

# Automatic Sleep Stage Scoring on Raw Single-Channel EEG : A comparative analysis of CNN Architectures

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**Abstract**—Medicine has long reached an overwhelming consensus on the importance of sleep in maintaining mental and physiological homeostasis, and the link that sleep disruption has with both disease and mortality. With the advent of the domain of HealthTech, Deep Learning approaches have generated State Of The Art performance in solving several problems in the medicinal arena. The study of sleep- Polysomnography- uses Electroencephalogram (EEG) readings, among other parameters, to gain a clearer picture of a patient's sleep patterns since different brain activities correspond to different stages of sleep. Monitoring and interpreting EEG signals and the body's reactions to the changes in these cycles can help identify disruptions in sleep patterns. Successfully classified sleep patterns can in turn help medical professionals with the prognosis of several pervasive sleep related diseases like sleep apnea and seizures. To address the pitfalls associated with the traditional manual review of EEG signals that help classify sleep stages, in this work, several Convolutional Neural Networks were trained and analysed to classify the five sleep stages (Wake, N1, N2, N3, N4 and REM by AASM's standard) using data from raw, single channel EEG signals. With PhysioNet's Sleep-EDF dataset, this comparative analysis of the performance of popular convolutional neural network architectures can serve as a benchmark to the problem of sleep stage classification using EEG signals. The analysis shows that CNN based methods are adept at extracting and generalizing temporal information, making it suitable for classifying EEG based data.

**Index Terms**—Deep Learning, EEG analysis, Sleep stage scoring, Transfer Learning, Convolutional Neural Network

## I. BACKGROUND AND MOTIVATION

Sleep plays a principal role in mental and physiological homeostasis. Sleep related diseases like insomnia and sleep apnea reduce the quality of life for the multitude of people who are affected. As connections between sleep disruption and both disease and mortality have become more firmly established in [1], accurate and efficient diagnosis and management of sleep disorders have become increasingly critical. Observing sleep cycles, along with the body's reactions to the changes in these cycles, can help identify disruptions in sleep patterns. Typically, all-night polysomnographic (PSG) recording consisting of an electrooculogram (EOG), electroencephalogram (EEG) and electromyogram (EMG) are analyzed for determining the quality of sleep. The aforementioned

PSGs are used to create epochs ( segments of 30-second recordings ) that are then classified by the experts into the different sleep stages. Guidelines such as the Rechtschaffen and Kales (R & K) [2] and the American Academy of Sleep Medicine (AASM) [3] are followed during classification. The process of sleep stage scoring or sleep stage classification is therefore completed. In the AASM classification, there exists a wake stage, referred to as stage W, three Non-REM sleep stages named as N1, N2, and N3, with N3 reflecting slow wave sleep and one REM sleep stage, referred to as stage R. This procedure of sleep scoring is, however, manual and hence labor-intensive and time-consuming [4]. The demand for automatic sleep scoring can be attributed to the fact that traditionally all the PSG epochs are visually inspected and labeled by experts, making the process arduously inefficient.

Artificial intelligence (AI) is at the cusp of making several facets of healthcare more efficient, consequently creating better clinical applications. The progress has the potential for improved patient care and smoother operations. Deep Learning can not just handle large amounts of data efficiently, but also learn to extract relevant hidden representations automatically. The approach is therefore popular in various domains, and has similarly received appreciable attention from the field of sleep research. Deep Learning can provide real-time, automatic sleep stage classification and sleep scoring, aiding physicians at hospitals and health systems at large. Physicians can alter and monitor results using their expertise. Academia has generated several sleep scoring methods for automatic classification of PSG data. Some works have been discussed in the section II.

