## 1 General properties of Conditional Expectation

## 1.1 Idea

Mimic general properties of ordinary expectations

$$\mathbb{E}(X_1 + X_2) = \mathbb{E}X_1 + \mathbb{E}X_2 \qquad \mathbb{E}(cX) = c\mathbb{E}X \tag{1.1}$$

but with  $\mathcal{G}$ -measurable RVs playing the role of constants c.

## 1.2 Some basic properties of CE

Let  $X : (\Omega, \mathcal{F}P) \to \mathbb{R}$ ,  $\mathbb{E}|X| < \infty$ ,  $\mathcal{G} \subset \mathcal{F}$ .  $\mathbb{E}[X \mid \mathcal{G}]$  is *the* RV Z such that

- (a) Z is  $\mathcal{G}$ -measurable
- (b)  $\mathbb{E}[Z1_G] = \mathbb{E}[X1_G] \quad \forall G \in \mathcal{G}.$

**Lemma 1.1.** For  $Z = \mathbb{E}[X \mid \mathcal{G}]$ ,  $\mathbb{E}[VZ] = \mathbb{E}(VX]$ , we have

- (a)  $\mathbb{E}[X_1 + X_2 \mid \mathcal{G}] = \mathbb{E}[X_1 \mid \mathcal{G}] + \mathbb{E}[X_2 \mid \mathcal{G}]$
- (b)  $\mathbb{E}[VX \mid \mathcal{G}] = V\mathbb{E}[X \mid \mathcal{G}]$  for bounded  $\mathcal{G}$ -measurable V.
- (c) If  $0 \le X_n \uparrow X$  a.s., then  $\mathbb{E}[X_n \mid \mathcal{G}] \uparrow \mathbb{E}[X \mid Y]$  a.s.
- (d) If  $X \ge 0$  a.s., then  $\mathbb{E}[X \mid \mathcal{G}] \ge 0$  a.s.
- (e)  $|\mathbb{E}[X \mid \mathcal{G}]| \leq \mathbb{E}[|X| \mid \mathcal{G}] \text{ a.s.}$
- (f)  $\mathbb{E}[\mathbb{E}[X \mid \mathcal{G}]] = \mathbb{E}X$
- (g) If X is G-measurbale, then  $\mathbb{E}[X \mid G] = X$ If G is trivial, then  $\mathbb{E}[X \mid G] = \mathbb{E}X$ .
- (h) Tower Property: If  $\mathcal{G} \subset \mathcal{H}$  then  $\mathbb{E}[X \mid \mathcal{G}] = \mathbb{E}[\mathbb{E}[X \mid \mathcal{H} \mid \mathcal{G}]]$ .

*Proof.* (a) Write  $Z_i = \mathbb{E}[X_i \mid \mathcal{G}]$ .

Need to show  $Z := Z_1 + Z_2 = \mathbb{E}[X_1 + X_2 \mid \mathcal{G}]$ 

Z is  $\mathcal{G}$ -measurable because  $Z_i$  are  $\mathcal{G}$ -measurable.

$$\underbrace{\mathbb{E}[Z1_G]}_{=\mathbb{E}[X_11_G]+\mathbb{E}[X_21_G]}\underbrace{(X_1+X_2)1_G}_{=\mathbb{E}[X_11_G]+\mathbb{E}[X_21_G]} \quad \forall G \in \mathcal{G}$$

$$(1.2)$$

(b) Define  $Z = V\mathbb{E}[X \mid \mathcal{G}]$ . To show  $Z = \mathbb{E}[VX \mid \mathcal{G}]$ , need to show Z, V, and  $\mathbb{E}[X \mid \mathcal{G}]$  are  $\mathcal{G}$ -measurable.

Z is  $\mathcal{G}$ -measurable by Lemma applied to  $V1_G$ . TODO: Check

$$\mathbb{E}[\mathbb{E}[X \mid \mathcal{G}]] \underbrace{V1_G}_{\mathcal{G}\text{-meas}} = \mathbb{E}[X \underbrace{V1_G}_{\mathcal{G}\text{-meas}}] \quad \forall G \in \mathcal{G}$$
(1.3)

- (c) Exercise.
- (d) Exercise.
- (e) Exercise.
- (f)  $G = \Omega$  in def.
- (g) By definition.

