The following are tasks that need to be completed this term:

- 1. Finish non-motorized telescope assembly.
 - a) Drill holes into turntable and assemble uprights.



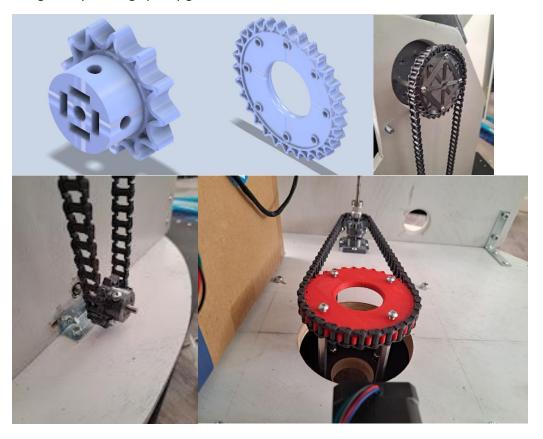
b) Drill holes and screw in horizontal struct piece.



c) Paint unfinished pieces



- 2. Create gearing system.
 - a) Design and print large pulley gear.



b) Order smaller gear and timing belts.

(you saw the timing belt in demo, now using chain I already had)

3. Connect power adapter to power supply.

(Saw in demo)

4. Connect power supply to stepper drivers.

(Saw in demo)

5. Connect level shifter for the 3.3V I/O of Raspberry Pi to 5V of the stepper motor driver.

(Completed, but later used 2222NPN transistors instead)

- 6. Develop software to drive motors.
 - a) Develop software to drive 2 motors at once.

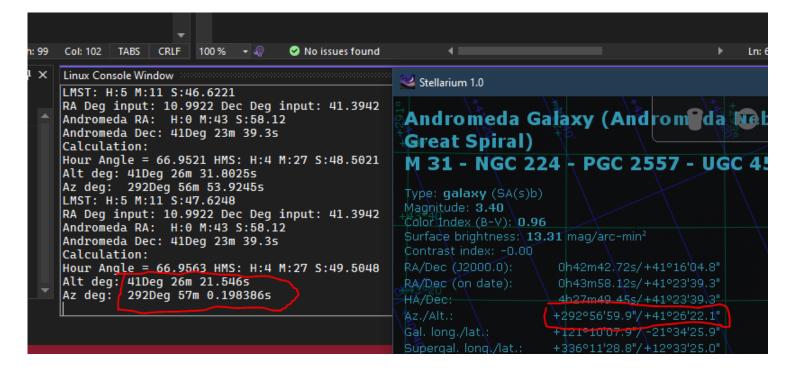
(see video)

https://photos.google.com/photo/AF1QipPvImcMB4 67zJRhahv9zSW7swaBpVDf2k44Kmo

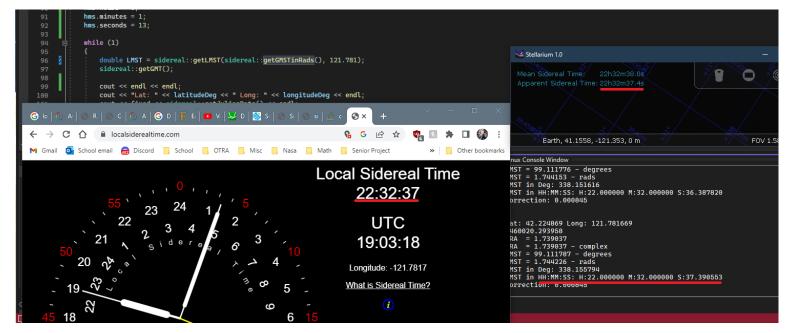
- 7. Develop software to aim telescope.
 - a) Find the math behind aiming 2 axis control in 3D geometric space.

"A rigorous algorithm for telescope pointing" – Patrick Wallace (2002)

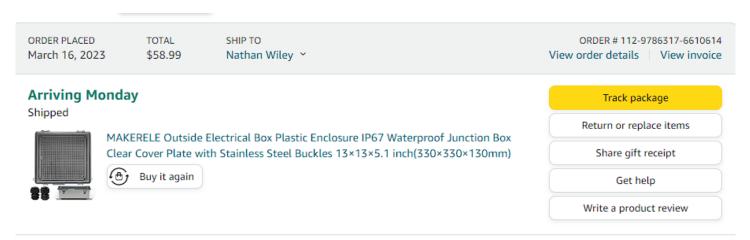
b) Apply the math to the code for driving the motors.



- 8. Develop software to track a coordinate as the earth rotates.
 - a) Develop software for calculating sidereal time.



9. Create or purchase board and electronic housing.



Signed:

Embedded Senior Project – Wo	rk A	greement
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Nathan Wiley

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