

# Written Assignment 1

Niraj Venkat

## Exercise 1

(a)

$$\begin{aligned}
 v \wedge w &= (e_1 + 2e_2) \wedge (e_2 + 2e_3) && \text{(Distributivity over addition)} \\
 &= (e_1 \wedge e_2) + 2(e_1 \wedge e_3) + \cancel{2(e_2 \wedge e_2)}^0 + 4(e_2 \wedge e_3) \\
 &= (e_1 \wedge e_2) + 2(e_1 \wedge e_3) + 4(e_2 \wedge e_3)
 \end{aligned}$$

(b)

$$\begin{aligned}
 w \wedge v &= -(v \wedge w) && \text{(Antisymmetric property)} \\
 &= -(e_1 \wedge e_2) - 2(e_1 \wedge e_3) - 4(e_2 \wedge e_3)
 \end{aligned}$$

(c)

$$v \wedge v = 0$$

## Exercise 2

The result is a zero 3-vector.

$$\begin{aligned}
 \alpha_0 \wedge \alpha_1 \wedge \alpha_2 &= (e_1 + e_2) \wedge (e_1 + 2e_2) \wedge (e_1 + 4e_2) \\
 &= ((e_1 \wedge e_1) + 2(e_1 \wedge e_2) + (e_2 \wedge e_1) + 2(e_2 \wedge e_2)) \wedge (e_1 + 4e_2) \\
 &= (\cancel{(e_1 \wedge e_1)}^0 + 2(e_1 \wedge e_2) - (e_1 \wedge e_2) + \cancel{2(e_2 \wedge e_2)}^0) \wedge (e_1 + 4e_2) \\
 &= e_1 \wedge e_2 \wedge (e_1 + 4e_2) \\
 &= (e_1 \wedge e_2 \wedge e_1) + 4(e_1 \wedge e_2 \wedge e_2) && \text{(Antisymmetric property)} \\
 &= 0
 \end{aligned}$$

## Exercise 3

Starting with 1-vectors  $u, v \in \mathbb{R}^3$ :

$$u \wedge v = -2(e_1 \wedge e_2) + 2(e_2 \wedge e_3)$$

which is a 2-vector in  $\mathbb{R}^3$ .

$$u \times v = 2e_1 - 2e_3$$

which is a 1-vector in  $\mathbb{R}^3$ .

Exercise 4

(a)

$$\begin{aligned}
 u \wedge v + v \wedge w &= u \wedge v - w \wedge v = (u - w) \wedge v && \text{(Distributivity)} \\
 &= (e_1 + e_2 - e_3 - 3e_1 - e_2) \wedge (e_1 - e_2 + 2e_3) \\
 &= 2(e_1 \wedge e_2) - 3(e_1 \wedge e_3) - (e_2 \wedge e_3)
 \end{aligned}$$

(b)

$$\begin{aligned}
 u \wedge v \wedge w &= (e_1 + e_2 - e_3) \wedge (e_1 - e_2 + 2e_3) \wedge (3e_1 + e_2) && \text{(Skipping zero terms)} \\
 &= [-2(e_1 \wedge e_2) + 3(e_1 \wedge e_3) + 3(e_2 \wedge e_3)] \wedge (3e_1 + e_2) \\
 &= 3(e_2 \wedge e_3 \wedge e_1) + 3(e_1 \wedge e_3 \wedge e_2) \\
 &= 3(e_2 \wedge e_3 \wedge e_1) - 3(e_2 \wedge e_3 \wedge e_1) \\
 &= 0
 \end{aligned}$$

Exercise 5

(a)  $\star e_1 = e_2$

(b)  $\star e_1 = e_2 \wedge e_3$

(c) Hodge star of  $k$ -vector is an  $(n - k)$ -vector.

In  $\mathbb{R}^2$ :  $n = 2, k = 1$  so  $\star e_1$  is a 1-vector.

In  $\mathbb{R}^3$ :  $n = 3, k = 1$  so  $\star e_1$  is a 2-vector.

Exercise 6

(a)

$$\begin{aligned}
 \star \alpha &= \star(e_1 + e_2 + e_3) && \text{(Distributivity over addition)} \\
 &= \star e_1 + \star e_2 + \star e_3 \\
 &= (e_2 \wedge e_3) + (e_3 \wedge e_1) + (e_1 \wedge e_2)
 \end{aligned}$$

$$\begin{aligned}
 \star \beta &= \star(e_1 - e_2 + 2e_3) \\
 &= \star e_1 - \star e_2 + 2 \star e_3 \\
 &= (e_2 \wedge e_3) - (e_3 \wedge e_1) + 2(e_1 \wedge e_2)
 \end{aligned}$$

(b)

$$\star(\alpha \wedge \beta) = 3e_1 - e_2 - 2e_3$$

(c)

$$\star \alpha \wedge \star \beta = 0$$

(d) Hodge star operator does not distribute over the wedge product.