 $\mathcal{G}$  trivial  $\Longrightarrow \mathbb{E}[X \mid \mathcal{G}]$  constant  $\Longrightarrow \mathbb{E}[X \mid \mathcal{G}] = \mathbb{E}X$ 

(h) Write  $Z = \mathbb{E}[X \mid \mathcal{G}]$ . Need to check  $\mathbb{E}[Z1_G] = \mathbb{E}[\mathbb{E}[X \mid \mathcal{H}]1_G]$ . But LHS  $= \mathbb{E}[X1_G]$  by definition of Z, and RHS  $= \mathbb{E}[X1_G]$  by definition of  $\mathbb{E}[X \mid H]$  and  $G \in \mathcal{G} \implies G \in \mathcal{H}$ .

( $L^2$  setting): Now assume  $\mathbb{E}X^2 < \infty$ .

- $X \mapsto \mathbb{E}[X \mid \mathcal{G}]$  is the orthogonal projection in Hilbert space
- Cauchy-Schwarz  $\mathbb{E}|VX| \leq \sqrt{(\mathbb{E}X)^2(\mathbb{E}V)^2} < \infty$

From Lemma

$$\mathbb{E}[(X - \mathbb{E}[X \mid \mathcal{G}]) \mid V] = 0 \tag{1.4}$$

for V  $\mathcal{G}$ -measurable and  $\mathbb{E}V^2 < \infty$ . This gives

**Lemma 1.2.**  $X - \mathbb{E}[X \mid \mathcal{G}]$  and V are orthogonal  $\forall V$   $\mathcal{G}$ -measurable.

Recall  $Var(X) = \mathbb{E}[X - \mathbb{E}[X]]^2$ .

**Definition 1.3.** The conditional variance

$$Var(X \mid \mathcal{G}) = \mathbb{E}[(X - \mathbb{E}[X \mid \mathcal{G}])^2 \mid \mathcal{G}]$$
(1.5)

**Lemma 1.4** (Bias-variance decomposition). *If* Y *is* G-*measurable*,  $\mathbb{E}Y^2 < \infty$ 

$$\mathbb{E}[(X - Y)^2 \mid \mathcal{G}] = Var(X \mid \mathcal{G}) + (\mathbb{E}[X \mid \mathcal{G}] - Y)^2$$
(1.6)

Proof.

$$\mathbb{E}[(X-Y)^2 \mid \mathcal{G}] = \mathbb{E}[X^2 - 2XY + Y^2 \mid \mathcal{G}]$$
(1.7)

$$= \mathbb{E}[X^2 \mid \mathcal{G}] - 2Y \mathbb{E}[X \mid \mathcal{G}] + Y^2 \tag{1.8}$$

$$= (\mathbb{E}[X^2 \mid \mathcal{G}] - \mathbb{E}[X \mid \mathcal{G}]^2) + (\mathbb{E}[X \mid \mathcal{G}]^2 - 2Y\mathbb{E}[X \mid \mathcal{G}] + Y^2)$$
(1.9)

$$= \operatorname{Var}(X \mid \mathcal{G}) + (\mathbb{E}[X \mid \mathcal{G}] - Y)^{2}$$
(1.10)

**Lemma 1.5.**  $Var(X) = \mathbb{E}Var(X \mid \mathcal{G}) + Var\mathbb{E}[X \mid \mathcal{G}]$ 

*Proof.* Replace X by X – changes no term, so wlog assume  $\mathbb{E}X = 0$ .

