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12.05.2006	1.0.0	AUTOSAR Administration	Initial release



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1 Introduction and functional overview

This specification describes the functionality, APIs and the configuration of the AUTOSAR Basic Software module I-PDU Multiplexer IpduM.

PDU multiplexing means using the same PCI (Protocol Control Information) of a PDU (Protocol Data Unit) with more than one unique layout of its SDU (Service Data Unit). A selector field is a piece of the SDU of the multiplexed PDU. It is used to distinguish the contents of the multiplexed PDUs from each other.

Multiplexing of PDUs is currently known from CAN, but is not restricted to this communication system.

On sender-side, the I-PDU Multiplexer module is responsible to combine appropriate I-PDUs from COM to new, multiplexed I-PDUs and send them back to the PDU-Router. On receiver-side, it is responsible to interpret the content of multiplexed I-PDUs and provide COM with its appropriate separated I-PDUs taking into account the value of the selector field.



2 Acronyms and abbreviations

Abbreviation / Acronym:	Description:
IpduM	I-PDU Multiplexer
dynamic part	see [6]
static part	see [6]
selector field	see [6]
signal	see [7]
signal group	see [7]
segment	The static or dynamic part may consist of more than one piece. These pieces are called segments. See also IPDUM006 and Figure 2.
COM I-PDU	I-PDU assembled in the COM module out of COM Signals
IpduM I-PDU	I-PDU assembled in the IpduM module out of two COM I-PDUs
multiplexed I-PDU	see IpduM I-PDU
instance of an I-PDU	IpduM I-PDU with one specific layout and content



3 Related documentation

3.1 Input documents

- [1] List of Basic Software Modules AUTOSAR_TR_BSWModuleList.pdf
- [2] Layered Software Architecture AUTOSAR_EXP_LayeredSoftwareArchitecture.pdf
- [3] General Requirements on Basic Software Modules AUTOSAR_SRS_BSWGeneral.pdf
- [4] Specification of ECU Configuration AUTOSAR_TPS_ECUConfiguration.pdf
- [5] Specification of BSW Scheduler AUTOSAR_SWS_BSW_Scheduler.pdf
- [6] Requirements on I-PDU Multiplexer AUTOSAR_SRS_IPDUMultiplexer.pdf
- [7] Specification of Communication AUTOSAR_SWS_COM.pdf
- [8] Basic Software Module Description Template AUTOSAR_TPS_BSWModuleDescriptionTemplate.pdf
- [9] Concept of Debugging in BSW & RTE Features AUTOSAR RS BSWAndRTEFeatures

3.2 Related standards and norms

None



4 Constraints and assumptions

4.1 Limitations

For transmission of multiplexed I-PDUs, minimum delay time observation cannot be taken into account. For more details, see [7] and 7.4.1.

4.2 Applicability to car domains

No restrictions.

4.3 Applicability to safety related environments

This document has been created in absence of a safety case and a safety plan. Thus, the direct results of this document can only be used within safety relevant systems after repeating certain process steps as required in the IEC 61508.



5 Dependencies to other modules

This chapter lists all the features from other modules that are used by the AUTOSAR IpduM and functionalities that are provided by AUTOSAR IpduM to other modules. Because the IpduM module deals with PDUs that are either sourced or sunk by other modules, care must be taken that shared configuration items are consistent between the modules.

5.1 AUTOSAR OS

[IPDUM107] [The IpduM shall not directly access the AUTOSAR OS.] (BSW00429)

5.2 BSW Scheduler

The BSW-Scheduler (see [5]) schedules the main function of the IpduM.

The IpduM module relies on the BSW-schedule calling the IpduM_MainFunction function at a period as configured in IpduMConfigurationTimeBase.

5.3 PDU-Router

The following summarizes the functionality IpduM needs from the PDU-Router (for more details see Chapter 8.6):

- indication of incoming multiplexed I-PDUs
- sending interface for outgoing I-PDUs
- confirmation of I-PDUs which went out

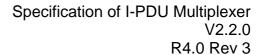
The following list summarizes the functionality provided by the IpduM module for the PDU-Router module:

- indication interface for incoming I-PDUs, which are de-multiplexed
- sending interface for to be multiplexed I-PDUs
- confirmation interface for transmitted I-PDUs

The configuration of the PDU-Router module (e.g. look-up tables) must be such that the I-PDUs, which belong to multiplexed I-PDUs and represent a static or a dynamic part of a multiplexed I-PDU, are routed to the IpduM module.

5.4 COM

The configuration of the IpduM module relies on a corresponding configuration of the AUTOSAR COM module. For each multiplexed I-PDU, there needs to be different I-PDUs configured in the COM module for the static part and each layout of the dynamic part. For further information, see Chapter 7.1 and especially Figure 2.





The IpduM further assumes that the correct selector field values are already contained in the COM's modules I-PDU representing the dynamic parts. See also IPDUM098.



5.5 File structure

5.5.1 Code file structure

This IpduM SWS does not define the code file structure completely.

[IPDUM095] [The module IpduM shall provide a file IpduM_Lcfg.c containing the link-time configurable parameters.] ()

[IPDUM096] [The module IpduM shall provide a file IpduM_PBcfg.c containing the post-build time configurable parameters.] ()

5.5.2 Header file structure

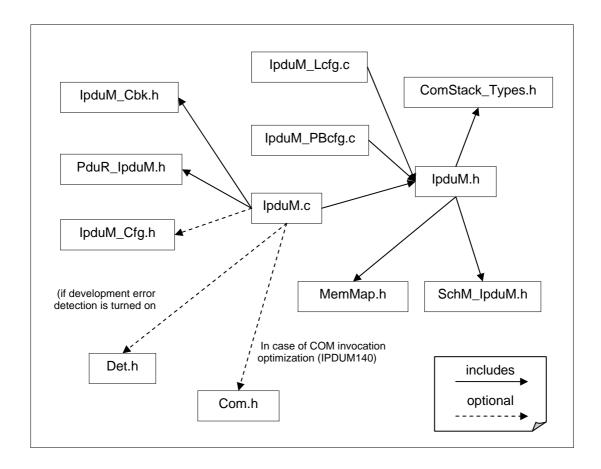


Figure 1 Header File Structure



[IPDUM148] [The file IpduM.c shall include IpduM.h, IpduM_Cbk.h, PduR_IpduM.h, and optionally IpduM_Cfg.h, Det.h and Com.h. | (BSW00415)

[IPDUM149] [The file IpduM_Lcfg.c shall include IpduM.h.] (BSW00415)

[IPDUM150] [The file IpduM_PBcfg.c shall include IpduM.h. | (BSW00415)

[IPDUM151] [File IpduM.h shall include MemMap.h, SchM_IpduM.h and Com-Stack_Types.h.] (BSW00415)

[IPDUM165] The IpduM module shall perform Inter Module Checks to avoid integration of incompatible files. The imported include files shall be checked by preprocessing directives. The following version numbers shall be verified:

- <MODULENAME> AR RELEASE MAJOR VERSION
- <MODULENAME>_AR_RELEASE_MINOR_VERSION

<MODULENAME> is the module's short name of the other (external) module, which provides header files included by the IpduM module.

If the values are not identical to the expected values, an error shall be reported.] (BSW004)

5.5.3 Design Rules

[IPDUM073] The code of the IpduM module, as long as it is written in C, shall conform to the HIS subset of the MISRA C Standard. | (BSW007)

[IPDUM074] [The code of the IpduM module shall avoid direct use of compiler and platform specific keywords.] (BSW161)

[IPDUM075] The code of the IpduM module shall indicate all global data with read-only purposes by explicitly assigning the const keyword. | (BSW00309)

[IPDUM076] [The IpduM module can use macros instead of functions where source code is used and runtime is critical.] (BSW00330)

[IPDUM077] [The IpduM module shall not define global data in the header files. If global variables are used, the definition shall take place in the C file.] (BSW00309)

[IPDUM078] [The source code of the IpduM module shall not be processor and compiler dependent.] (BSW161)



6 Requirements traceability

Document: AUTOSAR requirements on Basic Software [3]

Requirement	Satisfied by
-	IPDUM104
-	IPDUM144
-	IPDUM168
-	IPDUM146
-	IPDUM095
-	IPDUM096
-	IPDUM105
-	IPDUM145
-	IPDUM169
-	IPDUM147
BSW003	IPDUM037
BSW00309	IPDUM077, IPDUM075
BSW00314	IPDUM999
BSW00323	IPDUM028
BSW00325	IPDUM999
BSW00326	IPDUM999
BSW00330	IPDUM085, IPDUM076
BSW00336	IPDUM999
BSW00337	IPDUM106
BSW00338	IPDUM028, IPDUM027
BSW00339	IPDUM999
BSW00344	IPDUM032
BSW00350	IPDUM027
BSW00357	IPDUM102
BSW00369	IPDUM060, IPDUM043, IPDUM044, IPDUM037, IPDUM032
BSW00369;BSW02817	IPDUM040
BSW00375	IPDUM999
BSW00377	IPDUM999
BSW00386	IPDUM999
BSW004	IPDUM165, IPDUM039, IPDUM038
BSW00405	IPDUM032
BSW00406	IPDUM084, IPDUM083
BSW00407	IPDUM037
BSW00411	IPDUM039
BSW00415	IPDUM151, IPDUM150, IPDUM149, IPDUM148



BSW00417	IPDUM999
BSW00422	IPDUM999
BSW00423	IPDUM999
BSW00425	IPDUM103
BSW00427	IPDUM999
BSW00429	IPDUM107
BSW00431	IPDUM999
BSW00432	IPDUM999
BSW00433	IPDUM999
BSW00434	IPDUM999
BSW00437	IPDUM999
BSW00438	IPDUM159
BSW005	IPDUM999
BSW007	IPDUM073
BSW02800	IPDUM007, IPDUM004
BSW02801	IPDUM009
BSW02802	IPDUM005
BSW02804	IPDUM006
BSW02806	IPDUM010
BSW02807	IPDUM097
BSW02808	IPDUM004
BSW02809	IPDUM067, IPDUM068, IPDUM098, IPDUM143
BSW02810	IPDUM091, IPDUM090, IPDUM089
BSW02811	IPDUM021
BSW02812	IPDUM086, IPDUM041, IPDUM042, IPDUM140
BSW02813	IPDUM022, IPDUM101
BSW02814	IPDUM019, IPDUM020, IPDUM024, IPDUM023, IPDUM152, IPDUM088, IPDUM087
BSW02816	IPDUM017, IPDUM015
BSW02818	IPDUM022
BSW02819	IPDUM020, IPDUM023
BSW101	IPDUM032, IPDUM033
BSW161	IPDUM078, IPDUM074
BSW162	IPDUM999
BSW164	IPDUM999
BSW168	IPDUM999
BSW171	IPDUM999

Requirement	Satisfied by
[BSW00344]	Chapter 10.2.2, IPDUM032
Reference to link-time	
configuration	
[BSW00404]	Chapter 10.2



