \text{E})$
where SD is the synchronization delay and E is the average execution time.

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Four Major Classes



- Symmetric algorithms
- Diffusion Computation based algorithms
- Token based algorithms
- Edge Chasing algorithms

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Four Major Classes

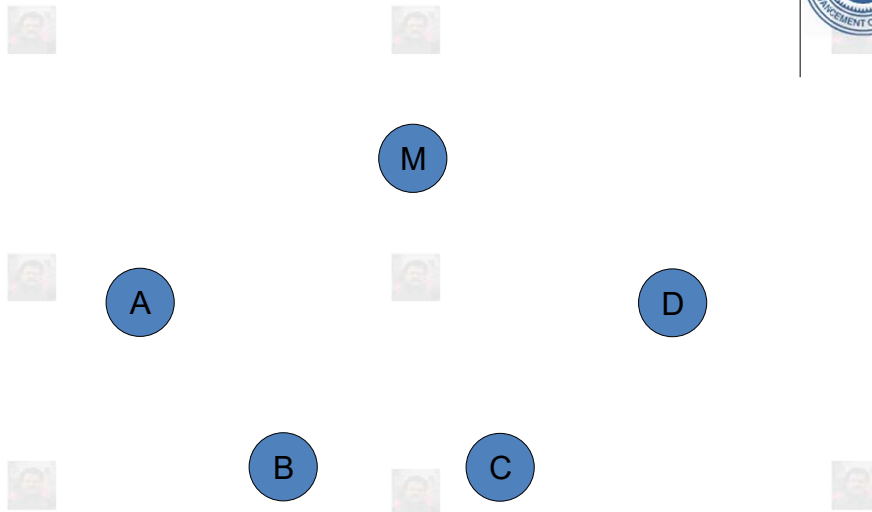


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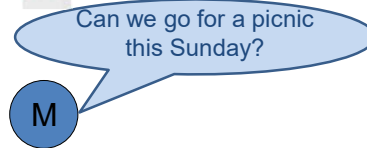
Symmetric Algorithms



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Symmetric Algorithms



A



D



B



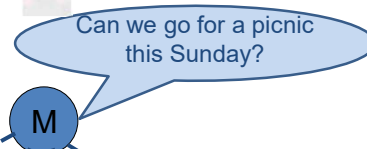
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Symmetric Algorithms



A



D



B



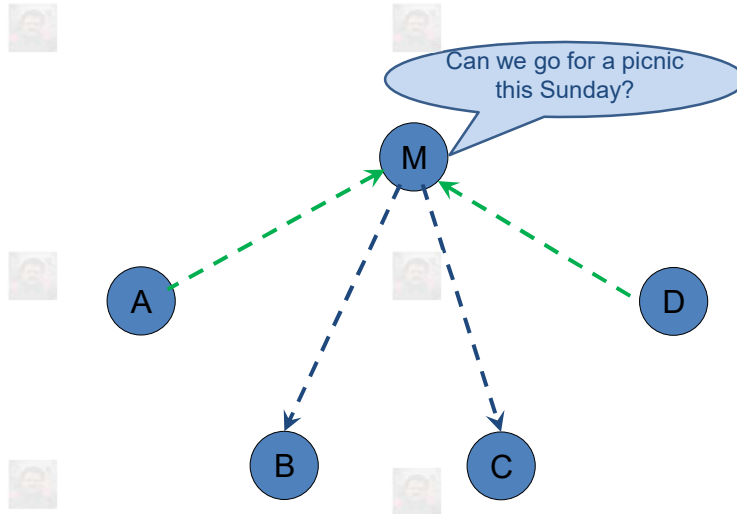
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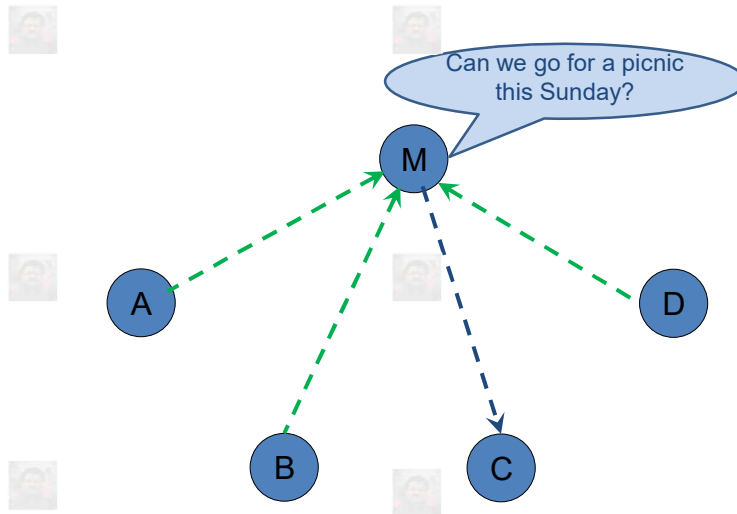
Symmetric Algorithms



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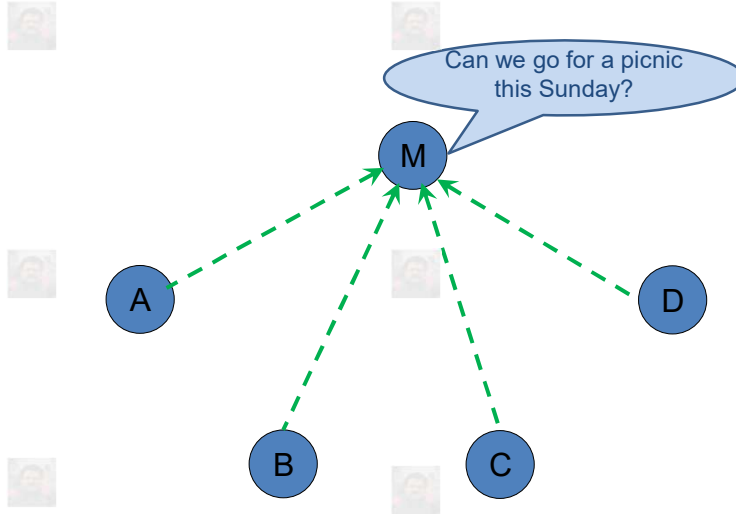
Symmetric Algorithms



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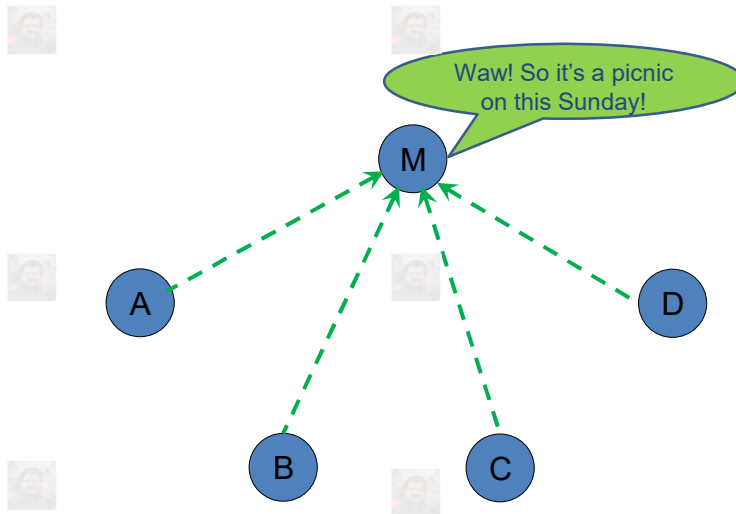
Symmetric Algorithms



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Symmetric Algorithms



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Symmetric Algorithms



- Decisions are taken collectively and based on mutual consent
- Simple to understand, design and implement
- Large number of messages are exchanged between the participating processes

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Four Major Classes



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Diffusion Computation Algorithms



Image courtesy: Fine Art America

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Diffusion Computation Algorithms



- Just like salt diffuses in water, the computing problem starts spreading from an **INITIATOR** node

- Growth Phase



- Shrinking Phase



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Diffusion Computation Algorithms



- Engaging queries
 - Engaging replies
- Non-engaging queries
 - Non-engaging replies

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Diffusion Computation Algorithms



- Partial results are queued in a node, till all the sub-tasks are done
- Lower message complexity as compared to symmetric algorithms
- Fault tolerant

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A scenario...

