ADJOINT OF A SQUARE MATRIX

Let the determinant of the square matrix A be |A|.

If
$$A = \begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix}$$
, Than $|A| = \begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix}$.

The matrix formed by the co-factors of the elements in

where
$$A_1 = \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} = b_2 c_3 - b_3 c_2$$
, $A_2 = -\begin{vmatrix} b_1 & b_3 \\ c_1 & c_2 \end{vmatrix} = -b_1 c_3 + b_3 c_1$
 $A_3 = \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix} = b_1 c_2 - b_2 c_1$, $B_1 = -\begin{vmatrix} a_2 & a_3 \\ c_2 & c_3 \end{vmatrix} = -a_2 c_3 + a_3 c_2$
 $B_2 = \begin{vmatrix} a_1 & a_3 \\ c_1 & c_3 \end{vmatrix} = a_1 c_3 - a_3 c_1$, $B_3 = -\begin{vmatrix} a_1 & a_2 \\ c_1 & c_2 \end{vmatrix} = -a_1 c_2 + a_2 c_1$
 $C_1 = \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} = a_2 b_3 - a_3 b_2$, $C_2 = -\begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} = -a_1 b_3 + a_3 b_1$
 $C_3 = \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} = a_1 b_2 - a_2 b_1$

Then the transpose of the matrix of co-factors

$$\begin{bmatrix} A_1 & B_1 & C_1 \\ A_2 & B_2 & C_2 \\ A_3 & B_3 & C_3 \end{bmatrix}^{\mathsf{T}} \quad \text{is called the adjoint of the}$$

$$= \mathsf{matrix} \; A \; \mathsf{and} \; \mathsf{is} \; \mathsf{written} \; \mathsf{as} \; \mathsf{adj} \; A.$$

Ex. Find the adjoint of the matrix
$$\begin{bmatrix} 1 & -1 & 1 \\ 2 & 1 & -3 \\ 1 & 1 & 1 \end{bmatrix}$$

PROPERTY OF ADJOINT MATRIX

(1) $A.adj(A) = adj(A).A = |A|.I_n$ where, A is a square matrix, I is an identity matrix of same order.

(2) if A is invertible square matrix
$$|adj(A)| = |A|^{n-1}$$

(3) if A is invertible square matrix

$$adj(adj(A)) = |A|^{n-2} \cdot \underline{A}$$

if
$$P = \begin{bmatrix} 1 & \alpha & 3 \\ 1 & 3 & 3 \\ 2 & 4 & 4 \end{bmatrix}$$
 is adjoint of 3×3 matrix with $|A| = 4$ then the value of α is

a. 2
b. 11
c. 13
d. $1/3$

$$(4) adj(AB) = adj(B). adj(A)$$

$$(5)(adj(A))^{T} = adj(A^{T})$$

$$\mathbf{(6)}adj(kA) = k^{n-1}adj(A)$$

INVERSE OF A MATRIX

If A and B are two square matrices of the same order, such that AB = BA = I (I = unit matrix) then B is called the inverse of A i.e. $B = A^{-1}$ and A is the inverse of B.

To find the inverse of the Matrix A we use

$$A^{-1} = \frac{1}{|A|} (Adj(A)), \qquad if |A| \neq 0$$

Properties of inverse of the matrix

- 1. Inverse of the matrix is unique
- 2. $(AB)^{-1} = B^{-1}A^{-1}$
- 3. If A is an invertible square matrix; Then $(A)^T$ is also invertible and $(A^T)^{-1} = (A^{-1})^T$
- 4. The inverse of an invertible symmetric matrix is a symmetric matrix.

5.
$$|A^{-1}| = |A|^{-1}$$
 i. e. $|A^{-1}| = \frac{1}{|A|}$

Solution of $n \times n$ linear system of equation

Consider the system of n equations in n unknowns

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n.$$

In matrix form we can write this system as Ax = b

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & & & & \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

Note:

- 1. A is the coefficient matrix, b the right hand side, and x is the solution vector.
- 2. If b not equal to zero system is called non-homogeneous.
- 3. If b is zero its call homogeneous.
- 4. The system of equations is called consistent if it has at least one solution.

otherwise the system is inconsistent.