	NH.O NOV O
Reference to post build	
time configuration	
[BSW00405]	IPDUM032
Reference to multiple	
configuration sets	
[BSW00345]	Chapter 10.2.2, IPDUM059_CONF, IPDUM047_CONF,
Pre-compile-time	IPDUM048_CONF, IPDUM049_CONF,
configuration	IPDUM050 CONFIPDUM052 CONF, IPDUM053 CONF,
Comiguration	
	IPDUM056_CONFIPDUM156
[BSW159]	not scope of this specification
Tool-based configuration	Refers to Configuration WP.
[BSW167]	not scope of this specification
Static configuration check-	Refers to Configuration WP.
ing	
[BSW171]	not applicable
Configurability of optional	(there is no optional functionality)
functionality	(,
[BSW170]	not scope of this specification
Data for reconfiguration of	Refers to Configuration WP.
AUTOSAR SW-	Troisis to Somigaration III
Components	
[BSW00380]	IPDUM095, IPDUM096
Separate C-Files for	implementation specific
	Implementation specific
configuration parameters	Ol sates 5.5
[BSW00419]	Chapter 5.5
Separate C-Files for pre-	implementation specific
compile time configuration	
parameters	
[BSW00381]	Chapter 5.5
Separate configuration	implementation specific
header file for pre-compile	
time parameters	
[BSW00412]	Chapter 5.5
Separate H-File for	implementation specific
configuration parameters	
[BSW00383]	not scope of this specification
List dependencies of	
configuration files	
[BSW00384]	Chapter 5, IPDUM104, IPDUM105
List dependencies to other	
modules	
[BSW00387]	Chapter 8.5
Specify the configuration	Onaptor 0.0
class of callback function	
[BSW00388]	Chapter 10.2,IPDUM070 CONF, IPDUM071 CONF, IPDUM082 CONF,
	_ ' ' ' ' '
Introduce containers	IPDUM130_CONF
[BSW00389]	Chapter 10.2
Containers shall have	
names	
[BSW00390]	Chapter 10.2
Parameter content shall be	
unique within the module	
[BSW00391]	Chapter 10.2
Parameter shall have	
unique names	
[BSW00392]	Chapter 10.2
Parameters shall have a	'
type	
[BSW00393]	Chapter 10.2
[55115555]	Chapter Cold



Parameters shall have a	
range	
[BSW00394]	Chapter 10.2
Specify the scope of the	
parameters	
[BSW00395]	All parameter in Chapter 10.2 are required.
List the required	
parameters (per parameter)	
[BSW00396]	Chapter 10.2
Configuration classes	•
[BSW00397]	Chapter 10.2
Pre-compile-time	'
parameters	
[BSW00398]	Chapter 10.2
Link-time parameters	
[BSW00399]	Chapter 10.2
Loadable Post-build time	Onapior 10.2
parameters	
[BSW00400]	Chapter 10.2
Selectable Post-build time	Οπαριοί 10.2
parameters	Objection 40 0.4 IDDI IM450
[BSW00438] Post Build	Chapter 10.2.1, IPDUM159
Configuration Data	
Structure	IRRUMA A CONTE IRRUMA ACCOUNT IRRUMA CONTE
[BSW00402]	IPDUM141_CONF, IPDUM142_CONF, IPDUM160
Published information	
[BSW00375]	not applicable
Notification of wake-up	(this layer cannot perform a wake-up)
reason	
[BSW101]	IPDUM032, IPDUM033 IPDUM034IPDUM064 IPDUM065
Initialization interface	
[BSW00416]	not scope of this specification
Sequence of Initialization	refere to Mode Management Specification.
[BSW00406]	IPDUM083, IPDUM084
Check module initialization	
[BSW00437] NoInit—Area	not applicable (not needed)
in RAM	
[BSW168]	not applicable
Diagnostic interface	(not diagnostic interface included)
[BSW00407]	IPDUM037
Function to read out	
published parameters	
[BSW00423]	not applicable
Usage of SW-C template to	(this module has no connection to the RTE)
describe BSW modules	
with AUTOSAR Interfaces	
[BSW00424]	not scope of this specification
BSW main processing	Implementation specific
function task allocation	
[BSW00425]	IPDUM103, IPDUM131_CONF
Trigger conditions for	
schedulable objects	
[BSW00426]	not scope of this specification
Exclusive areas in BSW	
	Implementation specific
modules	not applicable
[BSW00427]	not applicable
ISR description for BSW	(module does not provide ISRs)
modules	Observan 0.0
[BSW00428]	Chapter 8.6



Execution order	
dependencies of main	
processing functions	
[BSW00429]	IPDUM107
Restricted BSW OS	
functionality access	
[BSW00431]	not applicable
The BSW Scheduler	(requirement for the scheduler)
module implements task	
bodies	
[BSW00432]	not applicable
Modules should have	(transmit and receive functions are called synchronous by the adjacent
separate main processing	layers)
functions for read/receive	layers)
and write/transmit data path	
[BSW00433]	not applicable
Calling of main processing	(requirement for the scheduler)
functions	
[BSW00434]	not applicable
The Schedule Module shall	(requirement for the scheduler)
provide an API for exclusive	(
1 -	
areas	not applicable
[BSW00336]	not applicable
Shutdown interface	(not needed)
[BSW00337]	IPDUM026, IPDUM106, IPDUM153
Classification of errors	
[BSW00338]	IPDUM027, IPDUM028, IPDUM059_CONF, IPDUM132_CONF,
Detection and Reporting of	IPDUM154
development errors	
	IPDUM032, IPDUM037, IPDUM040, IPDUM043, IPDUM044, IPDUM060
[BSW00369]	1PD0101032, 1PD0101037, 1PD0101040, 1PD0101043, 1PD0101044, 1PD0101000
Do not return development	
error codes via API	
[BSW00339]	not applicable
Reporting of production	(module does not define any production relevant errors)
relevant errors and excep-	
tions	
[BSW00422] Pre—de—	not applicable
bouncing of production	(not scope of this specification)
relevant error status	
	not applicable
[BSW00417]	not applicable
Reporting of Error Events	(this module is part of the basic software)
by Non-Basic Software	
[BSW00323]	IPDUM028
API parameter checking	
[BSW004]	IPDUM038, IPDUM039, IPDUM059_CONF, IPDUM134_CONF,
Version check	IPDUM165
[BSW00409]	
Header files for production	Figure 1
•	
code error IDs	IDDI IMAGO
[BSW00385]	IPDUM026
List possible error	
notifications	
[BSW00386]	not applicable
Configuration for detecting	(implementation specific)
an error	(mpionionalion opoolio)
	IDDI IMOZA IDDI IMOZO
[BSW161]	IPDUM074, IPDUM078
Microcontroller abstraction	
[BSW162]	not applicable
ECU layout abstraction	(not scope of this specification)
•	· · · · · · · · · · · · · · · · · · ·



IDOMOSTI	
[BSW005]	not applicable
No hard coded horizontal	(not scope of this specification)
interfaces within MCAL	
[BSW00415]	IPDUM148, IPDUM149, IPDUM150, IPDUM151
User dependent include	
files	
[BSW164]	not applicable
Implementation of interrupt	(module does not provide ISRs)
service routines	
[BSW00325]	not applicable
Runtime of interrupt service	(module does not provide ISRs)
routines	
[BSW00326]	not applicable
Transition from ISRs to OS	(module does not provide ISRs)
tasks	
[BSW00342]	Chapter 10.2
Usage of source code and	
object code	
[BSW00343]	Chapter 10.2
Specification and	
configuration of time	
[BSW160]	Chapter 10.2
Human-readable	
configuration data	
[BSW007]	IPDUM073
HIS MISRA C	
[BSW00300]	Figure 1
Module naming convention	Ŭ
[BSW00413]	not scope of this specification
Accessing instances of	implementation specific
BSW modules	
[BSW00347]	not scope of this specification
Naming separation of	implementation specific
different instances of BSW	
drivers	
[BSW00305]	Chapter 8.3.1
Self-defined data types	
naming convention	
[BSW00307]	not scope of this specification
Global variables naming	implementation specific
convention	
[BSW00310]	Chapter 8.4 and 8.5
API naming convention	
[BSW00373]	Chapter 8.6
Main processing function	
naming convention	
[BSW00327]	IPDUM026
Error values naming	
convention	
[BSW00335]	not scope of this specification
Status values naming	implementation specific
convention	
[BSW00350]	IPDUM027
Development error	
detection keyword	
[BSW00408]	Chapter 10.2
Configuration parameter	
naming convention	
[BSW00410]	not scope of this specification



Compiler switches shall	implementation specific
have defined values	
[BSW00411]	IPDUM039
Get version info keyword	
[BSW00346]	Figure 1
Basic set of module files	i iguic i
[BSW158]	Figure 1
Separation of configuration	i iguie i
from implementation	
[BSW00314]	not applicable
Separation of interrupt	(module does not provide ISRs)
frames and service routines	(module does not provide isits)
[BSW00370]	Chapter 9.5
Separation of callback	Chapter 8.5
interface from API	
	F: 4
[BSW00435] Module	Figure 1
Header File Structure for	
the Basic Software	
Scheduler IBSW004361 Madula	Firms 4
[BSW00436] Module	Figure 1
Header File Structure for	
the Basic Software Memory	
Mapping	
[BSW00348]	Figure 1
Standard type header	
[BSW00353]	not scope of this specification
Platform specific type	implementation specific
header	
[BSW00361]	not scope of this specification
Compiler specific language	implementation specific
extension header	
[BSW00301]	not scope of this specification
Limit imported information	implementation specific
[BSW00302]	not scope of this specification
Limit exported information	implementation specific
[BSW00328]	not scope of this specification
Avoid duplication of code	implementation specific
[BSW00312]	not scope of this specification
Shared code shall be	implementation specific
reentrant	'
[BSW006]	not scope of this specification
Platform independency	implementation specific
[BSW00357]	Chapter 8, IPDUM102
Standard API return type	
[BSW00377]	not applicable
Module specific API return	(no specific return types)
types	(··· -p···· ()p)
[BSW00304]	Figure 1
AUTOSAR integer data	Iguic I
types	
[BSW00355]	Chapter 8.3
Do not redefine AUTOSAR	implementation specific
integer data types	
	not scope of this specification
[BSW00378]	not scope of this specification
AUTOSAR boolean type	implementation specific
[BSW00306]	not scope of this specification
Avoid direct use of compiler	implementation specific
and platform specific	
keywords	



[BSW00308]	not scope of this specification
Definition of global data	implementation specific
[BSW00309]	IPDUM075, IPDUM077
Global data with read-only	
constraint	
[BSW00371]	Chapter 8.4 and 8.5
Do not pass function	·
pointers via API	
[BSW00358]	Chapter 8.4.1
Return type of init functions	'
[BSW00414]	Chapter 8.4.1
Parameter of init function	
[BSW00376]	Chapter 8.6
Return type and	
parameters of main	
processing functions	
[BSW00359]	Chapter 8.5
Return type of callback	
functions	
[BSW00360]	Chapter 8.5
Parameters of callback	
functions	
[BSW00329]	Chapter 8
Avoidance of generic	onapior o
interfaces	
[BSW00330]	IPDUM076, IPDUM085
Usage of macros / inline	II DOMOTO, II DOMOGO
functions instead of	
functions	
[BSW00331]	Chapter 8
Separation of error and	
status values	
[BSW009]	not scope of this specification
Module User	implementation specific
Documentation	
[BSW00401]	Chapter 10.2
Documentation of multiple	
instances of configuration	
parameters	
[BSW172]	not scope of this specification
Compatibility and	implementation specific
documentation of	<u>'</u>
scheduling strategy	
[BSW010]	not scope of this specification
Memory resource	implementation specific
documentation	· · · · · ·
[BSW00333]	not scope of this specification
Documentation of callback	implementation specific
function context	· · · · ·
[BSW00374]	Chapter 10.3
Module vendor	·
identification	
[BSW00379]	Chapter 10.3
Module identification	
[BSW003]	IPDUM037, IPDUM059_CONF
Version identification	
[BSW00318]	Chapter 10.3
Format of module version	
numbers	



[BSW00321]	not scope of this specification
Enumeration of module	implementation specific
version numbers	
[BSW00341]	not scope of this specification
Microcontroller compatibility	implementation specific
documentation	
[BSW00334]	not scope of this specification
Provision of XML file	Refers to Configuration WP

Document: AUTOSAR requirements on Basic Software cluster IPDUM [6]