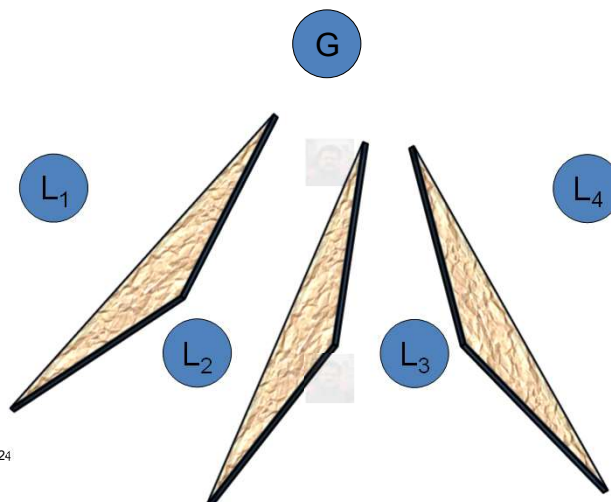


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Image courtesy: The New York Times

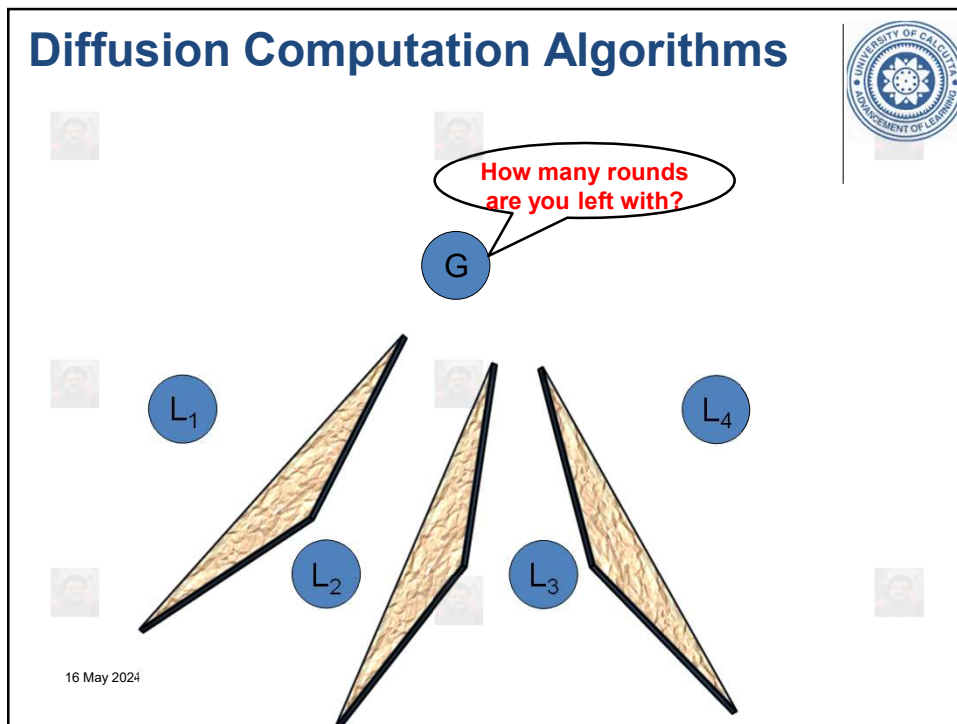
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Diffusion Computation Algorithms