## II. LITERATURE REVIEW

### A. Review of the Existing Work

Various review works have been focussed on the use of EEG waves in the problem of sleep scoring techniques. In [18], the authors have reviewed 154 papers that apply DL to EEG, spanning different application domains such as epilepsy, sleep, brain-computer interfacing, and cognitive and affective monitoring. [19] is a review of automated sleep stage scoring systems since the year 2000. They analyse the systems that were developed for Electrocardiogram (ECG),

TABLE I: Literature Review Analysis

Ref	Dataset Used	Architecture	Accuracy
[5]	MASS	SeqSleepNet - Hierarchical RNN	87.1%
[6]	Sleep-EDF	Transfer Learning Using CNN	84.3%
[7]	Sleep-EDF, MASS and SHHS	IITNet - transfer learning + bidirectional LSTM	Sleep-EDF: 83.9% MASS: 86.5% SHHS: 86.7%
[8]	Records from Massachusetts General Hospital Sleep Laboratory	SleepNet - RNN	85.76%
[9]	MASS	SVM	79.7%
[10]	Sleep-EDF and MASS	DeepSleepNet - CNN	MASS: 86.2%, Sleep-EDF: 82.0%
[11]	Sleep-EDF	Decision Tree	89.06%
[12]	Sleep-EDF	CNN + DNN with time-frequency image features	82.6%
[13]	Sleep-EDF	CNN + Temporal CNN + Conditional Random Field Layer	85.39%
[14]	Sleep-EDF	SleepEEGNet - CNN	84.26%
[15]	Records from Charite Clinic in Berlin	CNN + LSTM	40%
[16]	Sleep-EDF and MASS	CNN	Sleep-EDF: 82.3% MASS: 83.6 %
[17]	Sleep-EDF	bidirectional RNNs with + SVM attention	82.5%

Electroencephalogram (EEG), Electrooculogram (EOG), and a combination of signals.

A Mixed Neural Network (MNN) is proposed in [9] that simultaneously aims to target the concerns of population heterogeneity and temporal pattern recognition. The novel architecture is composed of a rectifier neural network which is adept at detecting naturally sparse patterns and a long short-term memory (LSTM) for the detection of temporally sequential patterns.

[10] proposes DeepSleepNet, a CNN to extract time invariant features, and bidirectional-Long Short-Term Memory to learn transition rules among sleep stages to classify raw single-channel EEG. The two step training process involves pre-training the model with an oversampled dataset to mitigate the class-imbalance problem followed by encoding temporal information into the model.

[8] deployed an annotation tool for sleep staging. SleepNet uses a recurrent neural network trained on the largest sleep physiology database, consisting of PSGs from over 10,000 patients from the Massachusetts General Hospital (MGH) Sleep Laboratory. The most successful model uses expert-defined features to represent 30 second intervals, annotating them with a recurrent neural network (RNN).

The authors of [14] proposed SleepEEGNet for automatic sleep stage annotation using a single-channel EEG signal. A sequence of deep learning models including CNN for feature extraction, BiRNNs for capturing temporal information and an attention network to learn apposite parts of the input sequence were used, alongside the SMOTE- Synthetic Minority Over-sampling Technique to tackle class imbalance.

The authors of [15] detect sleep stages by using heartbeat signals, respiratory signals, and movement signals. They employ a Convolutional Neural Network (CNN) and a Long-Short Term Memory network (LSTM) for classification.

A hierarchical recurrent neural network is proposed in [5] treated automatic sleep staging as a sequence-to-sequence classification problem for jointly classifying a sequence of multiple epochs at once.

A transfer learning approach using deep learning was presented in [6]. The work attempted to resolve the issue of data insufficiency in sleep studies while improving the performance of automatic sleep staging on small cohorts.

In the paper [7], raw single-channel EEG were used to consider inter- and intra-epoch temporal contexts. They use a modified ResNet-50 for extracting features and an RNN that uses a two-layered BiLSTM for learning transition rules. The results demonstrate that intra- and inter-epoch level temporal context learning is a successful approach for classifying time-series inputs.

[11] proposes the development of an Automatic Sleep Stage Classification (ASSC) system for detecting sleep stages using simple statistical features (called EnergySis and Maximum-Minimum Distance) that are applied to 10 s epochs of single-channel EEG signals. The work is most notable for its focus on making the design ideal for being implemented in an embedded device in real time.