For (b) we take the Hodge star of a 2-vector resulting in a 1-vector.

For (c) we take the wedge product of two 2-vectors after the Hodge star resulting in a 4-vector. This 4-vector is zero because of cancellation rules.

- (a) We know that in  $\mathbb{R}^2$ , the Hodge star can be geometrically interpreted as a  $90^\circ$  rotation. So  $\star(\star w)$  is a  $180^\circ$  rotation that reverses the vector.
- (b) Let  $w = a^1 e_1 + a^2 e_2 + a^3 e_3$  in  $\mathbb{R}^3$ . Following the rules of exterior algebra:

$$\begin{aligned}
 \star w &= \star(a^1 e_1 + a^2 e_2 + a^3 e_3) && \text{(Distributivity over addition)} \\
 &= a^1 \star e_1 + a^2 \star e_2 + a^3 \star e_3 \\
 &= a^1(e_2 \wedge e_3) + a^2(e_3 \wedge e_1) + a^3(e_1 \wedge e_2) \\
 \star(\star w) &= a^1 \star(e_2 \wedge e_3) + a^2 \star(e_3 \wedge e_1) + a^3 \star(e_1 \wedge e_2) \\
 &= a^1 e_1 + a^2 e_2 + a^3 e_3 = w
 \end{aligned}$$

- (c) In general if  $w = a^1 e_1 + a^2 e_2 + a^3 e_3 + \cdots + a^n e_n \in \mathbb{R}^n$ , where  $n \geq 2$ ,  $w$  is a 1-vector and  $\{e_1, e_2, \dots, e_n\}$  forms an orthonormal basis for  $\mathbb{R}^n$ , we have:

$$\begin{aligned}
 \star w &= \star(a^1 e_1 + a^2 e_2 + a^3 e_3 + \cdots + a^n e_n) && \text{because } \det(w \wedge \star w) = 1 \\
 &= a^1(e_2 \wedge e_3 \wedge \cdots \wedge e_n) + a^2(e_3 \wedge e_4 \wedge \cdots \wedge e_{n-1} \wedge e_n \wedge e_1) + \cdots + a^n(e_1 \wedge e_2 \wedge \cdots \wedge e_{n-1}) \\
 \star \star w &= a^1 \star(e_2 \wedge e_3 \wedge \cdots \wedge e_n) + a^2 \star(e_3 \wedge e_4 \wedge \cdots \wedge e_{n-1} \wedge e_n \wedge e_1) + \cdots + a^n \star(e_1 \wedge e_2 \wedge \cdots \wedge e_{n-1}) \\
 &= (-1)^{n-1}(a^1 e_1 + a^2 e_2 + a^3 e_3 + \cdots + a^n e_n) && \text{because } \det(\star w \wedge \star \star w) = 1 \\
 &= (-1)^{n-1} w
 \end{aligned}$$

- (d) Proof follows the course notes by Zuoqin Wang.

Let  $w = e_1 \wedge e_2 \wedge \cdots \wedge e_k$  be a  $k$ -vector in  $\mathbb{R}^n$ , where  $\{e_1, e_2, \dots, e_n\}$  forms an orthonormal basis like before.

Using the notes, we can prove that the wedge product of an arbitrary  $k$ -form with an arbitrary  $(n-k)$ -form should look like:

$$w^{i_1} \wedge \cdots \wedge w^{i_k} \wedge w^{j_1} \wedge \cdots \wedge w^{j_{n-k}} = (-1)^{i_1 + \cdots + i_k + 1 + \cdots + k} w^1 \wedge \cdots \wedge w^n$$

We still get an  $n$ -form, but a sign that is due to the anti-symmetry properties of the wedge product. The above is proved using the rule  $\det(w \wedge \star w) = 1$  along with a subtle rule that depends on the dual inner product induced by the Reimannian metric  $g$  on the dual space of the tangent space  $T_p^* \mathcal{M}$ .