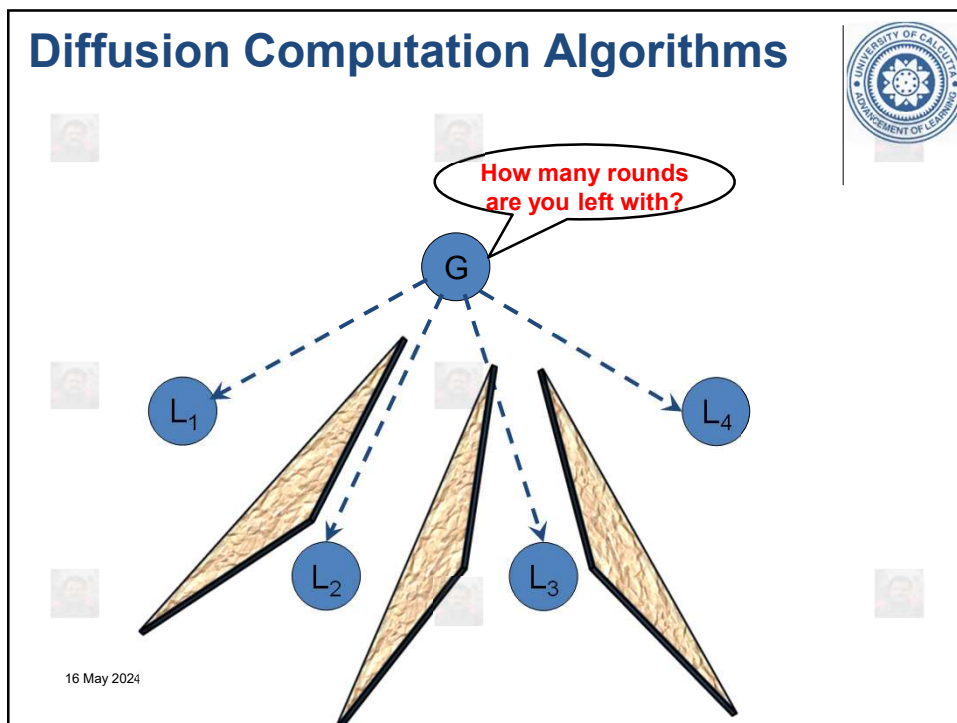


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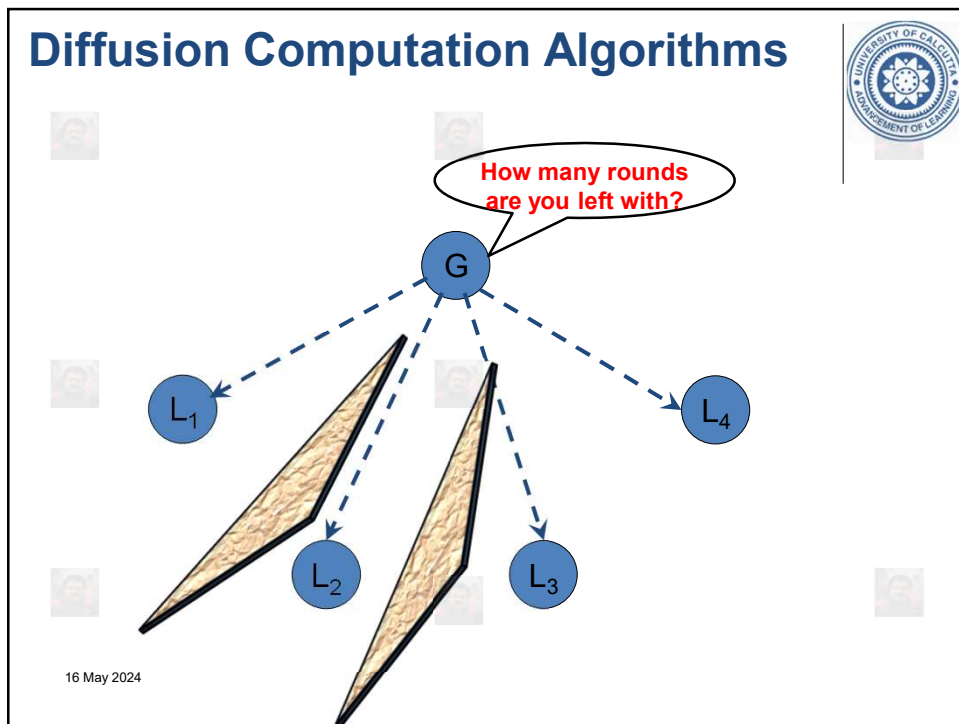
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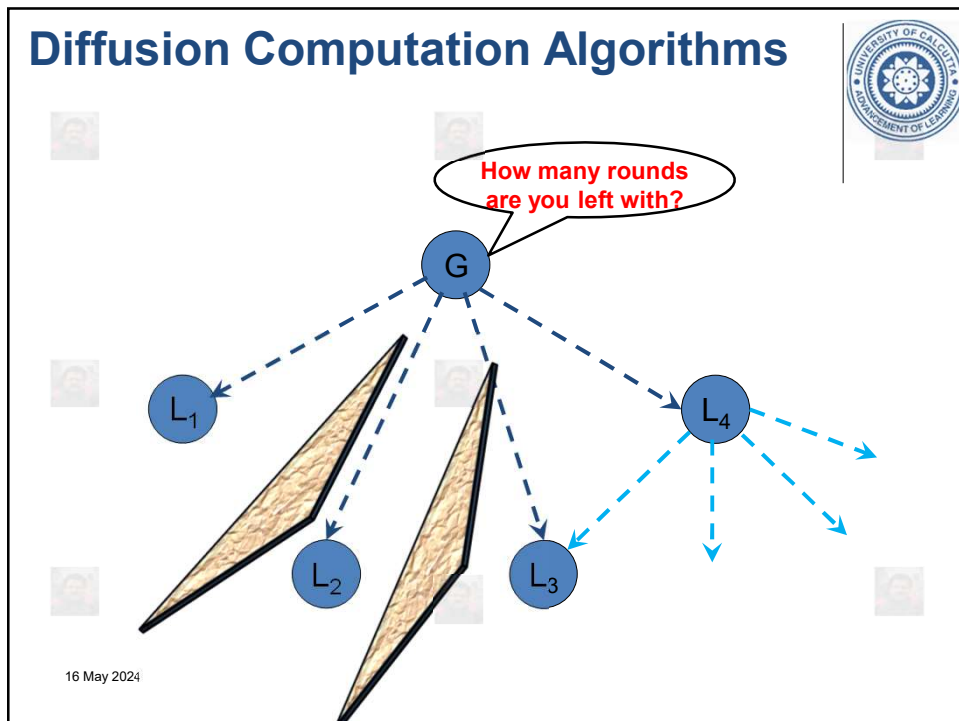
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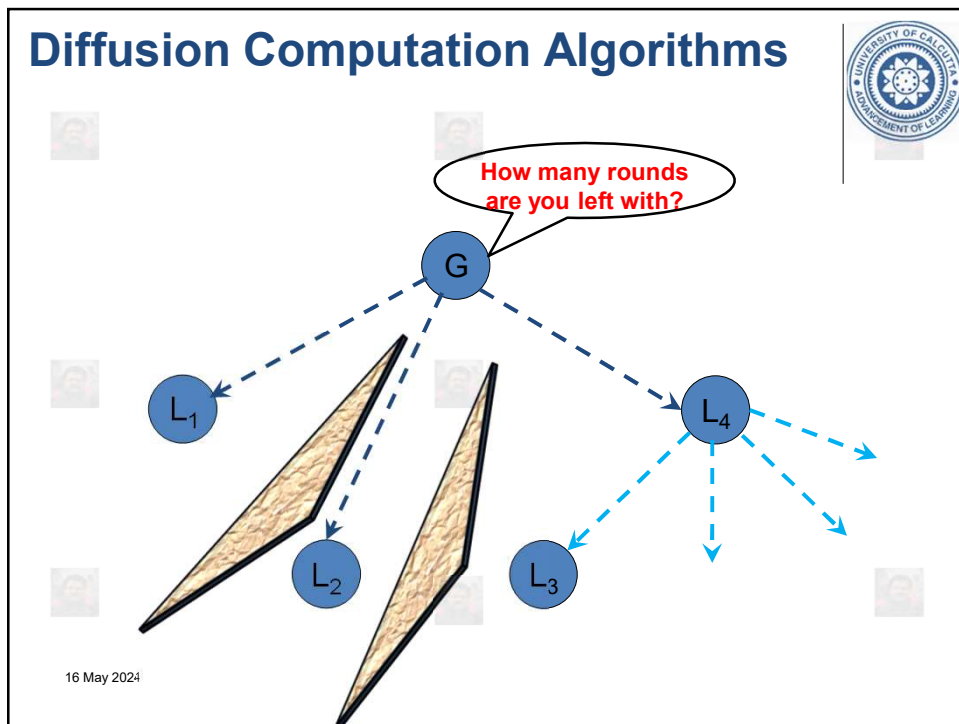
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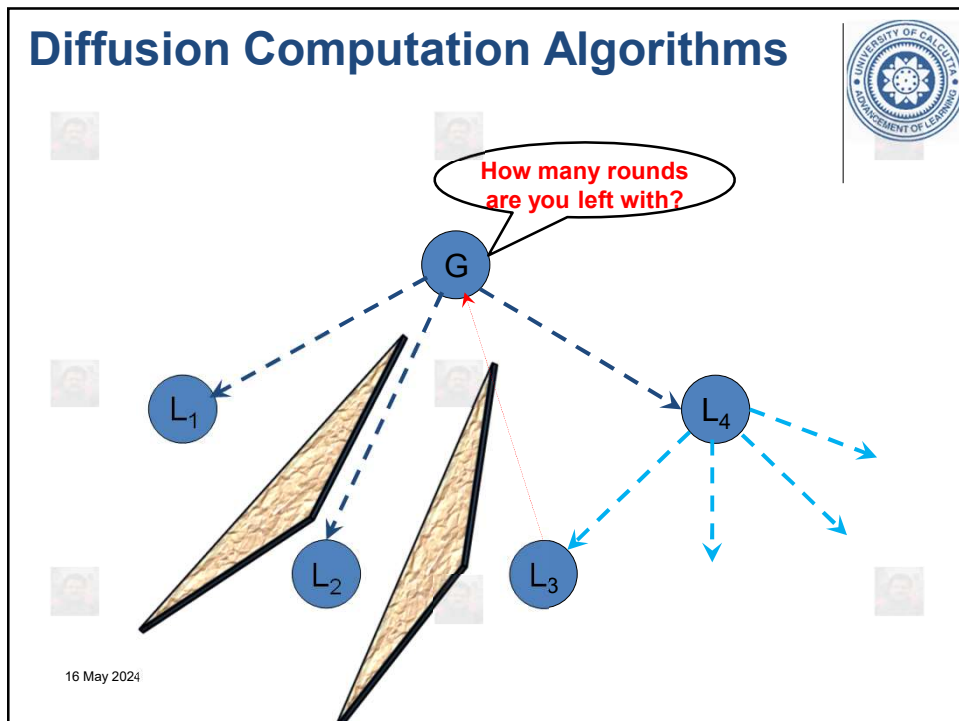