[12] proposes an efficient and simplified CNN that is capable of learning features at a multitude of temporal resolutions while capturing time shift-invariance property of EEG signals because of its 1-max pooling layer. The work also creates a novel deep neural network (DNN) to discriminatively learn a frequency-domain filter bank that pre-processes the time-frequency image features.

The authors of [16] used a novel CNN framework for sleep stage classification that simultaneously determined the classification label of the current epoch and the neighbouring epoch's prediction in the contextual output.

A framework for sleep stage classification in single-channel EEG is developed in [13]. It uses a CNN to initially extract features that could serve as an input to a Temporal Convolutional Neural Network (TCNN) to extract the temporal features.

In the paper [17], the authors used deep bidirectional RNNs with attention for single-channel sleep stage classification. The network works as a feature extractor to generate a high-level feature vector that is then given to an SVM for the classification.

Table I summarizes the existing work discussed in this section.

### B. Research Gaps

- The review clearly demonstrates that most research uses only single-channel EEG signals to make classifications, and does not utilize all the available signal data including Fpz and Pz. The paper hypothesizes that these signals contain valuable information about the temporal and spatial features of the waves and using all the signals can boost the accuracy.
- The existing architectures are also extremely bulky, requiring numerous layers and heavy preprocessing that inevitably increases the time required for training. Transfer learning can be invaluable in such a scenario.

## III. METHODOLOGY

### A. Dataset

In this study, two cohorts from the Physionet Sleep-EDF extended dataset contributed in 2018 are used for experimentation. The dataset contains PSG records and their corresponding sleep stages labeled by human sleep experts. The two cohorts present different health disorders which are, patients with healthy sleep patterns and with light sleep disorders (Sleep-EDF Sleep Cassette and Sleep-EDF Sleep Telemetry respectively) [20], [21].

- Sleep-EDF Sleep Cassette: This cohort of the Sleep-EDF 2018 dataset consists of 153 recordings of 77 subjects aged 25-101. Two successive night PSG recordings were collected for each subject.
- Sleep-EDF Sleep Telemetry: This cohort of the Sleep-EDF 2018 dataset was assembled for studying the effects of a sleep medication on patients. This cohort contains recordings of 22 subjects with age ranging from 18 to 79 with mild insomnia. The sleep stage scoring was done

manually by sleep experts identical to the Sleep Cassette cohort.

TABLE II: Demographic information of the cohorts of Sleep EDF dataset

Dataset	Avg. epochs	Category	No. of subjects	Age		
				mean	min	max
Sleep Cassette	2650	male	36	59.3	26	97
		female	41	58.5	25	101
		total	77	58.9	25	101
Sleep Telemetry	2453	male	7	35.71	20	60
		female	15	50.85	18	79
		total	22	40.18	18	79

Table II summarizes the demographic particulars of the two cohorts, with their gender data and age range. In each of the cohorts, each of the 30-second windows or epochs were labelled by sleep experts into one of eight stages N1, N2, N3, N4, Wake, REM, UNKNOWN MOVEMENT in accordance with the R & K manual [2]. Like some of the previous works [10], [12], [13], [16], N3 and N4 stages were combined to form a single stage N3 and UNKNOWN and MOVEMENT stages were eliminated to make the stages compliant to AASM standards [3]. The experiments were performed on the Fpz-Cz EEG and Pz-Oz EEG channels in this study.

### B. Data Exploration

Using the Visbrain tool [22], the visualizations of the sample waveforms of different stages of sleep in an epoch of 30 seconds are shown in Figure 1.

### C. Preprocessing

The dataset contains EDF [23] files for each recording. Each EDF file constitute one PSG record. For the scope of this experimentation, only two signals were required from the original files: Fpz-Cz EEG, and Pz-Oz EEG signals. By using pyEDFLib library [24], the mentioned signals were extracted and processed. Signals from each subject were split into time series of 3000 timesteps, which equate to 30-seconds epoch since the frequency of Fpz and Pz EEG signals is 100 Hz. The tabular dataset obtained for each record is shaped like a 3-dimensional vector as: (n epochs, 3000 timesteps, 2 signals) where the 2 signals are Fpz-Cz and Pz-Oz.