So we apply Hodge star twice:

$$\begin{aligned}
 w &= w^{i_1} \wedge \cdots \wedge w^{i_k} \\
 \star w &= (-1)^{i_1 + \cdots + i_k + 1 + \cdots + k} w^{j_1} \wedge \cdots \wedge w^{j_{n-k}} \\
 \star \star w &= (-1)^{i_1 + \cdots + i_k + 1 + \cdots + k} (-1)^{j_1 + \cdots + j_{n-k} + 1 + \cdots + n-k} w \\
 &= (-1)^{k(n-k)} w
 \end{aligned}$$

Exercise 8

(a)

$$\begin{aligned}
 \alpha \wedge (\beta + \star \gamma) &= 2e_3 \wedge ((e_1 - e_2) + \star(e_2 \wedge e_3)) \\
 &= 2e_3 \wedge ((e_1 - e_2) + e_1) \\
 &= 2e_3 \wedge (2e_1 - e_2) \\
 &= 4e_3 \wedge e_1 + 2e_2 \wedge e_3
 \end{aligned}$$

(b)

$$\begin{aligned}
 \alpha \wedge \beta &= 2e_3 \wedge (e_1 - e_2) \\
 &= 2e_3 \wedge e_1 - 2e_3 \wedge e_2 \\
 &= 2e_3 \wedge e_1 + 2e_2 \wedge e_3 \\
 \star(\alpha \wedge \beta) &= 2\star(e_3 \wedge e_1) + 2\star(e_2 \wedge e_3) \\
 &= 2e_2 + 2e_1 \\
 \gamma \wedge \star(\alpha \wedge \beta) &= e_2 \wedge e_3 \wedge (2e_2 + 2e_1) \\
 &= 2(e_2 \wedge e_3 \wedge e_2) + 2(e_2 \wedge e_3 \wedge e_1) \\
 &= 2(e_2 \wedge e_3 \wedge e_1) \\
 \star(\gamma \wedge \star(\alpha \wedge \beta)) &= 2\star(e_2 \wedge e_3 \wedge e_1) \\
 &= 2(1) = 2
 \end{aligned}$$

even permutation,  $\det(w \wedge \star w) = 1$

Exercise 9

(a)

$$\alpha = 2z \, dx + 3x^2 \, dy + 5 \cos(y) \, dz$$

(b) We use the fact that product of the basis 1-form and basis 1-vector and is the Kronecker delta:  $e^i e_j = \delta_i^j$   
We show the terms where it evaluates to 1.

$$\begin{aligned}
 \alpha(U) &= 2z(3) \overset{1}{dx} e_1 + 3x^2(2) \overset{1}{dy} e_2 + 5 \cos(y) \overset{1}{dz} e_1 \\
 &= 6z + 6x^2 + 5 \cos(y) \\
 \alpha(U)|_{p=(1,2,3)} &= 6(3) + 6(1) + 5 \cos(2) = 24 + 5 \cos(2)
 \end{aligned}$$

(c)

$$-\alpha = -2z \, dx - 3x^2 \, dy - 5 \cos(y) \, dz$$

Exercise 10

(a)  $\alpha(U)$  is a scalar field or  $\mathbb{R}$ -valued 0-form.

It is a function that takes no input and outputs a scalar at every point in  $\mathbb{R}^3$ .

(b)

$$\begin{aligned}
 \alpha(U) &= 2x \\
 \alpha(V) &= x^2 y \\
 \beta(U) &= 1 + x \\
 \beta(V) &= 4
 \end{aligned}$$

(c)

$$\begin{aligned}
(\alpha \wedge \beta)(U, V) &= \alpha(U)\beta(V) - \beta(U)\alpha(V) \\
&= (2x)(4) - (1+x)(x^2y) \\
&= -x^3y - x^2y + 8x
\end{aligned}$$

(d)

$$\begin{aligned}
(\alpha \wedge \beta)(V, U) &= -(\alpha \wedge \beta)(U, V) \\
&= x^3y + x^2y - 8x
\end{aligned}$$

Exercise 11

We will use the equivalent of Leibniz/product rule for exterior derivative over a wedge product. In particular if  $\alpha$  is a  $k$ -form then  $d$  obeys the rule:

$$d(\alpha \wedge \beta) = d\alpha \wedge \beta + (-1)^k \alpha \wedge d\beta$$

(a)

$$\begin{aligned}
(\star[d(e^y dx + \sin(z)dz)]) \wedge dz &= (\star[d(e^y dx) + d(\sin(z)dz)]) \wedge dz \\
&= (\star[e^y dy \wedge dx] + \star[\cos(z)dz \wedge dz]) \wedge dz \\
&\quad \text{because } d(e^y) = e^y dy, d(\sin(z)) = \cos(z)dz \text{ and } d \circ d = 0 \\
&= e^y (dz \wedge dx \wedge dz) \\
&= 0
\end{aligned}$$