Requirement	Satisfied by
[BSW02800]	IPDUM004, IPDUM007
Exactly one selector field per PDU	
[BSW02801]	IPDUM009, IPDUM052_CONF
Size of the selector field	
[BSW02802]	IPDUM005, IPDUM155
Position of the selector field	
[BSW02815]	IPDUM052_CONF
Compile Time configuration of the selector field	
[BSW02803]	IPDUM011
Unused values of the selector field	
[BSW02804]	IPDUM006
Support for static and dynamic parts of the PDU	
[BSW02808]	IPDUM004, IPDUM133_CONF
Support of multiplexed PDUs with a static part of	
length "zero"	
[BSW02809]	IPDUM068, IPDUM067, IPDUM098, IPDUM143
Initialization of multiplexed PDUs	
[BSW02806]	IPDUM010
Semantic of the multiplexer	
[BSW02810]	IPDUM063IPDUM089, IPDUM090, IPDUM091,
Routing of multiplexed PDUs on sender side	IPDUM112_CONF
[BSW02816]	IPDUM015, IPDUM017, IPDUM114_CONF,
Combining of multiplexed PDUs on sender side	IPDUM120_CONF, IPDUM121_CONF,
	IPDUM123IPDUM125_CONF,
	IPDUM126_CONF, IPDUM127_CONF,
	IPDUM128_CONF, IPDUM129_CONF,
	IPDUM157_CONF
[BSW02811]	IPDUM021, IPDUM052_CONF
Triggering condition on sender side	
[BSW02812]	IPDUM041, IPDUM042, IPDUM086,
Routing of multiplexed PDUs on receiver side	IPDUM108_CONF, IPDUM109_CONF,
	IPDUM140
[BSW02817]	IPDUM040, IPDUM113_CONF,
De-multiplexing PDUs on receiver side	IPDUM114_CONF, IPDUM115_CONF
[BSW02813]	IPDUM022, IPDUM050 CONFIPDUM101
Routing of Send Confirmations	23322, II 23.11333_3311 II 23.1131
[BSW02818]	IPDUM022, IPDUM124_CONF, IPDUM163_Conf,
Confirmation replication of multiplexed PDUs	IPDUM164_Conf ,
	IPDUM158_ConfIPDUM050_CONF
[BSW02814]	IPDUM023, IPDUM024, IPDUM019, IPDUM020,
Correct confirmation handling of multiplexed	IPDUM087,IPDUM088, IPDUM152
PDUs	Joinson, in Dollinos, in Dollinos
[BSW02807]	IPDUM097
No Runtime Overhead for systems without PDU	
multiplexing	
[BSW02819]	IPDUM020, IPDUM023
[501102010]	III DOIVIOZO, II DOIVIOZO



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Requirement	Satisfied by
No queuing of transmission requests on sender	
side	

AUTOSAR Release 4.0 Concept Incorporation

Concept	Satisfied by
Debugging concept [9]	IPDUM144, IPDUM145, IPDUM146, IPDUM147



7 Functional specification

7.1 Introduction and definitions

I-PDU multiplexing means using the same I-PDU ID transferred from the PDU-Router to the Communication Hardware Abstraction Layer with more than one unique layout of this I-PDU; see also [2].

[IPDUM004] [A multiplexed I-PDU consists of a static part and a dynamic part, where the static part consists of zero or more signals or signal groups. The dynamic part consists of the selector field and one or more signals or signal groups; see Figure 2. | (BSW02800, BSW02808)

The dynamic part of an I-PDU is comparable with a union in "C". With help of the selector field inside the I-PDU, the actual layout of the I-PDU is selected.

[IPDUM005] [The position of the static and the dynamic part of the multiplexer shall be arbitrary and has to be configurable per I-PDU; see Figure 2, for configuration see Chapter 10.2.2.] (BSW02802)

[IPDUM006] [It shall be possible that the static and the dynamic part consist of more than one element. These elements of the static or dynamic parts are called segments. | (BSW02804)

[IPDUM007] [There shall be only one selector field within one multiplexed I-PDU.] (BSW02800)

The value of the selector field defines how the content of the dynamic part of the I-PDU will be interpreted.

[IPDUM009] [The selector field of one I-PDU shall have a configurable size between one and eight contiguous bits.] (BSW02801)

[IPDUM010] [The position of the selector field within the I-PDU shall be defined by configuration.] (BSW02806)

The configuration rules for the selector field are defined in Chapter 10.4.1.

Multiplexing of PDUs is currently only known from CAN, but it is not restricted to this communication system.

However, because the module is layered next to the PDU-Router above the interface layer (Communication Hardware Abstraction) in the AUTOSAR layer architecture this feature also could be used with LIN or FlexRay.



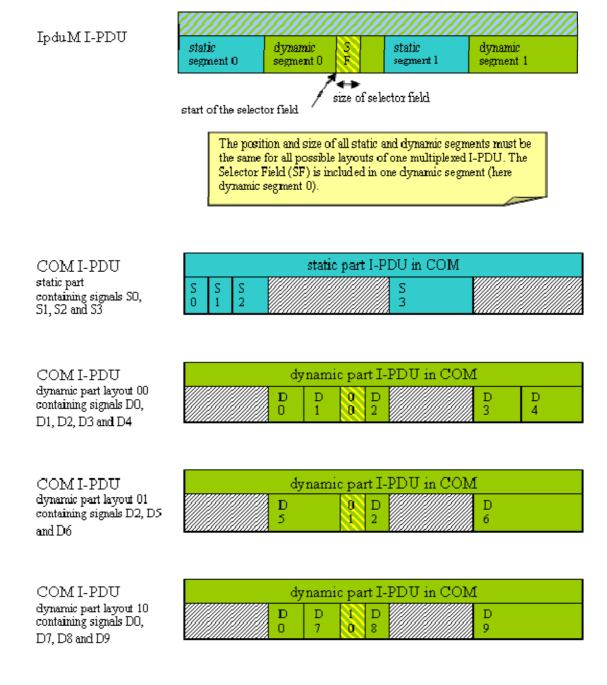


Figure 2 Possible layout of a multiplexed I-PDU

A segment of the dynamic or static part contains either a single signal or signal

group or a collection of signals and signal groups.



7.2 Overview

The IpduM is arranged next to the PDU-Router in the layered architecture of AUTOSAR; see [2] and Figure 3.

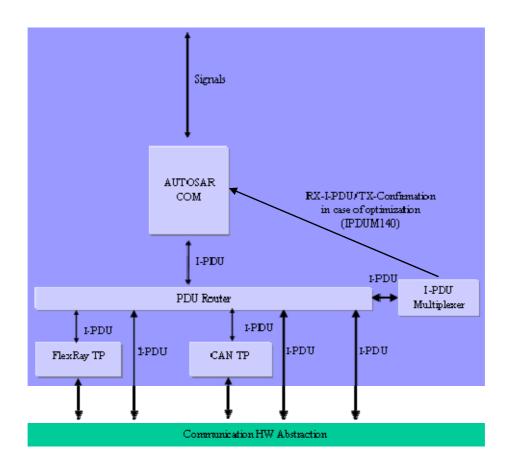


Figure 3 I-PDU Multiplexer in the AUTOSAR Architecture

[IPDUM097] [The IpduM shall be implemented so that no other modules depend on it and that it is be possible to build a system without the IpduM module if it is not needed.] (BSW02807)

There is one COM I-PDU for the static part and one COM I-PDU for each layout of the dynamic part of one multiplexed IpduM I-PDU, so the IpduM combines at most two I-PDUs of COM.

[IPDUM098] [The IpduM module shall not set the selector field. | (BSW02809)

The IpduM module relies on the configuration of the COM module. For each dynamic layout, an I-PDU needs to be configured in COM. Such I-PDUs already have to contain the correct selector field value. The selector field values in COM can be initialized by configuring them as signals that are initialized with an init value but are never written after initialization.



For a detailed description of the transmission and reception of a multiplexed I-PDU see Chapter 7.4 and 7.5.

[IPDUM140] [It shall be allowed to optimize the RX- and Tx-Confirmation path from the IpduM module via the PDU-Router module to the COM layer to call the COM API directly from the IpduM module without including the PDU-Router. This shall be indicated by setting the published parameter IpduMRxDirectComInvocation to TRUE, see IPDUM142_CONF. | (BSW02812)

In case of the COM invocation, optimization as defined above IpduM.c needs to include Com.h, see Figure 1 Header File Structure.

7.3 Initialization

The IpduM module provides an initialization function IpduM_Init defined in IPDUM032. This function initializes all internal global variables and the buffers of the IpduM I-PDUs. For more details, see Chapter 8.3.1.

The environment of the IpduM shall call IpduM_Init before calling any other function of the IPDUM module.

IpduM_Init uses the PduR_IpduMTriggerTransmit function to retrieve the initial I-PDU values from the COM module. Therefore, the COM module needs to be initialized via Com_Init before the IpduM module can be initialized via IpduM_Init. The integrator must take care of this dependency.

The implementer has to ensure that IPDUM_E_UNINIT is returned in development mode in case an API function is called before the module is initialized.

For the I-PDU data transmission pathway through the IpduM module, a buffer is allocated inside the IpduM module. This buffer needs to be initialized in case it is transmitted before it has been fully populated with data by COM. The initialization data for this buffer is derived by using configuration data from the IpduMTxRequest container as follows:

- a. **[IPDUM067]** [The IpduM internal buffer shall first be filled with the pattern defined in the configuration parameter IpduMIPduUnusedAreasDefault.] (BSW02809)
- b. **[IPDUM068]** [The initial signal values for the initial dynamic part, referenced by IpduMinitialDynamicPart, shall be fetched from the COM module via PduR_IpduMTriggerTransmit and the configured IpduMSegment operations of that dynamic part shall be processed.] (BSW02809)
- c. **[IPDUM143]** The initial signal values for the static part shall be fetched from the COM module via PduR_IpduMTriggerTransmit and the configured IpduM-



Segment operations of the static part shall be processed. | (BSW02809)

The selector field is contained within one segment of the dynamic part and therefore is initialized implicitly.

7.4 Transmission

Inside COM, there are separated I-PDUs for the static part and one for each dynamic part of a multiplexed I-PDU.

The static part and the dynamic parts are treated in COM as separate I-PDUs with their own I-PDU IDs.

[IPDUM015] For a multiplexed I-PDU IpduM shall merge the corresponding two COM I-PDUs representing the associated static part and the last received dynamic part into one single IpduM I-PDU with a new unique I-PDU ID. IpduM shall send out this new IpduM I-PDU to the PDU-Router module, see also Figure 2. | (BSW02816)

For details about the trigger of the transmission, see Chapter 7.4.2.

All control functionalities like deadline monitoring of the COM I-PDUs and update-bit evaluation are out of the scope of the IpduM and have to be done by the COM layer. For details about the timing-behavior of the new combined I-PDU see Chapter 7.4.2.

7.4.1 Transmission request

The IpduM module provides an IpduM_Transmit function so that the PDU-R is able to initiate the transmission of an I-PDU; see IPDUM043.

[IPDUM017] [The function IpduM_Transmit (called with a COM I-PDU) shall assemble the related IpduM I-PDU, using the related static and dynamic part, and transmit it according to the trigger conditions/ modes as defined in IPDUM021 and IPDUM125_CONF.] (BSW02816)

As defined in Chapter 7.3, each outgoing I-PDU has an initial value so that, should an I-PDU be transmitted by the IpduM module before both static and dynamic parts have been sent from COM to the IpduM, a value defined by the configuration is transmitted.

[IPDUM019] [The configuration of the IpduM shall contain a dedicated timeout for each IpduM I-PDU within the IpduM module in the configuration parameter IpduMTxConfirmationTimeout.] (BSW02814)

This timeout defines until when the transmission confirmation for this I-PDU has to be received after the transmission. For transmission confirmation, see Chapter 7.4.3.