Homogeneous system of equations:

Consider the homogeneous system of equations Ax = 0Trivial solution x = 0 is always a solution of this system.

If A is non singular, then $x = A^{-1}0 = 0$ is the solution.

Thus Ax = 0 is the always consistent.

We conclude that non-trivial solution for Ax = 0 exist if and only if A is singular, in this case this system has infinite solutions.

Ex. Solve the system of the equation using matrix method x-y+z=0, 2x+y-3z=0, x+y+z=0

Ex. If the system of the equations x - ky - z = 0, kx - y - z = 0, x + y - z = 0 has non-zero solution then values of K are

- a. -1,2
- b. 0,1
- c. 1,1
- d. -1,1

Ex. If the system of the equations kx + y + z = 0, -x + ky + z = 0, -x - y + kz = 0 has non-zero solution then value of K is

- a. 0
- b. 1
- c. -1
- d. 2

Solution of Non-homogeneous system of equations

The non-homogeneous system of equations Ax = b can be solved by the following methods

- (i) Matrix method
- (ii) Cramer's Rule

(i) Matrix method:

Let A be non-singular, then pre-multiplying Ax = b by

$$A^{-1}$$
, we obtain $x = A^{-1}b$

Ex. Solve the system of the equation using matrix method
$$x-y+z=4$$
, $2x+y-3z=0$, $x+y+z=2$

Ex. Solve the system of the equation using matrix method -x + y + 2z = 2, 3x - y + z = 3, -x + 3y + 4z = 6

Ex. Solve the system of the equation using matrix method 2x-z=1, 5x+y=7, y+3z=5

(ii) Cramer's Rule:

Let A be a non-singular matrix then by Cramer's rule solution of Ax=b is given by

$$x_i = \frac{|A_i|}{|A|}, \qquad i = 1, 2, 3, ..., n$$

Where $|A_i|$ is the determinant of the matrix $|A_i|$ obtained by replacing the ith column of A by the right hand side column vector b.

Ex. Solve the system of the equation using
$$x - y + z = 4$$
, $2x + y - 3z = 0$, $x + y + z = 2$

Note: We have the following cases in this method Case 1: when $|A| \neq 0$, the system is consistent and the unique solution is obtained by using the above method.

Case 2: When |A| = 0, and one or more of $|A_i|$, i = 1,2,3,...,n

are not zero then the system of the equations has no solution that is the system is inconsistent.

Case 3: When |A| = 0, and all $|A_i| = 0$, i = 1,2,3,...,n, then the system of equations is consistent and has infinite number of solutions. The system of equations has at least a one-parameter family of solutions.

Ex. Solve the system of the equation using 4x + 9y + 3z = 6, 2x + 3y + z = 2, 2x + 6y + 2z = 7

Ex. Solve the system of the equation using matrix method

$$x - y + 3z = 3$$
, $2x + 3y + z = 2$, $3x + 2y + 4z = 5$

Ex. The system of linear equations $x + y + z = 2, 2x + 3y + 2z = 5, 2x + 3y + (a^2 - 1)z = a + 1$

- a. Is inconsistent for a=4
- b. Has unique solution for $a = \sqrt{3}$
- c. Has infinite solution for a=4

- b. Has unique solution for $a = \sqrt{3}$
- c. Has infinite solution for a=4
- d. Inconsistent for $a = \sqrt{3}$

Ex.

If the system of linear equation x-4y+7z = g, 3y-5z = h, -2x+5y-9z = k is consistent, then

- \mathbf{A} g+h+k=0
- B 2g+h+k=0
- \mathbf{C} g+h+2k=0
- $\mathbf{D} \qquad \mathbf{g+2h+2k=0}$

(iii)Gauss elimination Method for Non-homogeneou System

Let we have the non-homogeneous system Ax=b

where

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & & & & \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}, \ \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}, \ \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}.$$

Now we write the augmented matrix of order $m \times (n+1)$

$$\mathbf{(A \mid b)} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & b_2 \\ \vdots & & & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & b_m \end{bmatrix}$$