(b) Breaking it down into steps:

$$\begin{aligned}
\star(d(dx \wedge z^2 dy)) &= \star((-1)dz \wedge 2z(dz \wedge dy)) \\
&= \star(2z dx \wedge dy \wedge dz) = 2z \\
\star(xyz(dx \wedge dz \wedge dy)) &= \star(-xyz(dx \wedge dy \wedge dz)) \\
&= -xyz \\
\therefore d[\star(d(dx \wedge z^2 dy)) + \star(xyz(dx \wedge dz \wedge dy))] &= d[2z - xyz] \\
&= 2dz - d(xyz) \\
&= 2dz - [dx \wedge (yz) + x \wedge d(yz)] \\
&= 2dz - [yz dx + x(z dy + y dz)] \\
&= -yz dx - xz dy + (2 - xy)dz
\end{aligned}$$

Exercise 12

(a) If  $\alpha$  is a 0-form:

$$\delta(0\text{-form}) = \star d \star (0\text{-form}) = \star d(n\text{-form})$$

The exterior derivative takes  $n$ -forms to  $(n+1)$ -forms. But there are no  $(n+1)$ -forms in  $\mathbb{R}^n$ . So  $\delta(\alpha) = 0$ .

(b) If  $\alpha$  is a  $k$ -form:

$$\begin{aligned}
\delta(k\text{-form}) &= \star d \star (k\text{-form}) \\
&= \star d((n-k)\text{-form}) \\
&= \star((n-k+1)\text{-form}) \\
&= (n-n+k-1)\text{-form} \\
&= (k-1)\text{-form}
\end{aligned}$$

So  $\delta(\alpha)$  is a  $(k-1)$ -form, and  $\delta : \omega^k \rightarrow \omega^{k-1}$  is the map taking us from the space of  $k$ -forms to  $(k-1)$ -forms.

(c)

$$\begin{aligned}
\delta\alpha &= \star d \star \alpha \\
&= \star d \star (e^y dx + (x+y)^2 dy) \\
&= \star d(e^y dy + (x+y)^2 (-dx)) \\
&= \star \cancel{d(e^y dy)}^0 - \star d((x+y)^2 dx) \\
&= \star(-2(x+y)(dx + dy)dx) \\
&= \star(-2(x+y)dy \wedge dx) \\
&= 2(x+y)
\end{aligned}$$

Exercise 13

(a) If  $\alpha$  is a 0-form,  $\delta(\alpha) = 0$ .

(b)

$$\Delta\phi = \frac{\partial^2\phi}{\partial^2x} + \frac{\partial^2\phi}{\partial^2y} = \frac{\partial(y)}{\partial x} + \frac{\partial(x+4y)}{\partial y} = 4$$

(c) Since  $\phi$  is a 0-form, we will discard the second term:

$$\begin{aligned}
\Delta\phi &= (\delta d + d\delta)\phi \\
&= \delta d\phi + \cancel{d\delta\phi}^0 \\
&= \star d \star d(xy + 2y^2) \\
&= \star d \star (ydx + xdy + 4ydy) \\
&= \star d(ydy - xdx - 4ydx) \\
&= \star(\cancel{d(ydy)}^0 - \cancel{d(xdx)}^0 - d(4ydx)) \\
&= \star(-4dy \wedge dx) \\
&= 4
\end{aligned}$$

(d) Wedge product is implicit here ( $ab = a \wedge b$ ):

$$\begin{aligned}
\Delta\alpha &= \star d \star d\alpha + d \star d \star \alpha \\
\star d \star d\alpha &= \star d \star d(xdx + zdy - ydz) \\
&= \star d \star (dzdy - dydz) \\
&= \star d(-dx - dx) \\
&= \star d(-2dx) \\
&= 0 \\
d \star d \star \alpha &= d \star d \star (xdx + zdy - ydz) \\
&= d \star d(xdydz + zdzdx - ydxdy) \\
&= d \star (d(xdydz) + \cancel{d(zdzdx)}^0 - \cancel{d(ydxdy)}^0) \\
&= d \star (dx \wedge dy \wedge dz) \\
&= d(1) \\
&= 0 \\
\therefore \Delta\alpha &= 0
\end{aligned}$$

Exercise 14

- The gradient in one argument (or derivative) gets measured, while the differential (or exterior derivative) performs the measurement. The differential when given a function outputs the derivatives in all possible directions.
- The relationship between gradient, differential and directional derivative gives us another picture:

$$d(d\phi) = d(D_X \phi) = d(\langle \nabla \phi, X \rangle) = 0$$

Measuring this inner product (which is already a measure of the scalar function  $\phi$  along vector field  $X$ ) should not have any result.