The timeout period shall take into account the delays in the lower layers.

[IPDUM020] In case the IpduMTxConfirmationTimeout was configured to a value greater than 0, as long as the corresponding timeout timer has not elapsed, and no transmission confirmation for that multiplexed I-PDU was received, the function IpduM_Transmit shall not allow a new transmission request from the upper layer with a COM I-PDU that belongs to the same IpduM I-PDUs. J (BSW02814, BSW02819)

In case IpduMTxConfirmationTimeout was omitted or configured to 0, the IpduM module does not block any new transmission requests.

[IPDUM152] [As long as the timeout (defined in the configuration parameter IpduMTxConfirmationTimeout) has not elapsed and as long as no transmission confirmation for the IpduM I-PDU is received, the function IpduM_Transmit shall return with E_NOT_OK for a new transmission request from the upper layer with a COM I-PDU that belongs to the same IpduM I-PDUs.] (BSW02814)

If the IpduMTxConfirmationTimeout is omitted or configured to 0, the parts of the multiplexed I-PDU may be overwritten even in case they were not already sent or confirmed.

In case a multiplexed I-PDU is only triggered for sending by either updating the dynamic or static part, the non-triggering part might be overwritten if updated multiple times between two transmissions even with a configured IpduMTxConfirmationTimeout. This happens, since the confirmation timeout timer is only started, if the triggering part is updated.

It maybe useful to configure the IpduM transmission confirmation timeout depended of the transmission deadline monitoring timeouts for the single COM I-PDUs of the COM layer configuration; see also [7].

7.4.2 Transmission trigger

The IpduM module receives the static and the dynamic part of a multiplexed I-PDU by separated two transmission requests as two single COM I-PDUs from the PDU-Router module.

[IPDUM021] [The IpduM module shall be configurable to send a transmission request for the new multiplexed I-PDU to the PDU-Router because of the following trigger conditions/ modes:

- receiving a static part
- receiving a dynamic part
- receiving a static or a dynamic part
- does not trigger transmission because of receiving anything of this I-PDU (IpduMTxTriggerMode None) in case of TriggerTransmit



For configuration, see IPDUM052_CONF. | (BSW02811)

The four trigger conditions/ modes defined by IPDUM021 allow controlling the transmission mode of the new assembled I-PDU by the transmission modes of the single I-PDUs sent by COM, see also [7].

Not all of four trigger conditions/ modes defined by IPDUM021 allow guaranteeing the minimum delay time between consecutive transmissions of different instances of multiplexed I-PDUs, because if the transmission is triggered by static and dynamic part or only by the dynamic part, COM does not take care for the minimum delay time. COM treats the static part and the different dynamic parts as unrelated standalone I-PDUs.

The configuration "does not trigger transmission because of receiving anything" is needed if an I-PDU is only sent out because of a TriggerTransmit of a lower layer. With the API IpduM_TriggerTransmit it is possible for lower layers to trigger a send out of an I-PDU.

7.4.3 Just-In-Time update of parts

Sometimes it may be unwanted that the IpduM module not just sends out the locally stored parts, since these parts may contain outdated information e.g. update-bits. Therefore, the IpduM supports a per part configurable just-in-time update mechanism.

[IPDUM168] [In case the transmission of a multiplexed I-PDU is triggered by the update of one part and IpduMJitUpdate is configured to true for the second part, the IpduM module shall update the second part via PduR_IpduMTriggerTransmit before the multiplexed I-PDU is sent out via PduR_IpduMTransmit. | ()

[IPDUM169] [In case the contents of a multiplexed I-PDU is requested via IpduM_TriggerTransmit, the IpduM module shall update all parts which have IpduMJitUpdate configured to true before returning the contents of the multiplexed I-PDU.] ()

7.4.4 Transmission confirmation

Transmission confirmations are given to the IpduM module by the PDU-Router according to the configuration of the I-PDUs in the PDU-Router.

[IPDUM022] [If the IpduM receives a TxConfirmation for a specific IpduM I-PDU, it shall translate this confirmation into the corresponding confirmations for the COM I-PDUs, which were contained in the last sent out multiplexed IpduM I-PDU.] (BSW02813, BSW02818)

Depending on the configuration of IpduMTxDynamicConfirmation (IPDUM163_Conf)



and IpduMTxStaticConfirmation (IPDUM164_Conf), the IpduM will pass zero, one or two confirmations towards COM for one send request. The number of confirmations given to the upper layer does not depend on the IpduMTxTriggerMode.

Examples:

- a) If neither IpduMTxDynamicConfirmation nor IpduMTxStaticConfirmation for the corresponding IpduMTxRequest is configured to true, no COM confirmation is generated.
- b) If IpduMTxStaticConfirmation is configured to true but and IpduMTxDynamicConfirmation is configured to false (or vice versa), then only one COM confirmation is generated.
- c) If both IpduMTxStaticConfirmation and IpduMTxDynamicConfirmation is configured to true, then two COM confirmations are generated; to the I-PDU representing the static part and the I-PDU representing the dynamic part.

[IPDUM023] [If the Tx-Confirmation is not received within the configured timeout IpduMTxConfirmationTimeout the IpduM shall allow new transmission requests for this specific I-PDU after timeout is elapsed. | (BSW02814, BSW02819)

[IPDUM024] [The IpduM shall discard unexpected Tx-Confirmations silently. This may happen if a previously requested transmit request has been timed out, but is confirmed now. | (BSW02814)

There is no need for an error entry in the case of timeout violation because this is already done in COM, if needed. In the case of a proper configuration of the communication stack, the timeout violation in the IpduM modules occurs at the same time than the Deadline Monitoring violation in the COM module.

7.5 Reception

Every I-PDU which is received by the Communication Hardware Abstraction (CAN Interface, Lin Interface, FlexRay Interface) is given to the PDU-Router. The PDU-Router routes multiplexed I-PDUs to the IpduM module. The IpduM module separately routes the static and dynamic parts of the multiplexed I-PDU to their destinations.

It is known at configuration-time which incoming I-PDU IDs correspond to multiplexed I-PDUs with a static part configured. The I-PDU ID is all that is necessary to work out if there is a static part present.

As all multiplexed I-PDUs contain a dynamic part this part always has to be routed.

There are no requirements to handle or notify wrongly configured parts. Hence, if the received I-PDU contains segments not configured for reception on this ECU, they will be ignored silently. Furthermore, if an I-PDU is configured with a PduLength of 0, it will also be ignored silently, since no meaningful processing can be configured.



This situation might occur in a gateway setting, if a multiplexed I-PDU is always routed onto another bus by the PDU Router, but contains a signal in one dynamic part that must be passed to the application. In this case, the multiplexed PDU would have to be routed to the IpduM as well.

7.6 Error classification

The following errors and exceptions shall be detectable by the IpduM module depending on its build version (development/production mode):

	Type or error	Relevance	Related error code	Value [hex]
IPDUM026:	API service called with wrong parameter	Development	IPDUM_E_PARAM	10
IPDUM162:	API service called with a NULL pointer. In case of this error, the API service shall return immediately without any further action, except for reporting this development error.	Development	IPDUM_E_PARAM_POINTER	11
IPDUM153:	API service used without module initialization	Development	IPDUM_E_UNINIT	20

[IPDUM106] | Development error values are of type uint8. | (BSW00337)



7.7 Error detection and notification

The detection of development errors can be configured at pre-compile time via the configuration parameter IpduMDevErrorDetect (IPDUM132_Conf).

[IPDUM027] If IpduMDevErrorDetect is configured to FALSE, the IpduM module shall not report any development errors. [(BSW00338, BSW00350)

[IPDUM028] If IpduMDevErrorDetect is configured to TRUE, all IpduM APIs shall check their input parameters and report detected errors to DET by IPDUM_E_PARAM for normal parameter and IPDUM_E_PARAM_POINTER for pointer parameters. (BSW00338, BSW00323)

7.8 Debugging

[IPDUM144] Feach variable that shall be accessible by AUTOSAR Debugging, shall be defined as global variable.] ()

[IPDUM145] Γ All type definitions of variables, which shall be debugged, shall be accessible by the header file IpduM.h. Γ ()

[IPDUM146] The declaration of variables in the header file shall be such, that it is possible to calculate the size of the variables by C-"sizeof". | ()

[IPDUM147] [Variables available for debugging shall be described in the respective Basic Software Module Description.] ()



8 API specification

8.1 Imported types

This chapter lists all imported types and the corresponding header files.

[IPDUM102] [

Module	Imported Type
ComStack_Types	PduldType
	PduInfoType
Std_Types	Std_ReturnType
	Std_VersionInfoType

^{」(}BSW00357)

8.2 Type definitions

8.2.1 IpduM_ConfigType

[IPDUM159] [

Name:	IpduM_ConfigType
Type:	Structure
Range:	Implementation specific.
Description:	This is the type of the data structure containing the initialization data for the I-PDU
	multiplexer.

⁽BSW00438)

8.3 Function definitions

This is a list of functions provided for upper layer modules.

8.3.1 IpduM_Init

[IPDUM032] [

Service name:	lpduM_Init	
Syntax:	void IpduM Init(
	const IpduM_ConfigType* config	
)	
Service ID[hex]:	0x00	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant	
Parameters (in):	config Implementation specific structure with configuration parameters.	
Parameters (inout):	None	



Parameters (out):	None
Return value:	None
Description:	Initializes the I-PDU Multiplexer.

⁽BSW00344, BSW00405, BSW101, BSW00369)

[IPDUM033] The function IpduM_Init shall initialize all module-related global variables.] (BSW101)

[IPDUM083] In case, the configuration parameter IpduMDevErrorDetect equals TRUE: if the parameter config does not reference a valid configuration, the function IpduM_Init_shall_raise the development error IPDUM_E_PARAM_POINTER. __ (BSW00406)

[IPDUM084] The behavior of the IpduM is unspecified until a correct call to IpduM_-Init is made. | (BSW00406)

8.3.2 IpduM_GetVersionInfo

[IPDUM037] [

Service name:	lpduM_GetVersionInfo		
Syntax:	void IpduM_GetVersionInfo(
	Std_VersionInfoType* versioninfo		
)		
Service ID[hex]:	0x01		
Sync/Async:	Synchronous		
Reentrancy:	Reentrant		
Parameters (in):	None		
Parameters (inout):	None		
Parameters (out):	versioninfo Pointer to where to store the version information of this module.		
Return value:	None		
Description:	Service returns the version information of this module.		

⁽BSW00407, BSW00369, BSW003)

[IPDUM038] The function IpduM_GetVersionInfo shall return the version information of this module. The version information includes:

- Module ID
- Vendor ID
- Vendor specific version numbers (BSW00407). (BSW004)

[IPDUM039] The function IpduM_GetVersionInfo shall be pre compile time configurable On/Off by the configuration parameter: IpduMVersionInfoApi. _ (BSW004, BSW00411)



[IPDUM085] If source code for caller and callee of the function lp-duM_GetVersionInfo are available, the module IpduM should realize this function as a macro, defined in the module's header file. (BSW00330)

8.3.3 **IpduM_Transmit**

[IPDUM043] [

Service name:	lpduM_Transmit			
Syntax:	Std_ReturnType IpduM_Transmit(
	PduIdType PdumTxPduId,			
	const PduInfoType* PduInfoPtr			
)			
Service ID[hex]:	0x03			
Sync/Async:	Synchronous			
Reentrancy:	Non Reentrant for the same PDU-ID. Reentrant for different PDU-ID.			
	PdumTxPduId	ID of I-PDU to be transmitted.		
Parameters (in):		Range: 0(maximum number of I-PDU IDs which are multiplexed)		
		- 1		
	PduInfoPtr	A pointer to a structure with I-PDU related data that shall be		
		transmitted: data length and pointer to I-SDU buffer		
Parameters (inout):	None			
Parameters (out):	None			
Return value:	Std_ReturnType	E_OK: Transmit request is accepted		
		E_NOT_OK: Transmit request is not accepted		
Description:	Service is called by the PDU-Router to request a transmission.			

