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DSL - Lab - 8

Que-1

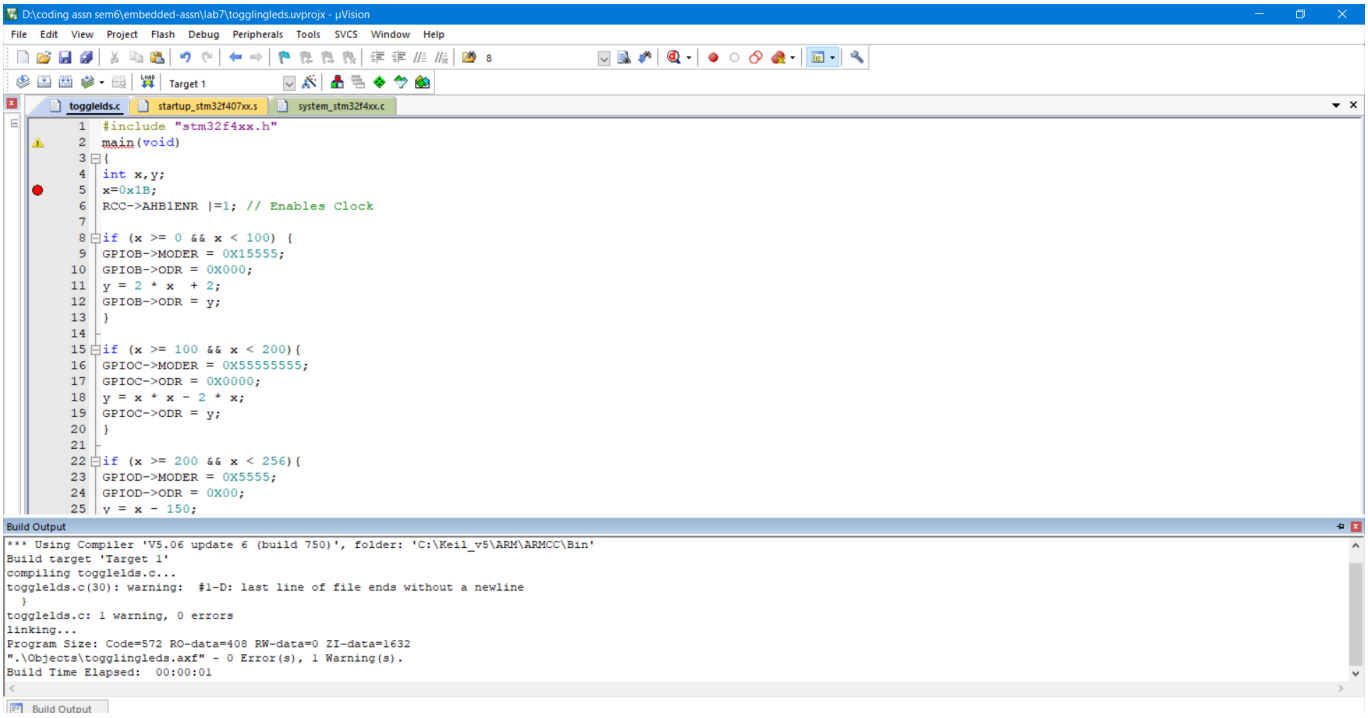
```
#include "stm32f4xx.h"
main(void)
{
int x,y;
x=0x1B;
RCC->AHB1ENR |= 0x0E; // Enables Clock

if (x >= 0 && x < 100) {
// RCC->AHB1ENR = 0x02;
GPIOB->MODER = 0X15555;
GPIOB->ODR = 0X000;
y = 2 * x  + 2;
GPIOB->ODR = y;
}

if (x >= 100 && x < 200){
// RCC->AHB1ENR = 0x04;
GPIOC->MODER = 0X55555555;
GPIOC->ODR = 0X0000;
y = x * x - 2 * x;
GPIOC->ODR = y;
}

if (x >= 200 && x < 256){
// RCC->AHB1ENR = 0x08;
GPIOD->MODER = 0X5555;
GPIOD->ODR = 0X00;
y = x - 150;
GPIOD->ODR = y;
}

}
```

code-explanation

- first we are enabling the clock
- then we are applying conditions on x and based on the three conditions we are assigning values to ports
- $(0 \leq x < 100)$ first we are setting moder value to (0001 0101 0101 0101 0101) which is $0x15555$ the last 1 is due to overflow since $2x$ can also be 9 bit number if x is 8 bit number. and then the calculated value is send to ODR

- $(100 \leq x < 200)$ here the value is $x^2 - 2x$ which can be maximum 16 bits so all the moders of port B is set to output mode
- $(200 \leq x < 256)$ here the value is $x - 150$ which is confined to 8 bits only so to support that only $0x5555$ is sufficient and the output is send to odr
- setting the clock to RCC->AHB1ENR=0x02 for port B, 0x04 for port C, 0x08 for port D.