$$Var(X) = \mathbb{E}[X^2] = \mathbb{E}[\mathbb{E}[X^2 \mid \mathcal{G}]]$$
(1.11)

$$\mathbb{E}[X^2 \mid \mathcal{G}] = \mathbb{E}\left[\left(\underbrace{(X - \mathbb{E}[X \mid \mathcal{G}])}_{\rightarrow a} + \underbrace{\mathbb{E}[X \mid \mathcal{G}]}_{\rightarrow b}\right)^2 \mid \mathcal{G}\right], \qquad \mathbb{E}[ab \mid \mathcal{G}] = 0 \qquad (1.12)$$

$$= \mathbb{E}[a^2 \mid \mathcal{G}] + b^2 \tag{1.13}$$

$$= \operatorname{Var}(X \mid \mathcal{G}) + (\mathbb{E}[X \mid \mathcal{G}])^{2}, \qquad \mathbb{E}[\mathbb{E}[X \mid \mathcal{G}]] = \mathbb{E}X = 0 \tag{1.14}$$

$$Var(X) = \mathbb{E}[Var(X \mid \mathcal{G}) + (\mathbb{E}[X \mid \mathcal{G}])^{2}]$$
(1.15)

$$= \mathbb{E} \operatorname{Var}(X \mid \mathcal{G}) + \underbrace{\mathbb{E}[\mathbb{E}[X \mid \mathcal{G}] - 0]^{2}}_{=\operatorname{Var}\mathbb{E}[X \mid \mathcal{G}]}$$
(1.16)

**Lemma 1.6** (Connection with independence). A *S*-valued *RV X* is independent of  $\mathcal{G} \iff \mathbb{E}[h(X) \mid \mathcal{G}] = \mathbb{E}h(X) \; \forall \; bounded \; measurable \; h : S \to \mathbb{R}.$ 

*Proof.* ⇒. NTS  $\mathbb{E}[\mathbb{E}h(x)1_G] = \mathbb{E}[h(X)1_G] \ \forall G \in \mathcal{G}$ . But  $\mathbb{E}h(X)$  is a consstant so LHS  $= (\mathbb{E}h(X))(\mathbb{E}1_G)$  and by independence RHS  $= (\mathbb{E}h(X))(\mathbb{E}1_G)$ 

 $\Leftarrow$ . Take  $h = 1_B$  for  $B \subset S$ . From the same argument

$$\mathbb{E}[h(X)1_G] = \mathbb{E}[h(x)]\mathbb{E}[1_G] \tag{1.17}$$

$$= P(X \in B, G) = P(X \in B)P(G)$$
 (1.18)

Holds  $\forall B, G \implies X$  and  $\mathcal{G}$  independent.

## 2 Background to conditional independence

Recall

**Definition 2.1.** X, Y independent  $\iff \mathbb{E}(h_1(X)h_2(Y)) = (\mathbb{E}h_1(X))(\mathbb{E}h_2(Y))$  for all bounded meas.  $h_1, h_2$ 

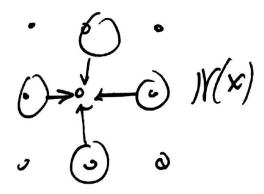
**Example 2.2. Bayes**  $(X_i)$  conditionally independent given  $\Theta$ 

- (i) Random  $\Theta$ , values in  $\{PMs \text{ on } \mathbb{R}\} = \mathcal{P}(\mathbb{R})$
- (ii) Conditional on  $\Theta = \theta \in \mathcal{P}(\mathbb{R})$  take  $X_1, X_2, X_3, \cdots$  IID $(\theta)$ .

**Simple Markov property for**  $(X_n, n \ge 0)$  Past  $X_{0:(n-1)}$  and future  $X_{n+1}$  conditionally independent given present  $X_n$ .

$$P(X_{n+1} = x_{n+1} \mid X_n = x_n, X_{n-1} = x_{n-1}, \dots, X_0 = x_0) = P(X_{n+1} = x_{n+1} \mid X_n = x_n)$$
(2.1)

**Locally dependent** : Given  $(W_{\tilde{x}}, \tilde{x} = (x_1, x_2) \in \mathbb{Z}^2)$ .



**Idea**:  $W_{\tilde{x}}$  depends only on  $W_{\tilde{y}}: \tilde{y} \in N(\tilde{x})$  and not on the other  $W_s$ .

Formally: TODO: Conditionally indep given ...