^{」(}BSW00369)

For a detailed description read Chapter 7.4.1.

8.4 Call-back notifications

8.4.1 IpduM_RxIndication

[IPDUM040] [

Service name:	lpduM_RxIndication		
Syntax:	<pre>void IpduM_RxIndication(</pre>		
	PduIdType RxPduId,		
	PduInfoType* PduInfoPtr		
Service ID[hex]:	0x42		
Sync/Async:	Synchronous		
Reentrancy:	Reentrant for different Pdulds. Non reentrant for the same Pduld.		
	RxPduld ID of the received I-PDU.		
Parameters (in):	PduInfoPtrContains the length (SduLength) of the received I-PDU and a pointer to		
	a buffer (SduDataPtr) containing the I-PDU.		
Parameters (inout):	None		
Parameters (out):	None		
Return value:	None		
Description:	Indication of a received I-PDU from a lower layer communication module.		

」(BSW00369; BSW02817)



[IPDUM041] 「If there is a static part configured in a multiplexed SDU received from the PDU-R, the function IpduM_RxIndication transforms the incoming I-PDU ID into the correct I-PDU ID for the static part's destination and then forwards the SDU via the PDU-R, see PduR_IpduMRxIndication in the PDU-R SWS. | (BSW02812)

[IPDUM042] 「When a multiplexed I-PDU is received from the PDU-R the function IpduM_RxIndication uses the incoming I-PDU ID and the selector field to find out the correct I-PDU ID for the dynamic part's destination and then forwards the I-PDU via the PDU-R, see PduR_IpduMRxIndication in the PDU-R SWS. | (BSW02812)

[IPDUM086] The function IpduM_RxIndication shall be callable in interrupt context, e.g. from receive interrupt. | (BSW02812)

8.4.2 IpduM_TxConfirmation

[IPDUM044] [

Service name:	IpduM TxConfirmation				
Syntax:	void IpduM_TxConfirmation(
	PduIdType TxPduId				
Service ID[hex]:	0x40				
Sync/Async:	Synchronous				
Reentrancy:	Reentrant for different Pdulds. Non reentrant for the same Pduld.				
Parameters (in):	TxPduId ID of the I-PDU that has been transmitted.				
Parameters (inout):	None				
Parameters (out):	None				
Return value:	None				
Description:	The lower layer communication module confirms the transmission of an I-PDU.				

⁽BSW00369)

[IPDUM088] 「The function IpduM_TxConfirmation shall translate the confirmation received from the PDU-Router into confirmations for the I-PDUs which where contained in the sent multiplexed I-PDU.] (BSW02814)

These confirmations are given again to the PDU-Router that has to route them to COM.

[IPDUM087] The function IpduM_TxConfirmation shall be callable in interrupt context, e.g. from a transmit interrupt. [BSW02814]

8.4.3 IpduM_TriggerTransmit

[IPDUM060] [



Service name:	lpduM_TriggerTransmit					
Syntax:	Std_ReturnType IpduM_TriggerTransmit(
	PduIdType TxPduId,					
	PduInfoT	PduInfoType* PduInfoPtr				
)					
Service ID[hex]:	0x41					
Sync/Async:	Synchronous					
Reentrancy:	Reentrant for different Pdulds. Non reentrant for the same Pduld.					
	TxPduld	ID of the SDU that is requested to be transmitted.				
Parameters (in):	PduInfoPtr	Contains a pointer to a buffer (SduDataPtr) to where the SDU				
raiailleleis (III).		shall be copied to. On return, the service will indicate the length of				
		the copied SDU data in SduLength.				
Parameters (inout):	None					
Parameters (out):	None					
	Std_ReturnType	E_OK: SDU has been copied and SduLength indicates the num-				
Return value:		ber of copied bytes.				
Retuiri value.		E_NOT_OK: No SDU has been copied. PduInfoPtr must not be				
		used since it may contain a NULL pointer or point to invalid data.				
Description:	The lower layer communication module requests the buffer of the SDU for trans-					
	mission from the upper layer module.					

」(BSW00369)

[IPDUM090] The function IpduM_TriggerTransmit shall copy the contents of its I-PDU transmit buffer to the I-PDU buffer given by PduInfoPtr. | (BSW02810)

[IPDUM091] The IpduM shall take care about the data consistency during providing the data. | (BSW02810)

Use case: This function is used e.g. by the LIN Master for sending out a LIN frame. In this case, the trigger transmit can be initiiated by the Master schedule table itself or a received LIN header.

This function is also used by the FlexRay Interface for requesting PDUs to be sent in static part (synchronous to the FlexRay global time).

[IPDUM089] 「The function IpduM_TriggerTransmit shall be callable in interrupt context. | (BSW02810)

8.5 Scheduled functions

Most of the functions of the IpduM module are called synchronous in the context of the upper layer (for transmission) and in the context of the lower layer (for reception). However, for the TxConfirmation timeout timer a scheduled function is needed.

[IPDUM103] [

Service name:	lpduM_MainFunction
Syntax:	void IpduM_MainFunction(
	void
Service ID[hex]:	0x10



IXED_CYCLIC_WITH_PRECONDITION
Performs the processes of the activities that are not directly initiated by the calls rom PDU-R.
•

」(BSW00425)

[IPDUM101] The function IpduM_MainFunction shall perform the processing of the IpduM activities that are not directly initiated by the calls from PDU-R. This includes at least the TxConfirmation time observation. (BSW02813)



8.6 Expected Interfaces

In this chapter, all interfaces required from other modules are listed.

8.6.1 Mandatory Interfaces

This chapter defines all interfaces that are required to fulfill the core functionality of the module.

[IPDUM104] [

API function	Description
APTIUNCTION	Description

Actually, the IpduM module needs no APIs of other modules compulsorily, since the IpduM module could be used only for reception or transmission of multiplexed I-PDUs. In such a case the not used reception or transmission APIs of the PduR are optional. Hence, depending on the use-case all used APIs are optional. ()

8.6.2 Optional Interfaces

This chapter defines all interfaces that are required to fulfill an optional functionality of the module.

[IPDUM105] [

API function	Description
Det_ReportError	Service to report development errors.
PduR_lpduMTransmit	Requests transmission of an I-PDU.
PduR_lpduMRxIndication	Indication of a received I-PDU from a lower layer communication mod-
	ule.
	The lower layer communication module requests the buffer of the SDU
	for transmission from the upper layer module.
PduR_lpduMTxConfirmation	The lower layer communication module confirms the transmission of an
	I-PDU.

]()

8.6.3 Configurable interfaces

Not applicable



9 Sequence diagrams

9.1 Transmission of a multiplexed I-PDU and Transmit confirmation

The following sequence chart shows a transmit request initiated by the COM layer. The transmit request is for an I-PDU which has to be transmitted within a multiplexed I-PDU. In the IpduM module is configured that this transmitted I-PDU triggers the sending of the multiplexed I-PDU.



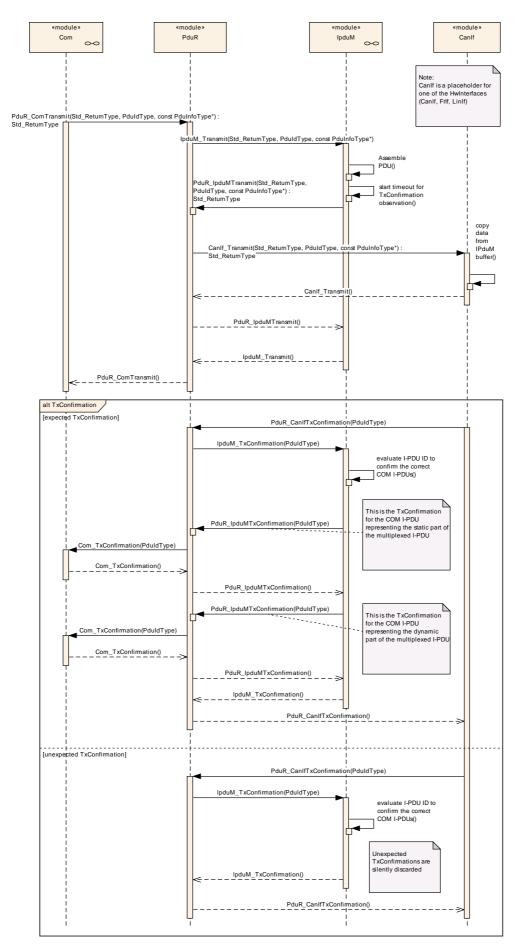




Figure 4 Transmission and confirmation of multiplexed I-PDU with triggering



9.2 Transmission of a multiplexed I-PDU without Trigger

The following sequence chart shows a transmit request initiated by the COM layer. Because of the configuration of the IpduM, no transmit request for the IpduM I-PDU takes place. For configuration see IPDUM052_CONF.

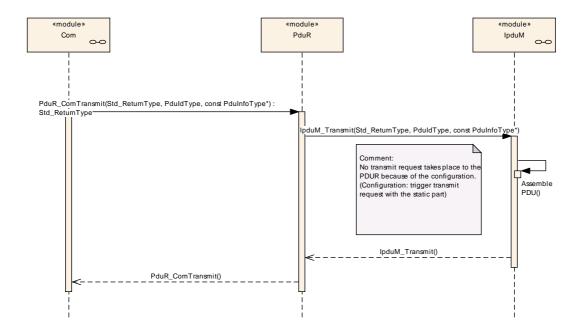


Figure 5 Transmission of a multiplexed I-PDU without triggering



9.3 Reception of the multiplexed I-PDU

The following sequence chart shows a reception of a multiplexed I-PDU. The I-PDU contains a static and a dynamic part and both are configured to create an RxIndication to the PDU-R module.

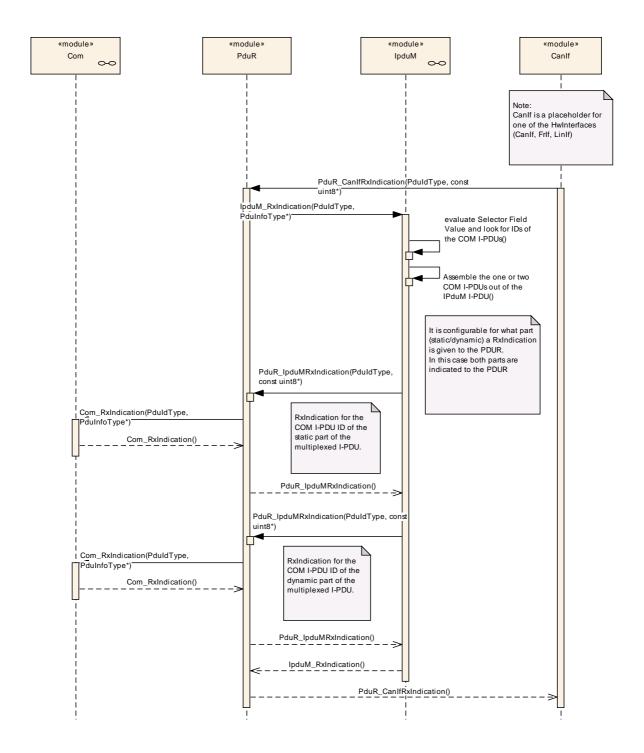


Figure 6 Reception of a multiplexed I-PDU



9.4 Trigger Transmit

The following sequence chart shows a Trigger Transmit request from an interface layer.