The obtained dataset was highly unbalanced with a high number of instances i.e. epochs of Wake stage. Due to the uneven distribution of data among the sleep stages, undersampling has been performed to address the data-skewing problem. To ensure a balanced and representative dataset across all the five classes, Wake, N1, N2, N3 and REM, 1000 epochs for each class were utilized for training and 50 epochs per class were used for testing.

Since great results have been achieved by processing data with deep learning techniques like convolutional neural networks (CNN) with images as input. Due to CNN's commendable performance for processing and extracting the most

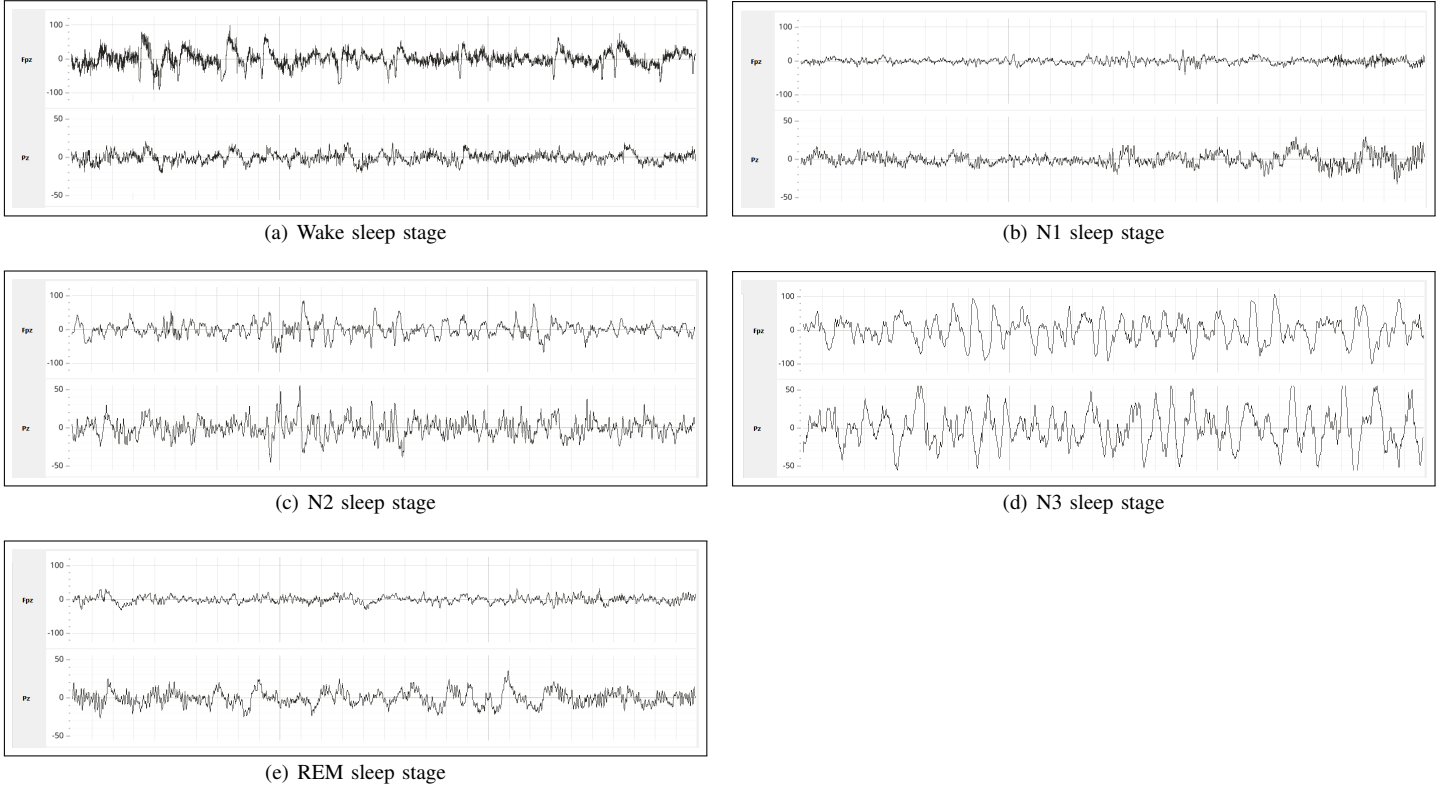


Fig. 1: Raw EEG waveforms for each of the sleep stages

important features of high dimensional data, this paper uses CNN architectures for experimentation as discussed in section IV. Since the obtained dataset is tabular signal data, which isn't formatted as an image, transformation methods have been applied to apply CNN models. So, the sampled epochs obtained in the previous steps are first converted into signal images of grayscale images using such transformations. A couple sample images obtained are referenced in Figure 2. This preprocessing step helps to detect hidden features and topologies like homogeneity, periodicity, driftiness and dispersion when dealing with time series like EEG signal data.

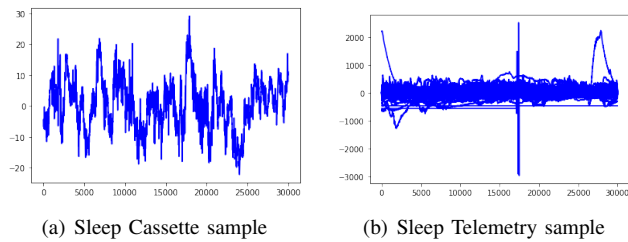


Fig. 2: Samples of plotted signals of sleep stage 'REM' after raw data converted to graphs from Sleep Cassette and Sleep Telemetry cohorts

Thus, our image data is ready to be fed into the proposed Deep Learning architectures for training the models.

#### IV. EXPERIMENTAL ARCHITECTURES

A convolutional neural network is a subtype of deep neural networks. It uses alternating layers of convolutions and pooling with trainable filter banks (made up of kernels) per layer. Kernels scan over a receptive field to compute the output feature map with a dot product and bias computation. The result is passed through an activation function, and then subsampled using max pooling to reduce sensitivity to distortions of stimuli in the upper layers. CNNs generally employ the Rectified Linear Unit activation function that converts negative values to 0, extracting