Computational Methods of Optimization Second Midterm(Oct 20, 2024)

Time: 70 minutes

Instructions

- $\bullet\,$ Answer all questions
- Please write your answer in the spaces provided. Answers written outside will not be graded.
- Rough work can be done in designated spaces.
- This is a closed book exam.

| Name: | | | |
|--------|-------|---------|-------|
| | | | |
| | | | |
| Index: | SRNO: | Degree: | Dept: |

| Question: | 1 | 2 | 3 | 4 | Total |
|-----------|----|----|----|----|-------|
| Points: | 10 | 10 | 10 | 15 | 45 |
| Score: | | | | | |

In the following, let $\mathbf{I} = [\mathbf{e}_1, \dots, \mathbf{e}_d]$ be a $d \times d$ matrix with e_j be the jth column. Also $\mathbf{x} = [x_1, x_2, \dots, x_d]^{\top} \in \mathbb{R}^d$ and $\|\mathbf{x}\| = \sqrt{\mathbf{x}^{\top}\mathbf{x}}$. Set of real symmetric $d \times d$ matrices will be denoted by \mathcal{S}_d . [n] will denote the set $\{1, 2, \dots, n\}$ We will denote

$$\mathbf{x}^* = \underset{\mathbf{x} \in \mathbb{R}^d}{\operatorname{argmin}} \ f(\mathbf{x}) \quad f(\mathbf{x}) = \frac{1}{2} \mathbf{x}^\top Q \mathbf{x} + b^\top \mathbf{x} + c \tag{Quad}$$

where $Q \in \mathcal{S}_d$, $Q \succ 0$, $b \in \mathbb{R}^d$, and $c \in \mathbb{R}$. Let λ_i be the eigenvalue and $\mathbf{v}^{(i)}, \|\mathbf{v}^{(i)}\| = 1$ be the corresponding eigenvector of Q. Assume $\lambda_1 > \lambda_2 > \dots, \lambda_d > a > 0$.

- 1. Consider (Quad). It is given that $c = 5, \lambda_2 = 5, b^{\top} \mathbf{v}^{(d)} = 2, b^{\top} \mathbf{v}^{(2)} = -10$. You have chosen to use the Conjugate Direction(CD) Algorithm. with $\mathbf{x}^{(0)} = 0$.
 - (a) Let $\mathbf{v}^{(d)}$ be the first conjugate direction. After one iteration of the Algorithm one finds that $f(\mathbf{x}^{(1)}) = -5$.

 - ii. (2 points) Justify.

Solution: By the question $\mathbf{x}^{(1)} = \alpha \mathbf{v}^{(d)}$. Note that $\nabla f(\mathbf{x}^{(0)}) = b$. By CD Algorithm stepsize is given by $\alpha = -\frac{\nabla f(\mathbf{x}^{(0)})^{\top}\mathbf{u}}{\mathbf{u}^{\top}Q\mathbf{u}}$ for a direction \mathbf{u} . The Decrease is given by $f(x^{(0)}) - f(\mathbf{x}^{(1)}) = \frac{1}{2}\alpha^2\mathbf{u}^{\top}Q\mathbf{u}$. Putting everything together we obtain $10 = \frac{1}{2}\alpha^2\lambda_d$, $\alpha = \frac{-2}{\lambda_d}$ which yields $\lambda_d = \frac{1}{5}$ and $\alpha = -10$.

iii. (1 point) Is $\mathbf{v}^{(d)}$ a descent Direction? Justify.

Solution: No. $\nabla f(\mathbf{x}^{(0)})^{\top} \mathbf{v}^{(d)} = b^{\top} \mathbf{v}^{(d)} = 2 > 0.$

(b) State and solve a problem in two variables which will yield $\tilde{\mathbf{x}}$ defined below.

$$\tilde{\mathbf{x}} = \operatorname{argmin}_{\mathbf{x} = \beta_1 \mathbf{v}^{(2)} + \beta_2 \mathbf{v}^{(d)}, \beta_1, \beta_2 \in \mathbb{R}} f(\mathbf{x})$$

i. (2 points) State the problem. All constants in the problem should be evaluted.