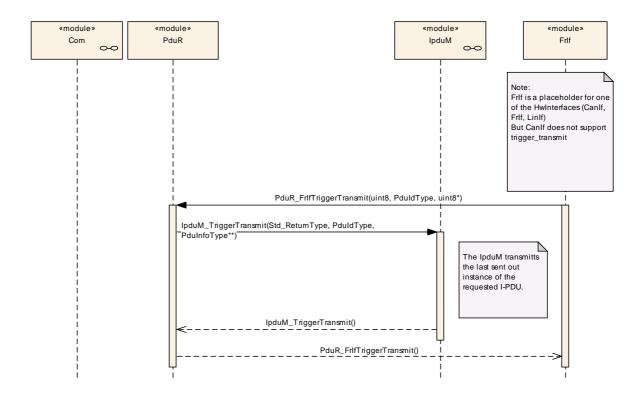


Figure 7 Trigger Transmit request from interface layer



9.5 Missing Transmit Confirmation

The following sequence chart shows the case that a TxConfirmation is not received by the IpduM module during the TX Confirmation timeout. After the timeout has elapsed, it is allowed to send the I-PDU again.

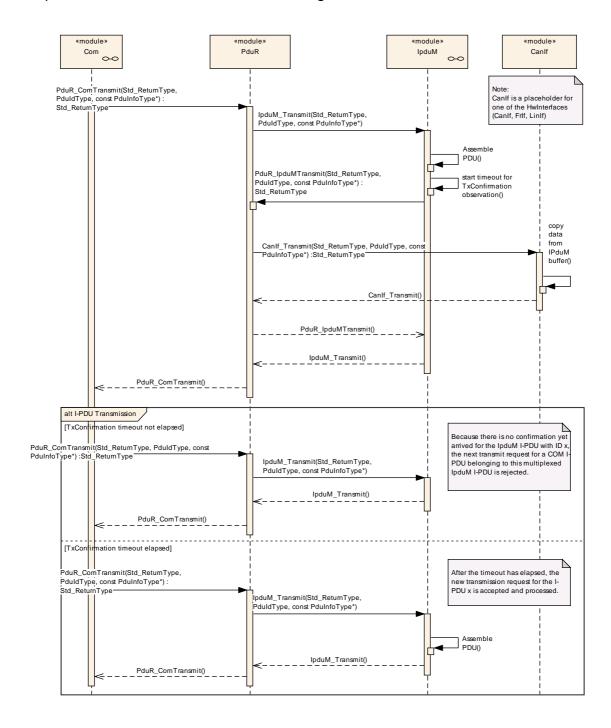


Figure 8 Missing Transmit Confirmation



10 Configuration specification

In general, this chapter defines configuration parameters and their clustering into containers. In order to support the specification Chapter 10.1 describes fundamentals. It also specifies a template (table) you shall use for the parameter specification. We intend to leave Chapter 10.1 in the specification to guarantee comprehension.

Chapter 10.2 specifies the structure (containers) and the parameters of the module IpduM.

Chapter 10.3 specifies published information of the module IpduM.

10.1 How to read this chapter

In addition to this section, it is highly recommended to read the documents:

- AUTOSAR Layered Software Architecture [2]
- AUTOSAR ECU Configuration Specification [4]
 This document describes the AUTOSAR configuration methodology and the AUTOSAR configuration Metamodel in detail.

The following is only a short survey of the topic and it will not replace the ECU Configuration Specification document.

10.1.1 Configuration and configuration parameters

Configuration parameters define the variability of the generic part(s) of implementation of a module. This means that only generic or configurable module implementation can be adapted to the environment (software/hardware) in use during system and/or ECU configuration.

The configuration of parameters can be achieved at different times during the software process: before compile time, before link time or after build time. In the following, the term "configuration class" (of a parameter) shall be used in order to refer to a specific configuration point in time.

10.1.2 Containers

Containers structure the set of configuration parameters. This means:

- all configuration parameters are kept in containers.
- (sub-) containers can reference (sub-) containers. It is possible to assign a multiplicity to these references. The multiplicity then defines the possible number of instances of the contained parameters.



10.2 Containers and configuration parameters

The following chapters summarize all configuration parameters. The detailed meanings of the parameters describe Chapters 7 and Chapter 8.

10.2.1 Variants

There are three variants called: VARIANT-PRE-COMPILE, VARIANT-LINK-TIME and VARIANT-POST-BUILD.

The VARIANT-PRE_COMPILE is designed for modules that are purely configured at pre-compile time. In this variant, all configuration parameters are fixed at compile-time.

The VARIANT-LINK-TIME is designed for the use case where parameters that affect code generation are fixed at compile-time and all other configuration parameters are fixed at link-time.

The VARIANT-POST-BUILD is designed for parameters that affect code generation to be fixed at compile-time and all other parameters to be fixed at post build-time.

10.2.2 Configuration overview

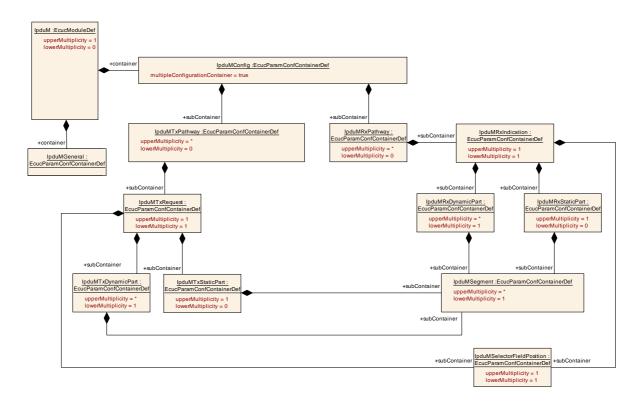


Figure 9 IpduM Configuration Overview



10.2.3 lpduM

Module Name	lpduM
Module Description	Configuration of the IpduM (Ipdu Multiplexer) module.

Included Containers		
Container Name	Multiplicity	Scope / Dependency
lpduMConfig	1	This container contains the sub containers of the IpduM module. The IpduMTxPathway subcontainer includes information about sent I-PDUs. The IpduMRxPathway includes information about received I-PDUs. This container is a MultipleConfigurationContainer, i.e. this container and its sub-containers exist once per configuration set.
IpduMGeneral	1	Contains the general configuration parameters of IpduM.
lpduMPublishedInformati- on	1	Additional published parameters not covered by CommonPublishedInformation container. Note that these parameters do not have any configuration class setting, since they are published information.

10.2.4 lpduMGeneral

SWS Item	IPDUM130_Conf:
Container Name	lpduMGeneral
Description	Contains the general configuration parameters of IpduM.
Configuration Parameters	

SWS Item	IPDUM131_Conf :	IPDUM131_Conf:				
Name	IpduMConfigurationTime	lpduMConfigurationTimeBase				
Description	The cycle time with whic invoked (in seconds).	The cycle time with which IpduM_MainFunction should be invoked (in seconds).				
Multiplicity	1	1				
Туре	EcucFloatParamDef	EcucFloatParamDef				
Range	0 3600	0 3600				
Default value		"				
ConfigurationClass	Pre-compile time	X	All Variants			
	Link time					
	Post-build time					
Scope / Dependency	scope: local					

SWS Item	IPDUM132_Conf:				
Name	IpduMDevErrorDetect				
Description	Active/Deactivate the detection of development errors, for production code this parameter has to be False. True: error detection activated False: error detection deactivated				
Multiplicity	1	1			
Type	EcucBooleanParamDef	EcucBooleanParamDef			
Default value					
ConfigurationClass	Pre-compile time	Х	All Variants		
	Link time				
	Post-build time				
Scope / Dependency	scope: local				



SWS Item	IPDUM133_Conf :	IPDUM133_Conf :				
Name	IpduMStaticPartExists	IpduMStaticPartExists				
Description	never be used with a st compile option. If this is possible to add static p	This is to allow optimizations in the case the IpduM will never be used with a static part. Note that this is a precompile option. If this is set to False then it will not be possible to add static parts after compilation. True: A static part may exist. False: A static part will never exist.				
Multiplicity	1	1				
Туре	EcucBooleanParamDe	EcucBooleanParamDef				
Default value						
ConfigurationClass	Pre-compile time	X	All Variants			
	Link time					
	Post-build time					
Scope / Dependency	scope: local					

SWS Item	IPDUM134_Conf :	IPDUM134_Conf:			
Name	lpduMVersionInfoApi	lpduMVersionInfoApi			
Description		Active/Deactivate the version information API. true: version information activated false: version information deactivated			
Multiplicity	1	1			
Туре	EcucBooleanParamDe	EcucBooleanParamDef			
Default value					
ConfigurationClass	Pre-compile time	X	All Variants		
	Link time	Link time			
	Post-build time	Post-build time			
Scope / Dependency	scope: local				

No Included C	ontainers		

10.2.5 IpduMTxPathway

SWS Item	IPDUM070_Conf:
Container Name	lpduMTxPathway
IDASCHIMION	Contains the configuration parameters transmitted I-PDUs by the IpduM module.
Configuration Parameters	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
lpduMTxRe- quest	1	configuration for a TxRequest

10.2.6 lpduMTxRequest

SWS Item	IPDUM052_Conf:
Container Name	lpduMTxRequest
	This is used to specify the configuration for Transmit requests.
Description	There will one instance of this container for each I-PDU that
	can be requested for transmission (the outgoing I-PDUs) by the



	lpduM.
Configuration Parameters	

SWS Item	IPDUM162_Conf :			
Name	lpduMByteOrder			
	This parameter defines the ByteOrder for all IpduMSegments (static and dynamic part) and for the selectorField within the MultiplexedPdu. The absolute position of a segment in the MultiplexedIPdu is determined by the definition of the ByteOrder parameter: If BIG_ENDIAN is specified, the SegmentPosition indicates the bit position of the most significant bit in an IPDU. If LITTLE_ENDIAN is specified, the SegmentPosition indicates the bit position of the least significant bit in an IPDU.			
Multiplicity	1			
Туре	EcucEnumerationParamDef			
Range	BIG_ENDIAN	ŀ		
	LITTLE_ENDIAN			
ConfigurationClass	Pre-compile time		VARIANT-PRE- COMPILE	
	Link time	Χ	VARIANT-LINK-TIME	
	Post-build time		VARIANT-POST- BUILD	
Scope / Dependency				

SWS Item	IPDUM121_Conf :	IPDUM121_Conf:				
Name	lpduMIPduUnusedAre	lpduMIPduUnusedAreasDefault				
Description		IpduM module fills not used areas of an I-PDU with this bit- pattern If this attribute is omitted the IpduM module does not fill the I-PDU.				
Multiplicity	01	01				
Туре	EcucIntegerParamDet	EcucIntegerParamDef				
Range	0 255	0 255				
Default value		,				
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE			
	Link time	Х	X VARIANT-LINK-TIME			
	Post-build time	X	VARIANT-POST-BUILD			
Scope / Dependency	scope: local					

SWS Item	IPDUM158_Conf:	IPDUM158_Conf:			
Name	lpduMTxConfirmationPduId	IpduMTxConfirmationPduId			
Description	The handle Id to be used by the PduR to confirm to mission of this Pdu. The existence of this parametrial for the PduR generation tool to actually find a symbolicNameValue for the OutgoingPdu.				
Multiplicity	01	01			
Туре	EcucIntegerParamDef (Symbolic Name generated parameter)	EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535	0 65535			
Default value					
ConfigurationClass	Pre-compile time X VARIANT-PRE-COM	MPILE			
	Link time X VARIANT-LINK-TIM	E			
	Post-build time X VARIANT-POST-BL	JILD			
Scope / Dependency	scope: local				