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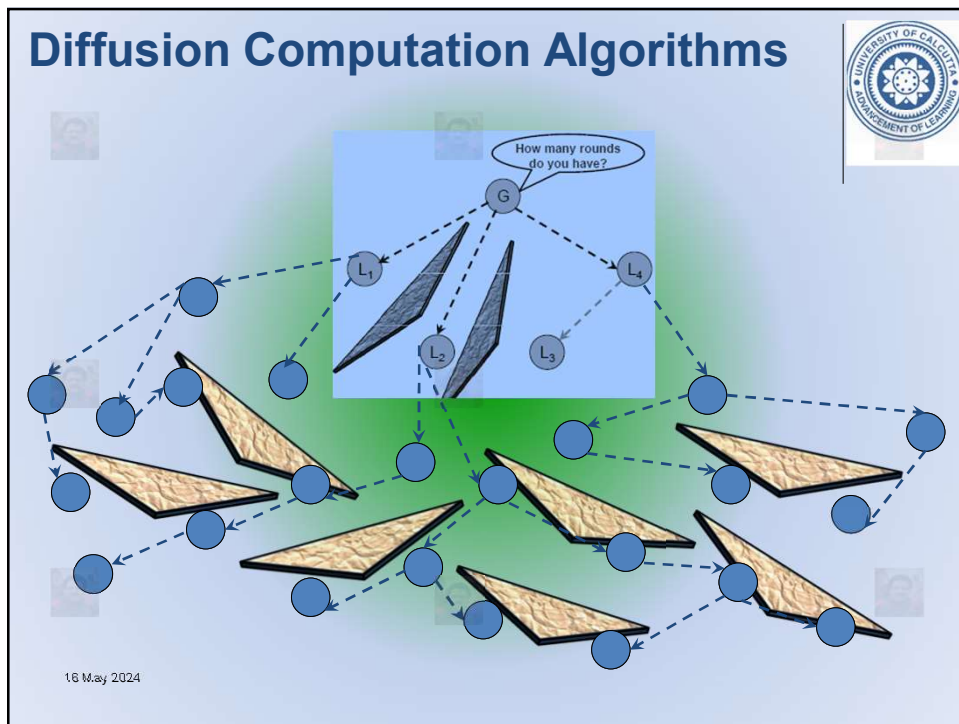
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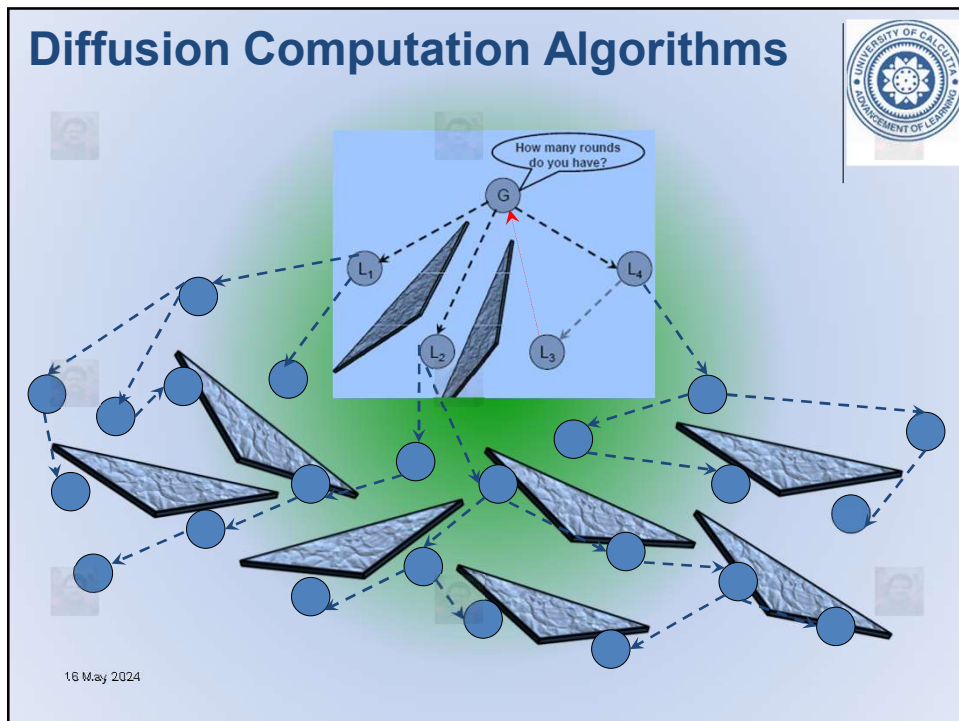
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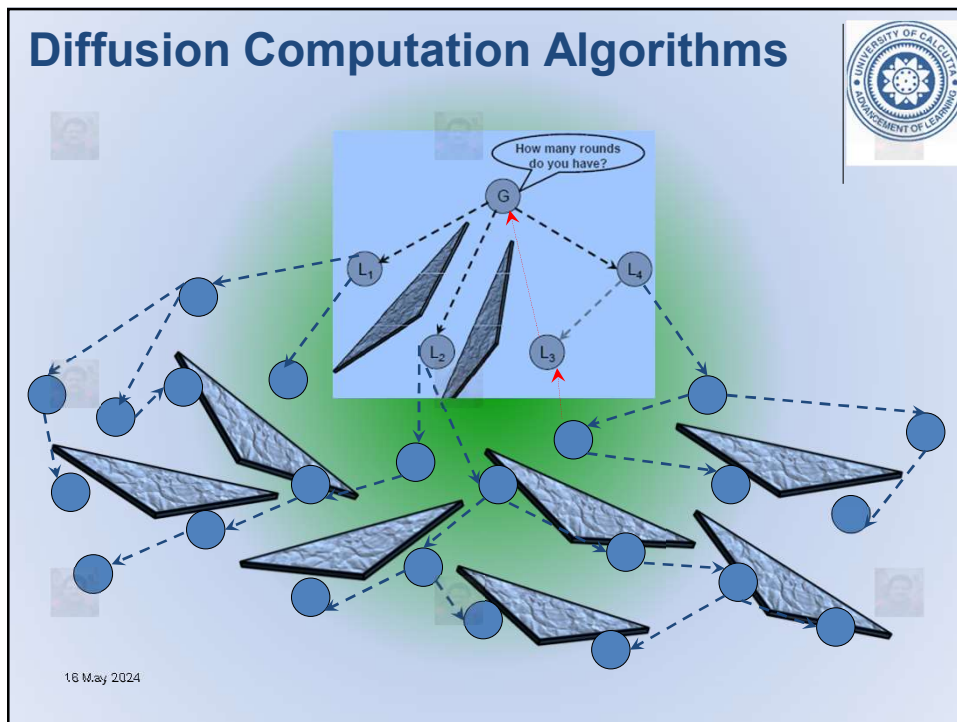
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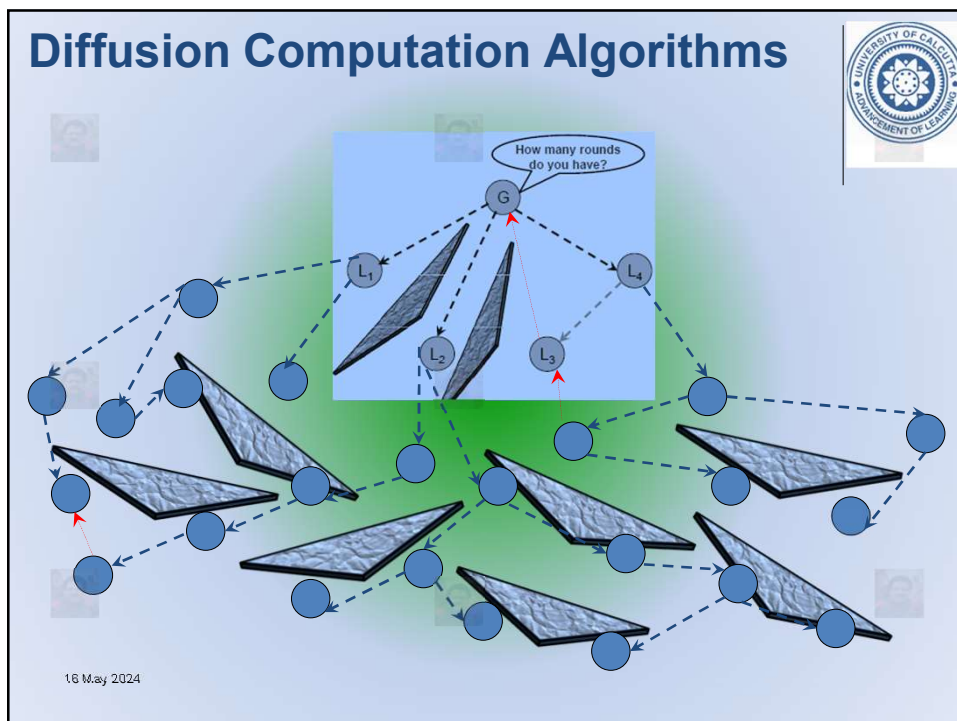
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Diffusion Computation Algorithms

