

AROS2Controller::HandleVelocity  
Command

```
graph LR; A[AROS2Controller::HandleVelocity Command] --> B[UQuadDroneController::SetDesiredVelocity]; A --> C[UQuadDroneController::SetDesiredYawRate];
```

UQuadDroneController  
::SetDesiredVelocity

UQuadDroneController  
::SetDesiredYawRate