SWS Item	IPDUM124_Conf:
Name	lpduMTxConfirmationTimeout



Description	toring the reception of	This timeout (in seconds) defines the timeout period for monitoring the reception of the TxConfirmation. It is not used when an I-PDU is requested using the trigger transmit API.			
Multiplicity	01				
Туре	EcucFloatParamDef				
Range	0 3600				
Default value					
ConfigurationClass	Pre-compile time	X VARIANT-PRE-COMPILE			
	Link time	X VARIANT-LINK-TIME			
	Post-build time	X VARIANT-POST-BUILD			
Scope / Dependency	scope: local				

SWS Item	IPDUM125_Conf :		
Name	lpduMTxTriggerMode		
Description	Selects whether to send the multiplexed I-PDU immediately or at some later date.		
Multiplicity	1		
Туре	EcucEnumerationParamDef		
Range	DYNAMIC_PART_TRIGGER	Writing the I-PDU representing the dynamic part does trigger a sending of the I-PDU.	
	NONE	Only the buffer in the IpduM are written but not send is triggered, used for IpduM I-PDUs which are requested by TriggerTransmit.	
	STATIC_OR_DYNAMIC_PART_TRIGGER	Writing the I-PDU representing the static or the dynamic part does trigger a sending of the I-PDU.	
	STATIC_PART_TRIGGER	Writing the I-PDU representing the static part does trigger a sending of the I-PDU.	
ConfigurationClass	Pre-compile time	X VARIANT- PRE- COMPILE	
	Link time	X VARIANT- LINK-TIME	
	Post-build time	X VARIANT- POST-BUILD	
Scope / Dependency	scope: local		

SWS Item	IPDUM157_Conf:
Name	lpduMInitialDynamicPart
· · · · · · · · · · · · · · · · · · ·	Reference to the dynamic part that shall be used to initialize this multiplexed TX-I-PDU.
Multiplicity	1



Туре	Reference to [lpduM	Reference to [IpduMTxDynamicPart]		
ConfigurationClass	Pre-compile time	X VARIANT-PRE-COMPILE		
	Link time	X VARIANT-LINK-TIME		
	Post-build time	X VARIANT-POST-BUILD		
Scope / Dependency	scope: local			

SWS Item	IPDUM120_Conf :			
Name	lpduMOutgoingPduRef	lpduMOutgoingPduRef		
Description	Reference to the PDU defining the outgoing I-PDU. When the outgoing I-PDU is sent this is the I-PDU ID give it. It is the IpduM I-PDU ID of the assembled I-PD	to OU.		
Multiplicity	1			
Туре	Reference to [Pdu]			
ConfigurationClass	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME			
	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: external			

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMSelectorFieldPositi- on	1	Specifies the position of the selector field in the outgoing I-PDU.
IpduMTxDynamicPart		This (These) included container(s) must exist for each unique selector field value for this outgoing IpduM I-PDU.
IpduMTxStaticPart	01	This included container configures the static part, if present.

10.2.7 IpduMTxDynamicPart

SWS Item	IPDUM056_Conf:
Container Name	lpduMTxDynamicPart
Description	Configuration parameters for an instance of a TxRequest call into the IpduM. When a Tx Request with the IpduMTxDynamicHandleId is received by the IpduM, all segments as defined by this container are copied from the incoming I-PDU into the outgoing I-PDU buffer and then the send mode honoured. This container is used by the dynamic part of a TxRequest configuration. Therefore, for each outgoing I-PDU there will be one instance of this container for the dynamic part.
Configuration Parameters	

SWS Item	IPDUM167_Conf:			
Name	lpduMJitUpdate			
Description		If configured to true fetch the data of this part Just-In- Time via the triggerTransmit API of the PduR.		
Multiplicity	01	01		
Туре	EcucBooleanParam	EcucBooleanParamDef		
Default value	false	false		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	X	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

SWS Item	IPDUM163_Conf:
Name	lpduMTxDynamicConfirmation



Description	A transmit request can be confirmed by the lower layer. If this parameter is set to true a confirmation of the I-PDU in COM representing the dynamic part is generated.		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value			
ConfigurationClass	Pre-compile time	Χ	VARIANT-PRE-COMPILE
	Link time	Χ	VARIANT-LINK-TIME
	Post-build time	Χ	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	IPDUM127_Conf :			
Name	lpduMTxDynamicHar	lpduMTxDynamicHandleId		
Description	ing Tx Request match	This is an incoming handle id. When the handle of an incoming Tx Request matches this, the bits fields (see IpduMSegment) are copied and the IpduMTxTriggerMode is honored.		
Multiplicity	1	1		
Туре	EcucIntegerParamDe parameter)	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
Range	0 65535	0 65535		
Default value				
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE	
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	X	VARIANT-POST-BUILD	
Scope / Dependency	scope: External			

SWS Item	IPDUM126_Conf :			
Name	IpduMTxDynamicPduRef	lpduMTxDynamicPduRef		
Description	Reference to the Pdu representation in the ECU Confition Description exchange file to be transmitted.	Reference to the Pdu representation in the ECU Configuration Description exchange file to be transmitted.		
Multiplicity	1	1		
Туре	Reference to [Pdu]	Reference to [Pdu]		
ConfigurationClass	Pre-compile time X VARIANT-PRE-COMPILE	=		
	Link time X VARIANT-LINK-TIME			
	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: external			

Included Conta	ncluded Containers		
Container Name	Multiplicity	Scope / Dependency	
IpduMSeg- ment		This is a list of all segments to be copied from the incoming I-PDU to the outgoing I-PDU.	

10.2.8 lpduMTxStaticPart

SWS Item	IPDUM082_Conf :
Container Name	lpduMTxStaticPart
Description	Configuration parameters for an instance of a Tx_Request call into the IpduM. When a Tx Request with the IpduMTxStaticHandleId is received by the IpduM, all segments as defined by this container are copied from the incoming I-PDU into the outgoing I-PDU buffer and then the send mode honoured. This container is used for the static part of a TxRequest configuration. Therefore, for each outgoing I-PDU



	there will be one instance of this container for the static p	part if it exists.
Configuration Parameters		

SWS Item	IPDUM167_Conf:	IPDUM167_Conf:			
Name	IpduMJitUpdate	lpduMJitUpdate			
Description		If configured to true fetch the data of this part Just-In- Time via the triggerTransmit API of the PduR.			
Multiplicity	01	01			
Туре	EcucBooleanParam	EcucBooleanParamDef			
Default value	false	false			
ConfigurationClass	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Link time X VARIANT-LINK-TIME			
	Post-build time	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: local				

SWS Item	IPDUM164_Conf:	IPDUM164_Conf:			
Name	IpduMTxStaticConfirr	nation			
Description	parameter is set to tru	A transmit request can be confirmed by the lower layer. If this parameter is set to true a confirmation of the I-PDU in COM representing the static part is generated.			
Multiplicity	1	1			
Туре	EcucBooleanParamD	EcucBooleanParamDef			
Default value					
ConfigurationClass	Pre-compile time	X VARIANT-PRE-COMPILE			
	Link time	Link time X VARIANT-LINK-TIME			
	Post-build time	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: local				

SWS Item	IPDUM129_Conf:	IPDUM129_Conf :			
Name	lpduMTxStaticHandle	IpduMTxStaticHandleId			
Description	incoming Tx Request	This is an incoming handle id. When the handle of an incoming Tx Request matches this, the segments are copied (IPduMSegment) and the IpduMTxTriggerMode is honored.			
Multiplicity	1	1			
Туре	EcucIntegerParamDe parameter)	EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535				
Default value					
ConfigurationClass	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	X VARIANT-LINK-TIME			
	Post-build time	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: External				

SWS Item	IPDUM128_Conf:	IPDUM128_Conf:			
Name	lpduMTxStaticPduR	lpduMTxStaticPduRef			
Description		Reference to the Pdu representation in the ECU Configuration Description exchange file to be transmitted.			
Multiplicity	1	1			
Туре	Reference to [Pdu]	Reference to [Pdu]			
ConfigurationClass	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	X	VARIANT-LINK-TIME		
	Post-build time	X	VARIANT-POST-BUILD		
Scope / Dependency	scope: external				

Included Containers



Container Name	Multiplicity	Scope / Dependency
lpduMSeg- ment	1 "	This is a list of all segments to be copied from the incoming I-PDU to the outgoing I-PDU.

10.2.9 IpduMRxPathway

SWS Item	IPDUM071_Conf:
Container Name	lpduMRxPathway
Description	Contains the configuration parameters received I-PDUs by the IpduM module.
Configuration Parameters	

Included Containers			
Container Name	Multiplicity	Scope / Dependency	
IpduMRxIndicati- on	1	configuration for RxIndication	

10.2.10 IpduMRxIndication

SWS Item	IPDUM047_Conf:
Container Name	lpduMRxIndication
Description	Contains the configuration for incoming RxIndication calls.
Configuration Parameters	

SWS Item	IPDUM162_Conf:		
Name	lpduMByteOrder		
	This parameter defines the ByteOrder for all IpduMSegments (static and dynamic part) and for the selectorField within the MultiplexedPdu. The absolute position of a segment in the MultiplexedIPdu is determined by the definition of the ByteOrder parameter: If BIG_ENDIAN is specified, the SegmentPosition indicates the bit position of the most significant bit in an IPDU. If LITTLE_ENDIAN is specified, the SegmentPosition indicates the bit position of the least significant bit in an IPDU.		
Multiplicity	1		
Туре	EcucEnumerationParamDef		
Range	BIG_ENDIAN		
	LITTLE_ENDIAN		
ConfigurationClass	Pre-compile time		VARIANT-PRE- COMPILE
	Link time	Χ	VARIANT-LINK-TIME
	Post-build time		VARIANT-POST- BUILD
Scope / Dependency			

SWS Item	IPDUM109_Conf:
Name	lpduMRxHandleId
Description	This is the I-PDU ID of the incoming I-PDU. If an incom-
	ing RxIndication's I-PDU ID matches this value then it is



	unpacked according tainer.	unpacked according to the specification in this container.			
Multiplicity	1	1			
Туре	EcucIntegerParamD this parameter)	EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535	0 65535			
Default value		,			
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME		
	Post-build time	X	VARIANT-POST-BUILD		
Scope / Dependency					

SWS Item	IPDUM108_Conf :	IPDUM108_Conf :		
Name	IpduMRxIndicationPo	lpduMRxIndicationPduRef		
Description		Reference to the received Pdu representation in the ECU Configuration Description exchange file.		
Multiplicity	1	1		
Туре	Reference to [Pdu]	Reference to [Pdu]		
ConfigurationClass	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	Post-build time X VARIANT-POST-BUILD		
Scope / Dependency	scope: external			

Included Containers				
Container Name	Multiplicity	Scope / Dependency		
IpduMRxDynamicPart	1*	Each of these containers contains the configuration for one value of the selector field for the incoming I-PDU's dynamic part.		
IpduMRxStaticPart		This contains the configuration for the incoming I-PDU's static part. If the incoming I-PDU has no static part then this is omitted.		
IpduMSelectorFieldPositi- on		This contains the location of the selector field. At run-time, the selector field is used to select which dynamic part is unpacked.		

