

# A STRUCTURAL TAXONOMY OF LLM-BASED CLINICAL AGENT SYSTEMS

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## ABSTRACT

### 1 INTRODUCTION

014 Large language models have rapidly entered clinical medicine, initially through applications such as  
015 single turn question answering, document summarization, and static decision support. Early medical  
016 uses largely treated these models as passive tools, evaluated through benchmark accuracy on curated  
017 datasets or examination style tasks. More recent work increasingly deploys large language models  
018 as agents that plan actions, invoke tools, coordinate with other agents, and interact with clinical  
019 environments over multiple steps. This transition from isolated model invocation to goal directed  
020 agentic systems marks a substantive change in the design space of medical artificial intelligence.  
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022 Clinical settings place unique demands on such systems. Medical decision making is constrained by  
023 safety requirements, accountability standards, auditability expectations, and the need for continuity  
024 across time. An agentic system in medicine is therefore expected not only to produce plausible  
025 outputs, but also to justify decisions, manage errors, respect authority boundaries, and maintain  
026 state across interactions. Under these conditions, system level design choices such as how agents  
027 coordinate, how decisions are verified, and how control is distributed become as important as the  
028 underlying language model itself.  
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030 Several recent surveys have begun to organize the growing literature on large language model based  
031 agents in medicine. Existing reviews distinguish between single agent and multi agent systems, dis-  
032 cuss centralized versus decentralized coordination strategies, and introduce workflow or paradigm  
033 level categorizations of agent behavior. These efforts provide valuable overviews of agent capabili-  
034 ties and application domains, and they reflect increasing recognition that architectural considerations  
035 matter in clinical artificial intelligence.  
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037 At the same time, existing surveys do not provide a clinical deployment oriented structural taxon-  
038 omy that jointly captures three dimensions that are central to reliable medical use. First, they do not  
039 systematize collaboration topology together with control distribution beyond coarse architectural  
040 categories. Second, they do not treat verification mechanisms with explicit veto or override strength  
041 as a first class organizing axis at the level of individual systems. Third, they do not classify agen-  
042 tic systems by temporal scope, ranging from episodic interactions to session level workflows and  
043 longitudinal care. As a result, current taxonomies offer limited support for reasoning about safety  
044 guarantees, auditability, and failure modes across different clinical deployment settings.  
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046 In this survey, we address this gap by organizing large language model based clinical agent systems  
047 through a structural lens. We classify systems according to their collaboration topology, verification  
048 mechanisms including veto and override behavior, and temporal scope of operation. By treating  
049 these dimensions as first class organizing axes rather than implementation details, this survey aims  
050 to clarify how architectural choices shape clinical reliability and to support principled design, eval-  
051 uation, and regulation of agentic artificial intelligence in medicine.  
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