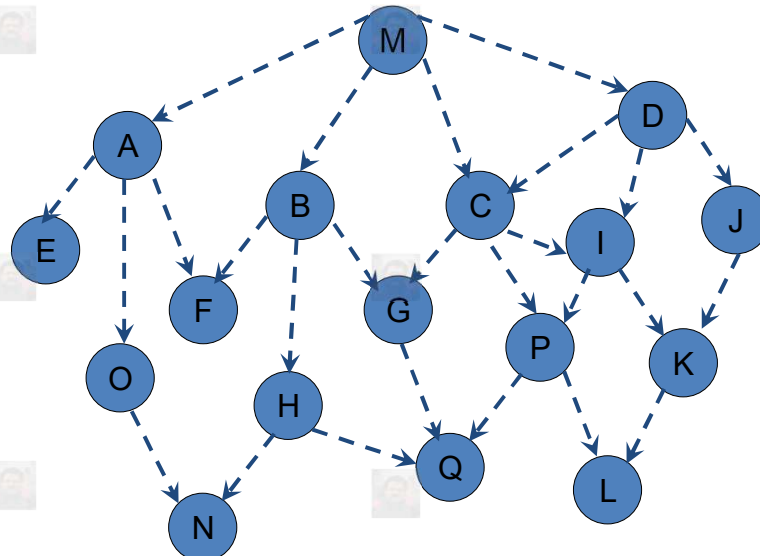


- Process that diffuse a query never knows whether the communication will be an engaging or non-engaging query for the recipient
- Recipient decides whether the diffusion is to continue
- A hierarchy evolves dynamically for a particular execution

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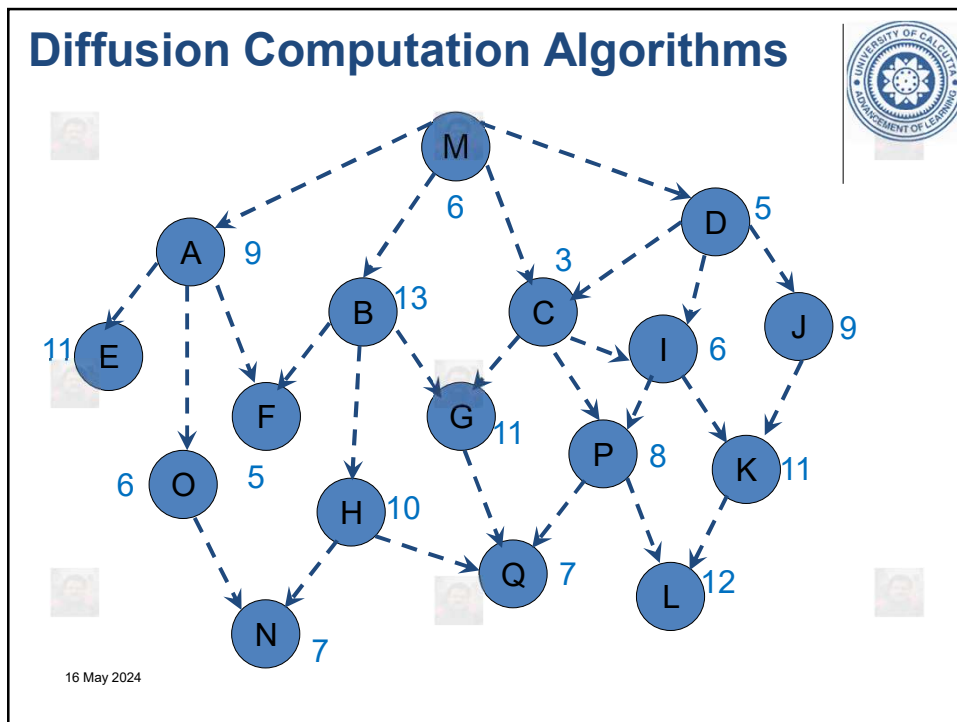
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Diffusion Computation Algorithms