10.2.11 IpduMRxDynamicPart

SWS Item	IPDUM048_Conf:
Container Name	lpduMRxDynamicPart
Description	This container contains the configuration for the dynamic part of incoming RxIndication calls. When an incoming received I-PDU's selector field matches the IpduM_Selector_Value, the new outgoing I-PDU for the dynamic part is constructed as defined by the segments of this container and sent out with the I-PDU ID referenced by IpduMOutgoingDynamicPduRef.
Configuration Parameter	ers

SWS Item	IPDUM113_Conf :		
Name	lpduMRxSelectorValue		
Description	This is the selector val	ue th	at this container refers to.
Multiplicity	1		
Туре	EcucIntegerParamDef		
Range	0 255		
Default value			
ConfigurationClass	Pre-compile time	Χ	VARIANT-PRE-COMPILE
	Link time	Χ	VARIANT-LINK-TIME
	Post-build time	Χ	VARIANT-POST-BUILD



Scope / Dependency

SWS Item	IPDUM112_Conf :	IPDUM112_Conf:		
Name	IpduMOutgoingDynam	icPduRe	ef	
Description	Reference to the sent	When the new I-PDU is sent out it is sent with this I-PDU ID. Reference to the sent PDU representation in the ECU Configuration Description exchange file.		
Multiplicity	1	1		
Туре	Reference to [Pdu]	Reference to [Pdu]		
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE	
	Link time	Link time X VARIANT-LINK-TIME		
	Post-build time	Х	VARIANT-POST-BUILD	
Scope / Dependency	scope: external			

scope: local

Included Containers			
Container Name	Multiplicity	Scope / Dependency	
lpduMSeg- ment		The DynamicPart can be separated in multiple segments within the multiplexed PDU.	

10.2.12 IpduMRxStaticPart

SWS Item	IPDUM049_Conf:
Container Name	lpduMRxStaticPart
Description	This container contains the configuration for the static part of incoming RxIndication calls. On reception, the new outgoing I-PDU for the static part is constructed as defined by the segments of this container and sent out with the I-PDU ID referenced by IpduMOutgoingStaticPduRef.
Configuration Parameters	

SWS Item	IPDUM115_Conf:	PDUM115_Conf:			
Name	IpduMOutgoingStaticF	lpduMOutgoingStaticPduRef			
Description	Reference to the sent	When the new I-PDU is sent out it is sent with this I-PDU ID. Reference to the sent Pdu representation in the ECU Configuration Description exchange file.			
Multiplicity	1	1			
Туре	Reference to [Pdu]	Reference to [Pdu]			
ConfigurationClass	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Link time X VARIANT-LINK-TIME			
	Post-build time	Х	VARIANT-POST-BUILD		
Scope / Dependency	scope: external				

Included Conta	ncluded Containers		
Container Name	Multiplicity	Scope / Dependency	
lpduMSeg- ment	1 "	The StaticPart can be separated in multiple segments within the multiplexed PDU.	



10.2.13 IpduMSegment

SWS Item	IPDUM053_Conf:
Container Name	lpduMSegment
Description	This contains the location and the length of a segment. A segment must fit inside the I-PDU. The segment in the source I-PDU that is located at the IpduMSegmentPosition is copied to the same position in the destination I-PDU.
Configuration Parameters	

SWS Item	IPDUM114_Conf :	IPDUM114_Conf :		
Name	lpduMSegmentLengt	lpduMSegmentLength		
Description	Length of the segme	nt in b	oits.	
Multiplicity	1			
Туре	EcucIntegerParamDe	EcucIntegerParamDef		
Range	1 2032	1 2032		
Default value				
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME	
	Post-build time	Х	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

SWS Item	IPDUM159_Conf:	IPDUM159_Conf :		
Name	IpduMSegmentPosit	lpduMSegmentPosition		
Description	Segments bit position	Segments bit position in the multiplexed Pdu.		
Multiplicity	1			
Туре	EcucIntegerParamD	EcucIntegerParamDef		
Range	0 2031			
Default value		·		
ConfigurationClass	Pre-compile time	X VARIANT-PRE-COMPILE		
	Link time	X VARIANT-LINK-TIME		
	Post-build time	X VARIANT-POST-BUILD		
Scope / Dependency	scope: local			

No Included Containers	

10.2.14 IpduMSelectorFieldPosition

SWS Item	IPDUM054_Conf:
Container Name	lpduMSelectorFieldPosition
Description	This contains the location and the length of the selector field.
Configuration Parameters	

SWS Item	IPDUM160_Conf:
Name	lpduMSelectorFieldLength
Description	Length of the selector field in bits.
Multiplicity	1
Туре	EcucIntegerParamDef
Range	18
Default value	
ConfigurationClass	Pre-compile time X VARIANT-PRE-COMPILE
	Link time X VARIANT-LINK-TIME



	Post-build time	Χ	VARIANT-POST-BUILD
Scope / Dependency	scope: local		
•	-		

SWS Item	IPDUM161_Conf:	IPDUM161_Conf:		
Name	IpduMSelectorFieldPo	pduMSelectorFieldPosition		
Description	Selector field bit posit	Selector field bit position in the multiplexed Pdu.		
Multiplicity	1			
Туре	EcucIntegerParamDe	EcucIntegerParamDef		
Range	0 2031			
Default value				
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	X	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

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No Included Containers
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10.2.15 IpduMConfig

SWS Item	IPDUM059_Conf:
Container Name	lpduMConfig [Multi Config Container]
Description	This container contains the sub containers of the IpduM module. The IpduMTxPathway subcontainer includes information about sent I-PDUs. The IpduMRxPathway includes information about received I-PDUs. This container is a MultipleConfigurationContainer, i.e. this container and its sub-containers exist once per configuration set.
Configuration Parameters	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMRx- Pathway	0*	includes information about received I-PDUs
IpduMTxPathway	0*	includes information about sent I-PDUs



10.3 Published Information

[IPDUM170] The standardized common published parameters as required by BSW00402 in the General Requirements on Basic Software Modules [3] shall be published within the header file of this module and need to be provided in the BSW Module Description. The according module abbreviation can be found in the List of Basic Software Modules [1]. | ()

Additional module-specific published parameters are listed below if applicable.

10.3.1 IpduMPublishedInformation

SWS Item	IPDUM141_Conf:
Container Name	lpduMPublishedInformation
Description	Additional published parameters not covered by CommonPublishedInformation container. Note that these parameters do not have any configuration class setting, since they are published information.
Configuration Parameters	

SWS Item	IPDUM142_Conf:
Name	lpduMRxDirectComInvocation
Description	If set to TRUE the COM invocation optimization as defined in IPDUM140 is implemented.
Multiplicity	1
Туре	EcucBooleanParamDef
Default value	
ConfigurationClass	Published Information X All Variants
Scope / Dependency	

No Included Containers

10.4 Configuration Rules

10.4.1 Selector Field

[IPDUM155] The selector fields shall not cross any byte-boundary within the I-PDU. (BSW02802)

Restricting the selector field to be within one byte helps avoiding endianness related problems regarding the selector field.



[IPDUM011] The number of values used of the selector field, i.e. values used to distinguish between different I-PDU layouts, does not have to be the whole range of possible values. J (BSW02803)

Example: The size of a selector field with 3 bits leads to 2³ possible selector field values; it shall be allowed to use only an arbitrary subset of these values. The used subset needs no to be contiguous.

10.4.2 Byte Order

The byte order of all signals and the selector field of a multiplexed I-PDU is restricted to be the same, see IPDUM162_Conf. Any necessary byte order conversion shall be handled within the COM module. The multiplexed I-PDUs in COM and IpduM have to be configured consistently to have the same endianness.

[IPDUM166] The endianness of signals of the de-multiplexed I-PDUs configured in COM must match the endianness of the corresponding multiplexed I-PDU in IpduM as configured per IpduMByteOrder (IPDUM162_Conf). \(\) ()

The above configuration rule also restricts all COM signals of a multiplexed attribute to have the same endianness.



11 Changes to Release 3.0

11.1 Deleted SWS Items

SWS Item	Rationale
IPDUM008	obsolete requirement
IPDUM013	requirement to other module
IPDUM029	obsolete requirement
IPDUM030	redundant to reformulated requirement IPDUM028
IPDUM034	configuration process of initial values changed
IPDUM035	configuration process of initial values changed
IPDUM050_Conf	simplified confirmation configuration
IPDUM051_Conf	simplified confirmation configuration
IPDUM063	requirement to other module
IPDUM064	requirement was implementation specific
IPDUM065	requirement was implementation specific
IPDUM069	became obsolete while updating IpduM initialization process
IPDUM072	requirement to other module
IPDUM092	turned into a note
IPDUM099	requirement to other module
IPDUM117_Conf	simplified confirmation configuration
IPDUM118_Conf	simplified confirmation configuration
IPDUM119_Conf	simplified confirmation configuration
	was removed from the MetaModel against the ECU Configuration Pa-
IPDUM123	rameter XML File; the length of the I-PDU has to looked up via Pdu-
	Length parameter of referenced by the IpduMOutgoingPduRef
IPDUM154	redundant to reformulated requirement IPDUM027

11.2 Replaced SWS Items

SWS Item of Release 1	replaced by SWS Item	Rationale
IPDUM002	IPDUM148 IPDUM149 IPDUM150 IPDUM151	CT SWS Analysis required to separate requirements regarding include file structure
IPDUM122	IPDUM157_CONF	configuration process of initial values changed

11.3 Changed SWS Items

SWS Item	Rationale
IPUDM006	rephrased due to FIBEX harmonization
IPDUM015	rephrased requirement and added reference to Figure
IPDUM017	clarified term trigger conditions
IPDUM020	clarified the case when no timeout was configured
IPDUM021	added a reference to clarify TriggerTransmit case
IPDUM027	clarified development error reporting
IPDUM028	clarified development error reporting
IPDUM032	added const to configuration pointer
IPDUM052_Conf	update description of included container IpduMBitField



IPDUM060	harmonized trigger transmit APIs within the communication stack	
IPDUM067	clarified term buffer	
IPDUM068	updated IpduM initialization process	
IPDUM083	added development error IPDUM_E_PARAM_POINTER	
IPDUM102	updated to actual BSW UML model	
IPDUM104	updated table of mandatory interfaces	
IPDUM105	updated table of optional interfaces	
IPDUM112_Conf	clarified description of PDU reference	
Chapter 10	the configuration structure was updated in order to harmonize the IpduM	
	configuration with FIBEX and the new configuration variant VARIANT-	
	PRE-COMPILE has been added	

11.4 Added SWS Items

SWS Item	Rationale
IPDUM140	turned note about direct COM invocation optimization into a requirement
IPDUM141_CONF	added new configuration container IpduMPublishedInformation
IPDUM142_CONF	added new published parameter IpduMRxDirectComInvocation
IPDUM143	updated IpduM initialization process
IPDUM144	added according to the debugging concept
IPDUM145	added according to the debugging concept
IPDUM146	added according to the debugging concept
IPDUM147	added according to the debugging concept
IPDUM148-IPDUM151	see replaced SWS items
IPDUM152	split IPDUM020 to IPDUM020 and IPDUM152
IPDUM153	split IPDUM026 to IPDUM026 and IPDUM153
IPDUM154	split IPDUM027 to IPDUM027 and IPDUM154
IPDUM155	restricted selector-field to be within one byte
IPDUM158_Conf	added IpduMTxConfirmationPduId
IPDUM159	added requirement ID for IpduM_ConfigType
IPDUM160	added requirement ID for published information
IPDUM161_Conf	explicit configuration of selector field
IPDUM001_PI	rework of Published Information
IPDUM162	added development error IPDUM_E_PARAM_POINTER
IPDUM162_Conf	added configuration parameter IpduMByteOrder
IPDUM163_Conf	simplified confirmation configuration
IPDUM164_Conf	simplified confirmation configuration
IPDUM165	added requirement for explicit version checking of include file
IPDUM166	added configuration restriction to clarify that the IpduM module shall provide no endianness conversion mechanism



12 Not applicable requirements

[IPDUM999] Γ These requirements are not applicable to this specification. \rfloor (BSW171, BSW00375, BSW00437, BSW168, BSW00423, BSW00427, BSW00431, BSW00432, BSW00433, BSW00434, BSW00336, BSW00339, BSW00422, BSW00417, BSW00386, BSW162, BSW005, BSW164, BSW00325, BSW00326, BSW00314, BSW00377)