- Derivative when composed is similar to velocity, acceleration, etc.  
Exterior derivative when composed is similar to gradient, curl, etc. When composed with the Hodge star, we get something is similar to divergence.  
We want the curl of a gradient to be zero in vector calculus and more generally in  $\mathbb{R}^n$ .
- By Stokes' Theorem:

$$\int_{\Omega} dd\phi = \int_{\partial\Omega} d\phi = \int_{\partial\partial\Omega} \phi$$

This works for any domain  $\Omega$  no matter how small. It would not matter if we shrink the domain  $\Omega$  around any point of interest. But we know that boundary of a boundary is empty:  $\partial\partial\Omega = \emptyset$ .

So,  $dd\phi = 0$  at every point in the domain  $\Omega$ .

Exercise 15

- (a) First compute the edge length  $L$  and unit tangent  $T$ :

$$\begin{aligned} L &= |B - A| = \sqrt{2} \\ T &= \frac{B - A}{L} \\ &= \frac{(1, 1) - (0, 0)}{\sqrt{2}} \\ &= \frac{(1, 1)}{\sqrt{2}} \end{aligned}$$

An arc-length parameterization of the edge is given by:

$$\begin{aligned} p(s) &= A + \frac{s}{L}(B - A), \quad s \in [0, L] \\ &= \left( \frac{s}{\sqrt{2}}, \frac{s}{\sqrt{2}} \right) \end{aligned}$$

The 1-form  $\alpha$  acting on  $T$  results in a scalar function (0-form) parameterized by  $(x, y)$ :

$$\begin{aligned} \alpha(T) &= 2dx + xdy \left( \frac{(1, 1)}{\sqrt{2}} \right) \\ &= \frac{1}{\sqrt{2}}(2 + x) \end{aligned}$$

Our function in arc-length parameterization becomes:  $\alpha(T)_{p(s)} = \frac{s}{2} + \sqrt{2}$

Integrating over the edge AB:

$$\hat{\alpha}(A, B) = \int_0^L \alpha(T)_{p(s)} = \int_0^{\sqrt{2}} \frac{s}{2} + \sqrt{2} = \frac{5}{2}$$

(b) First compute the edge length  $L$  and unit tangent  $T$ :

$$\begin{aligned} L &= |A - B| = \sqrt{2} \\ T &= \frac{A - B}{L} \\ &= \frac{(0,0) - (1,1)}{\sqrt{2}} \\ &= \frac{(-1,-1)}{\sqrt{2}} \end{aligned}$$

An arc-length parameterization of the edge is given by:

$$\begin{aligned} p(s) &= A + \frac{s}{L}(A - B), \quad s \in [0, L] \\ &= \left(1 - \frac{s}{\sqrt{2}}, 1 - \frac{s}{\sqrt{2}}\right) \end{aligned}$$

The 1-form  $\alpha$  acting on  $T$  results in a scalar function (0-form) parameterized by  $(x, y)$ :

$$\begin{aligned} \alpha(T) &= 2dx + xdy\left(\frac{(-1,-1)}{\sqrt{2}}\right) \\ &= \frac{1}{\sqrt{2}}(-2 - x) \end{aligned}$$

Our function in arc-length parameterization becomes:  $\alpha(T)_{p(s)} = \frac{1}{2}(s - 3\sqrt{2})$

Integrating over the edge BA:

$$\hat{\alpha}(B, A) = \int_0^L \alpha(T)_{p(s)} = \int_0^{\sqrt{2}} \frac{1}{2}(s - 3\sqrt{2}) = -\frac{5}{2}$$

(c)  $\hat{\alpha}(A, B) = -\hat{\alpha}(B, A)$  due to orientation.

Exercise 16

We can prove that the entries of the operator  $d_1 \circ d_0 \in \mathbb{R}^{|F| \times |V|}$  are all zero. This is a topological property that holds true for any triangle mesh.

Columns of  $d_0$  specify incoming/outgoing edges for each vertex.

Rows of  $d_1$  specify edges for each face respecting the relative orientation.

By performing  $d_1 \circ d_0$ , when edges for a face match up with edges for a vertex, we must have at least 2 with opposite relative orientation to cancel out. This works if our triangle mesh is an oriented simplicial 2-manifold, so it must have exactly 2 faces for each edge. These 2 neighboring faces sharing the edge will have opposite relative orientation. So the edges fanning out of a vertex (sorted in say CCW order) will alternate in sign and this causes the cancellation.