only the prominent features. The max pooling layer helps reduce complexity while allowing prominent features to pass through to upper layers of the network. This process is repeated to gain relevant, abstract and location invariant features that are accurate depictions for recognition problems. This manner of feature learning often produces state of the art results. Apart from dominating the domain of computer vision and image analysis, CNNs are also apt for 1D problems like time series, because of their reliance on a method's ability to learn features. CNNs greatly reduce the number of parameters when compared to traditional feed-forward networks because of their unique design consisting of weight sharing and pooling. Thus, because of sparse-connectivity and weight sharing helps achieve a similar degree of complexity with a significantly smaller number of parameters.

This paper performed experiments on several CNN architectures of varying complexity to analyse the effects of

the different design features to the problem statement. The experiments were run with the pretrained models trained on the ImageNet dataset. The last layer was modified to reflect the five sleep stages. With the dataset being constant, a comparative analysis of the performance of popular CNN architectures can serve as a benchmark to the problem of sleep stage classification using EEG signals. The architectures chosen vary in depth, parameters, design, complexity and efficiency. A comparative analysis of this performance can help give insight to the aspects that will be most relevant to an ideal solution. The following section provides an overview to the key features of the various CNNs used.

#### A. AlexNet

AlexNet [25] takes in images that are passed through 5 alternating convolution layers and 3 fully connected layers, with the last fully connected layer having neurons equivalent to the number of classes. The count of the total number of layers in the architecture does not include the max-pooling layers as they do not carry weights. Thus, AlexNet has 8 layers. AlexNet was proposed in 2012 as a significant improvement on the CNN performance at the time and has been used as a benchmark since. Its key contribution was using the ReLU activation function instead of tanh or sigmoid to achieve faster training times.