Now we can reduce this matrix in to row echelon form using elementary operations

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$$(\mathbf{A} \mid \mathbf{b}) = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1r} & \cdots & a_{1n} & b_1 \\ 0 & \overline{a}_{22} & \cdots & \overline{a}_{2r} & \cdots & \overline{a}_{2n} & \overline{b}_2 \\ \vdots & & & & \vdots \\ 0 & 0 & \cdots & a_{rr}^* & \cdots & a_{rn}^* & b_r^* \\ 0 & 0 & \cdots & 0 & \cdots & 0 & b_{r+1}^* \\ \vdots & & & & & \vdots \\ 0 & 0 & \cdots & 0 & \cdots & 0 & b_m^* \end{bmatrix}.$$

Ex. Solve following system using gauss elimination

(i)
$$\begin{bmatrix} 2 & 1 & -1 \\ 1 & -1 & 2 \\ -1 & 2 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \\ -2 \\ 2 \end{bmatrix},$$

Note:

- 1. Let r < m and one or more elements $b_{r+1}^*, b_{r+2}^*, \dots, b_m^*$ are not zero. Then $rank(A) \neq rank(A|b)$ and the system of equation has no solution .
- 2. Let $m \ge n$ and r = n (the number of columns in A) and $b^*_{+1}, b^*_{+2}, ..., b^*_n$ are all zero. In this case rank(A) = rank(A|b) = n and the system of equations has unique solution.
- 3. Let r < n and $b_{r+1}^*, b_{r+2}^*, \dots, b_m^*$ are all zero. In this case x_1, x_2, \dots, x_r can be determined in term of remaining (n-r) unknowns $x_{r+1}, x_{r+2}, \dots, x_n$.

(ii)
$$\begin{bmatrix} 2 & 0 & 1 \\ 1 & -1 & 1 \\ 4 & -2 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 3 \end{bmatrix},$$

(iii)
$$\begin{bmatrix} 1 & -1 & 1 \\ 2 & 1 & -1 \\ 5 & -2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 5 \end{bmatrix}.$$

(iv) Gauss-Jordan method

Ex. Using gauss-Jordan method solve the system of equations Ax=b, where

$$[A \mid b] \xrightarrow{\text{Elementary}} [I \mid c]$$

$$\mathbf{A} = \begin{bmatrix} 1 & -1 & 1 \\ 2 & 1 & -3 \\ 1 & 1 & 1 \end{bmatrix}, \quad \text{and} \quad \mathbf{b} = \begin{bmatrix} 0 \\ 4 \\ 1 \end{bmatrix}.$$

$$[A \mid b] = \begin{bmatrix} 1 & -1 & 1 & 0 \\ 2 & 1 & -3 & 4 \\ 1 & 1 & 1 & 1 \end{bmatrix} R_2 - 2R_1 \approx \begin{bmatrix} 1 & -1 & 1 & 0 \\ 0 & 3 & -5 & 4 \\ 0 & 2 & 0 & 1 \end{bmatrix} R_2/3$$

$$\approx \begin{bmatrix} 1 & -1 & 1 & 0 \\ 0 & 1 & -5/3 & 4/3 \\ 0 & 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} R_1 + R_2 \\ R_3 - 2R_2 \end{bmatrix}$$

$$\approx \begin{bmatrix} 1 & 0 & -2/3 & 4/3 \\ 0 & 1 & -5/3 & 4/3 \\ 0 & 0 & 10/3 & -5/3 \end{bmatrix} R_3/(10/3)$$

$$\approx \begin{bmatrix} 1 & 0 & -2/3 & 4/3 \\ 0 & 1 & -5/3 & 4/3 \\ 0 & 0 & 1 & -1/2 \end{bmatrix} R_1 + 2R_3/3 \approx \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1/2 \\ 0 & 0 & 1 & -1/2 \end{bmatrix}.$$

$$\mathbf{x} = [1 \quad 1/2 \quad -1/2]^T$$
.

Ex. Using Gauss-Jordan method find the inverse of the matrix

$$\mathbf{A} = \begin{bmatrix} -1 & 1 & 2 \\ 3 & -1 & 1 \\ -1 & 3 & 4 \end{bmatrix}$$

$$[A \mid I] \xrightarrow{\text{Elementary}} [I \mid A^{-1}]$$
row operations