Exercise 17

- (a)  $df$  is a 1-form.  
 (b) Domain is the edges, range is the reals.  $df : E \rightarrow \mathbb{R}$   
 (c)

$$\begin{aligned} df(A, B) &= f(B) - f(A) = -3 \\ df(B, C) &= f(C) - f(B) = 1 \\ df(C, D) &= f(D) - f(C) = 3 \\ df(A, D) &= f(D) - f(A) = 1 \\ df(D, B) &= f(B) - f(D) = -4 \end{aligned}$$

- (d)  $d(df) = 0$

Exercise 18

- (a)

$$\begin{aligned} f \wedge_{0,0} h(A) &= f(A)h(A) = -15 \\ f \wedge_{0,0} h(B) &= f(B)h(B) = 0 \\ f \wedge_{0,0} h(C) &= f(C)h(C) = 6 \\ f \wedge_{0,0} h(D) &= f(D)h(D) = 18 \end{aligned}$$

- (b)

$$\begin{aligned} df \wedge_{1,0} h(A, B) &= df(A, B) \frac{h(A) + h(B)}{2} = \frac{9}{2} \\ df \wedge_{1,0} h(B, C) &= df(B, C) \frac{h(B) + h(C)}{2} = 1 \\ df \wedge_{1,0} h(C, D) &= df(C, D) \frac{h(C) + h(D)}{2} = \frac{15}{2} \\ df \wedge_{1,0} h(A, D) &= df(A, D) \frac{h(A) + h(D)}{2} = 0 \\ df \wedge_{1,0} h(D, B) &= df(D, B) \frac{h(D) + h(B)}{2} = -6 \end{aligned}$$

- (c)

$$\begin{aligned} df \wedge_{1,0} h(A, B) &= df(A, B) \frac{h(A) + h(B)}{2} = \frac{9}{2} \\ df \wedge_{1,0} h(B, C) &= df(B, C) \frac{h(B) + h(C)}{2} = 1 \\ df \wedge_{1,0} h(C, D) &= df(C, D) \frac{h(C) + h(D)}{2} = \frac{15}{2} \\ df \wedge_{1,0} h(A, D) &= df(A, D) \frac{h(A) + h(D)}{2} = 0 \\ df \wedge_{1,0} h(D, B) &= df(D, B) \frac{h(D) + h(B)}{2} = -6 \end{aligned}$$

- (d)

$$\begin{aligned} d(df \wedge_{1,0} h)(A, D, B) &= df \wedge_{1,0} h(A, D) + df \wedge_{1,0} h(D, B) - df \wedge_{1,0} h(A, B) = \frac{-3}{2} \\ d(df \wedge_{1,0} h)(B, C, D) &= df \wedge_{1,0} h(B, C) + df \wedge_{1,0} h(C, D) + df \wedge_{1,0} h(D, B) = \frac{5}{2} \\ [d(df \wedge_{1,0} h)] \wedge_{2,0} h(A, D, B) &= \frac{-3}{2} \frac{h(A) + h(D) + h(B)}{3} = 0 \\ [d(df \wedge_{1,0} h)] \wedge_{2,0} h(B, C, D) &= \frac{5}{2} \frac{h(B) + h(C) + h(D)}{3} = \frac{25}{6} \end{aligned}$$

(e) First calculate  $dh$ :

$$\begin{aligned} dh(A, B) &= 3 \\ dh(B, C) &= 2 \\ dh(C, D) &= 1 \\ dh(A, D) &= 6 \\ dh(D, B) &= -3 \end{aligned}$$

$$\begin{aligned} (df) \wedge_{1,1} (dh)(A, D, B) &= \frac{1}{6} [df(A, D)dh(D, B) - df(D, B)dh(A, D) \\ &\quad + df(D, B)dh(B, A) - df(B, A)dh(D, B) \\ &\quad + df(B, A)dh(A, D) - df(A, D)dh(B, A)] \\ &= \frac{21}{2} \\ (df) \wedge_{1,1} (dh)(B, C, D) &= \frac{1}{6} [df(B, C)dh(C, D) - df(C, D)dh(B, C) \\ &\quad + df(C, D)dh(D, B) - df(D, B)dh(C, D) \\ &\quad + df(D, B)dh(B, C) - df(B, C)dh(D, A)] \\ &= -2 \end{aligned}$$