Solution:
$$f(\mathbf{x}) = c + (\beta_1 \mathbf{v}^{(2)} + \beta_2 \mathbf{v}^{(d)})^{\top} b + \frac{1}{2} (\lambda_2 \beta_1^2 + \lambda_d \beta_2^2)$$

$$\tilde{\mathbf{x}} = \beta_1^* \mathbf{v}^{(2)} + \beta_2^* \mathbf{v}^{(d)} \quad \beta_1^*, \beta_2^* = \operatorname*{argmin}_{\beta_1 \in \mathbb{R}, \beta_2 \in \mathbb{R}} - 10\beta_1 + 2\beta_2 + \frac{1}{2} (5\beta_1^2 + \frac{1}{5} \beta_2^2)$$

ii. (1 point) Solve the problem to determine $\tilde{\mathbf{x}} = 2\mathbf{v}^{(2)} - 10\mathbf{v}^{(d)}$



| (c) Su | pose the CD algorithm is continued from the first quest | tion with | $\mathbf{v}^{(2)}$ as | s the next | direction to |
|--------|--|-----------|-----------------------|------------|--------------|
| ob | $\operatorname{ain} \mathbf{x}^{(2)}$. | | | | |
| i | (1 point) For this choice find the value of $f(\mathbf{x}^{(2)}) = \underline{\hspace{1cm}}$ | -15 | | | |
| ii | (2 points) Justify. | | | | |

Solution: One can use the Expanding subspace theorem to note that $\mathbf{x}^{(2)} = \tilde{\mathbf{x}}$ and

$$f(\mathbf{x}^{(2)}) = c - 20 = -15$$

| Rough | Work |
|-------|---|
| TOUGH | * |

| I. | | | |
|----|--|--|--|

| 2. | Refer to (Quad). Let $\lambda_4 > 9 > \lambda_5$, $a = 1$, $d = 100$. It is expected that starting from an arbitrary point |
|----|---|
| | $\mathbf{x}^{(0)}$, the Conjugate Gradient Algorithm provably finds a point, $\tilde{\mathbf{x}}$, such |

$$E(\tilde{\mathbf{x}}) \le rE(\mathbf{x}^0), \quad E(\mathbf{x}) = \frac{1}{2}(\mathbf{x} - \mathbf{x}^*)^\top Q(\mathbf{x} - \mathbf{x}^*)$$

where r is a positive number less than 1.

Report your answers to first decimal place.

- (a) (2 points) In how many iterations will we reach r = 0.7? Number of iterations=_______5
- (b) (2 points) If $\lambda_9 = 7$, what is the value of r after 10 iterations? $r = \underline{\qquad} 0.6$
- (c) (2 points) Suppose you used partial conjugate gradient algorithm by restarting it after 5 iterations what is the obtained value of r after 10 iterations. $r = \underline{\qquad 0.4}$
- (d) (4 points) Justify your answer.

Solution: Recall that for the kth iterate $\mathbf{x}^{(k)}$ satisfies

$$E(\mathbf{x}^{(k)}) \le \bar{\lambda} E(\mathbf{x}^{(0)}), \quad \bar{\lambda} = \max_{1 \le i \le d} (q_k(\lambda_i))^2$$

for any kth degree polynomial, $q_k(t)$ such that $q_k(0)=1$. Consider the polynomial $q_k(t)=(1-\frac{t}{l+a})\prod_{i=1}^{k-1}\left(1-\frac{t}{\lambda_i}\right)$ where $\lambda_{k+1}\leq l\leq \lambda_k$. If we put k=5, l=9 we obtain $\bar{\lambda}=0.64$. If we put k=10, l=7 we obtain $\bar{\lambda}=0.5625$. If we do partial conjugate gradient we obtain $r=(0.64)^2\approx 0.37$.

3. Refer to (Quad). Let $G^{(k)} \succ 0, \delta_k = \mathbf{x}^{(k+1)} - \mathbf{x}^{(k)}$ and $\gamma_k = \nabla f(\mathbf{x}^{(k+1)}) - \nabla f(\mathbf{x}^{(k)})$ where $\mathbf{x}^{(k)}$ are the iterates of a Quasi Newton Algorithm of the form.

$$G^{(k+1)} = G^{(k)} + BAB^{\top}, B = \begin{bmatrix} \delta_k & G^{(k)} \gamma_k \end{bmatrix}, \quad A = \begin{bmatrix} a & b \\ b & c \end{bmatrix}$$

It is given that

$$\delta_k^{\top} \gamma_k = 10 \quad \gamma_k^{\top} G^{(k)} \gamma_k = 2$$

- (a) (2 points) Let a=0. Determine values b,c such that the update satisfies the Quasi-Newton condition $G^{(k+1)}\gamma_k=\delta_k$
- (b) (3 points) Justify your answer

Solution: From the expression $G^{(k+1)}\gamma_k = \delta_k$, we have

$$(1 + b\delta_k^{\top} \gamma_k + c\gamma_k^{\top} G^{(k)} \gamma_k) G^{(k)} \gamma_k + (-1 + b\gamma_k G^{(k)} \gamma_k) \delta_k = 0$$

Since a = 0 $1 = b\gamma_k^{\mathsf{T}} G^{(k)} \gamma_k$, $0 = 1 + b\delta_k^{\mathsf{T}} \gamma_k + c\gamma_k^{\mathsf{T}} G^{(k)} \gamma_k$

$$1 = 2b, -1 = 10b + 2c \implies b = \frac{1}{2}, c = -3$$

- (c) (2 points) Let b=0. Determine values a,c such that the update satisfies the Quasi-Newton condition $G^{(k+1)}\gamma_k=\delta_k$ $a=\frac{1}{10}$ $c=\frac{1}{10}$
- (d) (3 points) Between the choices where a=0 and b=0, which one should we prefer. Give brief justification.