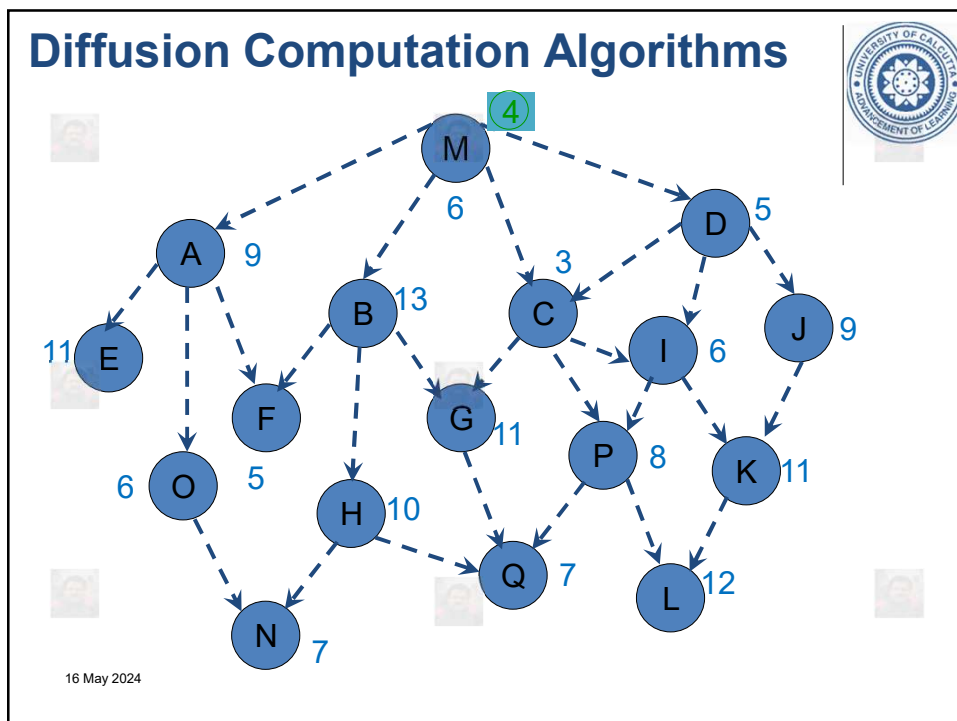


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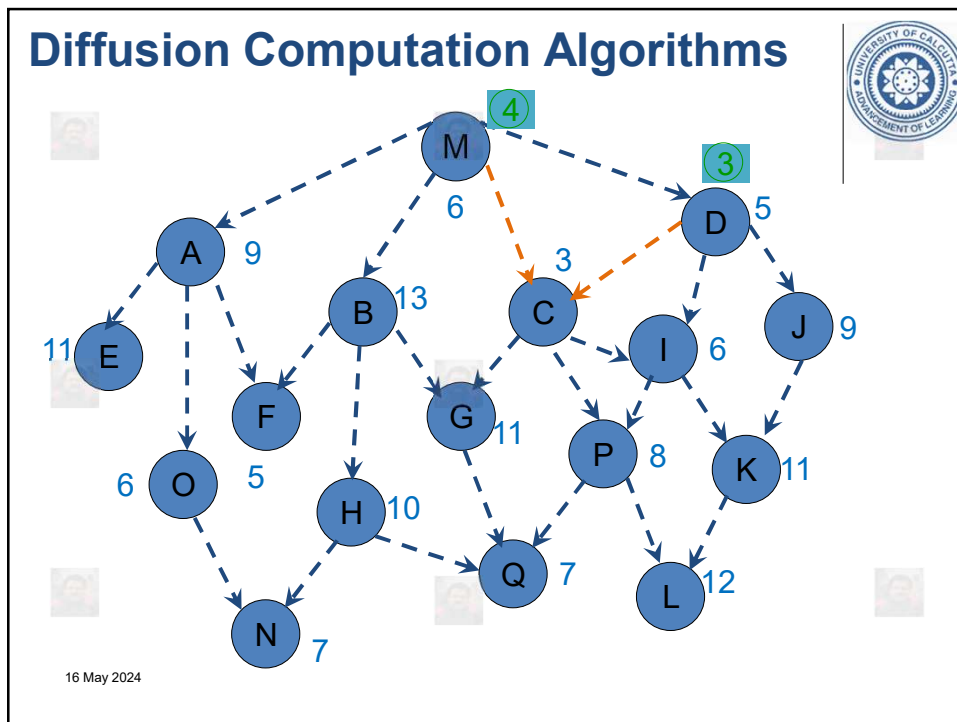
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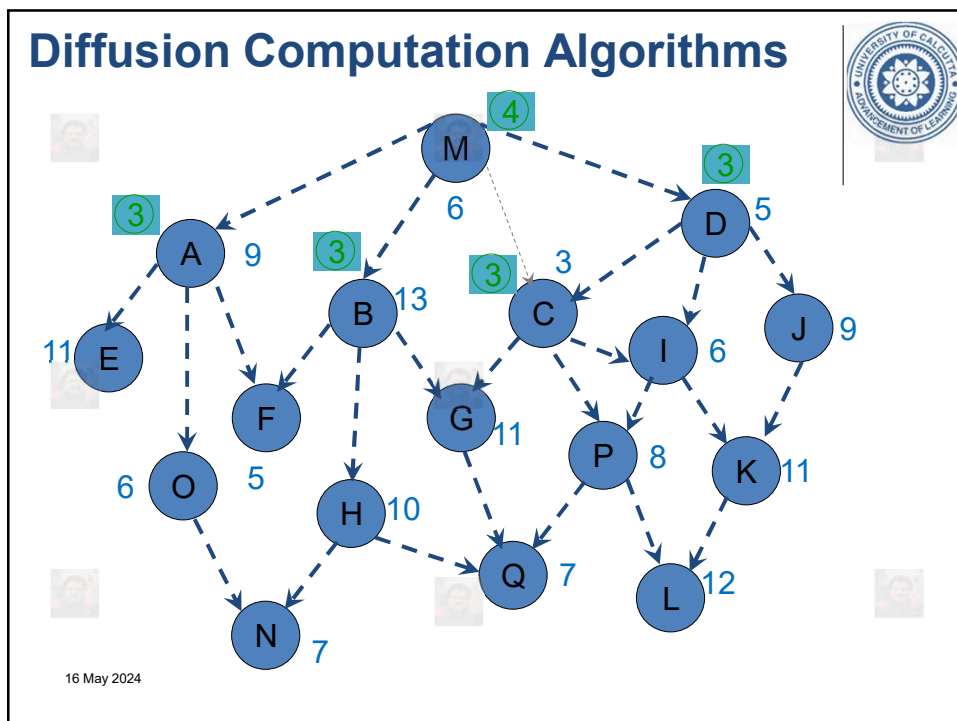
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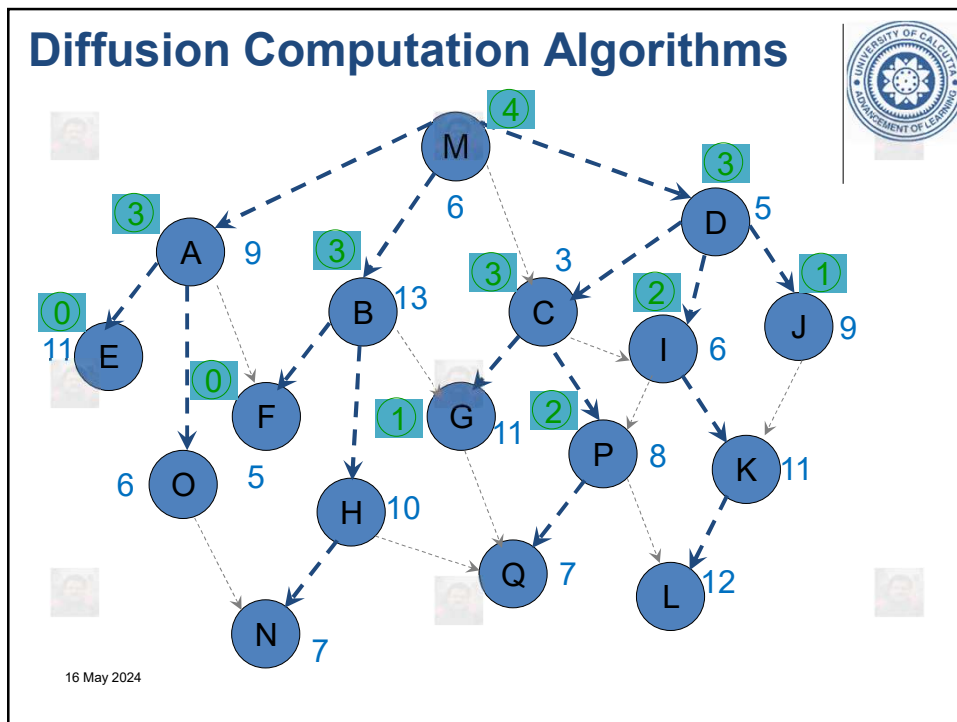