Exercise 19
-------------

(a)

$$\begin{aligned} \hat{g}(A) &= 2 \\ \hat{g}(B) &= 3 \\ \hat{g}(C) &= 0 \\ \hat{g}(D) &= 0 \end{aligned}$$

(b)

$$\begin{aligned} dg &= 2y(x + 2y)dy + y^2(dx + 2dy) \\ &= y^2 dx + (6y^2 + 2xy) dy \end{aligned}$$

(c)

$$\begin{aligned} d\hat{g}(A, B) &= \hat{g}(B) - \hat{g}(A) = 1 \\ d\hat{g}(B, C) &= \hat{g}(C) - \hat{g}(B) = -3 \\ d\hat{g}(C, D) &= \hat{g}(D) - \hat{g}(C) = 0 \\ d\hat{g}(A, D) &= \hat{g}(D) - \hat{g}(A) = -2 \\ d\hat{g}(D, B) &= \hat{g}(B) - \hat{g}(D) = 3 \end{aligned}$$

(d)

$$\begin{aligned} \int_{[A,B]} y^2 dx + (6y^2 + 2xy) dy &= 1 \\ \int_{[B,C]} y^2 dx + (6y^2 + 2xy) dy &= -3 \\ \int_{[C,D]} y^2 dx + (6y^2 + 2xy) dy &= 0 \\ \int_{[A,D]} y^2 dx + (6y^2 + 2xy) dy &= -2 \\ \int_{[D,B]} y^2 dx + (6y^2 + 2xy) dy &= 3 \end{aligned}$$

(e) Stokes' Theorem applied to the discrete setting gives an exact result.

Exercise 20

(a)

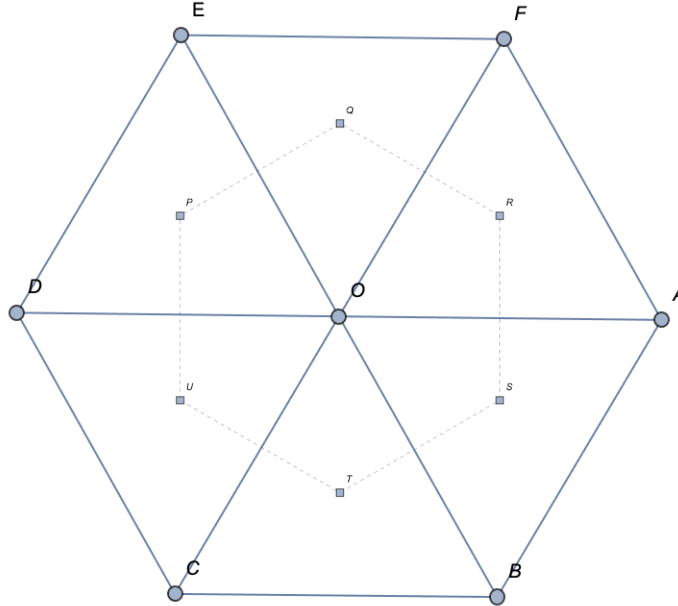
$$d_0 = \begin{matrix} & \begin{matrix} A & B & C & D \end{matrix} \\ \begin{matrix} AB \\ BC \\ CD \\ AD \\ DB \end{matrix} & \begin{bmatrix} -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \\ -1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -1 \end{bmatrix} \end{matrix}$$

(b)

$$d_1 = \begin{matrix} & \begin{matrix} AB & BC & CD & AD & DB \end{matrix} \\ \begin{matrix} ADB \\ BCD \end{matrix} & \begin{bmatrix} -1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 & 1 \end{bmatrix} \end{matrix}$$

Exercise 21

(a) The original graph has solid edges with circle vertices. The dual graph has dashed edges with square vertices:



(b)  $\star_0 \alpha_0$  is a dual 2-form.  
 $\star_1 \alpha_1$  is a dual 1-form.  
 $\star_2 \alpha_2$  is a dual 0-form.

(c) We will use the barycentric dual for vertices which is  $\frac{1}{3} \sum (\text{triangle area})$  where we sum over surrounding triangles.  
The vertices of the dual graph lie on the centroids, which we will use later.