#### B. VGG

During the design of the VGGNet [26], it was found that alternating convolution & pooling layers were not required, and consequently VGG uses multiple Convolutional layers in sequence with pooling layers in between. The VGG architecture has several versions like the VGG-16 (a 16 layer network), VGG-19 (a 19 layer network) and so forth. VGG demonstrated a solution to the pertinent problem of increasing depth of a CNN - the small-size convolution filters in the architecture allowed VGG to have a large number of weight layers; that increased depth and improved performance.

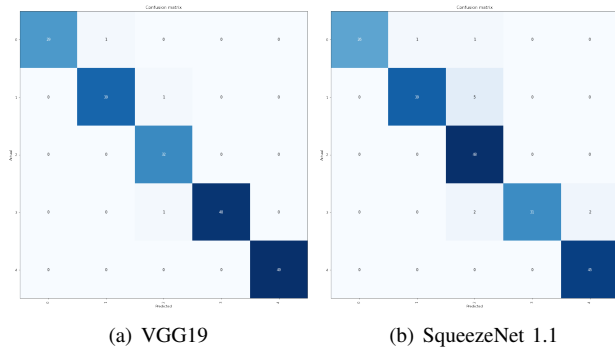


Fig. 3: Confusion Matrices for best (VGG19) and worst (SqueezeNet 1.1) performing model Fpz-Cz channel of Sleep Cassette Cohort

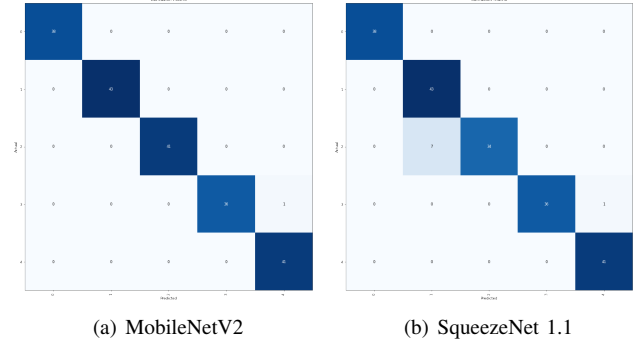


Fig. 4: Confusion Matrices for best (MobileNet-v2) and worst (SqueezeNet 1.1) performing model Pz-Oz channel of Sleep Cassette Cohort

#### C. ResNet

As the depth of the VGG network was increased, the model performance began to deteriorate. It was hypothesised that the gradients were not able to flow well through the deeper network. The scientists proposed a solution of passing the input information repeatedly in stages creating a Residual Network or the ResNet [27]. In ResNet after every two layers the input given to the first layer along with the output obtained at the second layer. The information from the input that was earlier getting highly morphed and by the time it reached the output layers is now passed as a residue of the input once again with the output. This helped the gradients to flow back better, improving training.

#### D. DenseNet

DenseNets [28] connect every layer to every other layer, implying that for  $L$  layers, there are  $L(L+1)/2$  direct connections. Every layer uses the feature maps of all the preceding layers as inputs, and consequently its output feature maps are used as input for subsequent layers. The network is divided into densely connected blocks within which the feature map size remains the same. This facilitates both downsampling and feature concatenation. DenseNets require fewer parameters than a comparable size traditional CNN as the need to learn redundant feature maps is eliminated. It also facilitates the flow of information and gradient as each layer has direct access to the input and the gradient of the loss function.

#### E. Squeezenet

SqueezeNets [29] attempt to reduce the number of parameters in the network by using Fire modules which have a squeeze layer of  $1 \times 1$  convolutions that can decrease parameters by restricting the number of input channels in every layer. SqueezeNets are therefore very low latency. They achieve AlexNet level accuracies while having 50 million fewer parameters.

