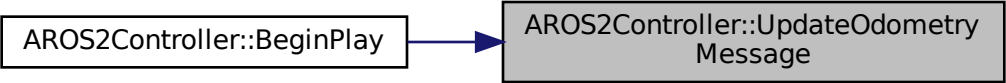


AROS2Controller::BeginPlay



```
graph LR; A[AROS2Controller::BeginPlay] --> B[AROS2Controller::UpdateOdometry Message]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'AROS2Controller::BeginPlay'. The right box is gray with a black border and contains the text 'AROS2Controller::UpdateOdometry Message' on two lines. A blue arrow points from the right side of the left box to the left side of the right box.

AROS2Controller::UpdateOdometry
Message