build-output



Que-2

Task-2

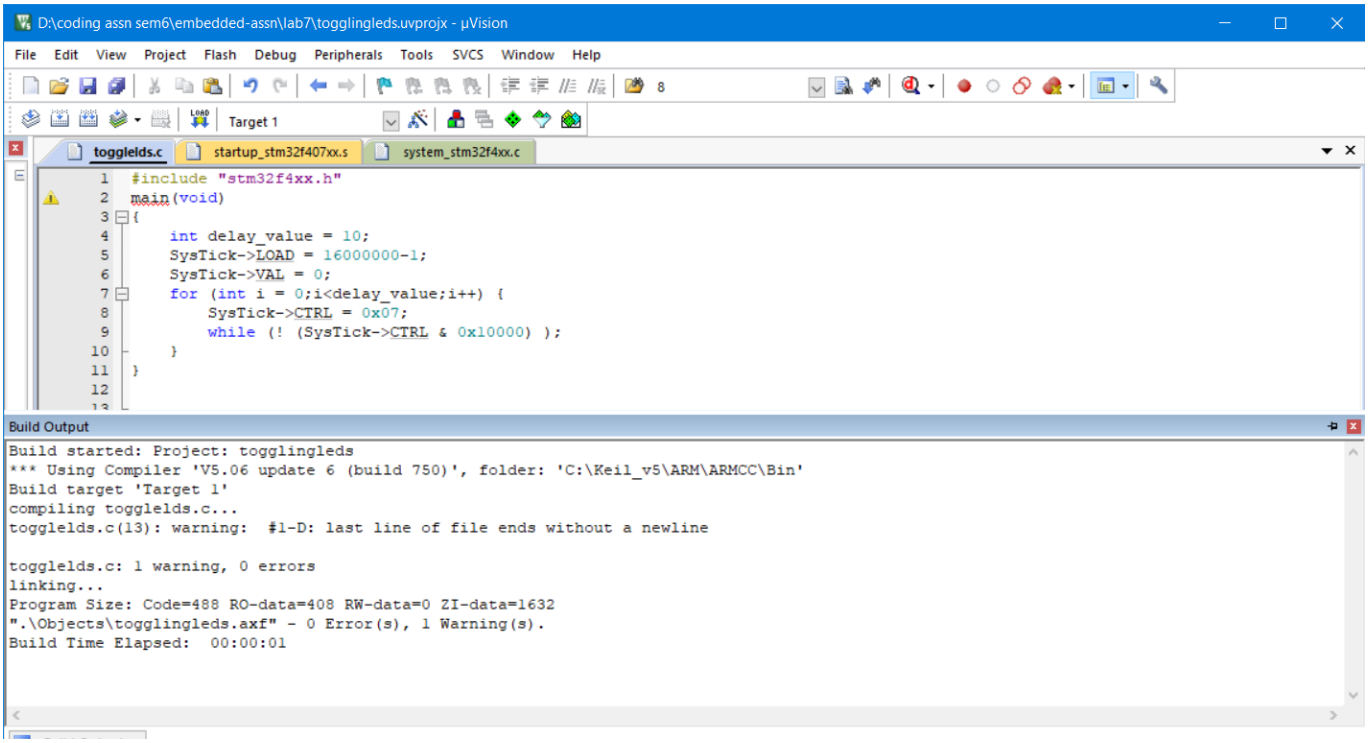
```c
#include "stm32f4xx.h"
main(void)
{
    int delay_value = 10;
    SysTick->LOAD = 16000000-1;
    SysTick->VAL = 0;
    for (int i = 0;i<delay_value;i++) {
        SysTick->CTRL = 0x07;
        while (! (SysTick->CTRL & 0x10000) );
    }
}
```

code-explanation

- first find the load value, it will take which is (Time * Freq - 1) = $16 \times 10^6 \times 1 - 1 = 15999999$
- the above value is for 1s delay so to make it 10 seconds we need to run the loop 10 times
- and hence for loop is there

- we are checking the condition for it to generate an interrupt once it completes the counting and once it completes it breaks the while loop and run again.

