

```
#include <Wire.h>

#include <LiquidCrystal_I2C.h>

#include <Servo.h>


LiquidCrystal_I2C lcd(0x27, 16, 2); //Change the HEX address if needed

Servo myservo1;


const int IR1 = 2;

const int IR2 = 4;

int Slot = 4; //Enter Total number of parking Slots

int flag1 = 0;

int flag2 = 0;


void setup() {

  lcd.init();

  lcd.backlight();

  Serial.begin(9600);

  pinMode(IR1, INPUT);

  pinMode(IR2, INPUT);


  lcd.clear();

  myservo1.attach(3);

  myservo1.write(100);


  Serial.println("Arduino Parking System");

  lcd.setCursor(0, 0);

  lcd.print("Arduino");

  lcd.setCursor(0, 1);

  lcd.print("Parking System");
```

```
    delay(2000);  
    lcd.clear();  
}
```

```
void loop() {  
    if (digitalRead(IR1) == LOW && flag1 == 0) {  
        if (Slot > 0) {  
            flag1 = 1;  
            if (flag2 == 0) {  
                myservo1.write(0);  
                Slot = Slot - 1;  
            }  
        } else {  
            lcd.setCursor(0, 0);  
            lcd.print("SORRY :(");  
            lcd.setCursor(0, 1);  
            lcd.print("Parking Full");  
            delay(500);  
            lcd.clear();  
        }  
    }  
}
```

```
if (digitalRead(IR2) == LOW && flag2 == 0) {  
    flag2 = 1;  
    if (flag1 == 0) {  
        myservo1.write(0);  
        Slot = Slot + 1;  
    }  
}
```

```
}
```

```
if (flag1 == 1 && flag2 == 1) {
```

```
    delay(2000);
```

```
    myservo1.write(100);
```

```
    flag1 = 0;
```

```
    flag2 = 0;
```

```
}
```

```
lcd.setCursor(0, 0);
```

```
lcd.print("WELCOME!");
```

```
lcd.setCursor(0, 1);
```

```
lcd.print("Slot Left: ");
```

```
lcd.print(Slot);
```

```
}
```