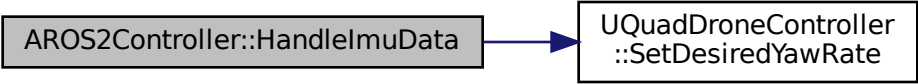


AROS2Controller::HandleImuData



```
graph LR; A[AROS2Controller::HandleImuData] --> B[UQuadDroneController::SetDesiredYawRate]
```

The diagram illustrates a function call. On the left, a gray rectangular box contains the text 'AROS2Controller::HandleImuData'. A dark blue arrow points from the right side of this box to the left side of a white rectangular box on the right. This white box contains the text 'UQuadDroneController::SetDesiredYawRate'.

UQuadDroneController
::SetDesiredYawRate