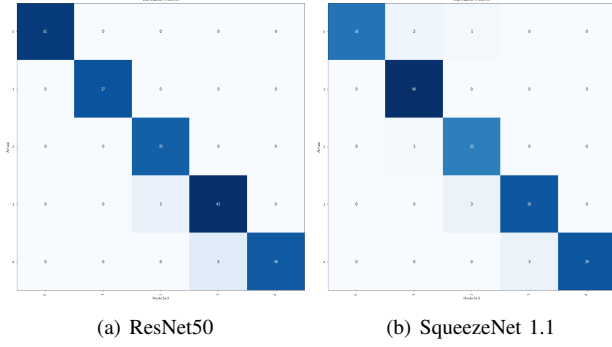


Fig. 5: Confusion Matrices for best (ResNet50) and worst (SqueezeNet 1.1) performing model Fpz-Cz channel of Sleep Telemetry Cohort

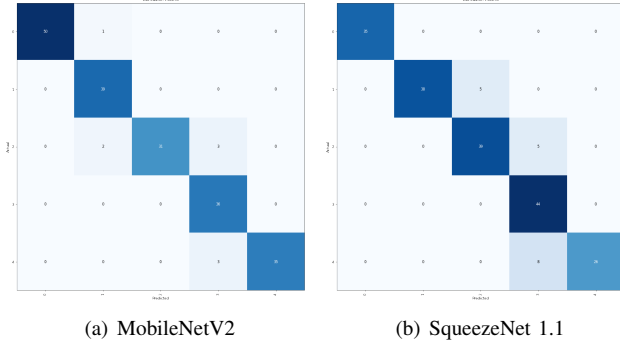


Fig. 6: Confusion Matrices for best (MobileNet-v2) and worst (SqueezeNet 1.1) performing model Pz-Oz channel of Sleep Telemetry Cohort

#### F. MobileNet

MobileNets [30] utilise Depth convolutions and point convolutions, reducing the comparison and recognition time. They are designed to increase accuracy while simultaneously factoring the resource constrained environments of embedded devices or mobile phones, therefore getting their name. They also reduce the number of parameters and hence latency. To construct an even smaller and computationally cheap model, MobileNets also have useful model-shrinking parameters that help make the network thinner in a uniform manner at every layer. The architecture helps explore a reasonable accuracy, latency and size trade off.

### V. RESULTS AND DISCUSSIONS

#### A. Evaluation measures

After training the models discussed in section IV, they were evaluated on the test data that the model has never seen before. The final dataset was split into training and testing data in the ratio 80% to 20%.

1. Accuracy: It is the fraction of classifications the model got correct.

$$\text{Accuracy} = \frac{TP + TN}{TP + TN + FP + FN} \quad (1)$$

Accuracy is one of the most widespread evaluation measures for Machine Learning models but is not always reliable. In cases of dataset skew, where number of instances of some class is remarkably higher, the model will give high accuracy by classifying every sample into that class. Hence, F1-score, precision and recall give a better insight into classification model performance.

2. Precision: Proportion of the positive identifications which are correct.

$$\text{Precision} = \frac{TP}{TP + FP} \quad (2)$$

3. Recall: Proportion of actual positives which were identified correctly.

$$\text{Recall} = \frac{TP}{TP + FN} \quad (3)$$

F1 score should be taken as a reliable metric as it is not influenced by bias in the number of samples per class.

4. F1-score: It is calculated as the harmonic mean of precision and recall.

$$F1 - \text{score} = \frac{2 \times \text{precision} \times \text{recall}}{\text{precision} + \text{recall}} \quad (4)$$

#### B. Results

The models discussed in section IV were used to classify the sleep recordings into 5 stages - the Wake stage, N1 stage, N2 stage, N3 stage and REM stage. The experimental results are tabulated in Table III, with respect to the previously described metrics. All metrics were calculated on the test dataset. For each model architecture and classification, the accuracy reached about 93-94%. Comparing the models, for the Sleep-EDF-SC cohort, the best performing model for Fpz-Cz is VGG-19 and for Pz-Oz, it is MobileNet-v2. Similarly, for the Sleep-EDF-ST cohort, ResNet50 and MobileNet-v2 shows the best performance for Fpz-Cz and Pz-Oz channels respectively. Also, SqueezeNet 1.1 has the worst performance in comparison to the other models for both channels in SC and ST cohorts.