$A, B, C, D, E, F$  have 2 surrounding triangles.  $O$  has 6.

$$(\star_0 \alpha_0)(v^\star) := |\text{Area}(v^\star)| \alpha_0(v)$$

$$(\star_0 \alpha_0)(A^\star) = 2 \times \frac{1}{3} \frac{\sqrt{3}}{4} \times 1 = \frac{1}{2\sqrt{3}}$$

$$(\star_0 \alpha_0)(B^\star) = 2 \times \frac{1}{3} \frac{\sqrt{3}}{4} \times 2 = \frac{1}{\sqrt{3}}$$

$$(\star_0 \alpha_0)(C^\star) = 2 \times \frac{1}{3} \frac{\sqrt{3}}{4} \times 3 = \frac{\sqrt{3}}{2}$$

$$(\star_0 \alpha_0)(D^\star) = 2 \times \frac{1}{3} \frac{\sqrt{3}}{4} \times 4 = \frac{2}{\sqrt{3}}$$

$$(\star_0 \alpha_0)(E^\star) = 2 \times \frac{1}{3} \frac{\sqrt{3}}{4} \times 5 = \frac{5}{2\sqrt{3}}$$

$$(\star_0 \alpha_0)(F^\star) = 2 \times \frac{1}{3} \frac{\sqrt{3}}{4} \times 6 = \sqrt{3}$$

$$(\star_0 \alpha_0)(O^\star) = 6 \times \frac{1}{3} \frac{\sqrt{3}}{4} \times 7 = \frac{7\sqrt{3}}{2}$$

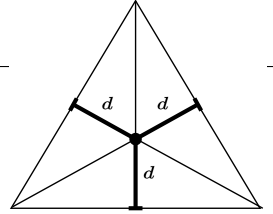
(d) We will say that length of boundary dual edges is zero, so we only consider edges fanning out of vertex  $O$ .

Height  $h$  of an equilateral triangle:  $1^2 = h^2 + \frac{1}{2}^2 \implies h = \frac{\sqrt{3}}{2}$ . Boxed here is Viviani's theorem [1][2] which states that:

Inside an equilateral triangle, the sum of the perpendicular distances from a point  $P$  to the three sides is independent of the position of  $P$  (and so equals the altitude of the triangle).

If  $P$  is the centroid, it would be exactly centered in the triangle, positioned equidistant to the sides. So, if  $d$  is the distance to the sides, we have:

$$3d = \frac{\sqrt{3}}{2} \implies d = \frac{1}{2\sqrt{3}}$$



By symmetry, we argue that the edges of our dual graph all have length  $2d = \frac{1}{\sqrt{3}}$ .

$$(\star_1 \alpha_1)(e^\star) := \frac{|\text{Length}(e^\star)|}{|\text{Length}(e)|} \alpha_1(e) = \frac{\alpha_1(e)}{\sqrt{3}}$$

$$(\star_1 \alpha_1)((O, A)^\star) = \frac{-2}{\sqrt{3}}$$

$$(\star_1 \alpha_1)((O, B)^\star) = \frac{-5}{\sqrt{3}}$$

$$(\star_1 \alpha_1)((O, C)^\star) = -\sqrt{3}$$

$$(\star_1 \alpha_1)((O, D)^\star) = \frac{1}{\sqrt{3}}$$

$$(\star_1 \alpha_1)((O, E)^\star) = \sqrt{3}$$

$$(\star_1 \alpha_1)((O, F)^\star) = \frac{-2}{\sqrt{3}}$$

(e)

$$\begin{aligned}
(\star_2 \alpha_2)(f^\star) &:= \frac{\alpha_2(f)}{|\text{Area}(f)|} = \frac{4}{\sqrt{3}} \alpha_2(f) \\
(\star_2 \alpha_2)((A, B, O)^\star) &= 4\sqrt{3} \\
(\star_2 \alpha_2)((C, B, O)^\star) &= -\frac{8}{\sqrt{3}} \\
(\star_2 \alpha_2)((D, C, O)^\star) &= \frac{4}{\sqrt{3}} \\
(\star_2 \alpha_2)((D, E, O)^\star) &= 0 \\
(\star_2 \alpha_2)((E, F, O)^\star) &= -\frac{4}{\sqrt{3}} \\
(\star_2 \alpha_2)((A, F, O)^\star) &= -\frac{8}{\sqrt{3}}
\end{aligned}$$

(f) Using the diagonal Hodge star from the lectures. For each edge  $ij$ , with halfedge  $\alpha_{ij}$  and its twin  $\eta(\alpha_{ij}) = \beta_{ij}$ :

$$\star_1 = \text{diag} \left\{ \begin{cases} \frac{1}{2}(\cot \alpha_{ij} + \cot \beta_{ij}), & \text{if } ij \notin \text{boundary} \\ 0, & \text{if } ij \in \text{boundary} \end{cases} \right\}$$

(g) For each face  $ijk$ :

$$\star_2 = \text{diag} \left\{ \frac{1}{A_{ijk}} \right\}$$