build-output



Task-3

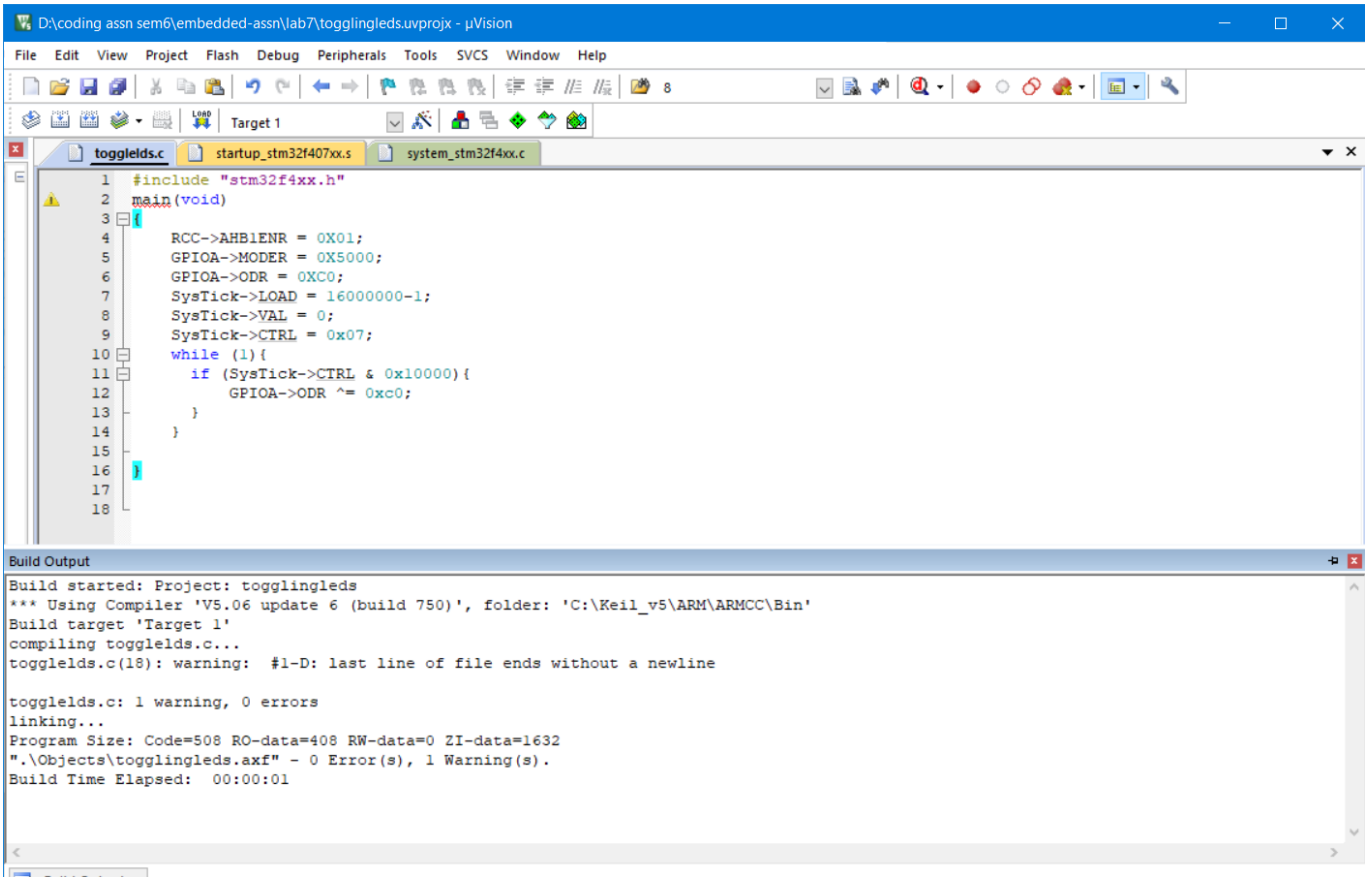
```c
#include "stm32f4xx.h"
main(void)
{
    RCC->AHB1ENR = 0X01;
    GPIOA->MODER = 0X5000;
    GPIOA->ODR = 0XC0;
    SysTick->LOAD = 16000000-1;
    SysTick->VAL = 0;
    SysTick->CTRL = 0x07;
    while (1){
        if (SysTick->CTRL & 0x10000){
            GPIOA->ODR ^= 0xc0;
        }
    }

}
```

code-explanation

- here we need to toggle PA6 and PA7 so again we are setting RCC->AHB1ENR to 1 and setting moder = 0x5000 and odr = 0xc0 for the purpose of PA6 and PA7
- and setting the load according to 16MHz freq and 1s delay

- and in while loop we are waiting systick->ctrl register to have countflag 1 and once it is 1 we are toggling the led