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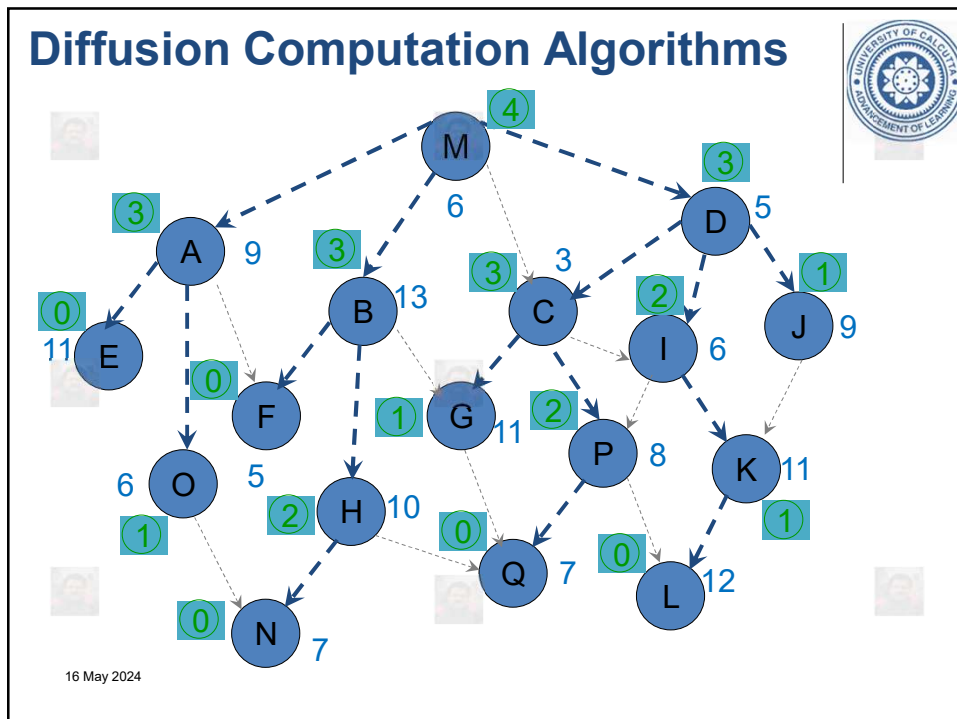
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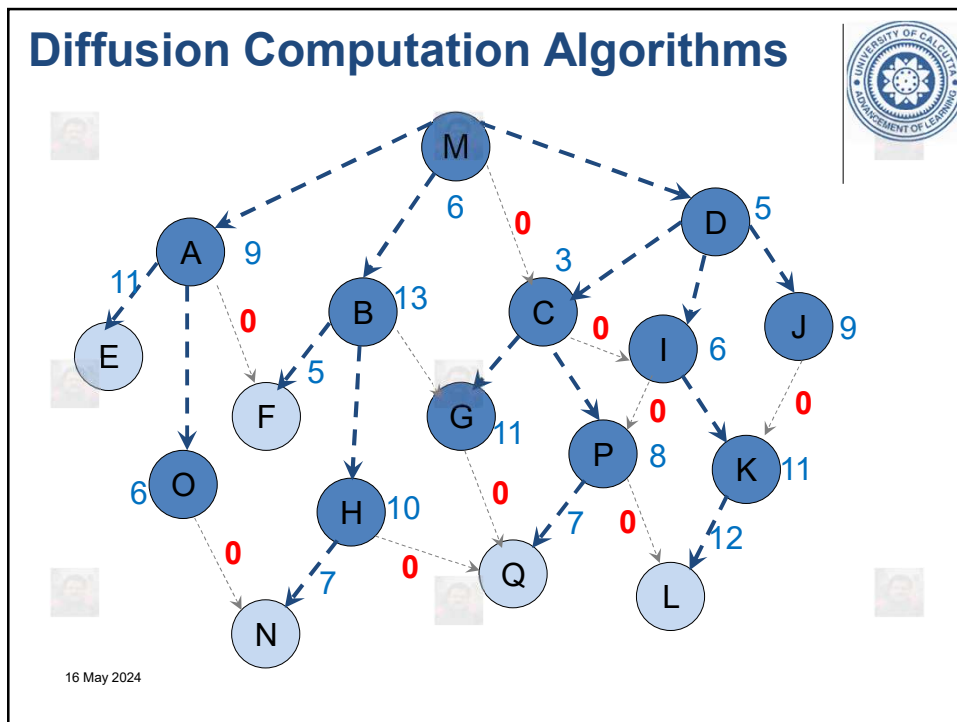
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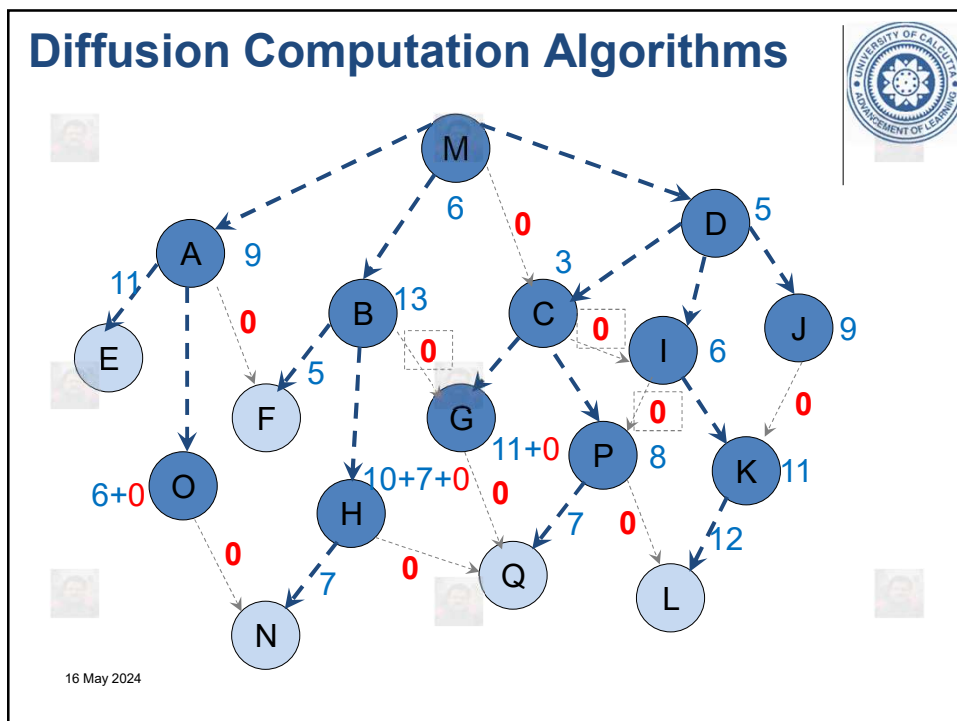
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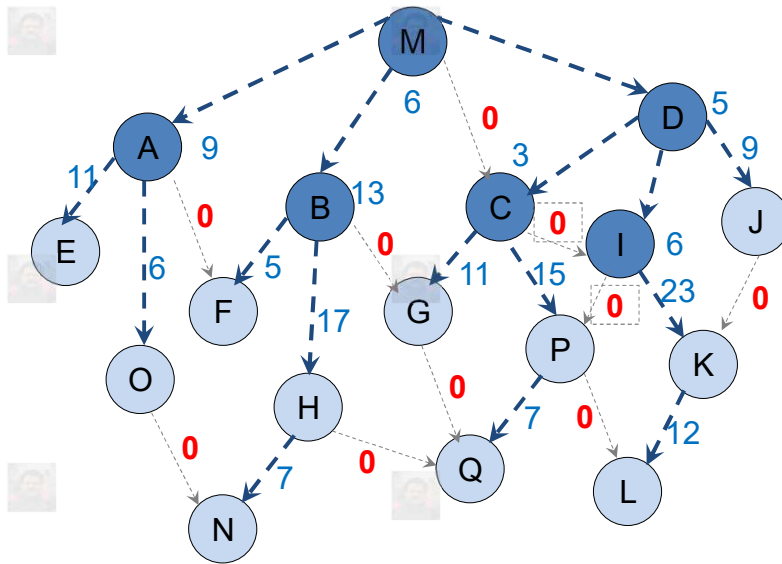