Solution: We prefer the second update as the obtained G would be positive definite. (Why?) No guarantee exists for a = 0.

4. Consider the problem

$$\min_{\mathbf{x} \in \mathbb{R}^d} f(\mathbf{x})$$
 subject to $\|\mathbf{x} - \mathbf{a}\|^2 \le r^2$

where $\mathbf{a} \in \mathbb{R}^d, r \in \mathbb{R}$ and f is defined in (Quad) with $Q = \mathbf{I}$.

(a) (1 point) State the Lagrangian of the problem, $\mathcal{L}(\mathbf{x}, \lambda)$.

Solution: $\mathcal{L}(\mathbf{x}, \lambda) = \frac{1}{2} ||\mathbf{x}||^2 + b^{\mathsf{T}} \mathbf{x} + c + \lambda (||\mathbf{x} - \mathbf{a}||^2 - r^2)$

(b) (2 points) State the KKT conditions of the problem.

Solution: $(1+2\lambda)\mathbf{x} + b - \lambda\mathbf{a} = 0$

$$\lambda(\|\mathbf{x} - \mathbf{a}\|^2 - r^2) = 0, \lambda \ge 0$$
$$\|\mathbf{x} - \mathbf{a}\|^2 < r^2$$

(c) (4 points) Find $\hat{\mathbf{x}}$, a KKT point for the problem. Express your answer in the form of $\hat{\mathbf{x}} = \mathbf{a} + \mathbf{v}$. Assume that $||b + \mathbf{a}||^2 > r^2$. Compute the value of λ .

Solution:

$$\hat{\mathbf{x}} = -\frac{1}{1+2\lambda}b + \mathbf{a}\frac{2\lambda}{1+2\lambda} = \mathbf{a} - \frac{1}{1+2\lambda}(\mathbf{a}+b)$$

$$\|\hat{\mathbf{x}} - \mathbf{a}\| = \frac{1}{1 + 2\lambda} \| - b - \mathbf{a}\| \le r, \ \lambda > 0$$

Since $\|-b-\mathbf{a}\|^2 > r^2$, it implies that $\lambda > 0$ and hence

$$r = \|\hat{\mathbf{x}} - \mathbf{a}\| = \frac{1}{1 + 2\lambda} \|b + \mathbf{a}\|$$

Thus $\hat{\mathbf{x}} = \mathbf{a} - \frac{r}{\|b+\mathbf{a}\|}(b+\mathbf{a})$ is a KKT point. The value of $\lambda = \frac{1}{2}(\frac{\|b+\mathbf{a}\|}{r} - 1)$.

(d) Consider the projection problem

$$\min_{\mathbf{x} \in \mathbb{R}^d} \frac{1}{2} \|\mathbf{x} - \mathbf{z}\|^2 \quad \text{subject to } \|\mathbf{x} - \mathbf{a}\|^2 \le r^2$$

i. (3 points) Find a KKT point for this problem.

Solution: Following the previous result

$$\hat{\mathbf{x}} = \mathbf{a} + \frac{r}{\|\mathbf{z} - \mathbf{a}\|} (\mathbf{z} - \mathbf{a})$$

is a KKT point

ii. (5 points) Is the obtained KKT point the optimal point? A self-contained argument based on discussions of topics in the class needs to be provided.

Solution: Denoting $P_S(\mathbf{z})$ the projection onto the given set, we note the property that

$$(P_S(\mathbf{z}) - \mathbf{z})^{\top}(\mathbf{x} - P_S(\mathbf{z})) \ge 0$$

For the KKT point, $\mathbf{a} + \frac{r}{\|\mathbf{z} - \mathbf{a}\|}(\mathbf{z} - \mathbf{a})$, and for any feasible $\mathbf{x} = \mathbf{a} + r\mathbf{v}$, $\|\mathbf{v}\| \le 1$, we have

$$r(\frac{r}{\|\mathbf{z} - \mathbf{a}\|} - 1)(\mathbf{z} - \mathbf{a})^{\top}(\mathbf{v} - \frac{1}{\|z - \mathbf{a}\|}(z - \mathbf{a})) \ge 0$$

. This is due to the inequality $(\mathbf{z} - \mathbf{a})^{\top} \mathbf{v} \leq \|\mathbf{z} - \mathbf{a}\|$ and $r < \|\mathbf{z} - \mathbf{a}\|$.