build-output



Que-3

Task-4

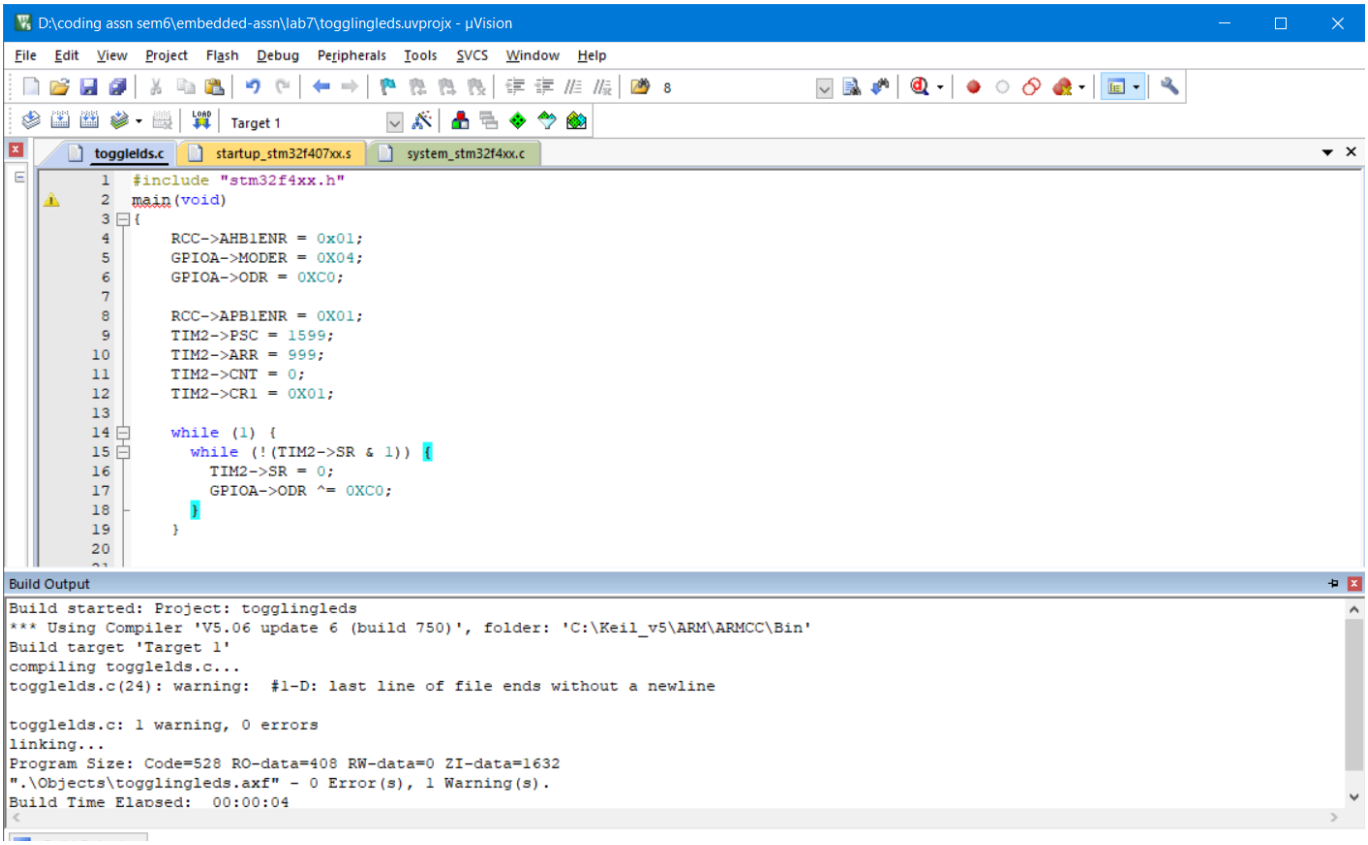
```c
#include "stm32f4xx.h"
main(void)
{
    RCC->AHB1ENR = 0x01;
    GPIOA->MODER = 0X04;
    GPIOA->ODR = 0XC0;

    RCC->APB1ENR = 0X01;
    TIM2->PSC = 1599;
    TIM2->ARR = 999;
    TIM2->CNT = 0;
    TIM2->CR1 = 0X01;

    while (1) {
        while (!(TIM2->SR & 1)) {
            TIM2->SR = 0;
            GPIOA->ODR ^= 0XC0;
        }
    }
```

```
}
```

code-explanation

- first enable the GPIOA clock and then set GPIOA->MODER in output mode for pinA1 and glow the led
- then enable tim2 using RCC->APB1ENR and set prescalar and arr value and set count register to 0 and enable the counter using TIM2->CR1
- and now until a request is pending toggle the led and it will generate a square wave since it will be 1 for sometime and 0 for other time

build-output



Que-4

```
#include "stm32f4xx.h"
main(void)
{

    RCC->APB2ENR |= 0X100;
    RCC->AHB1ENR |= 0X01;

    ADC1->CR2 |= 0X0402; // ENABLING 10TH AND 2ND BIT OF ADC1 REGISTER
    GPIOA->MODER |= 0X03; // ADC MODE
```

```
        while (1) {
            ADC1->CR2 |= 0X01;
            ADC1->SQR3 |= 0;
            ADC1->SR = 0;
            ADC1->CR2 |= (1<<30);
            while (!(ADC1->SR & (1<<1)));

        }


    }
```

code-explanation

build-output