Figure 3 and Figure 4 presents the confusion matrices processed by the best and worst performing models using the Fpz-Cz and Pz-Oz channels respectively of the Sleep-EDF-Sleep Cassette Cohort. Similarly, Figure 5 and Figure 6 shows the confusion matrices of the best and worst models using the Fpz and Pz-Oz channels respectively of the Sleep EDF Sleep Telemetry cohort. These confusion matrices give direct comparisons of values like True Positives, False Positives, True Negatives and False Negatives. The main diagonal in a confusion matrix denote the true positive (TP) values which show the number of sleep stages classified accurately. It is evident from the figures that the true positive values are significantly high, indicating notable performance of the models.

TABLE III: Result metrics of various experimental architectures

Dataset	Channel	Metric	Model					
			ResNet50	MobileNetV2	AlexNet	DenseNet121	VGG19	SqueezeNet 1.1
Sleep-EDF Sleep Cassette (SC)	Fpz-Cz	Accuracy	0.96	0.97	0.94	0.96	<b>0.98</b>	0.94
		Precision	0.97	0.98	0.95	0.97	<b>0.98</b>	0.96
		Recall	0.96	0.97	0.94	0.96	<b>0.98</b>	0.94
		F1-score	0.96	0.98	0.94	0.96	<b>0.98</b>	0.95
	Pz-Oz	Accuracy	0.98	<b>0.99</b>	0.98	0.97	0.98	0.96
		Precision	0.99	<b>1.00</b>	0.99	0.97	0.98	0.97
		Recall	0.98	<b>0.99</b>	0.98	0.98	0.99	0.96
		F1-score	0.99	<b>0.99</b>	0.98	0.97	0.98	0.96
Sleep-EDF Sleep Telemetry (ST)	Fpz-Cz	Accuracy	<b>0.96</b>	0.94	0.95	0.95	0.96	0.94
		Precision	<b>0.96</b>	0.93	0.95	0.95	0.95	0.93
		Recall	<b>0.95</b>	0.94	0.95	0.96	0.95	0.93
		F1-score	<b>0.95</b>	0.93	0.95	0.95	0.95	0.93
	Pz-Oz	Accuracy	0.94	<b>0.95</b>	0.95	0.94	0.94	0.91
		Precision	0.94	<b>0.96</b>	0.95	0.95	0.95	0.93
		Recall	0.94	<b>0.95</b>	0.95	0.94	0.93	0.91
		F1-score	0.94	<b>0.95</b>	0.95	0.94	0.94	0.91

## VI. CONCLUSION

The work has implemented and automated the sleep staging pipeline- when given raw, single channel EEG data signals of a patient from the Fpz-Cz and Pz-Oz signal data of the Sleep-EDF data sets, the datapoint is classified into one of the five sleep stages (Wake, N1, N2, N3, N4 and REM ) using several different Convolutional Neural Network architectures. The preprocessing and sampling implemented helps avoid model bias, ensuring that the models evaluate sleep scoring reliably according to the new AASM standards.

The pipeline utilizes CNNs to extract time-invariant features and learn stage transition rules among sleep stages from EEG epochs. The results also showed that the temporal information learned from the sequence residual learning helped improve the classification performance. The experiments clearly demonstrated that the models could learn features for sleep stage scoring from different raw single-channel EEGs. The paper also provides an exhaustive overview of the existing literature in the domain, allowing researchers to review the possible approaches of solving the problem. The work also benchmarked the performance of several popular CNN architectures on a consistent sleep stage classification dataset. A comparative analysis of the various CNN architectures demonstrates that a CNN based approach is a fitting solution for EEG data. This can serve as a step on tangible progress not just in the domain of sleep stage classification using EEG in particular but also aid the process of integrating AI in medicine.

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