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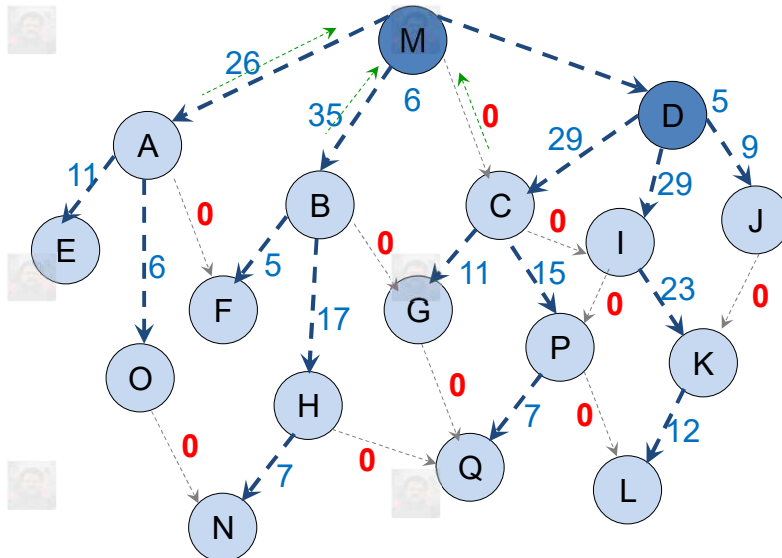
Diffusion Computation Algorithms



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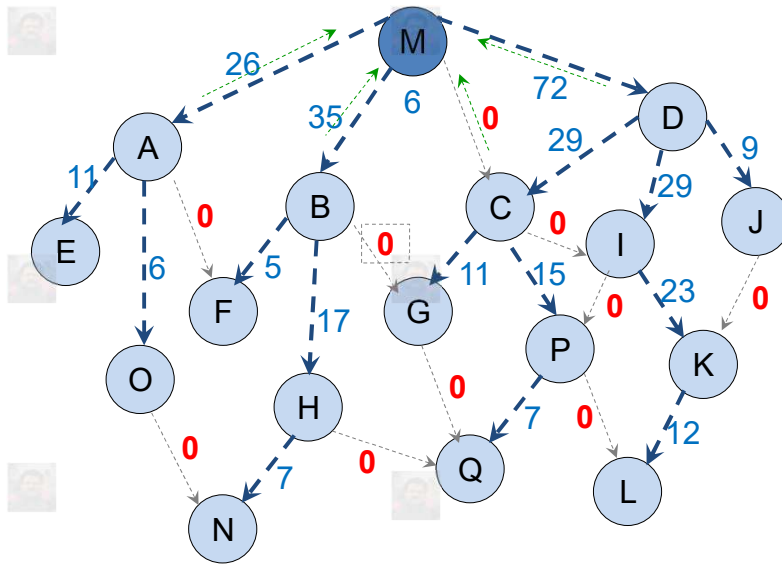
Diffusion Computation Algorithms



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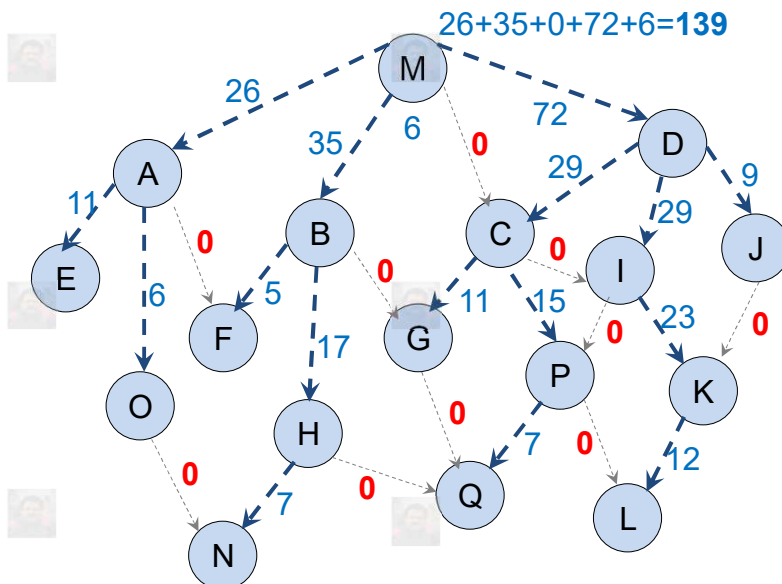
Diffusion Computation Algorithms



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Diffusion Computation Algorithms



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Four Major Classes



- Symmetric algorithms
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- **Token based algorithms**
- Edge Chasing algorithms

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Token-based Algorithms



- There will be a token for each instance of resource
- Algorithm is to be designed to get hold of the token in order to access the resource
- Predominantly used for scheduling, mutual exclusion

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Token-based Algorithms - Correctness



- A token-based algorithm is inherently safe as long as a single token exists for each instance of a resource under contention
- Thus, a token-based algorithm is correct if its liveness is ensured.

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Four Major Classes



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- **Edge Chasing algorithms**

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Edge Chasing Algorithms



- Edge-chasing is a technique, often used for deadlock detection in distributed systems.
- When a process, say P, is blocked for some resource held by another process, say Q, a probe message is sent to all processes in the wait for graph with P as the start node

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Edge Chasing Algorithms



- Non-blocked processes will discard the probe.
- If the probe returns to process P, a circular wait is detected along with the processes in the cycle.
- Intuitive and limited scope of applications

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Thanks for your kind attention

Questions??